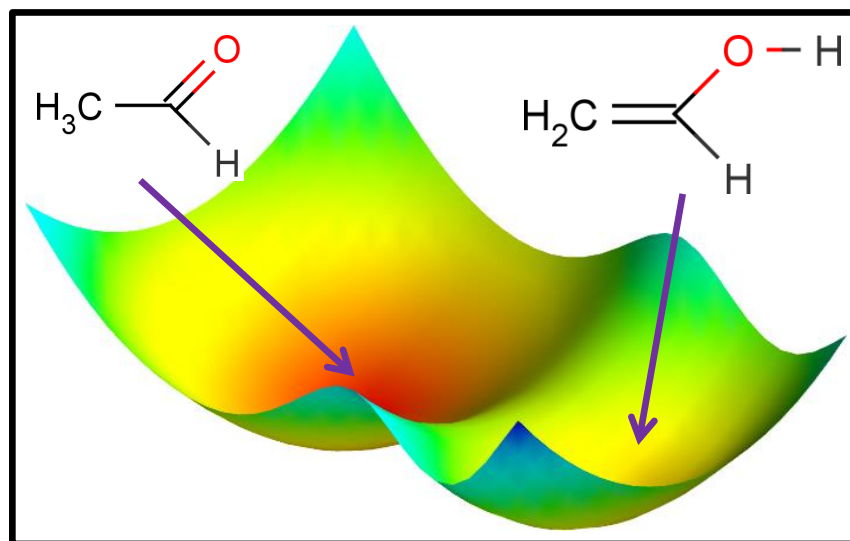


Applications of Electronic Structure Methods

Local Structure Optimization



Geometry update – (Quasi-)Newton Methods

Approximate PES by quadratic function

$$E(\Delta R) \approx E(R_{Min}) + \underbrace{\frac{\delta E}{\delta R} \Delta R}_{F(R)} + \frac{1}{2} \underbrace{\frac{\delta^2 E}{\delta R^2} \Delta R^2}_H$$

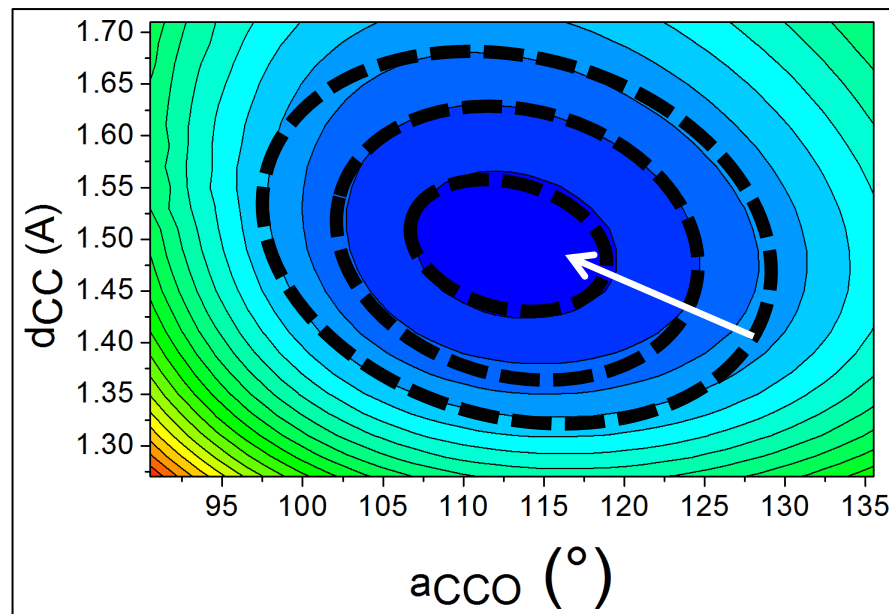
Forces Hessian

Find minimum using

$$\Delta R = -H^{-1}F$$

Two variants:

