

/*Implement c Program for minimum Heap Tree*/

```
#include <stdio.h>
```

```
// Function to heapify a subtree rooted with node i which is an index in arr[]
```

```
void minHeapify(int arr[], int n, int i) {
```

```
    int smallest = i; // Initialize smallest as root
```

```
    int left = 2 * i + 1; // left child
```

```
    int right = 2 * i + 2; // right child
```

```
    // If left child is smaller than root
```

```
    if (left < n && arr[left] < arr[smallest])
```

```
        smallest = left;
```

```
    // If right child is smaller than smallest so far
```

```
    if (right < n && arr[right] < arr[smallest])
```

```
        smallest = right;
```

```
    // If smallest is not root
```

```
    if (smallest != i) {
```

```
        // Swap the found smallest element with the root
```

```
        int temp = arr[i];
```

```
        arr[i] = arr[smallest];
```

```
        arr[smallest] = temp;
```

```
        // Recursively heapify the affected sub-tree
```

```
        minHeapify(arr, n, smallest);
```

```
    }
```

```
}
```

```
// Function to build a min heap from an array
```

```
void buildMinHeap(int arr[], int n) {
```

```
// Start from the last non-leaf node and heapify all nodes in reverse order
for (int i = n / 2 - 1; i >= 0; i--)
    minHeapify(arr, n, i);
}
```

```
// Function to print an array
void printArray(int arr[], int n) {
    for (int i = 0; i < n; ++i)
        printf("%d ", arr[i]);
    printf("\n");
}
```

```
// Test the heap construction function
int main() {
    // Test with a random array
    int randomArray[] = {4, 10, 3, 5, 15};
    int n1 = sizeof(randomArray) / sizeof(randomArray[0]);

    printf("\nOriginal Random Array: ");
    printArray(randomArray, n1);

    // Build heap
    buildMinHeap(randomArray, n1);

    printf("\nMin Heap from Random Array: ");
    printArray(randomArray, n1);

    printf("\n");
}
```

```
// Test with a sorted array
int sortedArray[] = {8, 6, 5, 4, 2};
```

```
int n2 = sizeof(sortedArray) / sizeof(sortedArray[0]);

printf("\nOriginal Sorted Array: ");
printArray(sortedArray, n2);

// Build heap
buildMinHeap(sortedArray, n2);

printf("\nMin Heap from Sorted Array: ");
printArray(sortedArray, n2);

return 0;
}
```

/*Implement c Program for DFS*/

```
#include <stdio.h>
```

```
#define MAX_VERTICES 100
```

```
// Function to perform Depth-First Search (DFS) traversal
```

```
void DFS(int graph[MAX_VERTICES][MAX_VERTICES], int visited[MAX_VERTICES], int vertices, int start) {
```

```
    printf("%d ", start); // Print the current vertex
```

```
    visited[start] = 1; // Mark the current vertex as visited
```

```
    // Visit all adjacent vertices
```

```
    for (int i = 0; i < vertices; i++) {
```

```
        if (graph[start][i] == 1 && !visited[i]) {
```

```
            DFS(graph, visited, vertices, i);
```

```
        }
```

```
    }
```

```
}
```

```
int main() {
```

```
    int vertices, edges;
```

```
    // Input the number of vertices
```

```
    printf("Enter the number of vertices: ");
```

```
    scanf("%d", &vertices);
```

```
    if (vertices <= 0 || vertices > MAX_VERTICES) {
```

```
        printf("Invalid number of vertices. Exiting...\n");
```

```
        return 1;
```

```
    }
```

```

int graph[MAX_VERTICES][MAX_VERTICES] = {0}; // Initialize the adjacency matrix with zeros
int visited[MAX_VERTICES] = {0};           // Initialize the visited array with zeros

// Input the number of edges
printf("Enter the number of edges: ");
scanf("%d", &edges);

if (edges < 0 || edges > vertices * (vertices - 1)) {
    printf("Invalid number of edges. Exiting...\n");
    return 1;
}

// Input edges and construct the adjacency matrix
for (int i = 0; i < edges; i++) {
    int start, end;
    printf("Enter edge %d (start end): ", i + 1);
    scanf("%d %d", &start, &end);

    // Validate input vertices
    if (start < 0 || start >= vertices || end < 0 || end >= vertices) {
        printf("Invalid vertices. Try again.\n");
        i--;
        continue;
    }

    graph[start][end] = 1;
    // For undirected graph, uncomment the following line:
    // graph[end][start] = 1;
}

