



Autoencoder Networks for ATLAS data compression: GSoC 2020

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Why Autoencoders?

At the **Large Hadron Collider, CERN**, storage is one of the main limiting factors to the recording of information from proton-proton collision events. Hence, the **ATLAS** experiment at the LHC uses a so-called **trigger system**, which selects and sends interesting events to the data storage system while throwing away the rest, but if these interesting events are buried in very large backgrounds, they will also be discarded together with the background. To alleviate this problem, we plan to reduce the size of the data that is recorded, and study compression algorithms that can be used directly within the trigger system, specifically with a method using autoencoder (AE) neural networks.

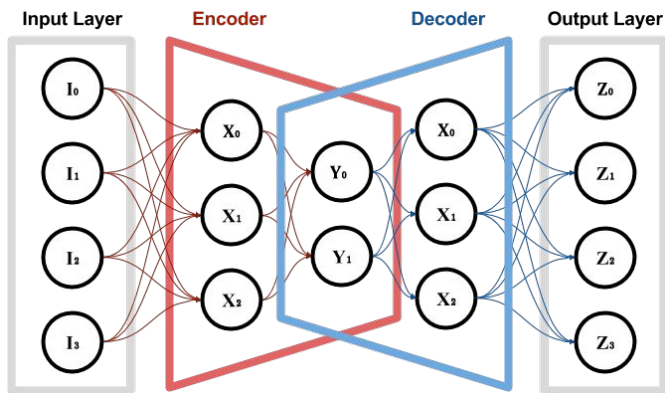


Fig. 1. Autoencoder

Autoencoders is a system that takes an input, chops it into some compressed version and then, attempts to produce output that matches the input as closely as possible. If an input x goes into hidden layer h , $h = f(x)$, it comes out as a reconstruction r , $r = g(h)$. The autoencoder is good when r is close to x , i.e. when the output looks like the input.

So, we can utilize this encoder layer to compress the data. Data can be regenerated by using the decoder layer. If there is a large difference between original and re-generated data, the data could be identified as an interesting event(anomaly).

The data

1. 111778 non-null float64 values in training set.
2. 27945 non-null float64 values in testing set.
3. Data keys:
 - a. m
 - b. pt
 - c. phi
 - d. eta

	m	pt	phi	eta
132784	3831.839355	22000.609375	1.567018	1.142924
99666	4582.417480	21648.210938	-2.680558	0.213654
26629	16747.765625	169514.281250	-1.948239	1.163296
80473	14789.586914	183085.609375	-1.641102	2.670927
48229	4646.724121	20527.130859	2.922270	-1.158871

Fig 2. Data snapshot

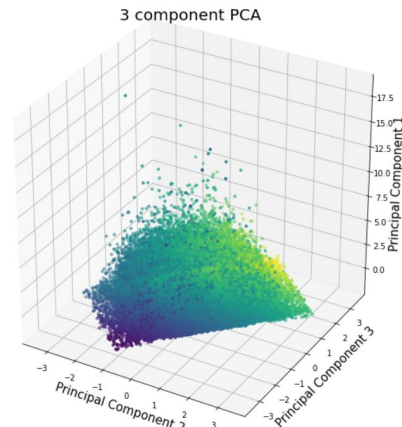


Fig 3.1. 3D Representation of Data using PCA

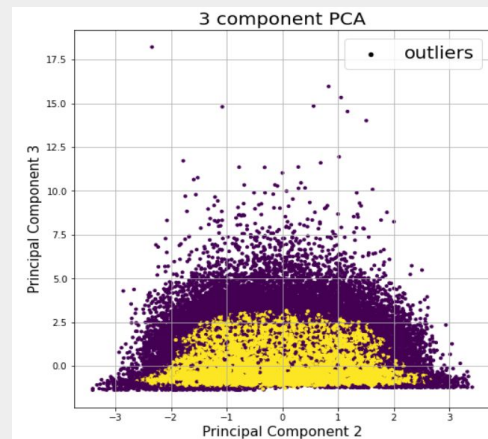


Fig 3.2. 2D Representation of Data showing outliers and inliers, predicted with Isolation Forest Algorithm