- Newton methods: calculate exact H
- *Quasi-newton*:
 - approximate H
 - update as search progresses [1]



$$\tilde{H} \leftarrow \tilde{H} - \frac{\tilde{H} \Delta R (\tilde{H} \Delta R)^T}{\Delta R^T \tilde{H} \Delta R} - \frac{\Delta F \Delta F^T}{\Delta F^T \Delta R}$$

[1] J. Nocedal and S. J. Wright, "Numerical optimization" (Springer, 2006)

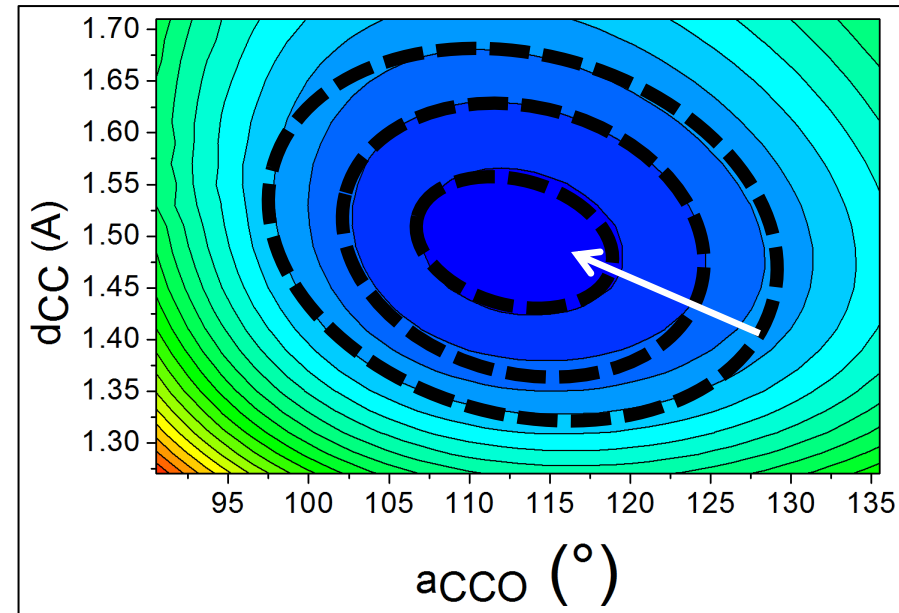
(Quasi-)Newton Methods

De-facto standard method

$$\tilde{H} \leftarrow \tilde{H} - \frac{\tilde{H} \Delta R (\tilde{H} \Delta R)^T}{\Delta R^T \tilde{H} \Delta R} - \frac{\Delta F \Delta F^T}{\Delta F^T \Delta R}$$

Iterative, depends on:

- Guess Hessian
- Step control
- Optimization History
- Starting point



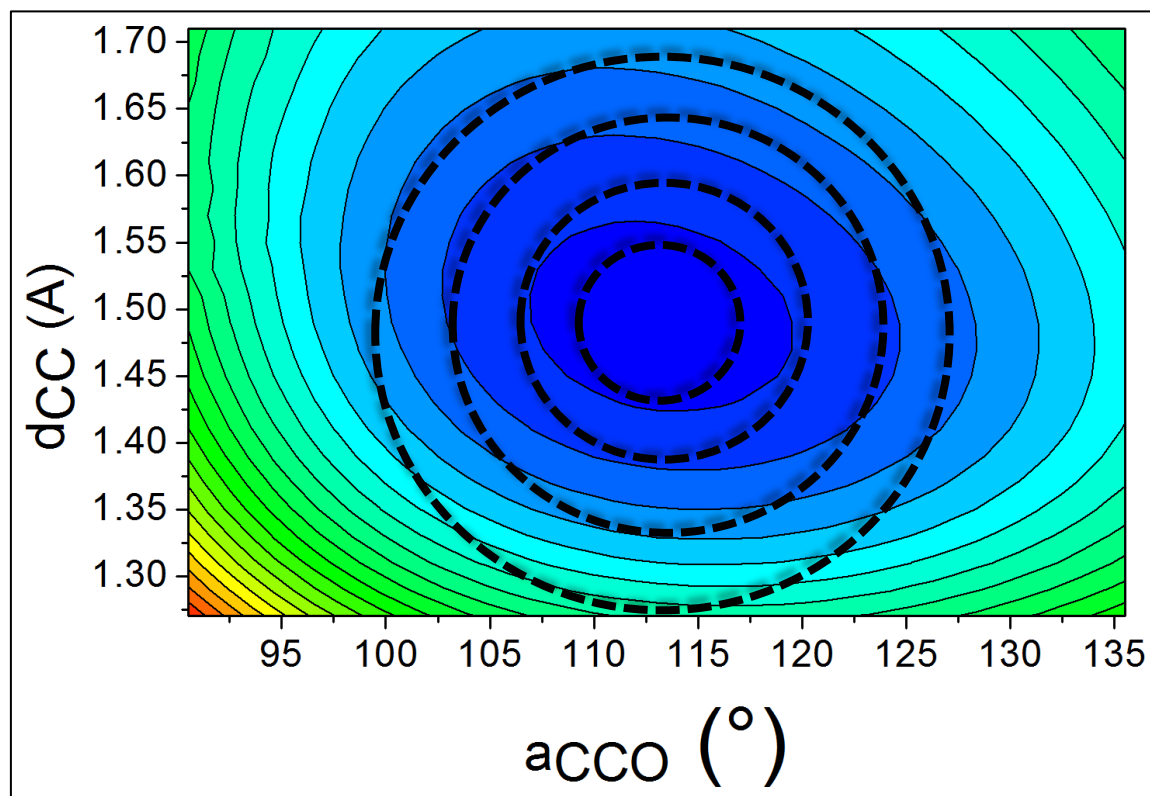
Note: Quasi-Newton methods converge to the closest stationary point → This can be a saddle point!

Guess Hessian: Scaled unit matrix

$$\tilde{H} = \beta \bar{\mathbf{I}}$$

Assumption: Each DoF has same force constant

- Typically good for bulk systems (esp. metals, vdW)
- Terrible for complex molecules

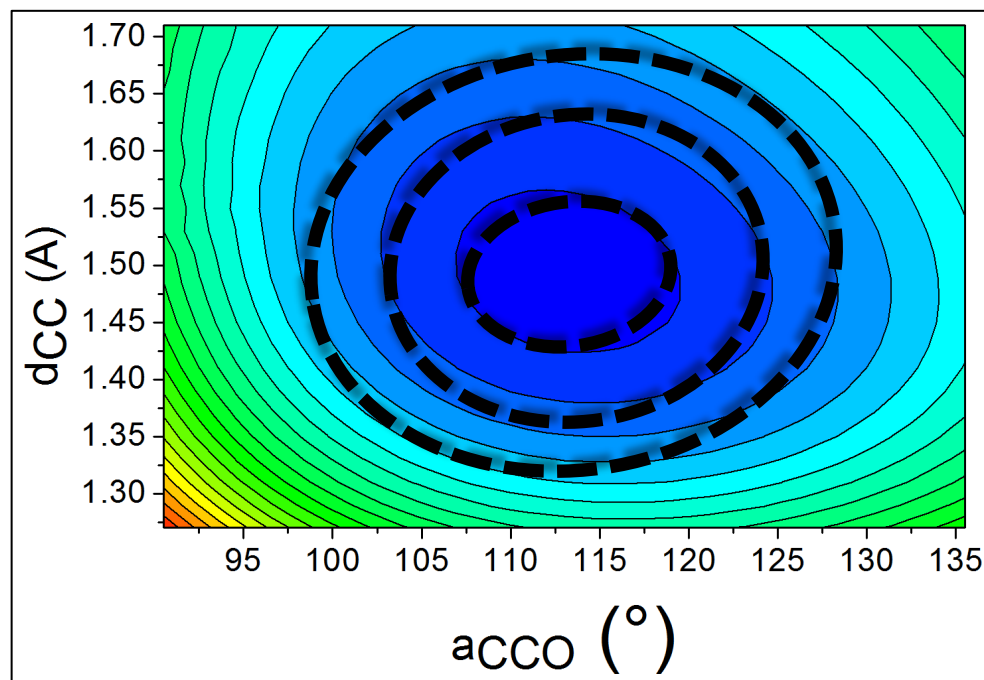


Guess Hessian: Chemically motivated

Properties:

- k 's parameterized [1]
- Different parameters exist
 - (e.g.: Lindh, Fischer)
- But not for everything
- Construction not unique

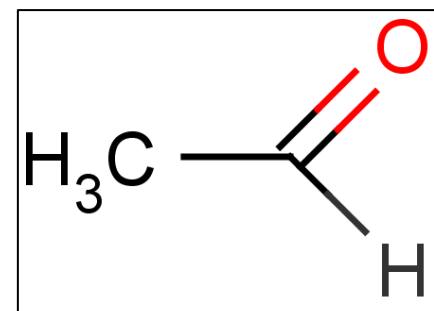
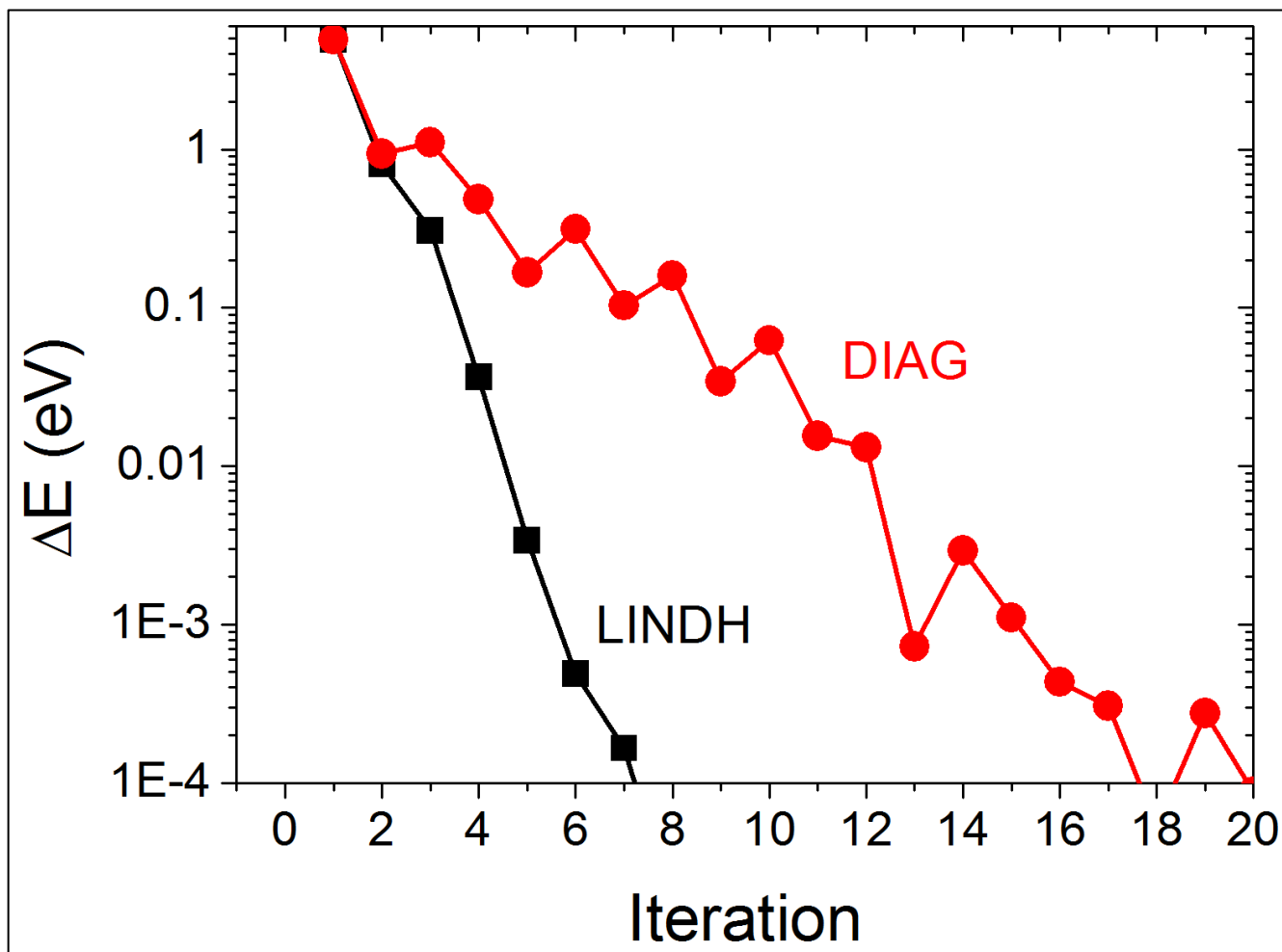
$$\begin{aligned}
 \tilde{E} &= E + F\Delta R \\
 &+ \sum_{ij} k_{ij} d_{ij}^2 \quad \text{stretching} \\
 &+ \sum_{ijl} k_{ijl} a_{ijl}^2 \quad \text{bending} \\
 &+ \sum_{ijlm} k_{ijlm} \tau_{ijlm}^2 \quad \text{torsion}
 \end{aligned}$$