```

```
// Input the starting vertex for DFS traversal

int startVertex;

printf("Enter the starting vertex for DFS traversal: ");
scanf("%d", &startVertex);

if (startVertex < 0 || startVertex >= vertices) {
    printf("Invalid starting vertex. Exiting...\n");
    return 1;
}

printf("DFS Traversal Order: ");
DFS(graph, visited, vertices, startVertex);

return 0;
}
```

```
/*  
* C program to implement BFS using adjacency matrix  
*/
```

```
#include <stdio.h>
```

```
int n, i, j, visited[10], queue[10], front = -1, rear = -1;  
int adj[10][10];
```

```
void bfs(int v)  
{  
    for (i = 1; i <= n; i++)  
        if (adj[v][i] && !visited[i])  
            queue[++rear] = i;  
    if (front <= rear)  
    {  
        visited[queue[front]] = 1;  
        bfs(queue[front++]);  
    }  
}
```

```
void main()  
{  
    int v;  
    printf("Enter the number of vertices: ");  
    scanf("%d", &n);  
    for (i = 1; i <= n; i++)  
    {  
        queue[i] = 0;  
        visited[i] = 0;  
    }  
}
```

```
printf("Enter graph data in matrix form:  \n");
for (i = 1; i <= n; i++)
    for (j = 1; j <= n; j++)
        scanf("%d", &adj[i][j]);
printf("Enter the starting vertex: ");
scanf("%d", &v);
bfs(v);
printf("The node which are reachable are:  \n");
for (i = 1; i <= n; i++)
    if (visited[i])
        printf("%d\t", i);
    else
        printf("BFS is not possible. Not all nodes are reachable");
return 0;
}
```


// C program for Dijkstra's single source shortest path

// algorithm. The program is for adjacency matrix

// representation of the graph

```
#include <limits.h>
```

```
#include <stdbool.h>
```

```
#include <stdio.h>
```

```
// Number of vertices in the graph
```

```
#define V 9
```

```
// A utility function to find the vertex with minimum
```

```
// distance value, from the set of vertices not yet included
```

```
// in shortest path tree
```

```
int minDistance(int dist[], bool sptSet[])
```

```
{
```

```
    // Initialize min value
```

```
    int min = INT_MAX, min_index;
```

```
    for (int v = 0; v < V; v++)
```

```
        if (sptSet[v] == false && dist[v] <= min)
```

```
            min = dist[v], min_index = v;
```

```
    return min_index;
```

```
}
```

```
// A utility function to print the constructed distance
```

```
// array
```

```
void printSolution(int dist[])
```

```
{
```

```
    printf("Vertex \t\t Distance from Source\n");
```

```

    for (int i = 0; i < V; i++)
        printf("%d \t\t %d\n", i, dist[i]);
}

// Function that implements Dijkstra's single source
// shortest path algorithm for a graph represented using
// adjacency matrix representation
void dijkstra(int graph[V][V], int src)
{
    int dist[V]; // The output array. dist[i] will hold the
                // shortest
                // distance from src to i

    bool sptSet[V]; // sptSet[i] will be true if vertex i is
                    // included in shortest
                    // path tree or shortest distance from src to i is
                    // finalized

    // Initialize all distances as INFINITE and stpSet[] as
    // false
    for (int i = 0; i < V; i++)
        dist[i] = INT_MAX, sptSet[i] = false;

    // Distance of source vertex from itself is always 0
    dist[src] = 0;

    // Find shortest path for all vertices
    for (int count = 0; count < V - 1; count++) {
        // Pick the minimum distance vertex from the set of
        // vertices not yet processed. u is always equal to
        // src in the first iteration.

