Optimal control of non-equilibrium processes in stochastic thermodynamics.

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Background: from time reversal of Markov Processes to Stochastic Thermodynamics

- Schrödinger & Nelson. Scope: interpretation of Q.M.
- Kolmogorov: from time reversal to detailed balance.
- A recent different application: non-equilibrium thermodynamics of small systems.
- The "Cost" of deterministic time reversal

Control of thermodynamic processes

- Over-damped dynamics: Work, Heat, Entropy production.
- "Coercivity" and control.
- A simple "universal" result.

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Schrödinger's diffusion problem

E. Schrödinger. "Über die Umkehrung der Naturgesetze". In: Sitzungsberichte der preussischen Akademie der Wissenschaften, physikalische mathematische Klasse 8.9 (1931), pp. 144–153. DOI: 10.1002/ange.19310443014

Given two probability densities

$$\mathbf{m}_o(\mathbf{d}^d x) = \mathbf{m}(\mathbf{d}^d x, t_o)$$
 & $\mathbf{m}_f(\mathbf{d}^d x) = \mathbf{m}(\mathbf{d}^d x, t_f)$

at the end-points of a time interval $[t_o, t_f]$,

find the interpolating diffusion

$$m(d^d x, t) \quad \forall t \in [t_o, t_f]$$

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Reciprocal diffusion processes

Let $\{\xi_t; t \in [t_o, t_f]\}$ be an e.g. \mathbb{R}^d -valued diffusion process

$$p(d^d x, t | \mathbf{x}_1, t_1) = P(\xi_t \in [\mathbf{x}, \mathbf{x} + d\mathbf{x}] | \xi_{t_1} = \mathbf{x}_1)$$

Schrödinger's (math-refinements: 1 see also e.g. 2) finding:

$$q(d^{d}x_{n}, t_{n}, ..., d^{d}x_{1}, t_{1}|m_{o}, m_{f}) =$$

$$\psi[m_{o}, m_{f}](d^{d}x_{o}) \bar{\psi}[m_{o}, m_{f}](d^{d}x_{f}) \prod_{i=1}^{n-1} p(d^{d}x_{i+1}, t|\mathbf{x}_{i}, t_{i})$$

The auxiliary scalar fields

$$\psi[m_o, m_f](d^dx_o)$$
 & $\bar{\psi}[m_o, m_f](d^dx_f)$

are Lagrange multipliers imposing the boundary conditions.

¹ Bernstein. 1932; Jamison. 1974.

² Dai Pra. 1991; Krener. 1997.

A. N. Kolmogorov. "Zur Umkehrbarkeit der statistischen Naturgesetze". In: Mathematische Annalen 113 (1 1937), pp. 766–772. DOI:

IO 1007/BF01571664

- Fix two densities m_o , m_f at the end-points of $[t_i, t_f]$.
- The time reversed Markov evolution must satisfy³ for any t₀ < t₁ < t₂ < t_f:

$$m(\mathbf{x}_2, t_2) \, \tilde{p}(\mathbf{x}_1, t_1 | \mathbf{x}_2, t_2) = p(\mathbf{x}_2, t_2 | \mathbf{x}_1, t_1) \, m(\mathbf{x}_1, t_1)$$

Add the hypotheses

• the diffusion is time-stationary: $p(x_2, t_2|x_1, t_1) = p(x_2, t_2 - t_1|x_1, 0)$ • $m(x, t) = m_*(x) > 0$ is stationary.

