

| Present state | Next state | | Output | |
|------------------|------------|-----|--------|-----|
| | x=0 | x=1 | x=0 | x=1 |
| a | b | b | 0 | 0 |
| b | d | c | 0 | 0 |
| c | f | e | 0 | 0 |
| d | g | a | 1 | 0 |
| e | d | c | 0 | 0 |
| f | f | b | 1 | 1 |
| g | g | b | 0 | 1 |
| h | g | a | 1 | 0 |

Present states d and h, b and e are equal.

| Present state | Next state | | Output | |
|------------------|------------|-----|--------|-----|
| | x=0 | x=1 | x=0 | x=1 |
| a | b | b | 0 | 0 |
| b | d | c | 0 | 0 |
| c | f | b | 0 | 0 |
| d | g | a | 1 | 0 |
| f | f | b | 1 | 1 |
| g | g | d | 0 | 1 |

Present states a and c are equal

| Present State | Next State | | Output | |
|------------------|------------|-----|--------|-----|
| | x=0 | x=1 | x=0 | x=1 |
| a | f | b | 0 | 0 |
| b | d | a | 0 | 0 |
| d | g | a | 1 | 0 |
| f | f | c | 1 | 1 |
| g | g | d | 0 | 1 |

converting to binary equivalents:

| Present State | Next State | | Output | |
|------------------|------------|-----|--------|-----|
| | x=0 | x=1 | x=0 | x=1 |
| 000 (a) | 011 | 001 | 0 | 0 |
| 001 (b) | 010 | 000 | 0 | 0 |
| 010 (d) | 100 | 000 | 1 | 0 |
| 011 (f) | 011 | 001 | 1 | 1 |
| 100 (g) | 100 | 010 | 0 | 1 |

states can be expressed with 3 variables.

| A | B | C | x | Q _A | Q _B | Q _C | J _A | J _B | J _C | K _A | K _B | K _C | Y |
|---|---|---|---|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|---|
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | X | X | X | 0 |
| 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | X | X | X | 0 |
| 0 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | X | X | X | 1 | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | X | X | X | 1 | 0 |
| 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | X | 0 | X | 1 | X | 1 |
| 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | X | 0 | X | 1 | X | 0 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | X | X | X | 0 | 0 | 1 |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | X | X | X | 1 | 0 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 0 | X | 0 | 0 | 0 | X | X | 0 |
| 1 | 0 | 0 | 1 | 0 | 1 | 0 | X | 1 | 0 | 1 | X | X | 1 |

JA

Cx

| | | | | | |
|----|---|----|----|----|----|
| | | | | | |
| | | | | | |
| | | 0 | 1 | 3 | 2 |
| | 1 | | | | |
| | 4 | 5 | 7 | 6 | |
| AB | | | | | |
| | | 12 | 13 | 15 | 14 |
| | X | X | | | |
| | 8 | 9 | 11 | 10 | |

$$J_A = \bar{A}B\bar{C}\bar{x}$$

Similarly:

$$J_B = \bar{A}\bar{x} + Ax$$

$$J_C = \bar{A}\bar{B}$$

$$K_A = \bar{B}\bar{C} + x$$

$$K_B = \bar{C} + x$$

$$K_C = \bar{A}\bar{B}$$

$$y = \bar{B}\bar{C} + B\bar{x} + BC + Ax$$

