

การสร้าง MQTT Server บน Raspberry Pi เพื่อใช้งาน Chatbot LINE ในฟาร์มอัจฉริยะ

Chatbot LINE from Raspberry Pi MQTT Server for Smart Farming

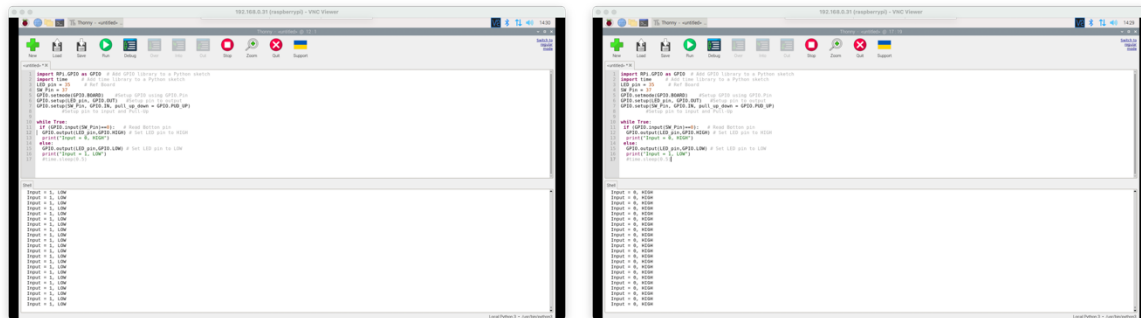
ชื่อ-สกุล : B6304577 นายภาณุพงศ์ แคนอินทร์

6/6 – คำถามท้ายบทเพื่อทดสอบความเข้าใจ

Quiz_101 – ทดสอบ RPi4 GPIO with Python

Python.1 - Python Switch control LED >> กดติด ปปล่อยดับ

โปรแกรมที่ใช้ทดสอบ



รูป Code Capture

```
import RPi.GPIO as GPIO # Add GPIO library to a Python sketch
import time             # Add time library to a Python sketch
LED_pin = 35            # Ref Board
SW_Pin = 37

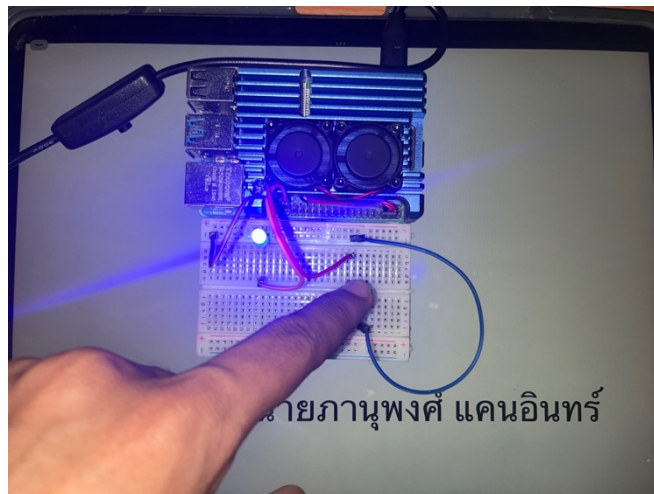
GPIO.setmode(GPIO.BOARD) #Setup GPIO using GPIO.Pin
GPIO.setup(LED_pin, GPIO.OUT) #Setup pin to output
GPIO.setup(SW_Pin, GPIO.IN, pull_up_down = GPIO.PUD_UP)
    #Setup pin to input and Pull-Up

while True:
    if (GPIO.input(SW_Pin)==0): # Read Botton pin
        GPIO.output(LED_pin,GPIO.HIGH) # Set LED pin to HIGH
        print("Input = 0, HIGH")
    else:
        GPIO.output(LED_pin,GPIO.LOW) # Set LED pin to LOW
        print("Input = 1, LOW")
        #time.sleep(0.5)
```