Question: under which conditions

$$\tilde{p}(\mathbf{x}_1, 0|\mathbf{x}_2, t_2 - t_1) = p(\mathbf{x}_1, t_2 - t_1|\mathbf{x}_2, 0)$$

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³ Kolmogorov 1936

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Multiplicative noise warning:

Even for an \mathbb{R}^d -valued process ξ the scale of the noise imposes a "Riemannian" metric $g: d\mathbf{x} \otimes d\mathbf{x}$ on the space.

$$\lim_{dt\downarrow 0} \operatorname{E}\left\{\left.\frac{\boldsymbol{\xi}_{t+dt} - \boldsymbol{\xi}_t}{dt}\right| \boldsymbol{\xi}_t = \boldsymbol{x}\right\} = \left(\boldsymbol{f} - \frac{1}{2}\Gamma: g^{-1}\right)(\boldsymbol{x})$$

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here: strictly positive definit

$$\lim_{dt\downarrow 0} \mathrm{E}\left\{\frac{(\boldsymbol{\xi}_{t+dt} - \boldsymbol{\xi}_t) \otimes (\boldsymbol{\xi}_{t+dt} - \boldsymbol{\xi}_t)}{dt} \middle| \boldsymbol{\xi}_t = \boldsymbol{x}\right\} = \mathbf{g}^{-1}(\boldsymbol{x})$$

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Edward Nelson's time reversal for smooth diffusions

E. Nelson. Dynamical Theories of Brownian Motion. second edition. Princeton University Press, 2001, p. 148

Mean backward derivatives

$$\lim_{dt\downarrow0}\mathrm{E}\left\{\left.\frac{\boldsymbol{\xi}_{t}-\boldsymbol{\xi}_{t-dt}}{dt}\right|\boldsymbol{\xi}_{t}=\boldsymbol{x}\right\}=\left(\tilde{\boldsymbol{f}}+\frac{1}{2}\Gamma:g^{-1}\right)(\boldsymbol{x})$$

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- Assigning (m_o, m_f) at $t_o \leq t_f$ specifies \tilde{f} in terms of f.
- Ito lemma in local coordinates becomes $(d\xi_t = \xi_t \xi_{t-dt})$

$$F(\xi_t, t) - F(\xi_{t-dt}, t - dt) = d\xi_t \cdot \partial_{\xi_t} F(\xi_t, t)$$
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Christoffel symbols of g

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Backward drift via Girsanov formula: covariant Wiener measure

Suppose as above that g be

- strictly positive definite;
- time independent.

The (Eells-Elworthy4) development map

$$d\omega_t = \mathbf{e}_t \stackrel{\diamond}{\cdot} d\beta_t$$

$$d\mathbf{e}_t = -\Gamma : \mathbf{e}_t \overset{\diamond}{\otimes} d\omega_t$$

gives a covariant description of a *d*-dimensional Riemann manifold-valued Wiener process.

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⁴ Eells and Elworthy, 1970.

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The important aspect here is covariance, the manifold may well be \mathbb{R}^d



⁴ Eells and Elworthy, 1970.

- The Wiener process $\omega \equiv \{\omega_t; t \in [t_o, t_f]\}$ is invariant under time reversal.
- Semi-martingale $\xi = \{\xi_t; t \in [t_o, t_f]\}$ absolutely continuous w.r.t. ω with non-vanishing covariant drift f. Girsanov formula permits to write for any n-tuple $t_o \leq t_1 \leq \ldots t_n \leq t_f$

$$EF(\boldsymbol{\xi}_{t_1},\ldots,\boldsymbol{\xi}_{t_n})=E\frac{dP_{\boldsymbol{\xi}}}{dP_{\boldsymbol{\omega}}}F(\boldsymbol{\omega}_{t_1},\ldots,\boldsymbol{\omega}_{t_n})$$

• Let $(m_o = \sqrt{\det g} \, n, \, m_f := \sqrt{\det g} \, n)$ at $t_o \leq t_f$ be assigned (as before)

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$$\mathrm{E}F(\boldsymbol{\xi}_{t_1},\ldots,\boldsymbol{\xi}_{t_n})=\mathrm{E}rac{d\mathrm{P}_{\boldsymbol{\xi}}}{d\mathrm{P}_{\boldsymbol{\omega}}}\,F(\boldsymbol{\omega}_{t_1},\ldots,\boldsymbol{\omega}_{t_n})$$

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scalar density: w.r.t. the invariant volume

