STEPPER-MOTOR CONTROL PROTOCOL

Command	Description	Sample
....@	@ - end ; ... - commands	Bandwith = 9600
ENA@	Enable the Motor	Send: ENA@ –– motor enabled
DIS@	Disable the Motor	Send: DIS@ –– motor disabled
RES@	Reset (back to origin)	Send: RES@ –– Axis back to 0 position
GTP....@	Go To xxxx mm position [Max=4950]	Send: GTP1234@ –– Axis go to 1234 mm Position
SST....@	Set delay of motor (default: 0) [2 byte]	Send: SST0@ –– Set delay of motor 0 **ms**
CTP@	send back the current position (2 byte) : xxxx	Send: CTP@ –– Return: "2341@" (current position 2341mm)
CTS@	send back the current speed (2 byte) : xxxx	Send: CTS@ –– Return: "450@" (current speed 450)