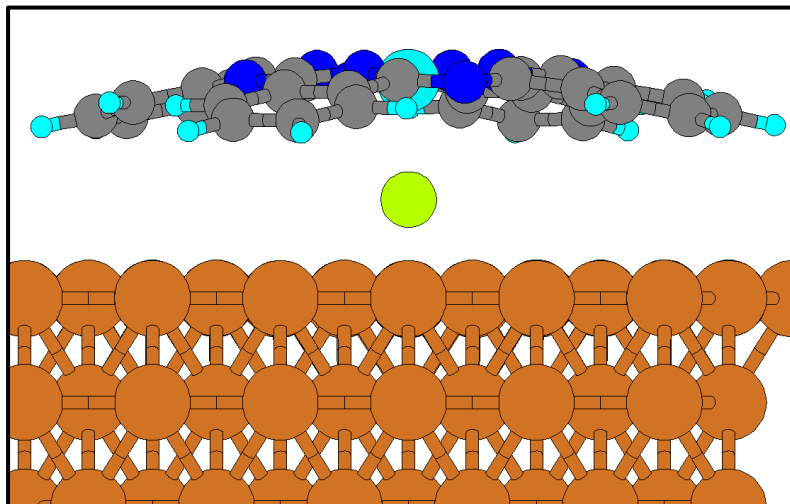
[1] R. Lindh et al. , Chem. Phys. Lett. 241 , 423 (1995).

Effect of Guess Hessian

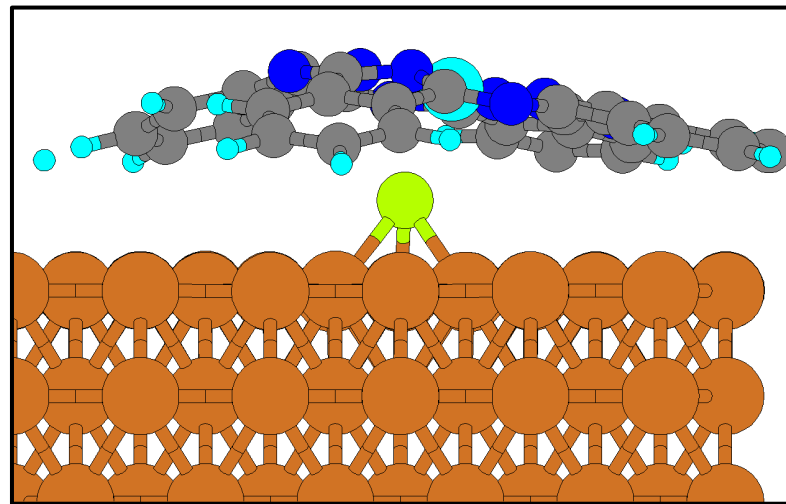
Speedup of calculation



Guess Hessian – Example 1



Diagonal Hessian
[higher in energy]



