# FINAL EXAM REPORT

# Course in Advanced HPC

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#### 1 Introduction

In this report are presented some strong scaling results on the Leonardo Cluster involving two type of parallel algorithm: the double precision matrix multiplication and the Jacobi iteration method to solve the 2D heat equation. The scalings were performed both on the CPU and and GPU nodes. The library used are MPI, OpenMP, Intel MKL, OpenBLAS, Cuda and OpenACC.

## 2 Scaling Setup

#### 2.1 CPU Nodes

- 1, 2, 4, 8, 16 nodes
- 1 MPI Task per node
- 112 OpenMP threads per node (1 per core)

#### 2.2 GPU Nodes

- 1, 2, 4, 8, 16 nodes
- 4 MPI Task per node (1 per GPU)
- 8 OpenMP threads per task (32 per node, 1 per core)

Each run was repeated 5 times in order to calculate the averages (except for Naive MatMul).

#### Part I

# Parallel Matrix Multiplication

# 3 Algorithm Implementation

#### 3.1 CPU version

To perform the parallel matrix multiplication C = AB on CPU we start by allocating and initializing two matrices of size  $N \times N$ : the identity matrix A and the matrix B. Each process allocates its local portion for each matrix  $A_{LOC}$  and  $B_{LOC}$ . Moreover we allocate for each process:

- $B_{TEMP}$  of size  $(N/nprocs + 1) \times N_{LOC}$ , the block of matrix B that a process send with AllGather operation
- $B_{TEMP\_N}$  of size  $(N/nprocs + 1) \times N$ , the array that stores the result of AllGather operation for each process.
- $C_{TEMP\_N}$  of size  $(N/nprocs + 1) \times N$ , which stores the results (by row) of the multiplication for each process.

 $N_{LOC}$  is the number of rows assigned to each process, nprocs the number of processes and (N/nprocs + 1) is the maximum number of column of matrix B that a process can have at each iteration of matrix multiplication.

Then, the iterations from 0 to nprocs works for each process as shown in Algorithm 1 and illustrated in Figure 1.

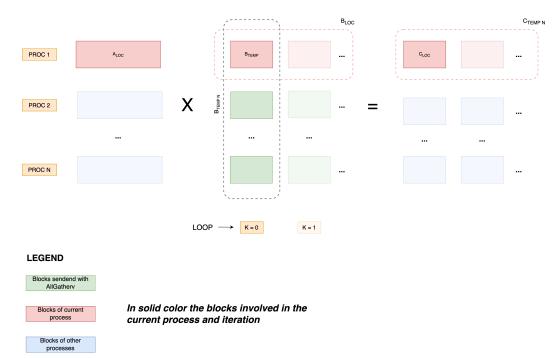


Figure 1: Jacobi Matrix Allocation for each process.

#### Algorithm 1 Parallel Matrix Multiplication Iteration - CPU

```
1: for k \leftarrow 0 to nprocs do
      if k < \text{rest then}
         N_{COL} \leftarrow N/nprocs + 1
3:
         C_{LOC} points to C_{TEMP\_N} + (N_{COL} * k)
 4:
      else
5:
         N_{COL} \leftarrow N/nprocs
6:
         C_{LOC} points to C_{TEMP\_N} + (N_{COL} * k + rest)
7:
      end if
 8:
      copy the k block of B_{LOC} in B_{TEMP}
9:
      calculate the receivecounts and displacements for the AllGatherv operation
10:
      AllGatherv(send:B_{TEMP}, receive:B_{TEMP-N})
11:
      C_{LOC} \leftarrow matmul(A_{LOC}, B_{TEMP-N})
12:
13: end for
14: save C_{TEMP\_N} in binary file with MPI I/O
```

This Algorithm is performed by each process. The *matmul* function on CPU has two variants:

- naive: use the classical naive algorithm of Matrix Multiplication with 3 for loops on CPU
- blas: use the CBLAS dgemm function (multithreaded) on CPU to perform the matrix multiplication

