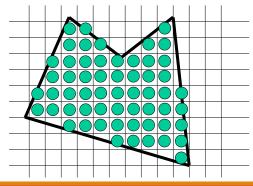
Lecture 6

Rasterizing polygons

1

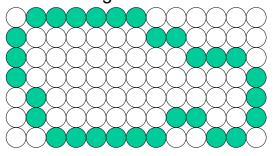
Rasterizing Polygons

Given a set of vertices and edges, find the pixels that fill the polygon.



Flood Fill

First, rasterizing its edges into the frame buffer using Bresenham's algorithm

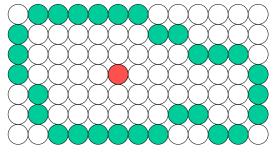


How to fill polygons whose edges are already drawn?

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Flood Fill

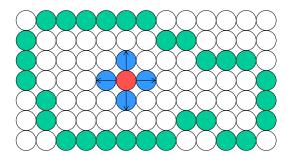
First, rasterizing its edges into the frame buffer using Bresenham's algorithm



Choose a point inside, and fill outwards

Flood Fill

First rasterizing its edges into the frame buffer using Bresenham's algorithm



Choose a point inside, and fill outwards

5

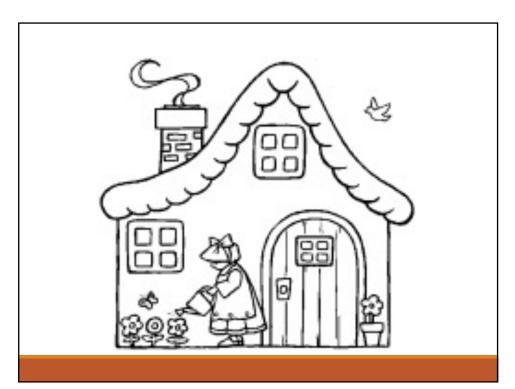
Flood Fill

Fill a point and recurse to all of its neighbors

```
floodFill(int x, int y, color c)
  if(stop(x,y,c))
    return;

setPixel(x,y,c);
  floodFill(x-1,y,c);
  floodFill(x+1,y,c);
  floodFill(x,y-1,c);
  floodFill(x,y+1,c);

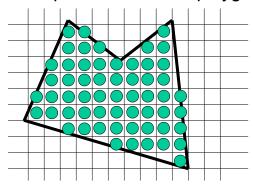
int stop(int x, int y, color c)
  return colorBuffer[x][y] == c;
```





Rasterizing Polygons

Given a set of vertices and edges, find the pixels that fill the polygon.



Rasterizing Polygons vList is an ordered list of the polygon's vertices

```
fillPoly(vertex vList[ ])
 boundingBox b = getBounds(vList);
 int xmin = b.minX;
 int xmax = b.maxX;
 int ymin = b.minY;
 int ymax = b.maxY;
 for(int y = ymin; y \le ymax; y++)
   for(int x = xmin; x \le xmax; x++)
     if(insidePoly(x,y,vList))
       setPixel(x,y);
```

What does 'inside' mean?

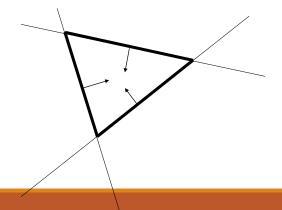
How to test if a point is inside a polygon

- 1. Half-space tests
- 2. Jordan Curve Theorem (even/odd or +1/-1)
- 3. Winding number test

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Half Space Tests

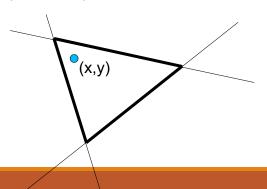
Given the edges of a triangle, the inside is the intersection of half-spaces defined by the edges



Half Space Tests

Easily computable:

l(x,y) = ax + by + c < 0 Iff (x,y) is inside



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Half Space Tests

lineEq computes the implicit line value for 2 vertices & a point

```
fillTriangle(vertex vList[3])

//-- get the bounding box as before --//
float e1 = lineEq(vList[0],vList[1],xmin,ymin);
float e2 = lineEq(vList[1],vList[2],xmin,ymin);
float e3 = lineEq(vList[2],vList[0],xmin,ymin);
int xDim = xMax - xMin;

for(int y = ymin; y <= ymax; y++)
   for(int x = xmin; x <= xmax; x++)
      if(e1<0 && e2<0 && e3<0)
        setPixel(x,y);
   e1 += a1; e2 += a2; e3+= a3;
e1 += -xDim*a1+b1; e2 = -xDim*a2+b2; e3 = -xDim*a3+b3
```

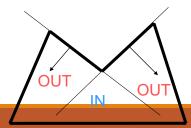
Half Space Tests

Easily computable:

$$l(x,y) = ax + by + c < 0$$
 Iff (x,y) is inside

Doesn't work on concave objects!!

→ triangulate



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What does 'inside' mean?