รูปการทดสอบ 1



รูปการทดสอบ 2



Python.2 - Python Switch control LED >> กดติด กดดับ

โปรแกรมที่ใช้ทดสอบ

```

import RPi.GPIO as GPIO
import time

LED_PIN = 27
ON_TIME = 1
OFF_TIME = 1
PULSE_WIDTH = 0.5 # Adjust this value to set the pulse width (in seconds)

GPIO.setmode(GPIO.BCM)
GPIO.setup(LED_PIN, GPIO.OUT)

def toggle_led_state():
    global LED_PIN, ON_TIME, OFF_TIME, PULSE_WIDTH
    if GPIO.inPin(LED_PIN):
        # LED is currently ON
        print("LED is ON")
        # Turn the LED OFF
        GPIO.writePin(LED_PIN, GPIO.LOW)
        print("LED is OFF")
    else:
        # LED is currently OFF
        print("LED is OFF")
        # Turn the LED ON
        GPIO.writePin(LED_PIN, GPIO.HIGH)
        print("LED is ON")

def main():
    while True:
        toggle_led_state()
        time.sleep(ON_TIME)
        toggle_led_state()
        time.sleep(OFF_TIME)

if __name__ == '__main__':
    main()
    
```

```

import RPi.GPIO as GPIO
import time

LED_PIN = 27
ON_TIME = 1
OFF_TIME = 1
PULSE_WIDTH = 0.5 # Adjust this value to set the pulse width (in seconds)

GPIO.setmode(GPIO.BCM)
GPIO.setup(LED_PIN, GPIO.OUT)

def toggle_led_state():
    global LED_PIN, ON_TIME, OFF_TIME, PULSE_WIDTH
    if GPIO.inPin(LED_PIN):
        # LED is currently ON
        print("LED is ON")
        # Turn the LED OFF
        GPIO.writePin(LED_PIN, GPIO.LOW)
        print("LED is OFF")
    else:
        # LED is currently OFF
        print("LED is OFF")
        # Turn the LED ON
        GPIO.writePin(LED_PIN, GPIO.HIGH)
        print("LED is ON")

def main():
    while True:
        toggle_led_state()
        time.sleep(ON_TIME)
        toggle_led_state()
        time.sleep(OFF_TIME)

if __name__ == '__main__':
    main()
    
```

รูป Code Capture

```

import RPi.GPIO as GPIO
import time

LED_pin = 35
SW_Pin = 37
SW_State = 0
debounce_time = 0.1 # Adjust this value to set the debounce time (in seconds)

GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)
GPIO.setup(LED_pin, GPIO.OUT)
GPIO.setup(SW_Pin, GPIO.IN, pull_up_down=GPIO.PUD_UP)

def toggle_led_state():
    global SW_State
    if SW_State == 0:
        SW_State = 1
        GPIO.output(LED_pin, GPIO.HIGH)
        print("State = 1, HIGH")
    else:
        SW_State = 0
        GPIO.output(LED_pin, GPIO.LOW)
        print("State = 0, LOW")

def handle_switch_press():
    start_time = time.time()
    previous_state = GPIO.input(SW_Pin)

    while GPIO.input(SW_Pin) == previous_state:
        if time.time() - start_time >= 1.0: # Adjust the duration as needed
            return # Exit the function without changing the LED state
        time.sleep(0.1)

    toggle_led_state()

previous_state = GPIO.HIGH
current_state = GPIO.HIGH
state_changed_time = time.time()

```

```
while True:
    previous_state = current_state
    current_state = GPIO.input(SW_Pin)

    if current_state != previous_state:
        state_changed_time = time.time()

    if current_state == GPIO.LOW and time.time() - state_changed_time >= debounce_time:
        handle_switch_press()
```