Previous Work

Reference: <https://github.com/Skelpdar/HEPAutoencoders>

Loss: 0.5058

Structure:

- Model name: fastai_AE_3D_200
- 8 layered Linear Neural Network
- 4 encoding layers
- 4 decoding layers
- Activation function: tanh
- Loss: Mean Squared error

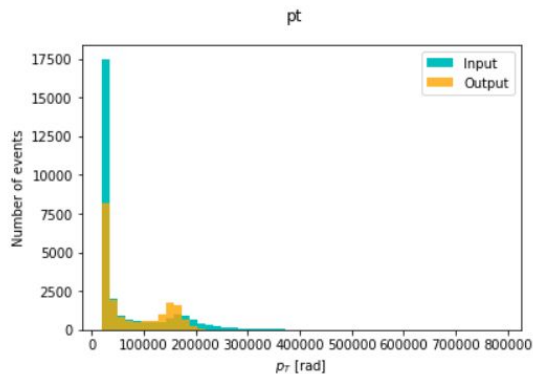


Fig 4.2. Input p_T Vs Output p_T distribution

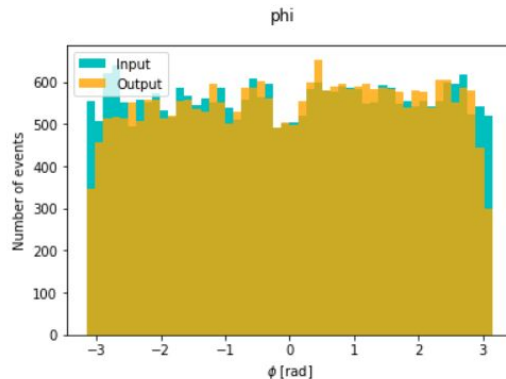


Fig 4.3. Input ϕ Vs Output ϕ distribution

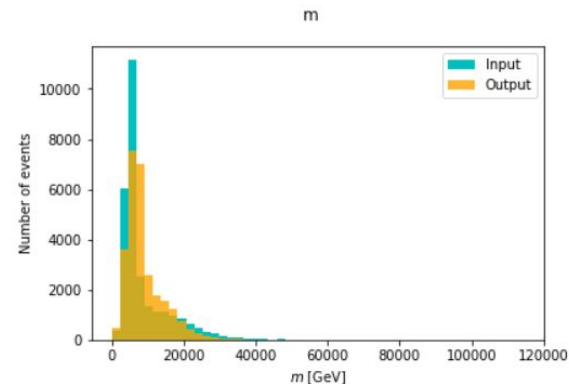


Fig 4.1. Input m Vs Output m distribution

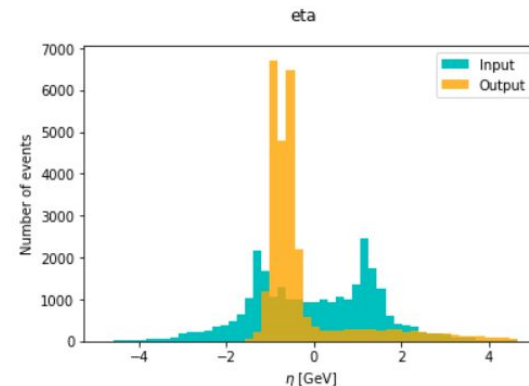


Fig 4.4. Input η Vs Output η distribution

Simple 4x3x4 Deep Autoencoder Neural Network

Loss: 0.5309

Structure:

- 2 Layered deep Neural Network
- 1 Encoding Layer
- 1 Decoding Layer
- Activation: Sigmoid & ReLu
- Loss: Mean Square error

Intuition:

- Used as a benchmark to compare different proposed variations.

