

# Best-response dynamics (with applications to distributed protocols and mechanisms)\*

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## 1 Warm up

Which of these three games have **pure Nash equilibria (PNE)**?

	<i>H</i>	<i>T</i>
<i>H</i>	1, -1	-1, 1
<i>T</i>	-1, 1	1, -1

Matching Pennies

	<i>B</i>	<i>S</i>
<i>B</i>	2, 1	0, 0
<i>S</i>	0, 0	1, 2

Battle of Sexes

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\*The material of this lecture is taken from [Nisan et al. \(2011a\)](#) where you can find several other applications of best-response mechanisms. There you have a more precise, extensive, and formal description of best-response mechanisms, plus further pointers into the literature.

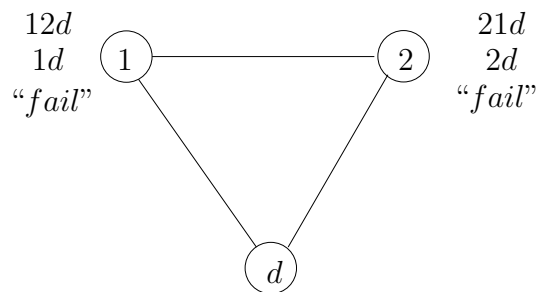
	$A$	$S$
$A$	$-2 \quad -2$	$0 \quad -3$
$S$	$0 \quad -3$	$-1 \quad -1$

Prisoners' Dilemma

**(Synchronous) Best-Response Dynamics:** Players play their best response infinitely many times, one by one in a fixed order (round robin).

What happens for the three games above?

**Example 1** Two nodes, 1 and 2, want to send traffic to another destination node  $d$ . Their strategy is to choose the *next hop* the traffic is sent to (one of the neighbors). The following picture shows the physical network and the preferences of each node (which path to use) near the corresponding node:



Each node prefers to reach  $d$  via the other node, but if they both send their own traffic to each other they fail (which is the least preferable option for both). ■

**Question:** What happens if the two nodes move (play) always simultaneously? What happens if node 1 plays “ $1 \rightarrow 2$ ” at each step (while the other node plays best-response)?

Best Response:

1. No convergence in *asynchronous* settings.
2. Not incentive compatible.

For which games this does not happen?

**Asynchronous Best-Response Dynamics:** At each step an adversary activates an arbitrary subset of players who best respond to the current profile (the adversary also chooses a starting strategy profile). The adversary must activate each player an infinite number of times.

The choice of the adversary and the “response strategies” of each player determine an infinite sequence

$$s^0 \implies s^1 \implies \dots s^t \implies \dots$$

If the game converges (after finitely many steps  $T$  we have  $s^T = s^{T+1} = s^{T+2} = \dots$ ) then the utility of each player  $i$  is  $u_i(s^T)$ . If the game keeps “oscillating” then we consider an upper bound on what the player can get (the worst case for us and the best for the player) that is  $\limsup_{t \rightarrow \infty} u_i(s^t)$ .

Base game $G$	$\implies$	Repeated game $G^*$
$s_i \in S_i$		response strategy $R_i() \in S_i$
$u_i(s)$		total utility $\Gamma_i := \limsup_{t \rightarrow \infty} u_i(s^t)$

**Definition 2** Best-response are *incentive compatible* for  $G$  if repeated best-responding is a Nash equilibrium for the repeated game  $G^*$ , that is, for every  $i$

$$\Gamma_i \geq \Gamma'_i$$

where  $\Gamma_i$  is the total utility when all players best respond and  $\Gamma'_i$  is the total utility when all but  $i$  best respond (starting from the same initial profile  $s^0$  and applying the same activation sequence).