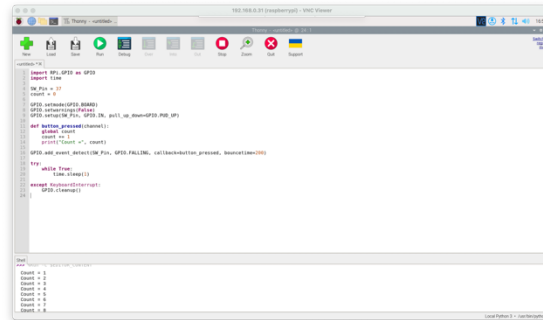
รูปการทดสอบ 1



รูปการทดสอบ 2



โปรแกรมที่ใช้ทดสอบ



รูป Code Capture

```
import RPi.GPIO as GPIO
```

```
import time
```

```
SW_Pin = 37
```

```
count = 0
```

```
GPIO.setmode(GPIO.BOARD)
```

```
GPIO.setwarnings(False)
```

```
GPIO.setup(SW_Pin, GPIO.IN, pull_up_down=GPIO.PUD_UP)
```

```
def button_pressed(channel):
```

```
    global count
```

```
    count += 1
```

```
    print("Count =", count)
```

```
GPIO.add_event_detect(SW_Pin, GPIO.FALLING, callback=button_pressed, bouncetime=200)
```

```
try:
```

```
    while True:
```

```
        time.sleep(1)
```

```
except KeyboardInterrupt:
```

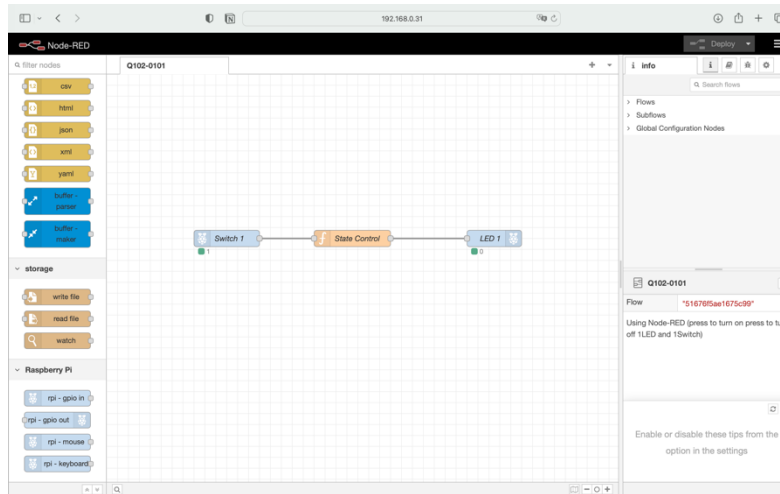
```
    GPIO.cleanup()
```

รูปการทดสอบ 1



รูปการทดสอบ 2



Quiz_102 – ทดสอบ RPi4 GPIO with Node-RED**Node-RED.1 – Node-RED เพื่อควบคุมสวิตช์กดแบบ กดติด กดดับ {Switch-LED 1 คู่}****โปรแกรมที่ใช้ทดสอบ****รูป Code Capture**

```
[
  {
    "id": "51676f5ae1675c99",
    "type": "tab",
    "label": "Q102-0101",
    "disabled": false,
    "info": "Using Node-RED (press to turn on press to turn off 1LED and 1Switch) ",
    "env": []
  },
  {
    "id": "eec1119ce2081360",
    "type": "rpi-gpio in",
    "z": "51676f5ae1675c99",
    "name": "Switch 1",
    "pin": "26",
    "intype": "up",
    "debounce": "25",
    "read": false,
    "bcm": true,
    "x": 220,
    "y": 300,
```

```

    "wires": [
      [
        "016c3e9be89901e3"
      ]
    ]
  },
  {
    "id": "06cb6823737d2dfc",
    "type": "rpi-gpio out",
    "z": "51676f5ae1675c99",
    "name": "LED 1",
    "pin": "19",
    "set": "",
    "level": "0",
    "freq": "",
    "out": "out",
    "bcm": true,
    "x": 710,
    "y": 300,
    "wires": []
  },
  {
    "id": "016c3e9be89901e3",
    "type": "function",
    "z": "51676f5ae1675c99",
    "name": "State Control",
    "func": "context.state = context.state | false;\ncontext.state =
!context.state\n\nvar myContext = context.state;\nvar count =
context.get(\"count\")||0;\ncount += 1;\ncontext.set(\"count\",count);\nmsg.count =
count;\n\nfunction isOdd(num) { \n  return num % 2;\n}\n\nif(myContext === true &&
isOdd((count+1)/2) ===1){\n  msg.payload = 1;\n  return msg;\n} else if (myContext ===
true && isOdd((count+1)/2) ===0){\n  msg.payload = 0;\n  return msg;\n}",
    "outputs": 1,
    "noerr": 0,
    "initialize": "",
    "finalize": "",
    "libs": [],
    "x": 450,
    "y": 300,
    "wires": [

