

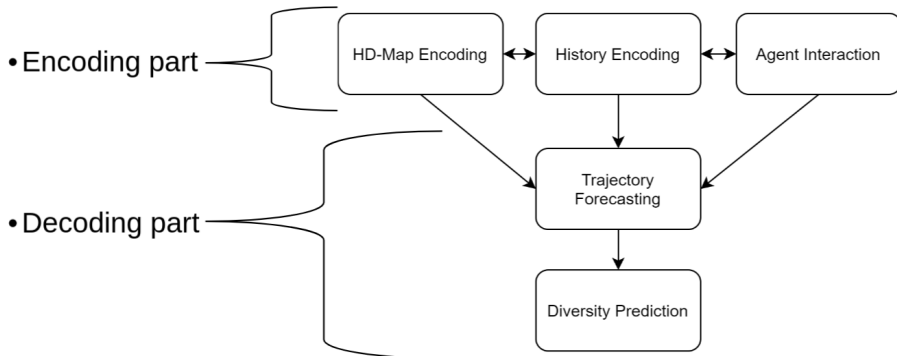
Trajectory Prediction

Чупахин Андрей Андреевич

МГУ им. М.В. Ломоносова, факультет ВМК, кафедра АСВК, аспирант



Pipeline for Trajectory Prediction



We evaluate two metrics for each scale:

- Average Displacement Error (ADE): The average L2 distance between the predicted trajectories and the ground truth
- Final Displacement Error (FDE): The average L2 distance between the endpoint of the predicted trajectories and the ground truth

Proposed solution

- Based on Convolutional neural network
- Augmentation: rotation, shifts
- 2D Convolution on neighbours
- Variation of train/test split

- Use Graph Convolutional Networks for trajectory prediction
 - AVGCN: Trajectory Prediction using Graph Convolutional Networks Guided by Human Attention // <https://arxiv.org/abs/2101.05682>
- Use end-to-end models
 - MP3: A Unified Model to Map, Perceive, Predict and Plan // <https://arxiv.org/pdf/2101.06806.pdf>