## 2 “Nice” Games

Consider this game (with a unique PNE):

		Player 2	
		A	B
Player 1	A	1 2	0 0
	B	0 3	2 1

Best response works as follows

$$(A, A) \xrightarrow{\text{Player } 1} (B, A) \xrightarrow{\text{Player } 2} (B, B) \xrightarrow{\text{Player } 1} (B, B) \xrightarrow{\text{Player } 2} (B, B) \cdots \Rightarrow (B, B)$$

Player 1 improves if he/she does not best response (keep playing A):

$$(A, A) \xrightarrow{\text{Player } 1} (A, A) \xrightarrow{\text{Player } 2} (A, A) \xrightarrow{\text{Player } 1} (A, A) \Rightarrow \cdots \Rightarrow (A, A)$$

Convergence but no incentive compatibility

**Exercise 1** For the following game

		Player 2	
		A	B
Player 1	A	1 1	1 1
	B	1 1	1 1

find best response strategies that *never converge* (keep oscillating between different profiles). Find other best response strategies for which we *do have convergence*. ■

Two intuitions/ideas:

1. Introduce tie breaking rule.
2. Eliminate “useless” strategies.

## 2.1 Convergence

Consider this game

	$A$	$B$	$C$
$a$	1 2	0 0	0 0
$b$	2 1	-1 1	1 -1
$c$	-2 -1	1 -1	-1 1

**Exercise 2** Prove that for this game best-response dynamics converge to a unique PNE.

Note that in the previous game no strategy is dominant and no strategy is dominated. Strategy  $C$  satisfies the following (weaker) definition:

**Definition 3 (never best response (NBR))** A strategy  $s_i \in S_i$  is a never best response (for tie breaking rule  $\prec$ ) if there is always another strategy that gives a better payoff or that gives the same payoff but is better w.r.t. to this tie breaking rule: for all  $s_{-i}$  there exists  $s'_i \in S_i$  such that one of these holds

1.  $u_i(s_i, s_{-i}) < u_i(s'_i, s_{-i})$  or
2.  $u_i(s_i, s_{-i}) = u_i(s'_i, s_{-i})$  and  $s_i \prec_i s'_i$ .

The following condition is enough to guarantee convergence:

**Definition 4 (NBR-solvable)** A game  $G$  is NBR-solvable if iteratively eliminating NBR strategies results in a game with one strategy per player. That is, there exists a tie breaking rule  $\prec$ , sequence  $p_1, \dots, p_\ell$  of players, and a corresponding sequence of subsets of strategies  $E_1, \dots, E_\ell$  such that:

1. Initially  $G_0 = G$  and  $G_{i+1}$  is the game obtained from  $G_i$  by removing the strategies  $E_i$  of player  $p_i$ ;
2. Strategies  $E_i$  are NBR for  $\prec$  in the game  $G_{i-1}$ .

3. The final game  $G_\ell$  has one strategy for each player (this unique profile is thus a PNE for  $G$ ).

A sequence of players and of strategies as above is called an *elimination sequence* for the game  $G$ .

**Exercise 3** Prove that the game described at the beginning of this section is NBR-solvable. Provide also a bound on the parameter  $\ell$ .

**Lemma 5 (rounds vs subgames)** Let  $p_1, \dots, p_\ell$  be the players of any elimination sequence for the game under consideration. Suppose that players  $p_1, \dots, p_k$  always best respond (according to the prescribed tie breaking rule  $\prec$ ). Then, for any initial profile and for any activation sequence, every profile after the  $k^{\text{th}}$  round is a profile in the subgame  $G_k$ .

Before proving the lemma we observe that it implies convergence:

**Theorem 6 (convergence)** For NBR-solvable games best response (according to the prescribed tie breaking rule  $\prec$ ) converge even in the asynchronous case.

PROOF. Take  $k = \ell$  and observe that  $G_\ell$  contains only one profile.  $\square$

PROOF OF LEMMA 5. Denote by  $\text{round}_j$  the last time step of the  $j^{\text{th}}$  round in the activation sequence. Obviously for any  $t$  we have  $s^t \in G_0 = G$ . Now consider  $t \geq \text{round}_1$  and observe that, since player  $p_1$  has been activated at least once the corresponding strategy satisfies <sup>1</sup>

$$s_{p_1}^t \notin E_1$$

which is equivalent to  $s^t \in G_1$  for all  $t \geq \text{round}_1$ .

To prove the analogous for player  $p_2$  we observe that, in the  $2^{\text{nd}}$  round player  $p_2$  is activated and, since  $s^t \in G_1$  and since  $p_2$  plays best response, for  $t \geq \text{round}_2$  we have  $s_{p_2}^t \notin E_2$ . Since we have previously proved  $s_{p_1}^t \notin E_1$ , this implies  $s^t \in G_2$  for  $t \geq \text{round}_2$ .

