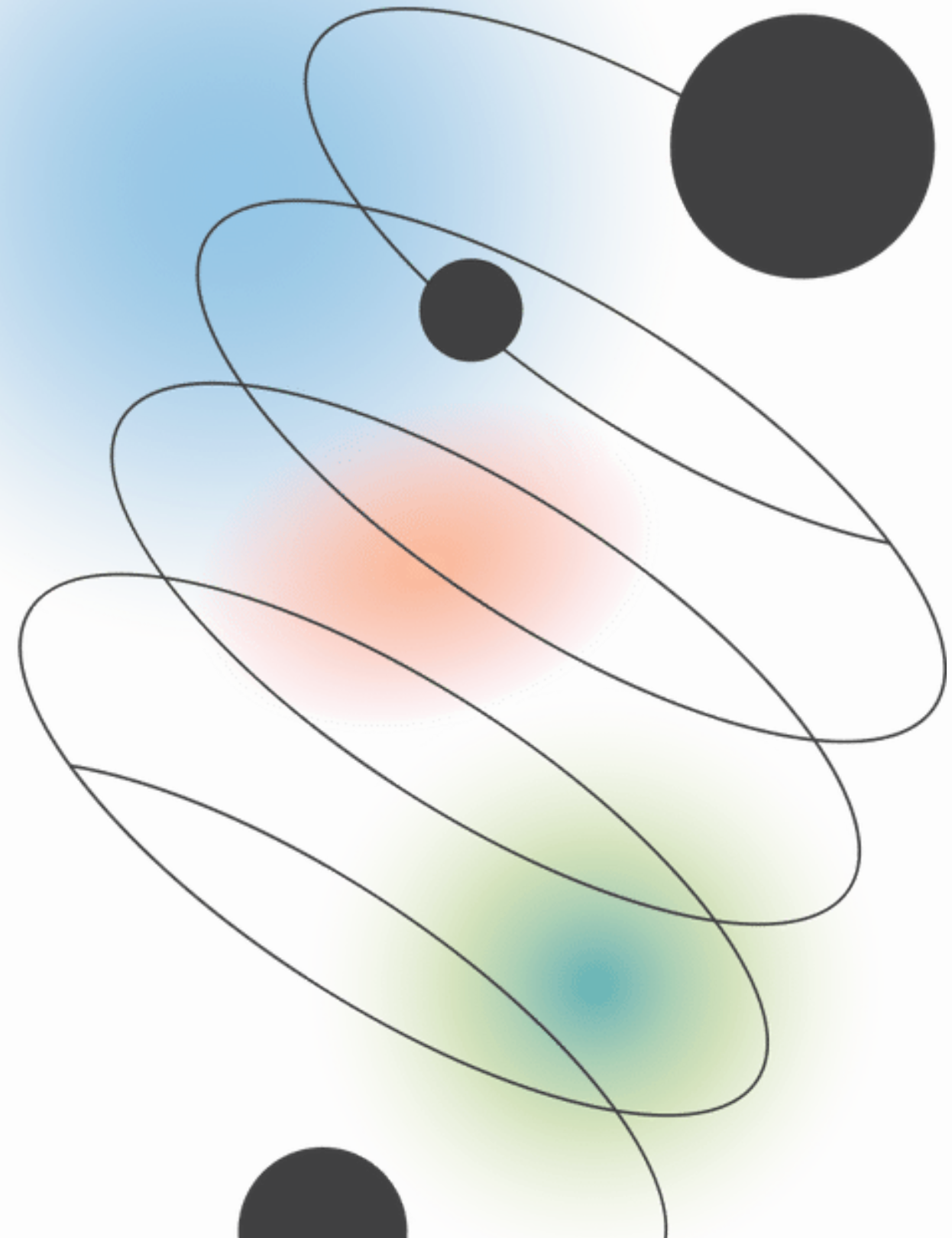


Augmentation comparison in Motion Prediction

By Khomutova Ksenia
SFU (Siberian Federal University)
Software Engineering, 3d year

