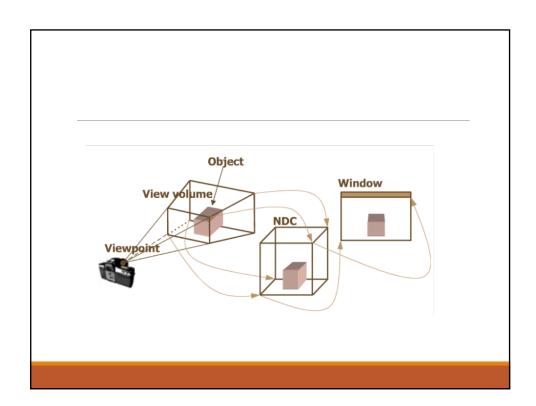
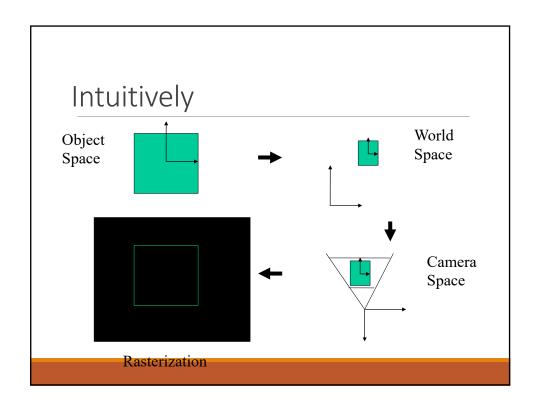
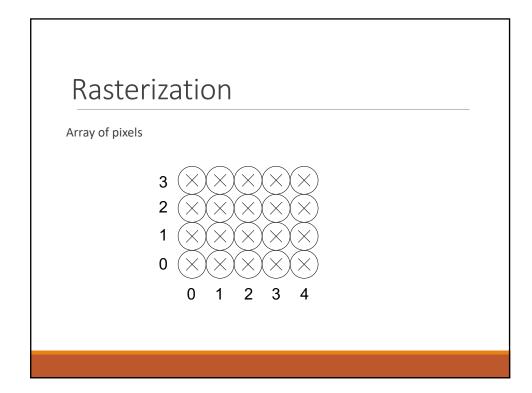
# Lecture 6

Rasterizing lines, polygons







#### Rasterization (scan conversion)

Final step in pipeline: rasterization

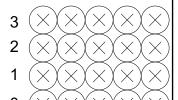
From screen coordinates (float) to pixels (int)

Writing pixels into frame buffer

Separate buffers:

- depth (z-buffer),
- display (frame buffer),
- shadows (stencil buffer)
- blending (accumulation buffer)

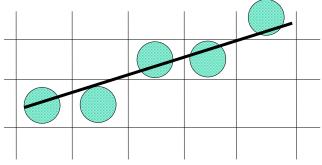
Array of pixels



0 1 2 3 4

#### Rasterizing Lines

Given two endpoints,  $(x_0, y_0)$ ,  $(x_1, y_1)$  find the pixels that make up the line.



#### Rasterizing Lines

#### Requirements

- 1. No gaps
- 1. Minimize error (distance to line)

#### Rasterizing Lines

Equation of a Line:

$$y = mx + h = f(x)$$

Taylor Expansion:

$$f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \frac{f^{(3)}(a)}{3!}(x-a)^3 + \cdots$$

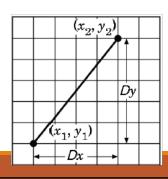
$$f(x + \Delta x) = f(x) + f'(x) \Delta x$$

So if we have an x,y on the line, we can find the next point incrementally.