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o integral w.r.t. Euclidean Wiener process

$$\begin{split} \frac{d\mathrm{P}_{\boldsymbol{\xi}}}{d\mathrm{P}_{\boldsymbol{\omega}}} &= \mathrm{n}_{o}(\boldsymbol{\omega}_{t_{o}}) \, e^{\int_{t_{o}}^{t_{f}} \left[(\mathbf{g} \cdot \boldsymbol{f})(\boldsymbol{\omega}_{t},t) \cdot (\mathbf{e} \cdot d\boldsymbol{\beta}_{t}) - \frac{\|\boldsymbol{f}(\boldsymbol{\omega}_{t},t)\|_{\mathbf{g}}^{2}}{2} \, dt \right]}}{\mathrm{post-point differential: martingale with respect to the "future" filtration} \\ &= \mathrm{n}_{f}(\boldsymbol{\omega}_{t_{f}}) \, e^{\int_{t_{o}}^{t_{f}} \left[(\mathbf{g} \cdot \tilde{\boldsymbol{f}})(\boldsymbol{\omega}_{t},t) \cdot (\mathbf{e}^{\triangleright} d\boldsymbol{\beta}_{t}) - \frac{\|\tilde{\boldsymbol{f}}(\boldsymbol{\omega}_{t},t)\|_{\mathbf{g}}^{2}}{2} \, dt \right]}}\\ &\Rightarrow \, (\boldsymbol{f} - \tilde{\boldsymbol{f}})(\boldsymbol{x},t) = \mathrm{g}^{-1}(\boldsymbol{x}) \cdot \partial_{\boldsymbol{x}} \ln \mathrm{n}(\boldsymbol{x},t) \end{split}}$$

A change of perspective: non-equilibrium thermodynamics of small systems

- molecular fluctuations play a fundamental role for transport processes (phase transitions, nucleation, chemical reactions, DNA mutations).
- dynamical fluctuations contrary to the thermodynamic forces are likely to occur in small systems.
- nano-scales: size of the fluctuations are of the same order of the magnitude of the observables

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A change of perspective: fluctuation theorems

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The statistical "cost" of deterministic reversal

Girsanov martingale and time reversal

$$\int_{t_o}^{t_f} (\mathbf{g} \cdot \boldsymbol{f}) \cdot (\mathbf{e} \cdot d\boldsymbol{\beta}_t) \quad \Rightarrow \int_{t_o}^{t_f} (\mathbf{g} \cdot \tilde{\boldsymbol{f}}) \cdot (\mathbf{e} \cdot d\boldsymbol{\beta}_t)$$

What if we replace $\tilde{\mathbf{f}}$ with $-\mathbf{f}$?

$$\int_{t_{o}}^{t_{f}} (\mathbf{g} \cdot \mathbf{f}) \cdot (\mathbf{e} \stackrel{\triangleright}{\cdot} d\beta_{t}) =$$

$$2 \int_{t_{o}}^{t_{f}} (\mathbf{g} \cdot \mathbf{f}) \cdot (\mathbf{e} \stackrel{\diamond}{\cdot} d\beta_{t}) - \int_{t_{o}}^{t_{f}} (\mathbf{g} \cdot \mathbf{f}) \cdot (\mathbf{e} \stackrel{\triangleleft}{\cdot} d\beta_{t})$$

Log-Cost of the deterministic reversal for ξ

$$\mathcal{J}[\boldsymbol{\xi}] = 2 \int_{t_{-}}^{t_{f}} d\boldsymbol{\xi} \cdot \mathbf{g} \cdot \boldsymbol{f}$$



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Thermodynamics of over-damped dynamics

Suppose

$$\mathbf{f}(\mathbf{x},t) = -(g^{-1} \cdot \partial_{\mathbf{x}} U)(\mathbf{x},t)$$

then

$$\begin{split} \mathcal{J}[\boldsymbol{\xi}] &= -2 \int_{t_o}^{t_f} d\boldsymbol{\xi} \stackrel{\diamond}{\cdot} (\partial_{\boldsymbol{\xi}_t} U)(\boldsymbol{\xi}_t, t) \\ &= -2 [U(\boldsymbol{\xi}_{t_f}, t_f) - U(\boldsymbol{\xi}_{t_o}, t_o)] + 2 \int_{t_o}^{t_f} dt \, (\partial_t U)(\boldsymbol{\xi}_t, t) \end{split}$$