#### 3.2 GPU version

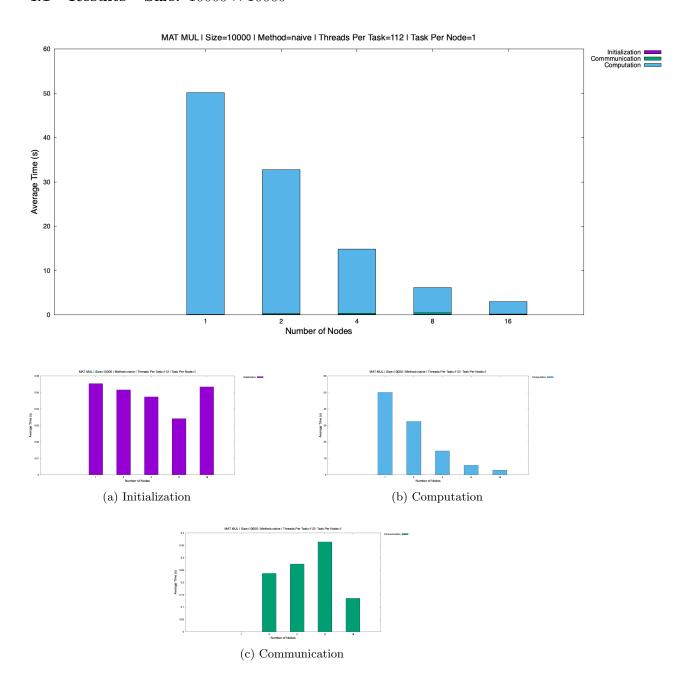
The GPU version of the algorithm is very similar to the previous but this time on CPU we perform only the initialization. All the pieces of matrices needed for an iteration are sended then to the GPUs which perform the computation phase with the *cublas\_dgemm* function. Moreover, this function reads by default the matrix in column major order. To avoid each time the transposition, we instead calculate the results as  $B^TA^T = C^T$ . In this way, we already have  $B^T$  and  $A^T$ . Finally, the result  $C^T$  (that is stored in column major order) can be transposed to C by simply read it in row major order. After all the iterations, each process send the  $C_{TEMP_N}$  block stored on GPU to the CPU and saves the result in parallel. This version is shown in the Algorithm 2.

## Algorithm 2 Parallel Matrix Multiplication Iteration - GPU

```
1: allocate cu\_A_{LOC}, cu\_B_{TEMP\_N}, cu\_C_{TEMP\_N} on GPU
2: memcpy A_{LOC} in cu\_A_{LOC}
3: for k \leftarrow 0 to nprocs do
      if k < \text{rest then}
         N_{COL} \leftarrow N/nprocs + 1
        cu\_C_{LOC} points to cu\_C_{TEMP\_N} + (N_{COL} * k)
7:
        N_{COL} \leftarrow N/nprocs
8:
        cu\_C_{LOC} points to cu\_C_{TEMP\_N} + (N_{COL} * k + rest)
9:
      end if
10:
      copy the k block of B_{LOC} in B_{TEMP}
11:
      calculate the receivecounts and displacements for the AllGatherv operation
      AllGatherv(send:B_{TEMP}, receive:cu\_B_{TEMP\_N})
13:
      memcpy B_{TEMP-N} in cu_{-}B_{TEMP-N}
14:
      cu\_C_{LOC} \leftarrow cublas(cu\_B_{TEMP\_N}, cu\_A_{LOC})
15:
16: end for
17: memcpy cu\_C_{TEMP\_N} in C_{TEMP\_N}
18: save C_{TEMP\_N} in binary file with MPI I/O
```

# 4 Naive Parallel Matrix Multiplication

## 4.1 Results - Size: $10000 \times 10000$



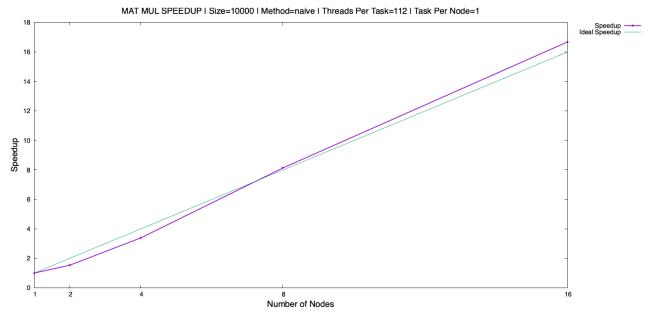
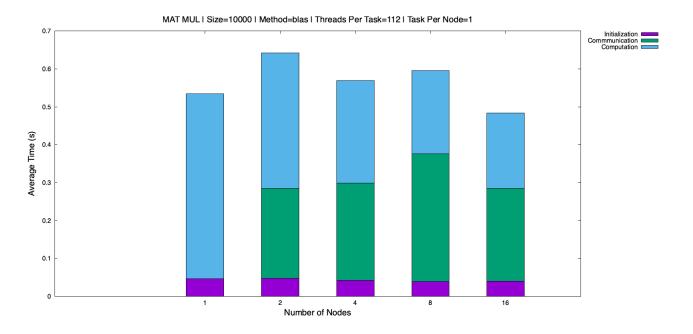
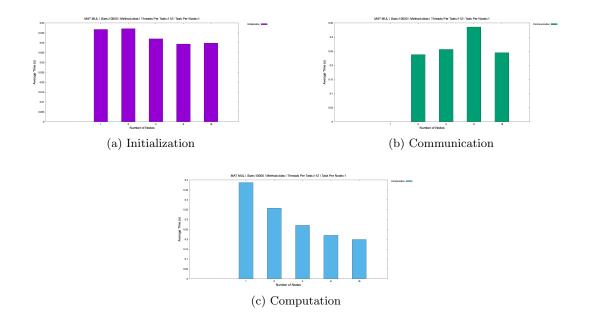


