### Gravitational-Wave Astronomy

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Lecture 2: Main Noise Sources, Waveform Sources and Phenomenology

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Key Concepts in Lecture 1

### Syllabus

- Introduction to the course, General Relativity, gravitational waves and interferometric detectors
- Waveform sources and phenomenology
- 3 Gravitational-wave searches and the case of GW150914
- 4 Gravitational-wave inference and the case of GW150914
- 5 Multimessenger astronomy and the case of GW170817

# Key Concepts in Lecture 1 (1/3)

- Starting point Strong Principle of Equivalence: in an arbitrary gravitational field, at any given spacetime point, we can choose a locally inertial reference frame such that locally all physical laws take the form prescribed in absence of gravity by Special Relativity (⇒ ∃ GWs)
- Write laws of physics using tensors and they will automatically be valid in all frames (not just locally).
- Einstein Equation:  $R_{\alpha\beta} \frac{1}{2} g_{\alpha\beta} R = \frac{8\pi G}{c^4} T_{\alpha\beta}$
- Detecting spacetime curvature requires monitoring the relative motion of at least two freely-falling test bodies.

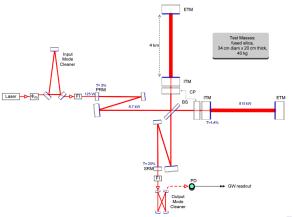
# Key Concepts in Lecture 1 (2/3)

- Gravitational waves travel at the speed of light (c), are transverse to the propagation direction, have two independent polarisation states  $(+ \text{ and } \times)$ , carry energy away from a radiating system.
- As a gravitational wave passes through two bodies initially at rest, their coordinate positions (not tensors!) do not change, but the proper distance between them (tensor-related!) does.

└Key Concepts in Lecture 1

# Key Concepts in Lecture 1 (3/3)

The Michelson sensitivity  $h=\delta\ell/\ell\sim 10^{-9}$  can be improved to  $h=\delta\ell/\ell_{\rm eff}\sim 10^{-20}$  for a 1 W laser.



- Fabry–Perot cavities
- Power recycling (and 150 W)
- Signal recycling

Key Concepts in Lecture 1

# Bibliography

- Einstein, Relatività: esposizione divulgativa, Bollati Boringhieri (1967)
- Born, La sintesi einsteiniana [Cap.6-7], Bollati Boringhieri (1969)
- https://www.ligo.caltech.edu/page/learn-more

### Limits to Detector Sensitivity

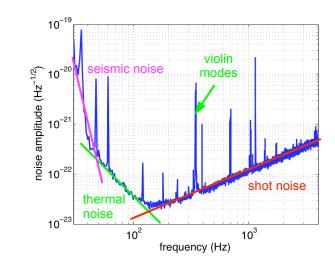
Characterize sensitivity using the noise spectral density

$$\frac{1}{2}S_h(f)=\langle |\tilde{n}(f)|^2\rangle$$

or amplitude strain sensitivity  $S_h^{1/2}(f)$ .

- Let's look at some of the sources of noise that limit the sensitivity
  - Quantum noise: shot noise and radiation pressure.
  - 2 Thermal noise
  - 3 Seismic noise

### LIGO-Hanford Detector Noise Spectrum, 2007



### 1. Quantum Noise: Shot Noise

Shot noise is simply the photon counting noise we met before.

$$rac{\Delta \ell}{\ell} \sim rac{\lambda_{\mathsf{laser}}}{\ell \mathit{N}_{\mathsf{photons}}^{1/2}} = rac{1}{\ell} \sqrt{rac{\mathit{h}_{\mathsf{Planck}} c \lambda_{\mathsf{laser}}}{\mathit{P} au}}$$

Detailed calculation for a Michelson interferometer yields:

$$S_{
m shot}^{1/2}(f) = rac{\lambda_{
m laser}}{4\pi L} \left(rac{2\hbar\omega_{
m laser}}{P}
ight)^{1/2}$$

- Frequency independent (but for a realistic Fabry Perot interferometer need to account for detector response).
- 2 Reduced by higher power.

#### 1. Quantum Noise: Radiation Pressure

We cannot increase laser power indefinitely.

- Photons bouncing off mirrors impart momentum, moving the mirrors stochastically.
- More power → more photons → more radiation pressure noise.

Force due to wave with power P(F = 2P/c) fluctuates over time: the power spectrum of the fractional relative length change from the sum of the 2 arms is

$$S_{\mathsf{rad}}^{1/2}(f) = \frac{4\sqrt{2\hbar\omega_{\mathsf{laser}}P}}{\mathsf{MLc}(2\pi f)^2}$$

- Frequency dependent
- 2 Reduced by lower power

### 1. Quantum Noise: the Standard Quantum Limit

■ At any given frequency f,  $S_{\text{shot}} + S_{\text{rad}}$  is minimized by choosing the power P such that  $S_{\text{shot}} = S_{\text{rad}}$ . The total noise is then

$$S_{\mathsf{SQL}}^{1/2} = rac{1}{2\pi f L} \sqrt{rac{8\hbar}{M}} \,.$$

- This minimum noise level is called the standard quantum limit.
- We have a km-scale machine that "sees" the consequences of Heisenberg's uncertainty principle.