We can then continue and prove, by induction, that after the  $k^{\text{th}}$  round player  $p_k$  does not play any strategy in  $E_k$  and thus  $s^t \in G_k$  for all  $t \geq \text{round}_k$ .  $\square$

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<sup>1</sup>More in detail, if the player is activated at time  $t'$  then at time  $t' + 1$  his/her profile is not in  $E_1$ ; If the player is not activated at time  $t'$  then her strategy at time  $t' + 1$  remains the same.

## 2.2 Incentive Compatible

Look (again) at this game:

		Player 2	
		A	B
Player 1	A	2, 1	0, 0
	B	3, 0	1, 2

**Bad for incentive compatibility:** The unique PNE does not give Player 1 the highest possible payoff he/she can get in this game.

**Definition 7 (NBR-solvable with clear outcome)** A NBR-solvable game  $G$  has a clear outcome if there exists a tie breaking rule  $\prec$  such that the following holds. For every player  $i$  there exists an elimination sequence consisting of players  $p_1, \dots, p_a, \dots, p_\ell$  and strategies  $E_1, \dots, E_a, \dots, E_\ell$  (according to Definition 4) such that,

1.  $p_a$  denotes the first appearance of  $i$  in the sequence, that is,

$$p_a = i \neq p_1, p_2, \dots, p_{a-1};$$

2. in the corresponding subgame

$$G_{a-1} = G \setminus (E_1 \cup E_2 \cup \dots \cup E_{a-1})$$

the PNE  $s^*$  is globally optimal for  $i$ , that is,

$$u_i(\hat{s}) \leq u_i(s^*) \quad \text{for all } \hat{s} \in G_{a-1}.$$

(Recall that  $s^*$  is the unique profile in the final subgame  $G_\ell$ .)

**Theorem 8 (incentive compatibility)** For NBR-solvable games best response (according to the prescribed tie breaking rule  $\prec$ ) are also incentive compatible.

PROOF. Compare the case in which all players best respond to the case in which player  $i$  does not best respond (while the others best respond). In particular, we consider the two sequences of profiles

$$\begin{aligned} \text{All best respond: } s^0 &\implies s^1 \implies s^2 \implies \dots \implies s^* \implies s^* \dots \\ \text{All but } i \text{ best respond: } s^0 &\implies \hat{s}^1 \implies \hat{s}^2 \implies \dots \implies \hat{s}^t \implies \hat{s}^{t+1} \dots \end{aligned}$$

We want to show that starting from some finite  $T$  the utility of  $i$  in the second sequence is not better than the “final” utility in the first sequence:

$$u_i(\hat{s}^t) \leq u_i(s^*) \quad \text{for all } t \geq T \quad (1)$$

This implies  $\hat{\Gamma}_i \leq \Gamma_i$  that is the incentive compatibility condition (see Definition 2). Consider the elimination sequence of definition of NBR-solvable game (Definition 7) and let  $p_k = i$  be the first occurrence of  $i$  in the sequence (i.e.  $i \neq p_1, \dots, i \neq p_{k-1}$ ):

$$\begin{array}{l} \text{Player:} \\ \text{NBR Strategies:} \\ \text{Current Game:} \end{array} \left| \begin{array}{cccccc} p_1 & \dots & p_{k-1} & i & p_{k+1} & \dots \\ E_1 & \dots & E_{k-1} & E_k & E_{k+1} & \dots \\ G_0 & \dots & G_{k-2} & G_{k-1} & G_k & \dots \end{array} \right.$$

We know from Lemma 5 that after round  $k-1$  the profile must be in the game  $G_{k-1}$  (since  $i$  does not appear in the elimination sequence before position  $k$ , all players  $p_1, \dots, p_{k-1}$  are different from  $i$  and thus they all play best response). Since the PNE  $s^*$  is globally optimal for  $i$  in this subgame, we have  $u_i(s^t) \leq u_i(s^*)$  for all  $t \geq \text{round}_{k-1}$ . This proves Inequality (1) and thus the theorem.  $\square$

### 3 TCP Games

We begin with a toy example. Two players want to send data through a link of a certain capacity  $C$ . Each player  $i$  can select a sending rate  $s_i$  (the *strategy* of player  $i$ ) in an interval  $[0, M_i]$ , and the channel policy (if capacity is exceeded some packets are dropped) determines the actual rate  $r_i$  for each player (this amount is the *payoff* of player  $i$ ).