#### Rasterizing Lines

$$y = mx + h$$
 where  $m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{\Delta y}{\Delta x}$ 

if  $\Delta x = 1$  pixel, we have  $\Delta y = m$ ,



#### Rasterizing Lines

Case1: **-1 < m < 1**, x0 < x1

Line(int x0, int y0, int x1, int y1)

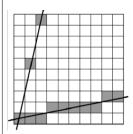
float dx = x1 - x0;

float dy = y1 - y0;

float m = dy/dx;

float x = x0, y = y0;

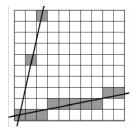
for(x = x0; x <= x1; x++)
writePixel(x,round(y));
y = y+m;</pre>



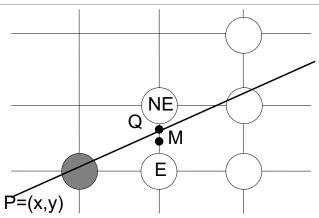
# Rasterizing Lines

#### Problems with previous algorithm

- 1. round takes time
- 2. requires floating point addition
- 3. missing pixels with steep slopes:
  - slope restriction needed



# Midpoint Algorithm



If Q <= M, choose E. If Q > M, choose NE

#### Implicit Form of a Line

Implicit form

**Explicit form** 

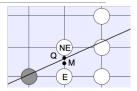
$$ax + by + c = 0 y = \frac{dy}{dx}x + B$$
$$dy x - dx y + B dx = 0$$

$$a = dy$$
  $b = -dx$   $c = B dx$ 

#### **Decision Function**

Assume 0 < m < 1, x0 < x1

Line equation: ax + by + c = 0



$$d = F(x,y) = a x + b y + c$$

mid point: 
$$d = F(x+1, y+\frac{1}{2}) = a(x+1) + b(y+\frac{1}{2}) + c$$

If d positive: M is below the line If d negative: M is above the line Zero on the line



Choose NE if d > 0Choose E if  $d \le 0$ 

#### Incrementing d

#### If choosing E:

→next midpoint:

$$d_{new} = F(x+2,y+\frac{1}{2}) = a(x+2) + b(y+\frac{1}{2}) + c$$



$$d_{old} = F(x+1, y+\frac{1}{2}) = a(x+1) + b(y+\frac{1}{2}) + c$$

$$d_{inc} = d_{new} - d_{old} = a = \Delta E$$

#### Incrementing d

#### If choosing NE:

→next midpoint:

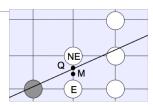
$$d_{new} = F(x+2, y+\frac{3}{2}) = a(x+2) + b(y+\frac{3}{2}) + c$$

But:

$$d_{old} = F(x+1,y+\frac{1}{2}) = a(x+1) + b(y+\frac{1}{2}) + c$$

So:

$$d_{inc} = d_{new} - d_{old} = a + b = \Delta NE$$



#### Initializing d

$$d = F(x_0 + 1, y_0 + \frac{1}{2}) = a(x_0 + 1) + b(y_0 + \frac{1}{2}) + c$$

$$= a x_0 + b y_0 + c + a + b \frac{1}{2}$$

$$= a + b \frac{1}{2}$$

$$\Rightarrow d = dy - \frac{1}{2} dx$$

Multiply everything by 2 to remove fractions (doesn't change the sign)

See: Bresenham Algorithm

#### Midpoint Algorithm

0 < m < 1, x0 < x1 only!!

$$dy x - dx y + B dx = 0$$

$$a = dy$$

$$b = -dx$$

$$d = a + b \frac{1}{2} = dy - \frac{1}{2}dx$$
$$\Delta E = a = dy$$
$$\Delta NE = a + b = dy - dx$$

### Bresenham's Algorithm

Highly efficient

Easy to implement

Widely used

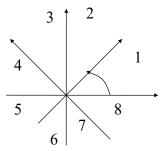
#### Limitations?