Sekimoto's interpretation

$$\mathcal{W} := \int_{t_0}^{t_f} dt \, (\partial_t U)(\xi_t, t)$$
 work

$$\mathcal{Q}:=-\int_{t_0}^{t_t}d\xi \stackrel{\diamond}{\cdot} (\partial_{m{\xi}_t} U)(m{\xi}_t,t)$$
 heat

Heat and development map

$$Q = -\int_{t_o}^{t_f} d\xi \stackrel{\diamond}{\cdot} (\partial_{\xi_t} U)(\xi_t, t)$$

$$= \int_{t_o}^{t_f} \left\{ -(\mathbf{e} \cdot d\beta)_t \cdot (\partial_{\xi_t} U)(\xi_t, t) + \left(\| \mathbf{g} \cdot \partial_{\xi_t} U \|_{g}^{2} - \frac{1}{2} \Delta_{\xi_t} U \right) dt \right\}$$

hence

covariant density

$$\mathbf{E}\mathcal{Q} = \int_{t_0}^{t_f} \left\{ \| \mathbf{g}^{-1} \cdot \partial_{\boldsymbol{\xi}_t} U \|_{\mathbf{g}}^2 + \frac{1}{2} (\partial_{\boldsymbol{\xi}_t} \ln \mathbf{n}) \cdot \mathbf{g}^{-1} \cdot (\partial_{\boldsymbol{\xi}_t} U) \right\} d\mathbf{g}$$

Heat and development map

$$\begin{aligned} \mathcal{Q} &= -\int_{t_o}^{t_f} d\xi \stackrel{\diamond}{\cdot} (\partial_{\xi_t} U)(\xi_t, t) & \text{$d = -\Gamma : e \otimes d\xi$} \\ &= \int_{t_o}^{t_f} \left\{ -(e \cdot d\beta)_t \cdot (\partial_{\xi_t} U)(\xi_t, t) + \left(\parallel g \cdot \partial_{\xi_t} U \parallel_g^2 - \frac{1}{2} \overleftarrow{\Delta_{\xi_t}} U \right) dt \right\} \end{aligned}$$

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Nelson's current and osmotic velocity

$$\mathbf{v} = \frac{\mathbf{f} + \tilde{\mathbf{f}}}{2}$$
 & $\mathbf{u} = \frac{\mathbf{f} - \tilde{\mathbf{f}}}{2} = \frac{1}{2} \mathbf{g}^{-1} \partial_{\mathbf{x}} \ln \mathbf{n}$
 $\partial_t \mathbf{n} + \nabla_{\mathbf{x}} \cdot (\mathbf{v} \, \mathbf{n}) = 0$

- lacktriangle current $oldsymbol{v}$ and osmotic velocities $oldsymbol{u}$ transform as vector fields
- v behaves as the velocity field of a deterministic ensemble.

$$\mathbf{E}\mathcal{Q} = \mathbf{E} \ln \mathbf{n}(\mathbf{x}_t, t)|_{t_0}^{t_f} + \mathbf{E} \int_{t_0}^{t_f} dt \parallel \mathbf{v} \parallel_{\mathbf{g}}^2$$



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Bound for the Heat

$$\mathrm{E}\mathcal{Q} \, \geq \, \mathrm{E} \ln \mathrm{n}(\pmb{x}_t,t)|_{t_0}^{t_f} = - \mathrm{variation} \ \mathrm{of} \ \mathrm{Shannon} ext{-Gibbs Entropy}$$

Bound for the work

$$\begin{split} \mathbf{E}\mathcal{W} &= \mathbf{E}\left\{U(\boldsymbol{x}_t,t)|_{t_0}^{t_t} + \mathcal{Q}\right\} \geq \\ &\quad \mathbf{E}\left\{U(\boldsymbol{x}_t,t) + \frac{1}{2}\ln \mathbf{n}(\boldsymbol{x}_t,t)\right\}|_{t_0}^{t_t} = \text{variation of equilibrium free energy} \end{split}$$

Current velocity: deviation from equilibrium

$$\mathbf{v} = -\mathbf{g}^{-1} \cdot \partial_{\mathbf{x}} \left(U + \frac{1}{2} \ln n \right)$$
 vanishes at equilibrium !!!