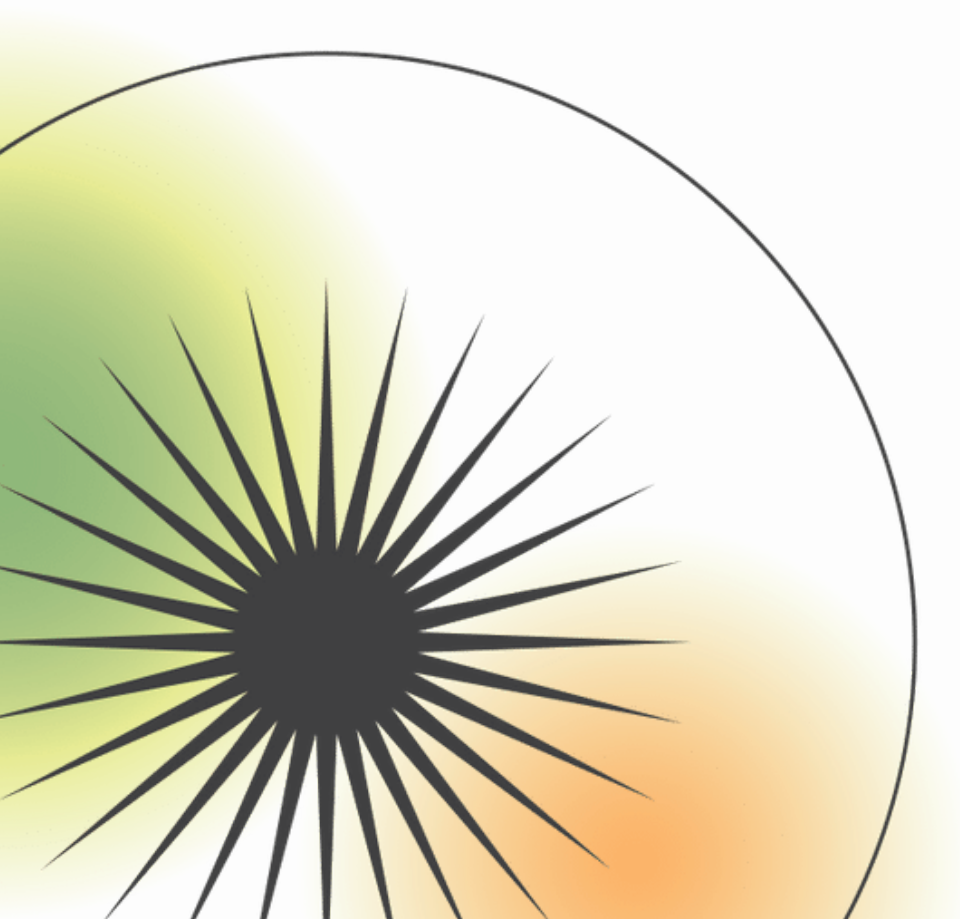


Problem







A small variety of trajectories in the input data.

Solution

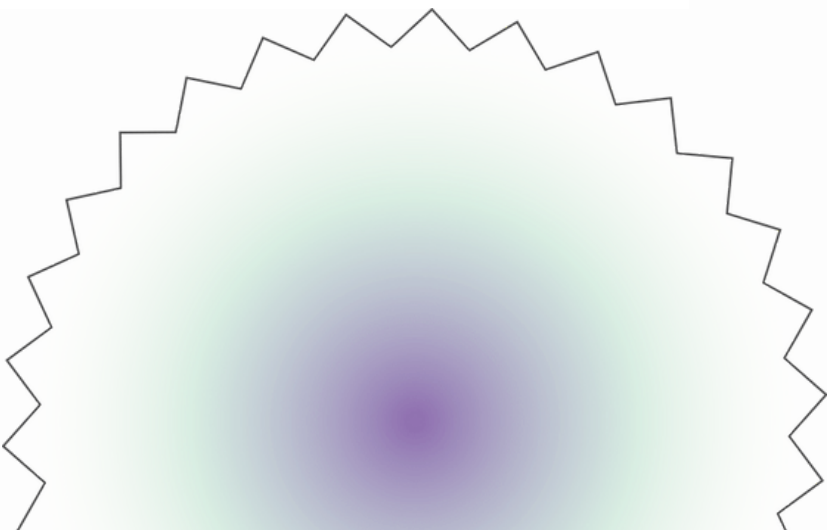
Artificial increase in the training sample by modifying the existing data.