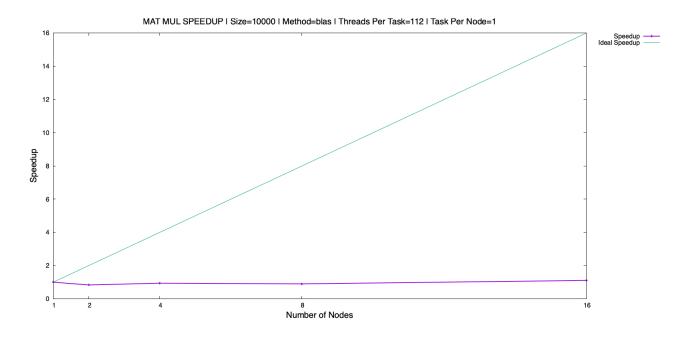
Figure 3: Speedup

# 5 BLAS Parallel Matrix Multiplication

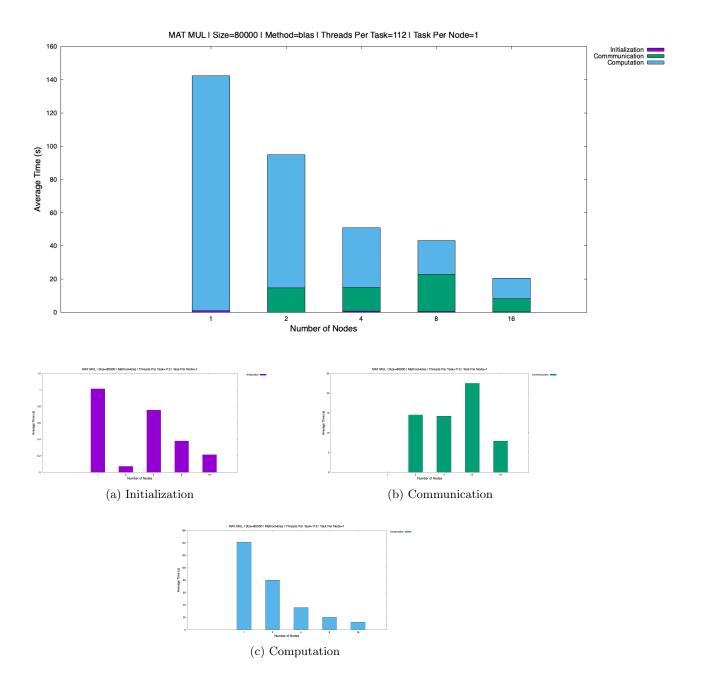
## 5.1 Results - Size: $10000 \times 10000$

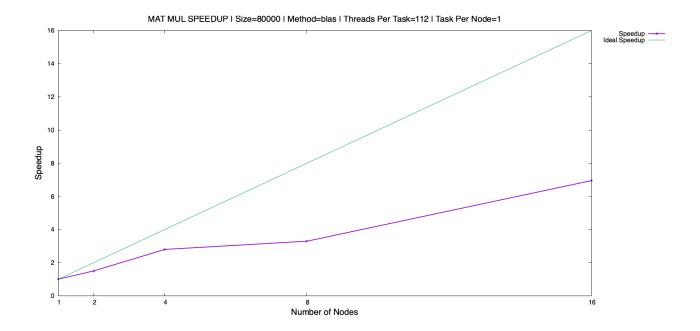






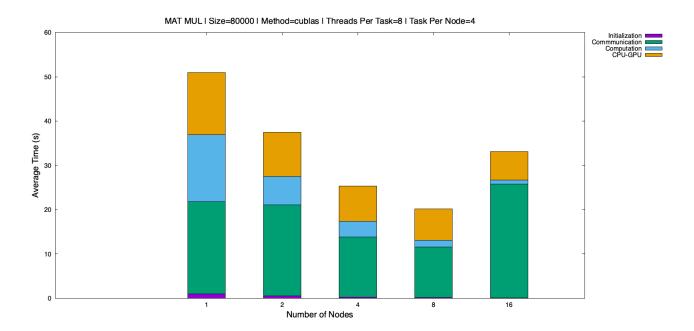
# **5.2** Results - Size: $80000 \times 80000$