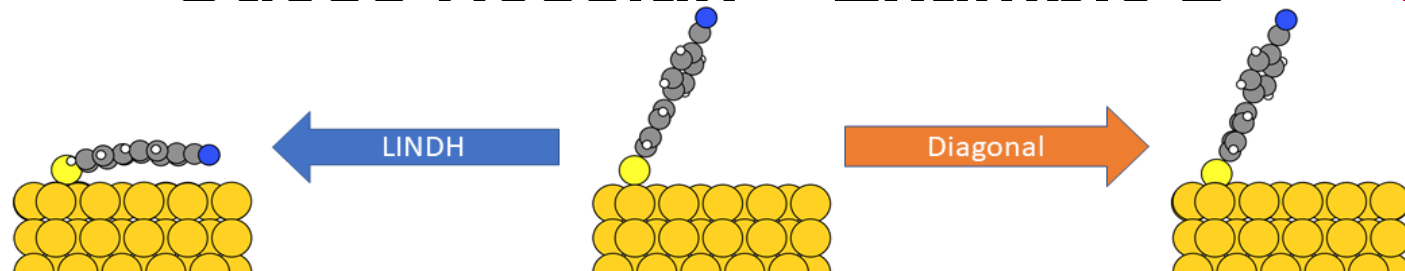
Model Hessian (Fischer)
[lower in energy]

Diagonal Hessian struggles with complex DoFs
(e.g., bending of a planar molecule)

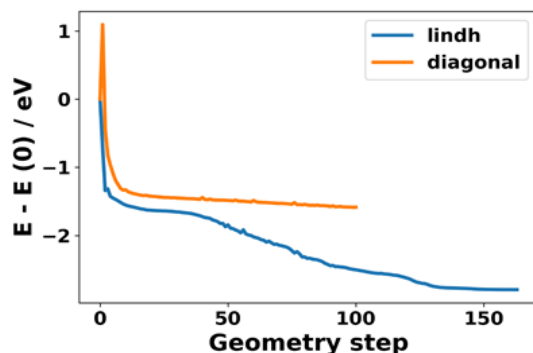
Courtesy of Elisabeth Wruss

Guess Hessian – Example 2

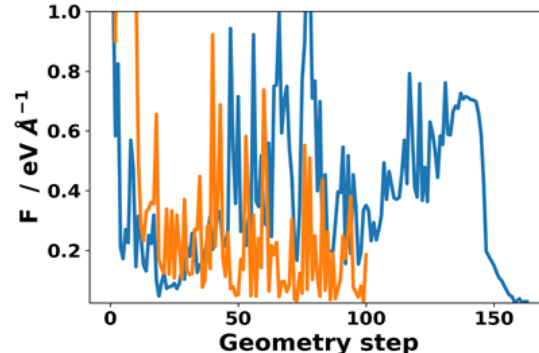
a)



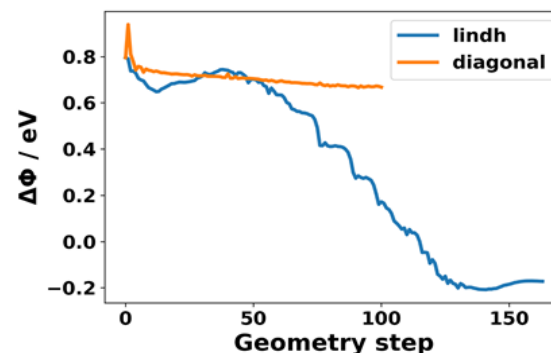
b)



c)



d)



**Diagonal Hessian struggles
with complex DoFs
(e.g., falling over of a
molecule)**

**==> Atoms which experience
least forces have to move
most!**

Challenges of Quasi-Newton Methods

Soft degrees of freedom can cause large ΔR

$$\Delta R = \alpha H^{-1} F$$

Step control needed:

- **Line search method:**

- If new point is worse than old, interpolate

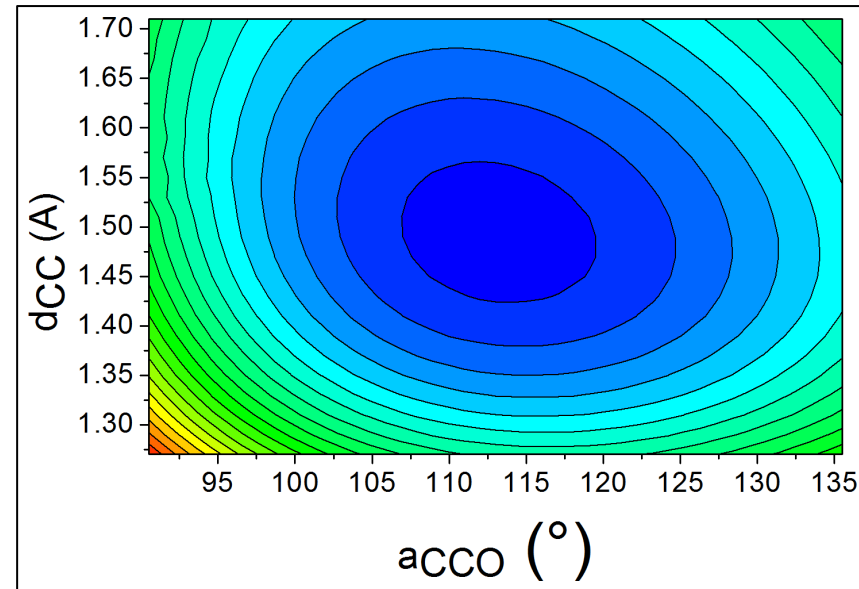
- **Trust radius method**

- Enforce upper limit for ΔR
- Evaluate quality q of quadratic model
- Adjust ΔR_{\max} based on q

$$q = \frac{E_{\text{true}}}{E_{\text{expected}}} \quad \rightarrow$$

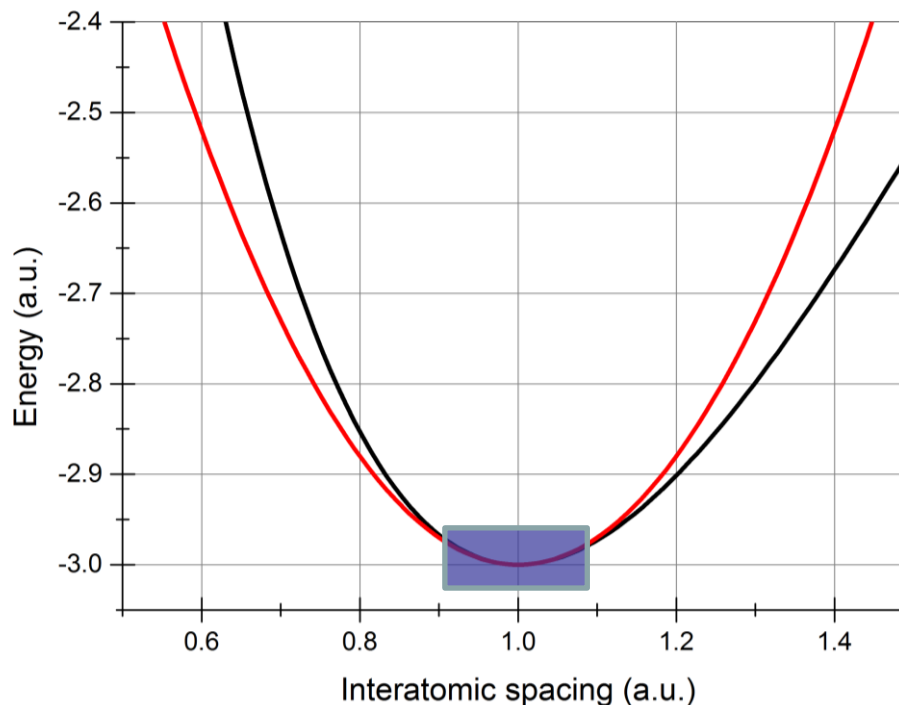
Step size can become very small

- Far away from the minimum
- When Hessian is bad
- When convergence is bad



Search History

- Points far away from minimum give „wrong“ Forces/Hessian
- Errors accumulate, deteriorate Harmonic Expectation Value
- Only finite number of steps can/should be stored:
 - Linear Dependency ($\# \text{steps} < \text{DOFs}$)
 - Memory (H is $3N \times 3N$ large)