```



```
[  
  "06cb6823737d2dfc"  
]  
}  
]
```

รูปการทดสอบ 1

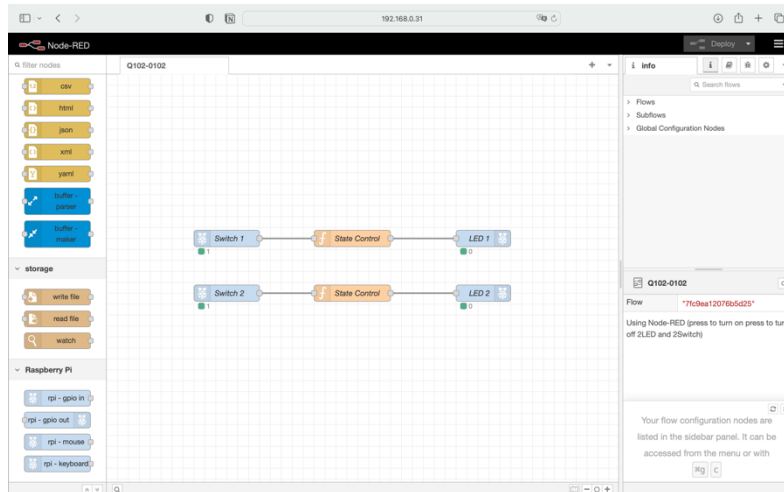


รูปการทดสอบ 2



Node-RED.2 - Node-RED เพื่อควบคุมสวิตช์กดแบบ กดติด กดดับ 2 คู่

โปรแกรมที่ใช้ทดสอบ



รูป Code Capture

```
[
  {
    "id": "7fc9ea12076b5d25",
    "type": "tab",
    "label": "Q102-0102",
    "disabled": false,
    "info": "Using Node-RED (press to turn on press to turn off 2LED and 2Switch) ",
    "env": []
  },
  {
    "id": "5e0e47b70cfa15b3",
    "type": "rpi-gpio in",
    "z": "7fc9ea12076b5d25",
    "name": "Switch 1",
    "pin": "26",
    "intype": "up",
    "debounce": "25",
    "read": false,
    "bcm": true,
    "x": 220,
    "y": 300,
```

```

    "wires": [
      [
        "e9a1afc0ccd95ad2"
      ]
    ]
  },
  {
    "id": "ece0b86753b4806e",
    "type": "rpi-gpio out",
    "z": "7fc9ea12076b5d25",
    "name": "LED 1",
    "pin": "19",
    "set": "",
    "level": "0",
    "freq": "",
    "out": "out",
    "bcm": true,
    "x": 690,
    "y": 300,
    "wires": []
  },
  {
    "id": "e9a1afc0ccd95ad2",
    "type": "function",
    "z": "7fc9ea12076b5d25",
    "name": "State Control",
    "func": "context.state = context.state | false;\ncontext.state =
!context.state\n\nvar myContext = context.state;\nvar count =
context.get(\"count\")||0;\ncount += 1;\ncontext.set(\"count\",count);\nmsg.count =
count;\n\nfunction isOdd(num) { \n  return num % 2;\n}\n\nif(myContext === true &&
isOdd((count+1)/2) ===1){\n  msg.payload = 1;\n  return msg;\n} else if (myContext ===
true && isOdd((count+1)/2) ===0){\n  msg.payload = 0;\n  return msg;\n}",
    "outputs": 1,
    "noerr": 0,
    "initialize": "",
    "finalize": "",
    "libs": [],
    "x": 450,
    "y": 300,
    "wires": [