Need different cases to handle m > 1

 The midpoint line algorithm assumes that the slope (m) is between 0 and 1

This implies that this algorithm only applies to lines in region 1

Extending to other regions left as a programming assignment



# Midpoint Algorithm Region2

# Anti-aliasing

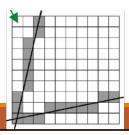
# Aliasing

Artifacts created during scan conversion

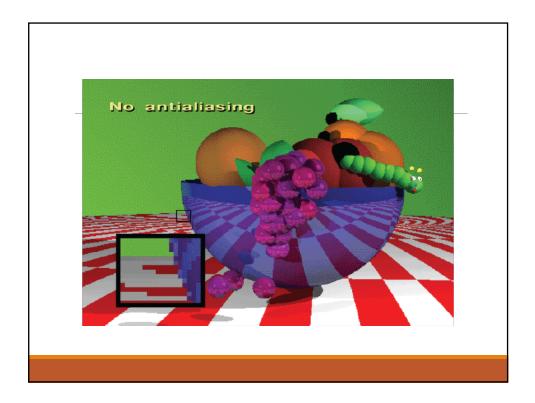
Inevitable (going from continuous to discrete)

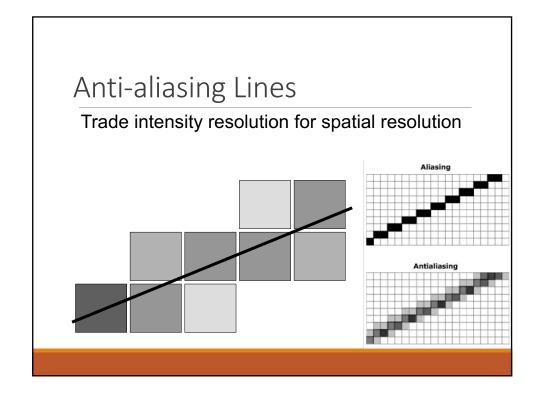
#### Aliasing

- we sample a continues image at grid points
- Jagged edges



# Anti-aliasing Lines Lines appear jaggy Sampling is inadequate





# Anti-aliasing Lines Assume 0 < m < 1, x0 < x1

```
Line(int x0, int y0, int x1, int y1)
 float dx = x1 - x0;
 float dy = y1 - y0;
 float m = dy/dx;
 float x = x0, y = y0;
 for(x = x0; x \le x1; x++)
   int yi = floor(y); float f = y - yi;
   setPixel(x,yi, 1-f);
   setPixel(x,yi+1, f);
   y = y+m;
```

#### Putting it all together!!

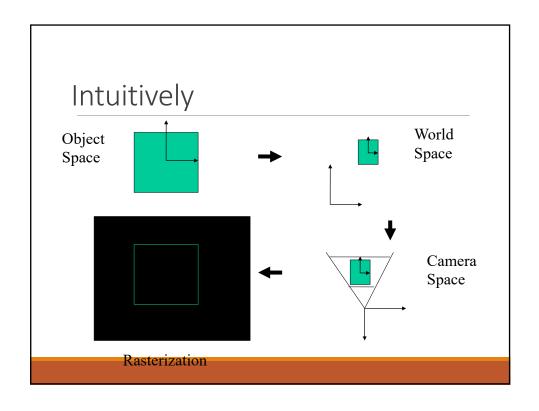
Take your representation (points) and transform it from Object Space to World Space

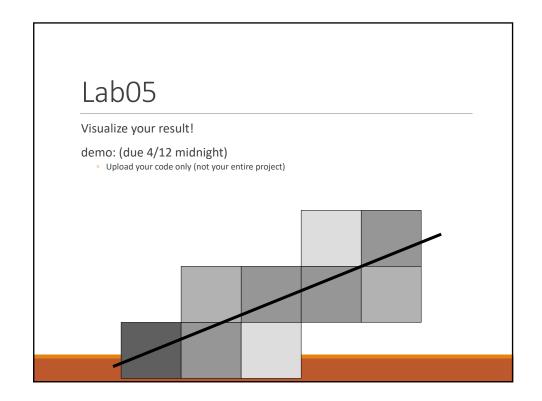
Take your World Space point and transform it to Camera Space

Perform the remapping and projection onto the image plane in Normalized Device Coordinates

Perform this set of transformations on each point of the polygonal object

"Connect the dots" through line rasterization





# Next: Rasterizing Polygons

Given a set of vertices and edges, find the pixels that fill the polygon.