Choice of the coordinate system

Coordinate system cannot affect physics, but numerics

$$E(x) = (1 - y)^2 \xleftarrow{y = e^{-x}} E(x) = (1 - e^{-x})^2 \xrightarrow{y = e^x} E(x) = \left(1 - \frac{1}{z}\right)^2$$

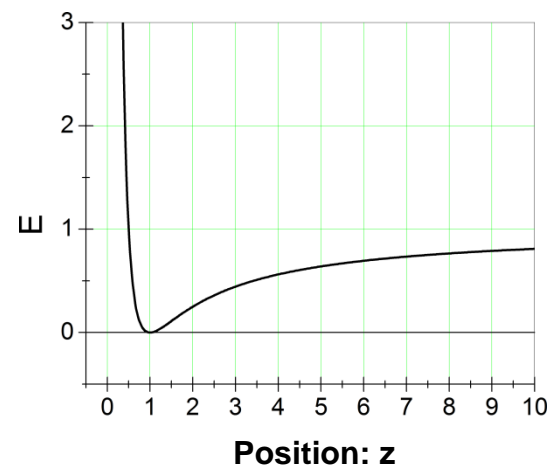
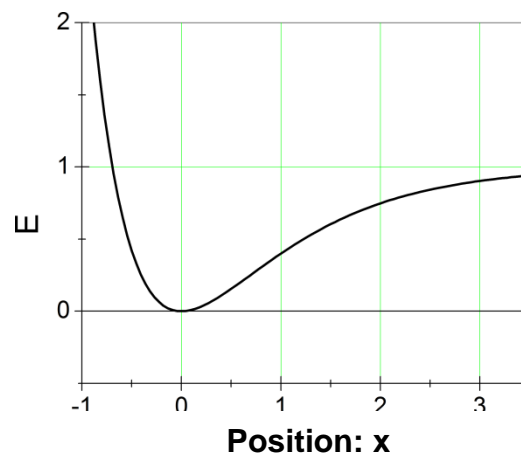
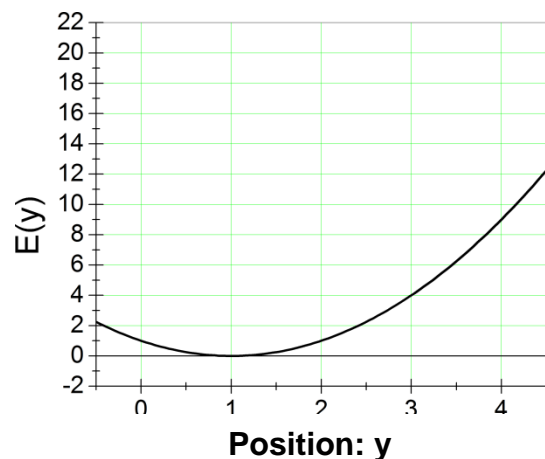


Table 12.2 Convergence for different choices of variables

Iteration	$x_{\text{start}} = 0.30$			$x_{\text{start}} = 1.00$		
	x	y	z	x	y	z
0	0.3000	0.7408	1.3499	1.0000	0.3679	2.7183
1	-0.2381	1.0000	-0.2229	3.3922	1.0000	4.6352
2	-0.0633		-0.3020	4.4283		7.3225
3	-0.0055		-0.4110	5.4405		11.2981
4	0.0000		-0.5628	6.4449		17.2354

Example taken from Jensen, Introduction to Computational Chemistry