#### 2. Seismic Noise

- Seismic noise is due to shaking of the ground, due to earthquakes, weather, human activity, etc. It affects the interferometer by shaking the optical components.
- If the mirrors were resting on the ground, it would be

$$S_{\rm seis}^{1/2} \sim 10^{-12} {
m Hz}^{-1/2} \left( rac{10 {
m Hz}}{f} 
ight)^2 \quad {
m for} \, f > 10 {
m Hz}$$

- This is many orders of magnitude larger than the gravitational wave signal we are trying to measure.
- To suppress the effect of seismic motion, the mirrors are suspended as pendula.

#### 2. Seismic Noise

- Suspended mirrors are simple harmonic oscillators.
- If X is the position of the pivot point, and x is the position of the mirror and  $\ell$  is the length of the pendulum, the two are related by

$$ilde{x}(f) = A(f) ilde{X}(f) \quad ext{where} \quad A(f) = rac{1}{1-(f/f_{ ext{pend}})^2}$$
 and  $f_{ ext{pend}} = rac{1}{2\pi}\sqrt{rac{g}{\ell}}$ 

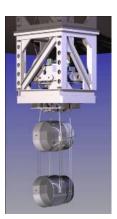
■ For  $f > f_{\text{pend}}$ ,  $\tilde{x}(f) \approx -(f_{\text{pend}}/f)^2 \tilde{X}(f)$ , so seismic noise is suppressed.

#### 2. Seismic Noise

Increase isolation from ground by "stacking." E.g., Advanced LIGO/Virgo use a quadruple/heptaple stage pendulum.

They also use **active isolation**: sensors monitor motion of suspension system; control motors that push back on system to cancel ground motion.

Can get required sensitivity, but not easy, especially at low frequencies.



Advanced LIGO suspension.

#### 3. Thermal Noise

**Equipartition Theorem:** each degree of freedom of a system in thermodynamic equilibrium at temperature T should have an energy with expectation value  $\frac{1}{2}k_{\rm B}T$ .

Main physical manifestations of thermal noise:

- Random motion of atoms in mirrors.
- Vibration in wire suspensions of mirrors ("violin modes").
- Swinging of the mirror pendula.

Induces random "jittering" of mirror positions:

■  $m = 10 \, \text{kg mirror suspended from an } \ell = 1 \, \text{m}$  wire:

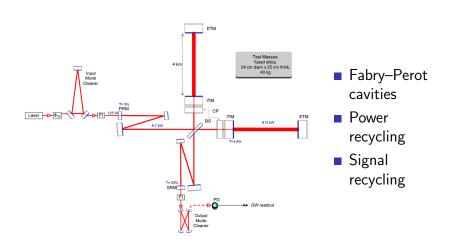
$$\Delta L_{
m rms} \simeq \sqrt{rac{k_B T \ell}{mg}} \simeq 6 imes 10^{-12} m \quad [{
m Increase} \,\, m] \,.$$

#### 3. Thermal Noise

Can minimize impact by concentrating thermal noise power at resonant frequency  $f_0$ . In the pendulum example, this is equivalent to minimizing the coefficient in the dissipative force  $-\beta v$ .

- Suspend mirrors as pendulums (low  $\beta$ , resonant frequency  $\sim 1 Hz$  well below observation band).
- Use high-quality-factor wires for suspensions, so vibrational motion of "violin modes" is concentrated in narrow frequency range.
- Minimize the thermal noise from mirror internal vibrations by making them from material with very low dissipation at acoustic frequencies at room temperature (fused silica).

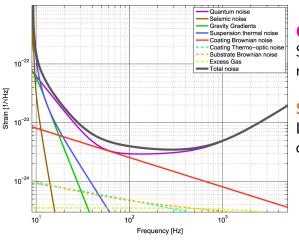
#### Gravitational-Wave Detector



Lecture 2: Main Noise Sources, Waveform Sources and Phenomenology

└ Noise sources

### Noise Budget Example



**Quantum noise:**Shot noise and radiation pressure

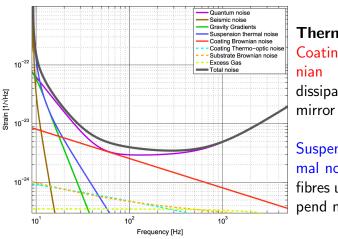
Seismic noise: Limits low frequency sensitivity

[Try out the Gravitational Wave Interferometer Noise Calculator]

Lecture 2: Main Noise Sources, Waveform Sources and Phenomenology

└ Noise sources

### Noise Budget Example



Thermal noise:
Coating Brownian noise:
dissipation in
mirror coatings

Suspension thermal noise: loss in fibres used to suspend mirrors

[Try out the Gravitational Wave Interferometer Noise Calculator]

## **Key Components**

- Vacuum
- Laser source: Maximum power 200 W.
- Input mode cleaner: stabilize beam position and only let through the desired modes.
- Core optics: transmission, smoothness
- Suspensions
- Active seismic isolation
- Scattered light control
- Global sensing and control
- Physical environment monitoring:  $\mathcal{O}(10^6)$  auxiliary channels
- Calibration