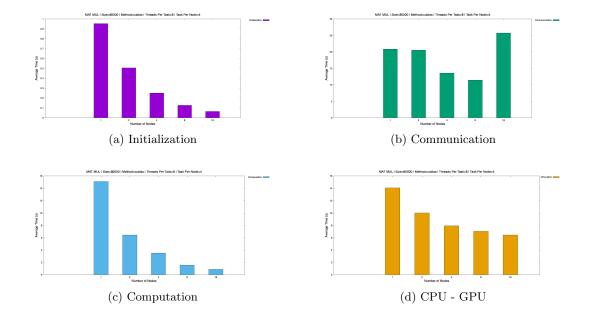


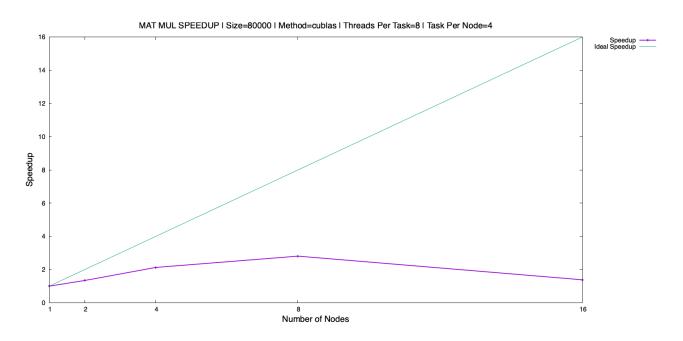


# 6 CUBLAS Parallel Matrix Multiplication

# **6.1** Results - Size: $80000 \times 80000$







# 7 Comparing Results

Table 1: MatMul BLAS vs CUBLAS - Size:  $10000 \times 10000$ 

Number of Nodes	1	2	4	8	16	
Initialization Time (s)						
blas	0.046762	0.047169	0.042010	0.039395	0.039865	
naive	0.055397	0.051650	0.047349	0.034085	0.053422	
Communication Time (s)						
blas	0.000000	0.237954	0.256770	0.336044	0.244944	
naive	0.000000	0.236362	0.274776	0.364067	0.135636	
Computation Time (s)						
blas	0.487370	0.357325	0.270883	0.220210	0.198997	
naive	50.084395	32.435776	14.475794	5.762652	2.816488	
Total Time (s)						
blas	0.534132	0.642448	0.569663	0.595649	0.483806	
naive	50.139792	32.723788	14.797919	6.160804	3.005546	

Table 2: MatMul BLAS vs CUBLAS - Size:  $80000 \times 80000$ 

Number of Nodes	1	2	4	8	16		
	Initialization Time (s)						
blas	1.013511	0.072719	0.755066	0.380928	0.212851		
cublas	0.953505	0.505618	0.250112	0.126880	0.064923		
	Communication Time (s)						
blas	0.000000	14.526843	14.203894	22.508671	7.906259		
cublas	20.862211	20.564119	13.570731	11.461551	25.754809		
Computation Time (s)							
blas	141.395141	80.197248	35.916465	20.336584	12.376804		
cublas	15.122763	6.443149	3.532343	1.565885	0.894362		
	CPU-GPU Time (s)						
cublas	14.070837	10.008605	7.946371	7.042651	6.451190		
Total Time (s)							
blas	142.408652	94.796810	50.875425	43.226183	20.495914		
cublas	51.009316	37.521491	25.299557	20.196967	33.165284		

## Part II

# Parallel Jacobi Iteration

## 8 CPU Two-Side MPI Jacobi Iteration

In this section we explain the algorithm to perform in parallel the Jacobi Iteration Method on a 2D grid using classical MPI non-blocking communications. We start by two matrix MAT and MAT2 of size  $N \times N$ . Each process allocates its own portion of these two matrix  $MAT_{LOC}$  and  $MAT_{LOC}$ . Moreover, each internal process allocates two rows more (the ghost regions which will be sended), while the first and the last process allocate only one row (this because the first row and last row of the total matrix will not be shared). The schema of allocation is provided in Figure 7.

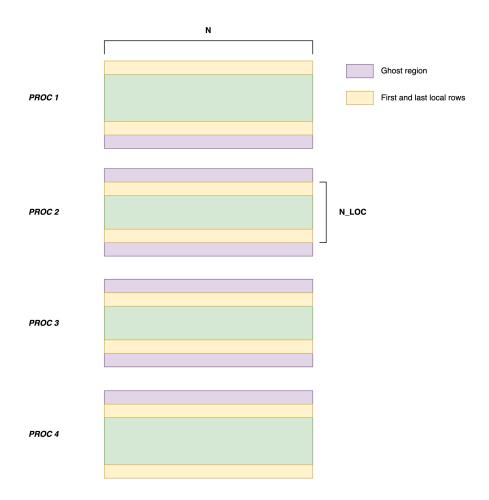


Figure 7: Jacobi Matrix Allocation for each process.

Next, each of 2 matrices is initialized (except for the ghost regions) in the following way:

- Top row and most right column of the matrix with all zeros
- Internal matrix values equal to 0.5

• Bottom row the most left column with a linear gradient from 0 to 100 An example of initialization is shown in Figure 8.

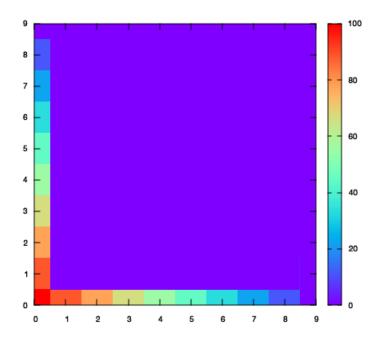


Figure 8: Initialization of a 10x10 matrix for the Jacobi Iteration.