Coercivity

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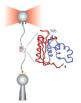
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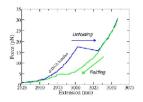
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Physical motivations for control

Nano motors

- mainly in steady operation
- what external control should be apply that maximizes the output power?
- operation under minimal dissipation
- efficiency at maximum power





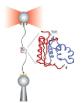
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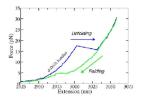
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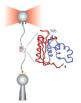
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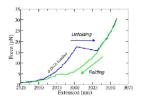
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 Heat minimization between fixed end-states (n_o, n_f) reduces to the deterministic control of

$$\mathrm{E}\,\mathcal{S} = \mathrm{E}\int_{t_{\mathsf{o}}}^{t_{\mathsf{f}}} dt \parallel \boldsymbol{v} \parallel_{\mathsf{g}}^{2}$$

- The problem is well-posed in the space of smooth diffusions
- The bound lower becomes tight if jump processes are admissible minimizers:
 - no penalty on acceleration.
 - jump between equilibria: current velocity identically vanishing.

- Suppose now g = I
- $\mathbf{V} = \partial_{\mathbf{X}} \varphi$

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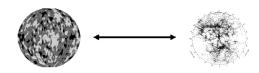
$$\begin{aligned} \partial_t \varphi + \frac{1}{2} \parallel \partial_{\mathbf{x}} \varphi \parallel^2 &= 0 \\ \partial_t \mathbf{m} + \partial_{\mathbf{x}} \cdot (\mathbf{m} \, \partial_{\mathbf{x}} \varphi) &= 0 \\ \mathbf{m}(\mathbf{x}, t_o) &= \mathbf{m}_o(\mathbf{x}) & \& & \mathbf{m}(\mathbf{x}, t_f) &= \mathbf{m}_f(\mathbf{x}) \end{aligned}$$

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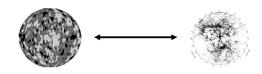


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Frisch et al, Nature **417**, 260 (2002) Brenier et al, MNRAS **346**, 501 (2003)

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Villani, Topics in Optimal Transportation (AMS 2003)



A "valley view" over optimal thermodynamic control

Ideas borrowed from instanton calculus in Quantum Field Theory.

$$egin{aligned} \mathcal{A} := \int_{t_o}^{t_f} dt \; \left(\parallel oldsymbol{v}_t \parallel^2 + arepsilon \parallel oldsymbol{a}_t \parallel^2
ight) \ + oldsymbol{\lambda} \cdot \int_{t_o}^{t_f} dt \; \left[oldsymbol{v}_t - rac{\phi(oldsymbol{x}_o) - oldsymbol{x}_o}{\Delta t}
ight] \end{aligned}$$

- \bullet $\dot{\boldsymbol{x}}_t = \boldsymbol{v}_t$
- λ enforces $\mathbf{x}_f = \phi(\mathbf{x}_o)$
- \bullet ϕ relates the initial and final states

$$\mathrm{m_{\it f}}(\phi(\textbf{\textit{x}}))\left|\det \frac{\partial \phi(\textbf{\textit{x}})}{\partial \textbf{\textit{x}}}\right| = \mathrm{m_{\it o}}(\textbf{\textit{x}})$$

• It is possible to impose boundary conditions on the state $\mathbf{x}_{t_o} = \mathbf{x}_o$, $\mathbf{x}_{t_t} = \mathbf{x}_f$ and on the initial and final velocities.



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$$\operatorname{m}_f(\phi({m{x}}))\left|\det rac{\partial \phi({m{x}})}{\partial {m{x}}}
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More about all the above

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