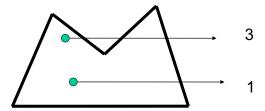
How to test if a point is inside a polygon

- 1. Half-space tests
- 2. Jordan Curve Theorem (even/odd or +1/-1)
 - Self-intersecting polygon OK
- 3. Winding number test

Jordan Curve Theorem

Even/odd approach

Hit test: inside or outside based on the number of intersected edges is even or odd



Any ray from a point inside a polygon will intersect the polygon's edges an odd number of times

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Jordan Curve Theorem

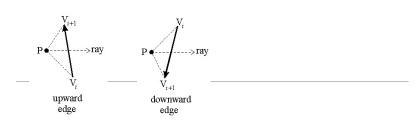
vList is an ordered list of the n polygon vertices

```
int jordanInside(vertex vList[], int n, float x, float y)
  int cross = 0;
  float x0, y0, x1, y1;
  x0 = vList[n-1].x - x; y0 = vList[n-1].y - y; for(int i = 0; i < n; i++)
     x1 = vList[i].x - x;
                               y1 = vList[i].y - y;
     if(y0 > 0)
       if(y1 <= 0)
                                                           (\mathbf{v}_{x_0}, \mathbf{v}_{y_0})
          if( x1*y0 > y1*x0)
             cross++

if(y1 > 0)

if(x0*y1 > y0*x1)

                                                                      (\mathbf{v}_{x_1}, \mathbf{v}_{y_1})
            cross++
     x0 = x1; y0 = y1;
  return cross & 1;
```



$$2 A(\Delta) = \begin{vmatrix} (x_1 - x_0) & (x_2 - x_0) \\ (y_1 - y_0) & (y_2 - y_0) \end{vmatrix} = \begin{vmatrix} x_0 & y_0 & 1 \\ x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \end{vmatrix}$$
$$= (x_1 - x_0)(y_2 - y_0) - (x_2 - x_0)(y_1 - y_0)$$
i.e., $x0y1 - x1y0$

where $V_i = (x_i, y_i)$ V_0 V_0

Vi=(xi,yi)

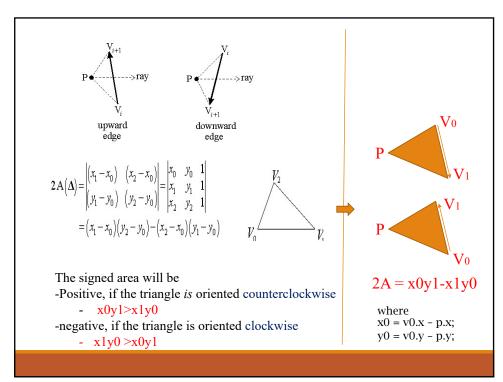
The signed area will be

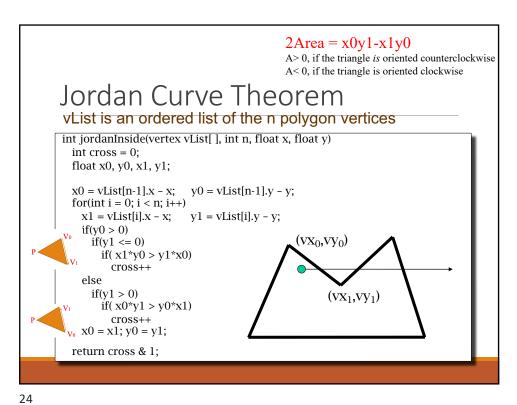
- -positive if the triangle is oriented counterclockwise
- -negative if the triangle is oriented clockwise

http://geomalgorithms.com/a03-_inclusion.html

http://geomalgorithms.com/a01- area.html

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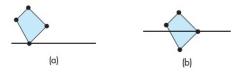


Jordan Curve Theorem

What if it goes through a vertex?

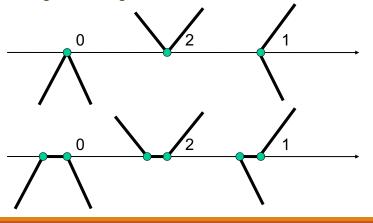
Treat these two cases differently:

- case (a): the vertex–scanline intersection is counted as either zero or two edge crossings
- case (b): the vertex–scanline intersection must be counted as one edge crossing.





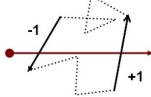
What if it goes through a vertex?

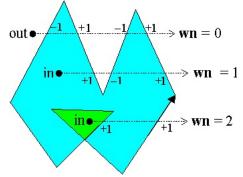


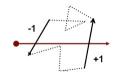
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Jordan Curve Theorem

- Non-zero winding rule:
 - Draw a line from the test point to the outside
 - Count +1 if you cross an edge in an anti-clockwise sense
 - □ Count -1 if you cross an edge in a clockwise sense ...







count +1, if you cross an edge in an anti-clockwise sense count -1, if you cross an edge in an clockwise sense Inside point : non-zero

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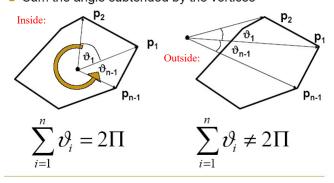
What does 'inside' mean?

How to test if a point is inside a polygon

- 1. Half-space tests
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- 3. Winding number test

Winding Number Test-Method I

Sum the angle subtended by the vertices



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Winding Number Test – Method II

The number of times it is encircled by the edges of the polygon

- +1: if clockwise encirclements
- -1 : if counterclockwise encirclements
- a point is inside the polygon if its winding number is not zero

winding number = 1
winding number = 2