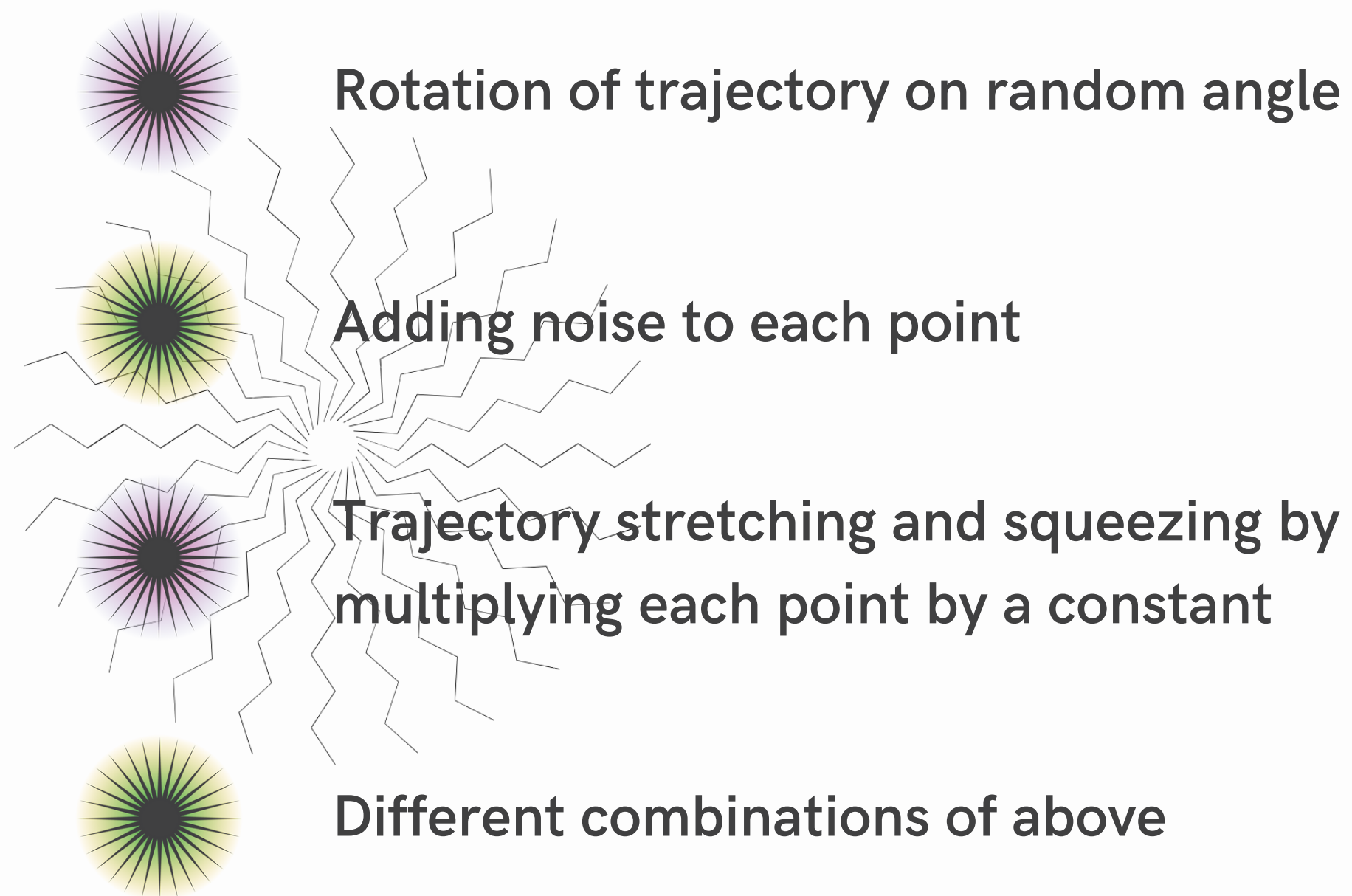
Results

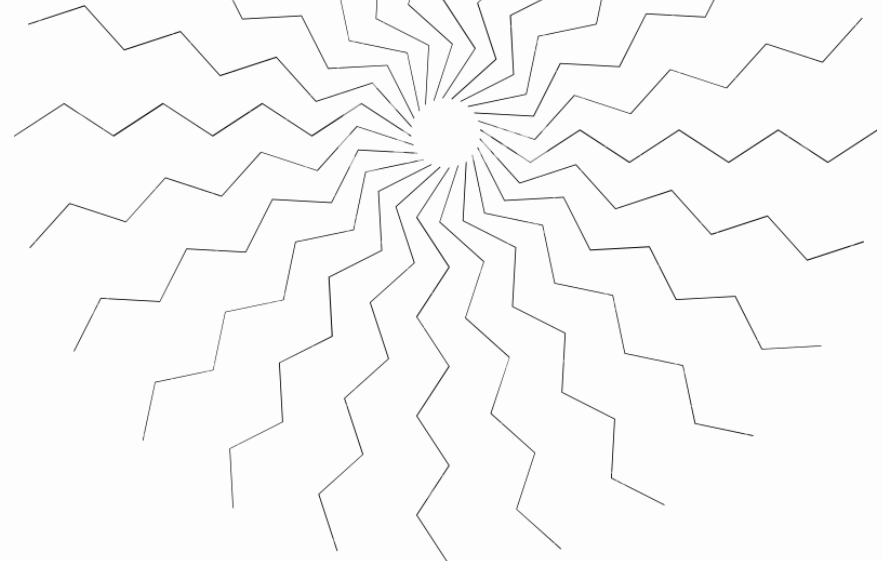
	Short ADE 	Short FDE 	Medium ADE 	Medium FDE 	Long ADE 	Long FDE 
My CNN submission	0.61	1.19	1.37	3.18	3.86	9.84
Baseline	0.72	1.50	1.69	3.93	4.60	11.38