```



```
{ 0, 0, 0, 9, 0, 10, 0, 0, 0 },  
{ 0, 0, 4, 14, 10, 0, 2, 0, 0 },  
{ 0, 0, 0, 0, 0, 2, 0, 1, 6 },  
{ 8, 11, 0, 0, 0, 0, 1, 0, 7 },  
{ 0, 0, 2, 0, 0, 0, 6, 7, 0 } };
```

```
// Function call
```

```
dijkstra(graph, 0);
```

```
return 0;
```

```
}
```

// C Program for Floyd Warshall Algorithm

```
#include <stdio.h>
```

```
// Number of vertices in the graph
```

```
#define V 4
```

```
/* Define Infinite as a large enough  
value. This value will be used  
for vertices not connected to each other */  
#define INF 99999
```

```
// A function to print the solution matrix
```

```
void printSolution(int dist[][V]);
```

```
// Solves the all-pairs shortest path
```

```
// problem using Floyd Warshall algorithm
```

```
void floydWarshall(int dist[][V])
```

```
{
```

```
    int i, j, k;
```

```
/* Add all vertices one by one to  
the set of intermediate vertices.  
---> Before start of an iteration, we  
have shortest distances between all  
pairs of vertices such that the shortest  
distances consider only the  
vertices in set {0, 1, 2, .. k-1} as  
intermediate vertices.  
----> After the end of an iteration,  
vertex no. k is added to the set of  
intermediate vertices and the set
```

```

    becomes {0, 1, 2, .. k} */
for (k = 0; k < V; k++) {
    // Pick all vertices as source one by one
    for (i = 0; i < V; i++) {
        // Pick all vertices as destination for the
        // above picked source
        for (j = 0; j < V; j++) {
            // If vertex k is on the shortest path from
            // i to j, then update the value of
            // dist[i][j]
            if (dist[i][k] + dist[k][j] < dist[i][j])
                dist[i][j] = dist[i][k] + dist[k][j];
        }
    }
}

// Print the shortest distance matrix
printSolution(dist);
}

/* A utility function to print solution */
void printSolution(int dist[][V])
{
    printf(
        "The following matrix shows the shortest distances"
        " between every pair of vertices \n");
    for (int i = 0; i < V; i++) {
        for (int j = 0; j < V; j++) {
            if (dist[i][j] == INF)
                printf("%7s", "INF");
            else

```

```

        printf("%7d", dist[i][j]);
    }
    printf("\n");
}
}

// driver's code
int main()
{
    /* Let us create the following weighted graph
        10
        (0)----->(3)
        |      /\
        5 |      |
        |      | 1
        \ |      |
        (1)----->(2)
        3      */
    int graph[V][V] = { { 0, 5, INF, 10 },
                        { INF, 0, 3, INF },
                        { INF, INF, 0, 1 },
                        { INF, INF, INF, 0 } };

    // Function call
    floydWarshall(graph);

    return 0;
}

```

// C Program for Kruskal Algorithm

```
#include<stdio.h>

void main()
{
    int a,b,n,ne=1,i,j,min,cost[10][10],mincost=0;
    printf("\n Enter The no of Vertices=");
    scanf("%d",&n);
    printf("\n Enter The adj Matrix\n");
    for(i=1;i<=n;i++)
    {
        for(j=1;j<=n;j++)
        {
            scanf("%d",&cost[i][j]);
            if(cost[i][j]==0)
            {
                cost[i][j]=999;
            }
        }
    }
    while(ne<n)
    {
        min=999;
        for(i=1;i<=n;i++)
        {
            for(j=1;j<=n;j++)
            {
                if(cost[i][j]<min)
                {
                    min=cost[i][j];
                }
            }
        }
    }
}
```



```
                a=i;
                b=j;
            }
        }
    }
    printf("edge(%d,%d)=%d\n",a,b,min);
    mincost=mincost+min;

    cost[a][b]=cost[b][a]=999;
    ne++;
}
printf("\nMinmum spanning Tree of wt=%d",mincost);
}
```