```

```

        [
            "ece0b86753b4806e"
        ]
    ],
    {
        "id": "0c4853c44002d61b",
        "type": "rpi-gpio out",
        "z": "7fc9ea12076b5d25",
        "name": "LED 2",
        "pin": "16",
        "set": "",
        "level": "0",
        "freq": "",
        "out": "out",
        "bcm": true,
        "x": 690,
        "y": 400,
        "wires": []
    },
    {
        "id": "6efb796920ac0f04",
        "type": "rpi-gpio in",
        "z": "7fc9ea12076b5d25",
        "name": "Switch 2",
        "pin": "21",
        "intype": "up",
        "debounce": "25",
        "read": false,
        "bcm": true,
        "x": 220,
        "y": 400,
        "wires": [
            [
                "aad96eb4d550ef39"
            ]
        ]
    },
    {

```

```

    "id": "aad96eb4d550ef39",
    "type": "function",
    "z": "7fc9ea12076b5d25",
    "name": "State Control",
    "func": "context.state = context.state | false;\ncontext.state = !context.state\nvar\nmyContext = context.state;\nvar count = context.get(\"count\")||0;\ncount +=\n1;\ncontext.set(\"count\",count);\nmsg.count = count;\nfunction isOdd(num) { return num %\n2;}\n\nif(myContext === true && isOdd((count+1)/2) ===1){\n    msg.payload = 1;\n    return\nmsg;\n} else if (myContext === true && isOdd((count+1)/2) ===0){\n    msg.payload = 0;\n    return msg;\n}",
    "outputs": 1,
    "noerr": 0,
    "initialize": "",
    "finalize": "",
    "libs": [],
    "x": 450,
    "y": 400,
    "wires": [
        [
            "0c4853c44002d61b"
        ]
    ]
}
]

```

รูปการทดสอบ 1

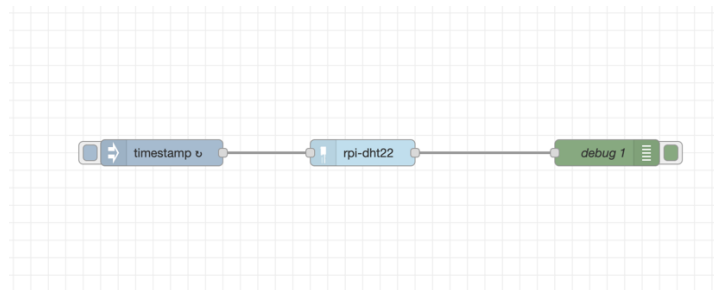


รูปการทดสอบ 2



Node-RED.3 - Node-RED เพื่ออ่าน DHT-22 Sensor

โปรแกรมที่ใช้ทดสอบ



รูป Code Capture

```
[
  {
    "id": "d6b35559496318d0",
    "type": "tab",
    "label": "Q102-0301",
    "disabled": false,
    "info": "",
    "env": []
  },
  {
    "id": "bcfc5be92bd00b6f",
    "type": "rpi-dht22",
    "z": "d6b35559496318d0",
    "name": "",
    "topic": "rpi-dht22",
    "dht": 22,
    "pintype": "0",
```

```

    "pin": "4",
    "x": 440,
    "y": 260,
    "wires": [
      [
        "ae17d2026071014f"
      ]
    ]
  },
  {
    "id": "1ff0c6a3eade9b3c",
    "type": "inject",
    "z": "d6b35559496318d0",
    "name": "",
    "props": [
      {
        "p": "payload"
      },
      {
        "p": "topic",
        "vt": "str"
      }
    ],
    "repeat": "30",
    "crontab": "",
    "once": false,
    "onceDelay": 0.1,
    "topic": "",
    "payload": "",
    "payloadType": "date",
    "x": 210,
    "y": 260,
    "wires": [
      [
        "bcfc5be92bd00b6f"
      ]
    ]
  },
  {

```

```

    "id": "ae17d2026071014f",
    "type": "debug",
    "z": "d6b35559496318d0",
    "name": "debug 1",
    "active": true,
    "tosidebar": true,
    "console": false,
    "tostatus": false,
    "complete": "true",
    "targetType": "full",
    "statusVal": "",
    "statusType": "auto",
    "x": 720,
    "y": 260,
    "wires": []
  }

```

]

รูปการทดสอบ 1



รูปการทดสอบ 2