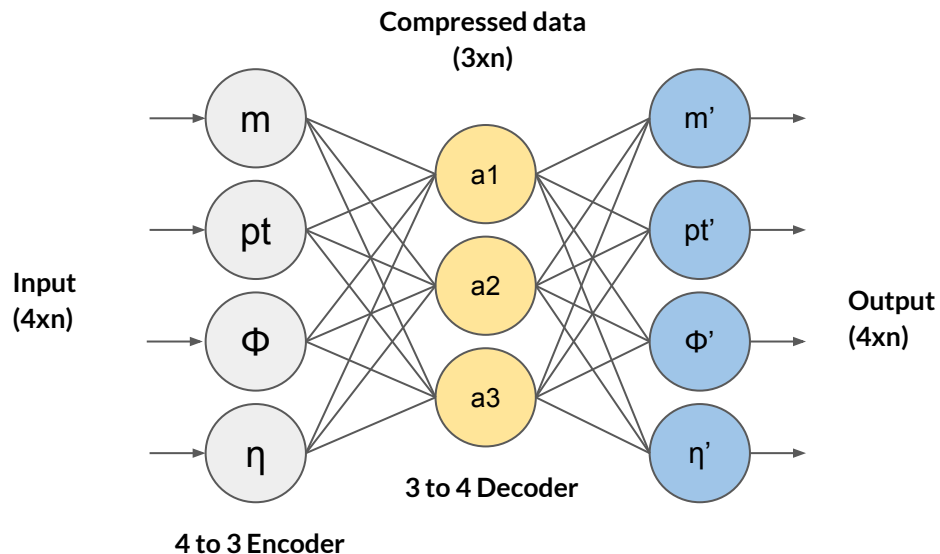


Fig 5. 4x3x4 DANN Architecture

Proposed Solutions

GitHub: https://github.com/panwalas/Autoencoder_ATLAS

1. Multistage 4x5x3x4 Deep Autoencoder Neural Network

Loss: 0.5290

Structure:

- 3 Layered deep Neural Network
- 1 Encoding Layer
- 2 Decoding Layers
- Activation: Sigmoid & ReLu
- Loss: Mean Square error

Intuition:

- By adding a decoding layer before the encoder it may be possible to develop a more complex model that may have better understanding about the data thus, it can encode the data in a better way.

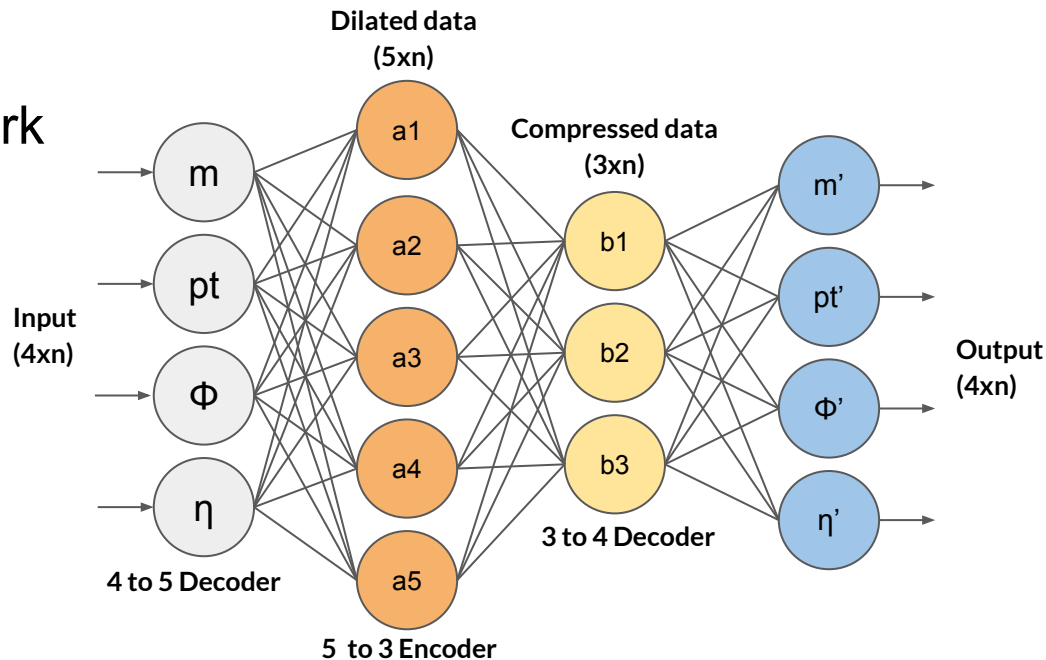


Fig 6. 4x5x3x4 Multistage DANN Architecture

Result: There was some increase in the accuracy (loss: 0.5290) when compared to 4x3x4 DANN (loss: 0.5309), although it is still less than the previous work (loss: 0.5058).