After the initialization, each process starts the loop for the jacobi iteration. This last procedure is described in the Algorithm 3 and the communication pattern is shown in Figure 9. The first and last process do not send their first and last row.

## Algorithm 3 Parallel Jacobi Iteration (Two Side Communication)

```
1: for k \leftarrow 0 to num\_iter do
      ghost\_up \leftarrow MAT_{LOC} ghost up region
2:
      ghost\_down \leftarrow MAT_{LOC} ghost down region
3:
      first\_row \leftarrow MAT_{LOC} first row
4:
      last\_row \leftarrow MAT_{LOC} last row
5:
      if proc \neq 0 then
6:
         Isend(send:first\_row, to:proc - 1)
7:
         IRecv(receive\ in:ghost\_up,\ from:proc-1)
8:
      end if
9:
10:
      if proc \neq nprocs - 1 then
         Isend(send:last\_row, to:proc + 1)
11:
         Irecv(receive\ in: ghost\_down,\ from: proc + 1)
12:
      end if
13:
      MPI_Wait()
14:
15:
      MAT2_{LOC} \leftarrow JacobiUpdate(MAT_{LOC})
      swap MAT_{LOC} and MAT2_{LOC} pointers
16:
17: end for
```

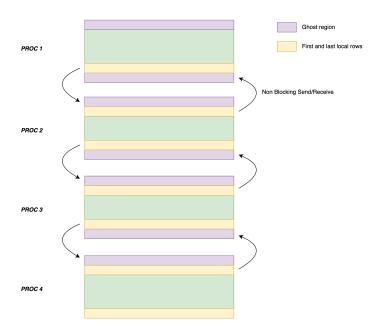


Figure 9: Parallel Jacobi Iteration Communication Pattern (Send/Receive).

When the loop finish, we save the matrix as a binary file in parallel using MPI I/O. An example plot of the final matrix is shown in Figure 10.

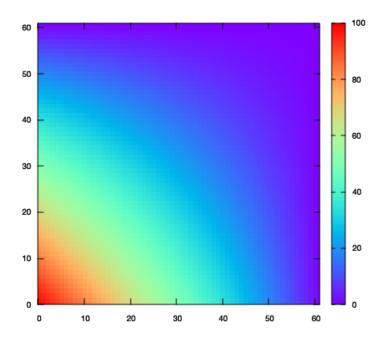
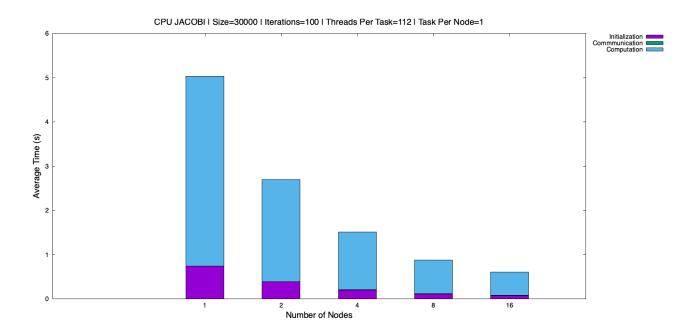
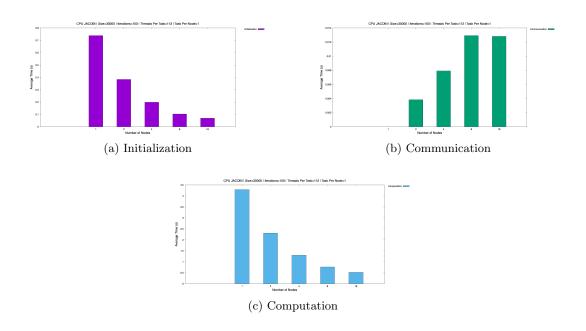
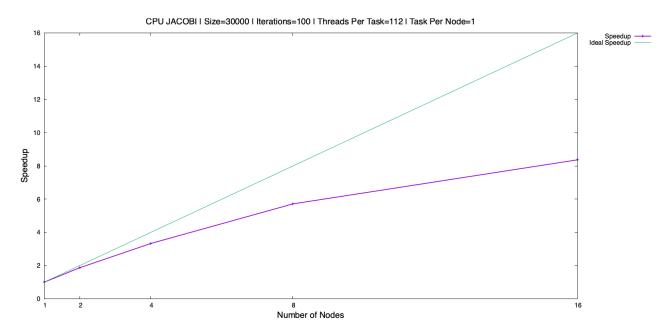


Figure 10: Final 60x60 matrix after 2000 Jacobi iterations.

# 8.1 Results - Size: $30000 \times 30000$ , Iterations: 100







# 9 GPU Two-Side MPI (Cuda Aware) Jacobi Iteration with OpenACC

This implementation is equivalent to the previous one but this time we perform initialization, communication and computation all on GPUs using OpenACC and Cuda Aware MPI.