// C Program for Prims Algorithm

```
#include <stdio.h>
```

```
#include <limits.h>
```

```
#define MAX_VERTICES 100
```

```
// Function to find the vertex with the minimum key value
```

```
int minKey(int key[], int mstSet[], int vertices) {
```

```
    int min = INT_MAX, minIndex;
```

```
    for (int v = 0; v < vertices; v++) {
```

```
        if (!mstSet[v] && key[v] < min) {
```

```
            min = key[v];
```

```
            minIndex = v;
```

```
        }
```

```
    }
```

```
    return minIndex;
```

```
}
```

```
// Function to print the constructed MST stored in parent[]
```

```
void printMST(int parent[], int graph[MAX_VERTICES][MAX_VERTICES], int vertices) {
```

```
    printf("Edge \tWeight\n");
```

```
    for (int i = 1; i < vertices; i++) {
```

```
        printf("%d - %d \t%d\n", parent[i], i, graph[i][parent[i]]);
```

```
    }
```

```
}
```

```
// Function to implement Prim's algorithm for a given graph
```

```
void primMST(int graph[MAX_VERTICES][MAX_VERTICES], int vertices) {
```

```

int parent[MAX_VERTICES]; // Array to store the constructed MST
int key[MAX_VERTICES]; // Key values used to pick the minimum weight edge
int mstSet[MAX_VERTICES]; // To represent set of vertices included in MST


// Initialize all keys as INFINITE and mstSet[] as false
for (int i = 0; i < vertices; i++) {
    key[i] = INT_MAX;
    mstSet[i] = 0;
}


// Always include the first vertex in the MST
key[0] = 0; // Make key 0 so that this vertex is picked as the first vertex
parent[0] = -1; // First node is always the root of the MST


// The MST will have vertices-1 edges
for (int count = 0; count < vertices - 1; count++) {
    // Pick the minimum key vertex from the set of vertices not yet included in the MST
    int u = minKey(key, mstSet, vertices);

    // Add the picked vertex to the MST Set
    mstSet[u] = 1;

    // Update key value and parent index of the adjacent vertices
    for (int v = 0; v < vertices; v++) {
        // graph[u][v] is non-zero only for adjacent vertices of u
        // mstSet[v] is false for vertices not yet included in MST
        // Update the key only if the graph[u][v] is smaller than the key[v]
        if (graph[u][v] && !mstSet[v] && graph[u][v] < key[v]) {
            parent[v] = u;
            key[v] = graph[u][v];
        }
    }
}

```

```

    }
}

// Print the constructed MST
printMST(parent, graph, vertices);
}

int main() {
    int vertices;

    // Input the number of vertices
    printf("Input the number of vertices: ");
    scanf("%d", &vertices);

    if (vertices <= 0 || vertices > MAX_VERTICES) {
        printf("Invalid number of vertices. Exiting...\n");
        return 1;
    }

    int graph[MAX_VERTICES][MAX_VERTICES];

    // Input the adjacency matrix representing the graph
    printf("Input the adjacency matrix for the graph:\n");
    for (int i = 0; i < vertices; i++) {
        for (int j = 0; j < vertices; j++) {
            scanf("%d", &graph[i][j]);
        }
    }

    // Perform Prim's algorithm to find the MST
    primMST(graph, vertices);
}

```

```
return 0;
```

```
}
```