Proposed Solutions

2. Reduced 2x1x2 Deep Autoencoder Neural Network

"Simple solution for a complex problem"

2.1. Correlation matrix

A correlation matrix is a table showing correlation coefficients between variables. Each cell in the table shows the correlation between two variables. A correlation matrix is used to summarize data, as an input into a more advanced analysis, and as a diagnostic for advanced analyses.

Most correlation matrices use Pearson's Product-Moment Correlation. It measures both the strength and direction of the linear relationship between two variables.

	m	pt	phi	eta
m	1.000000	0.873094	-0.000435	-0.013842
pt	0.873094	1.000000	-0.003258	-0.017933
phi	-0.000435	-0.003258	1.000000	-0.004038
eta	-0.013842	-0.017933	-0.004038	1.000000

Fig 7. Correlation Matrix for the training data

Note: Notice the large correlation coefficient between 'm' and 'pt'. The correlation coefficients between other variable pairs is too less.

Proposed Solutions

2. Reduced 2x1x2 Deep Autoencoder Neural Network

2.2. The Network

Loss(network): 0.5040

Loss(overall): 0.2520

Structure:

- 1 Layered deep Neural Network
- 1 Encoding Layer
- 2 Decoding Layers
- Activation: Sigmoid & ReLu
- Loss: Mean Square error

Intuition:

- By using an DANN, we generate a relationship between features, so, there may be a higher loss as these parameters are not correlated. So, what if we just try to compress the variables m and pt (i.e. 2 dim to 1 dim) as they are highly correlated?

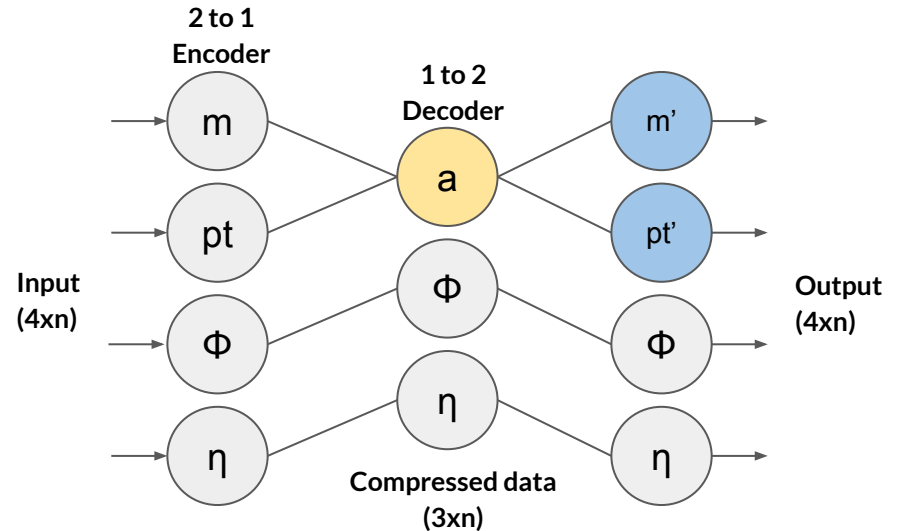


Fig 8. 2x1x2 Reduced DANN Architecture

Proposed Solutions

2. Reduced 2x1x2 Deep Autoencoder Neural Network

2.3. Result & Plots

The testing loss of Reduced 2x1x2 DANN was 0.5040 which is a little better than the previous work (loss: 0.5058). However, when we calculate the overall loss of the network it would result in 0.2520 as the features, phi and eta would also be considered for the calculation.