In particular, we call at the beginning of our code the directive #pragma acc enter data create to allocate  $MAT_{LOC}$  and  $MAT_{LOC}$  directly on GPU for each process. Then we perform all the initializations on GPU using #pragma acc parallel loop  $present(MAT_{LOC}, MAT_{LOC})$ . For the communication, we wrap the MPI ISend/IRecv calls in the scope of the #pragma acc  $host\_data$   $use\_device(MAT_{LOC}, MAT_{LOC})$ , which enables us to expose the device pointers

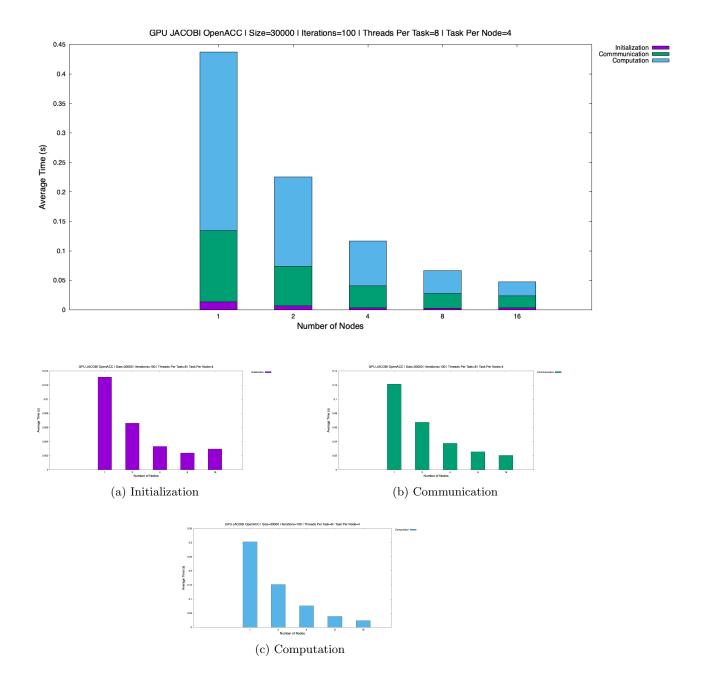
to the host and perform the MPI calls directly with them.

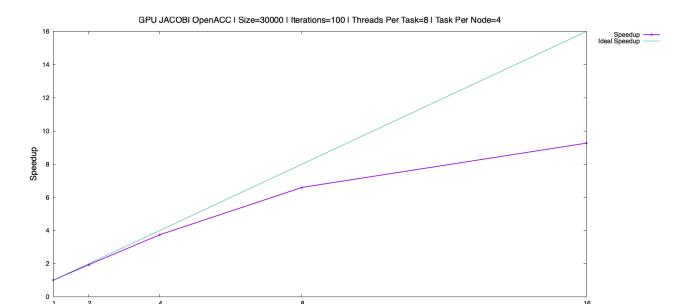
Then, the computation part is performed using again the #pragma acc parallel loop  $present(MAT_{LOC}, MAT_{LOC})$  directive with the addition of the #pragma acc loop independent directive to improve the performance.

Finally, the I/O part is performed directly by the GPUs again using  $\#pragma~acc~host\_data~use\_device(MAT2_{LOC}).$ 

At the end we close the unstructured data region calling #pragma~acc~exit~data~delete directive on  $MAT_{LOC}$  and  $MAT_{LOC}$ 

#### 9.1 Results - Size $30000 \times 30000$ , Iterations: 100





## 10 CPU One Side MPI Jacobi Iteration

In this section we explain the algorithm to perform in parallel the Jacobi Iteration Method on a 2D grid using One ide MPI communications.

Number of Nodes

There are two sub-implementations: the first use the  $MPI_{-}Put$  function while the second the  $MPI_{-}Get$ . We start again with two matrix MAT and MAT2 and using the same allocation and initialization of the Two-side version.

Then, we calculate the pointers for the first local row, last local row and the two ghost region for each of the 2 matrices.

Next, we define and create the two memory windows that will be shared. In the case of  $MPI_Put$  version the windows points to the ghost regions for each of the two matrices Instead, with the  $MPI_-Get$  routine, the windows will point to the first and to the last row of each matrices. So, in general, we have 2 windows per matrix.

Moreover, we optimize the windows creation by setting the related MPI\_Info with the following attributes equal to true:

- same\_size: suggests to the compiler that size is identical on all processes
- same\_disp\_unit: suggest to the compiler that the unit displacement is identical on all processes

Finally, we start with the Jacobi iteration loop in which each process uses the chosen routine. We illustrate the two versions in the Algorithms 4 and 5. Both will be syncronized using the MPI\_Win\_lock MPI\_Win\_unlock calls and placing an MPI Barrier after. Moreover, we use the lock calls with two argument:

- MPI\_LOCK\_EXCLUSIVE: ensure that no other process can access the window concurrently.
- MPI\_MODE\_NOCHECK: optimization that skips the lock checking mechanism to save time.