The following is an abstract view of what TCP prescribes to do:



**Probing Increase Educated Decrease (PIED):** Send exactly at the maximum rate that you can get (not more than that).

After gradually increasing the sending rate, at some point some packets are dropped. This is a way for player  $i$  to learn the maximum rate he/she can get without packets being dropped. PIED prescribes to send at this maximum rate, that is, to play

$$s_i^* := \max\{s_i \in [0, M_i] \mid r_i(s_i, s_{-i}) = s_i\},$$

where the actual rate  $r_i()$  depends on the channel policy.

**Exercise 4** *Explain why PIED is not incentive compatible if the channel policy is to divide the total capacity proportionally to the sending rate of the player (whenever their requests exceed  $C$ ):*

$$r_i = C \frac{s_i}{\sum_j s_j}.$$

We introduce a channel policy that makes PIED incentive compatible and uses the whole channel capacity:

**Strict Priority Queuing:** Try to satisfy the players requests one-by-one in a fixed order:

$$\begin{aligned} r_1 &\leftarrow \min(s_1, C) \\ r_2 &\leftarrow \min(s_2, C - r_1) \\ &\vdots \\ r_n &\leftarrow \min(s_n, C - r_1 - \dots - r_{n-1}) \end{aligned}$$

**Exercise 5** *Show that if the channel uses a Strict Priority Queuing policy then PIED converges and is incentive compatible.*

## References

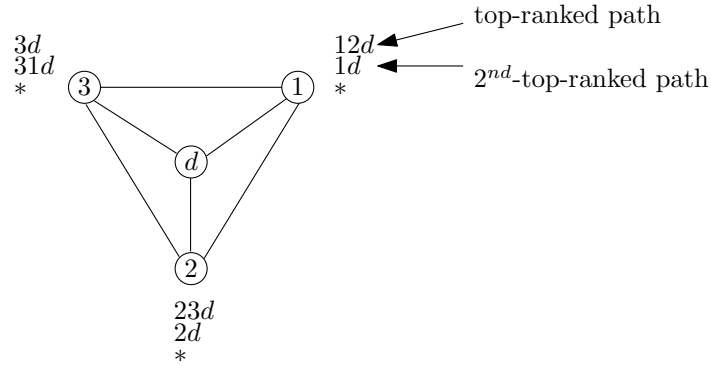
The material of this lecture is taken from [Nisan et al. \(2011a\)](#) where you can find more details about the applications and further pointers into the literature. More details about the analysis of BGP and auctions can be find in [Levin et al. \(2008\)](#) and in [Nisan et al. \(2011b\)](#), respectively.

- Hagay Levin, Michael Schapira, and Aviv Zohar. Inter-domain routing and games. In *ACM Symposium on Theory of computing (STOC)*, page 57, 2008. URL [http://www.cs.huji.ac.il/~schapiram/routing\\_games-full.pdf](http://www.cs.huji.ac.il/~schapiram/routing_games-full.pdf).
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## Exercises for Lecture 1

This exercise is on the games discussed in Example 1 in the lecture notes.

**Exercise 1 (on BGP games)** Consider the following simple instance of the “BGP games” (a network and the preferences of each node over the possible paths to  $d$ ):



where the symbol “ $*$ ” denotes any path connecting the node to  $d$  but different from the top two. The utilities correspond to the rank in the natural way:

Top-ranked path has utility 3, second-top-ranked has utility 2,  $*$  has utility 1, and the utility is 0 if the node does not reach  $d$  (e.g., if 3 and 1 point to each other, then their utility is 0).

Prove that the resulting game is NBR-solvable with clear outcome.

The next exercise is on the games in Section 3 of the lecture notes.

**Exercise 2 (on TCP games)** Consider a single channel of capacity  $C$  and two players with maximum sending rate  $M_1$  and  $M_2$ . Prove that PIED converges and is incentive compatible (for any  $C$  and any  $M_1$  and  $M_2$ ).