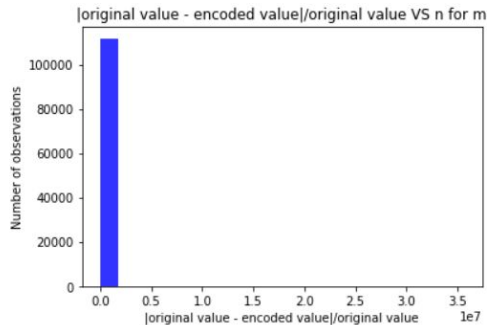


Fig 10.1. |Input - Output|/Output for m

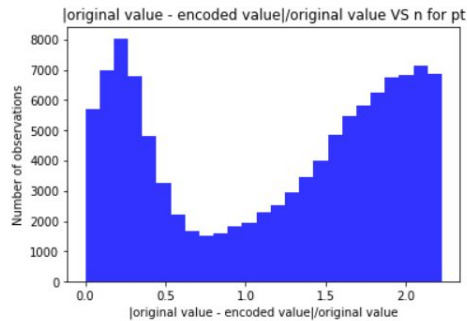


Fig 10.1. |Input - Output|/Output for pt

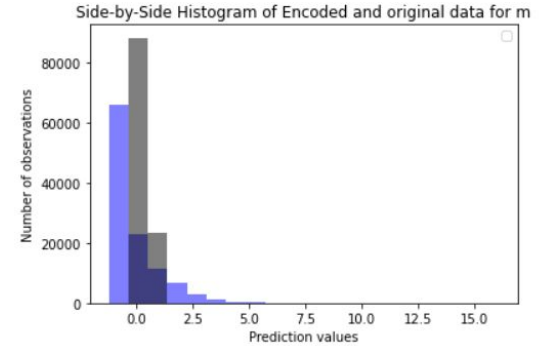


Fig 9.1. Input m Vs Output m distribution

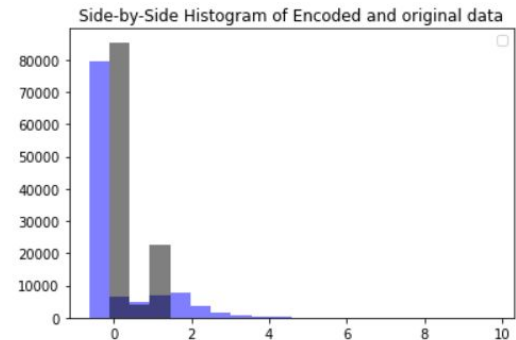


Fig 9.2. Input pt Vs Output pt distribution

How to further improve this network?

The following ways could be explored to further improve the accuracy of the network:

1. **Using positive normalisation technique:** On studying the fig. 9.1 & 9.2 carefully, you will notice that the 2x1x2 Reduced DANN Architecture has not predicted any negative values. So, the model is not able to learn negative features. We may solve this problem by not subtracting the mean from the data. We have originally used the formula,
$$\text{Normalized data}(i) = (\text{data}(i) - \text{data_mean}) / \text{data_standard_deviation}$$

Now,
$$\text{Normalized data}(i) = \text{data}(i) / \text{data_standard_deviation}$$
2. **Hybrid Network:** A Hybrid network could be generated using any two or all of the following networks, i.e., Fastai AE 3D 200, 4x5x3x4 Multistage DANN Architecture, and 2x1x2 Reduced DANN Architecture. It may have a better performance.
3. **Testing different hyper-parameters:** More networks could be generated by testing different combinations of hyper-parameters like, loss function, activation function, no. and type of layer, etc.. There is a possibility of achieving better results.

Summary

S. No.	Model	Mean Squared Error score
1.	Fastai AE 3D 200	0.5058
2.	4x3x4 DANN Architecture	0.5309
3.	4x5x3x4 Multistage DANN Architecture	0.5290
4.	2x1x2 Reduced DANN Architecture	0.2520

Fig 11. MSE Comparison of the discussed networks