At each iteration we swap the pointers of the matrices and change the windows used for communication: in this way we can create only two windows at the beginning and not at each iteration. The working of this method is illustrated in the Figure 13.

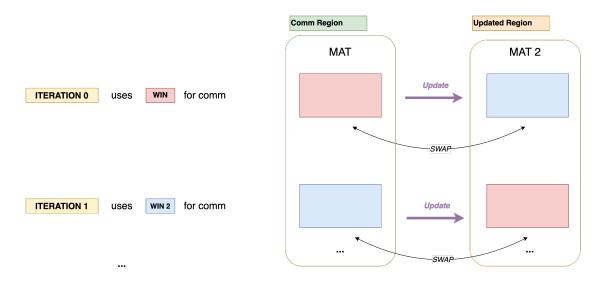


Figure 13: Iterations of the One side Jacobi Algorithm

#### Algorithm 4 Parallel Jacobi Iteration (One Side PUT Communication)

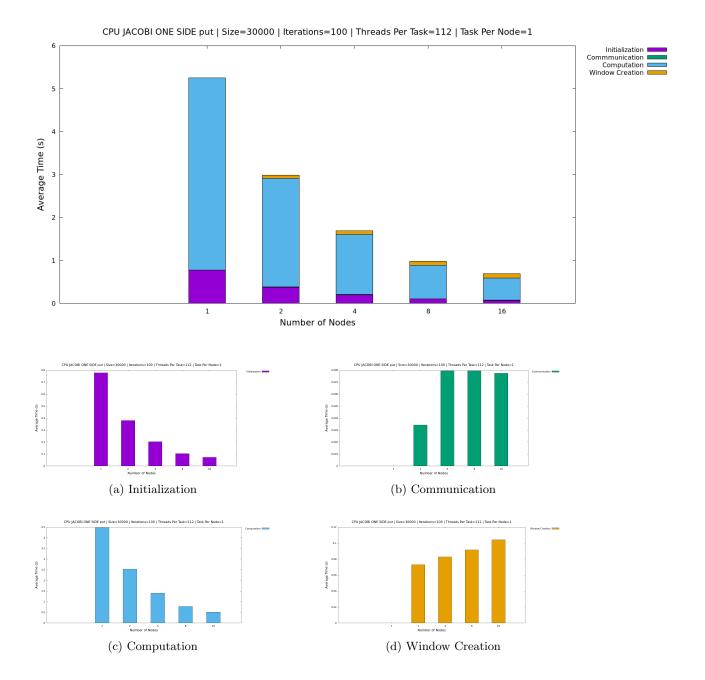
```
1: ghost\_up\_win \leftarrow MAT_{LOC} ghost up region window
2: ghost\_down\_win \leftarrow MAT_{LOC} ghost down region window
3: ghost\_up\_win\_2 \leftarrow MAT2_{LOC} ghost up region window
4: ghost\_down\_win\_2 \leftarrow MAT2_{LOC} ghost down region window
5: for k \leftarrow 0 to num\_iter do
      if k\%2 = 0 then
6:
        if proc \neq 0 then
7:
8:
           WinLock(ghost\_down\_win)
           PUT(send: first\_row, to: proc - 1, in:ghost\_down\_win)
9:
           WinUnlock(ghost\_down\_win)
10:
        end if
11:
        if proc \neq nprocs - 1 then
12:
           WinLock(ghost\_up\_win)
13:
           PUT(send:last\_row, to:proc + 1, in:ghost\_up\_win)
14:
           WinUnlock(ghost\_up\_win)
15:
        end if
16:
      else
17:
        Same as before but using MAT2\_LOC windows
18:
      end if
19:
      MPI_Barrier()
20:
21:
      MAT2_{LOC} \leftarrow JacobiUpdate(MAT_{LOC})
      swap MAT_{LOC} and MAT2_{LOC} pointers
22:
23: end for
```

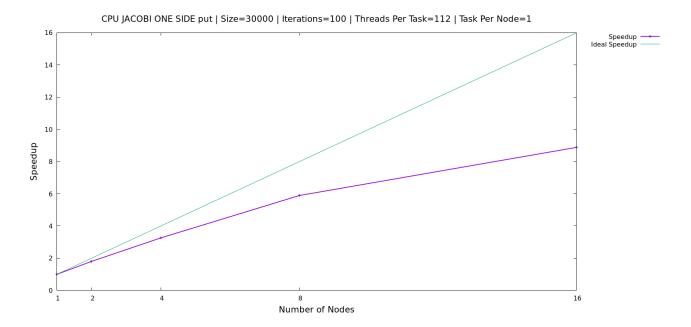
Again, When the loop finish we save the matrix as a binary file in parallel using MPI I/O.

#### Algorithm 5 Parallel Jacobi Iteration (One Side GET Communication)

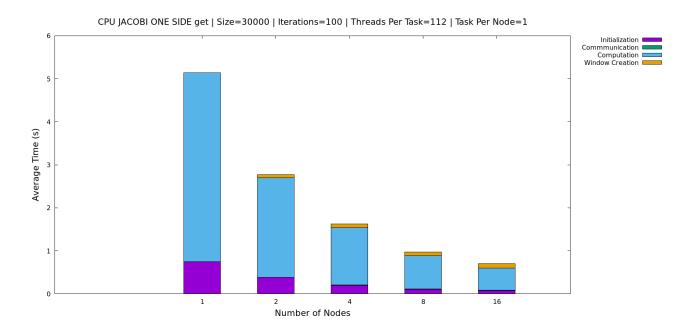
```
1: first\_row\_win \leftarrow MAT_{LOC} first row window
2: last\_row\_win \leftarrow MAT_{LOC} last row window
3: first\_row\_win\_2 \leftarrow MAT2_{LOC} first row window
4: last\_row\_win\_2 \leftarrow MAT2_{LOC} last row window
5: for k \leftarrow 0 to num\_iter do
      if k\%2 = 0 then
6:
        if proc \neq 0 then
7:
           WinLock(last\_row\_win)
8:
           GET(from: last\_row\_win, of: proc - 1, in: ghost\_up\_win)
9:
           WinUnlock(last\_row\_win)
10:
        end if
11:
        if proc \neq nprocs - 1 then
12:
13:
           WinLock(first\_row\_win)
           GET(from: first\_row\_win, of: proc + 1, in:ghost\_down\_win)
14:
           WinUnlock(first\_row\_win)
15:
        end if
16:
17:
      else
        Same as before but using MAT2\_LOC windows
18:
19:
      end if
      MPI_Barrier()
20:
      MAT2_{LOC} \leftarrow JacobiUpdate(MAT_{LOC})
      swap MAT_{LOC} and MAT2_{LOC} pointers
22:
23: end for
```

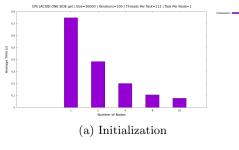
# 10.1 Results - PUT, Size $30000 \times 30000$ , Iterations: 100

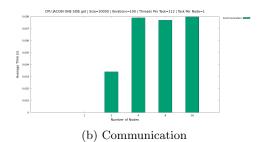


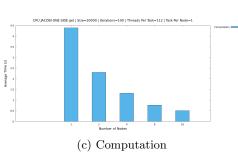


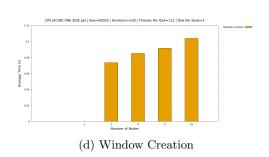
# 10.2 Results - GET, Size $30000 \times 30000$ , Iterations: 100

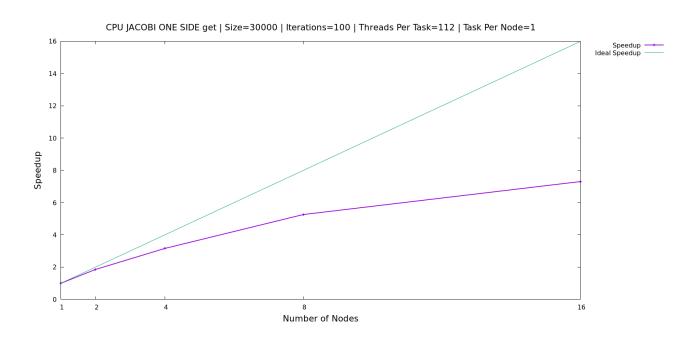












# 11 Comparing Results

Table 3: Jacobi Two-CPU vs Two-GPU vs Get-CPU vs Put-CPU - Size:  $80000\times80000$ 

Number of Nodes	1	2	4	8	16	
Initialization Time (s)						
two	0.741305	0.383529	0.199044	0.107419	0.063435	
acc	0.013149	0.006618	0.003316	0.002394	0.002959	
get	0.748542	0.383122	0.201019	0.106712	0.077819	
put	0.776928	0.380103	0.202724	0.103180	0.072892	
Communication Time (s)						
two	0.000006	0.003741	0.007838	0.007772	0.008648	
acc	0.121487	0.067450	0.037586	0.025486	0.020540	
get	0.000000	0.003393	0.007894	0.007697	0.007971	
put	0.000000	0.003429	0.007939	0.007931	0.007737	
Computation Time (s)						
two	4.244624	2.223538	1.213914	0.865562	0.439050	
acc	0.302801	0.151623	0.075955	0.038409	0.023701	
get	4.391596	2.309921	1.333212	0.770572	0.513563	
put	4.472803	2.530749	1.398870	0.779321	0.510175	
Windows Creation Time (s)						
get	0.000000	0.073715	0.085325	0.091813	0.104076	
put	0.000025	0.072929	0.082611	0.091378	0.104103	
Total Time (s)						
two	4.985935	2.610808	1.420796	0.980753	0.511133	
acc	0.437437	0.225691	0.116857	0.066289	0.047200	
get	5.140138	2.770151	1.627450	0.976794	0.703429	
put	5.249756	2.987210	1.692144	0.981810	0.694907	