<https://eval.ai/web/challenges/challenge-page/1194/overview>

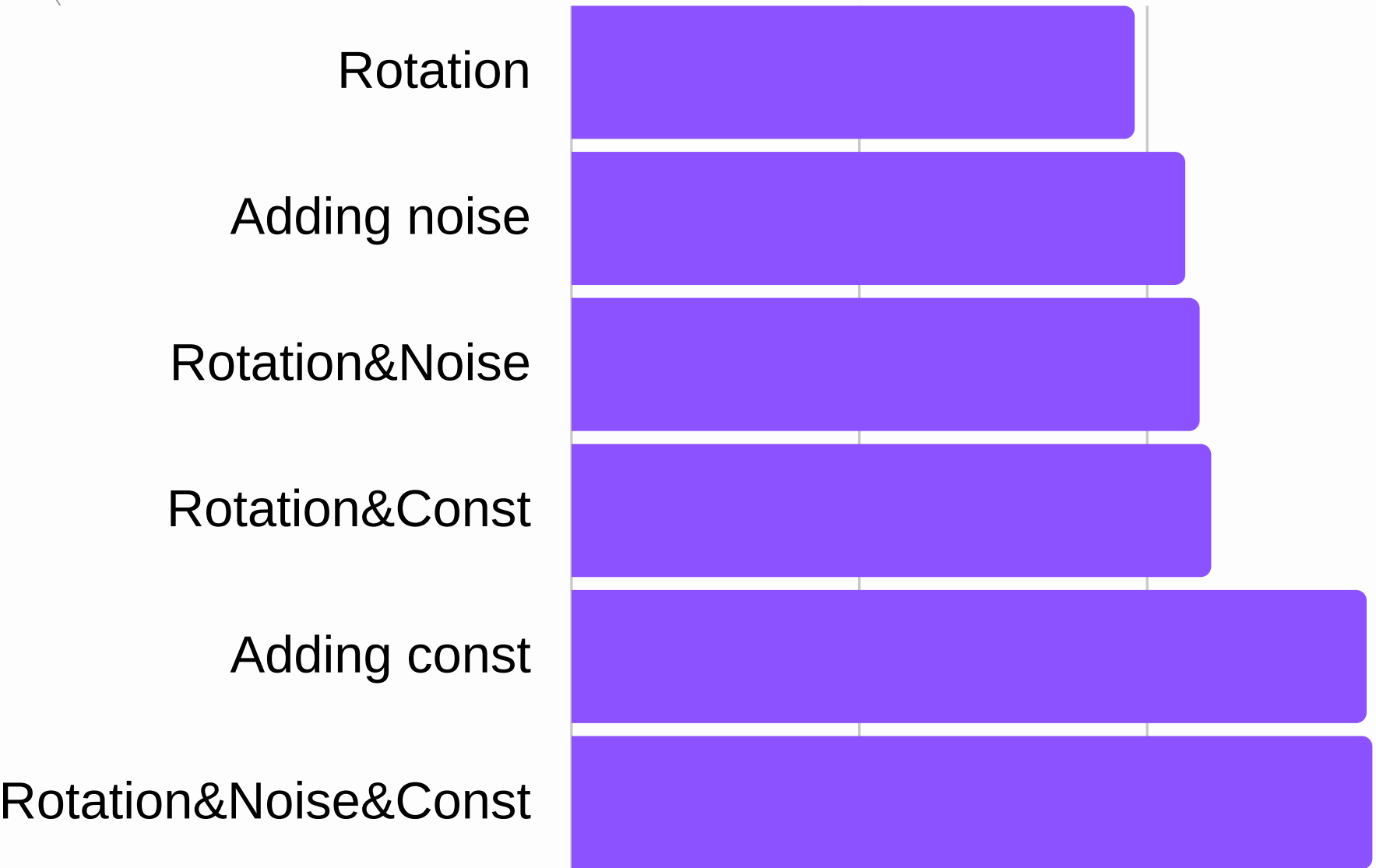


What was tried





Methods comparison



0

0,5

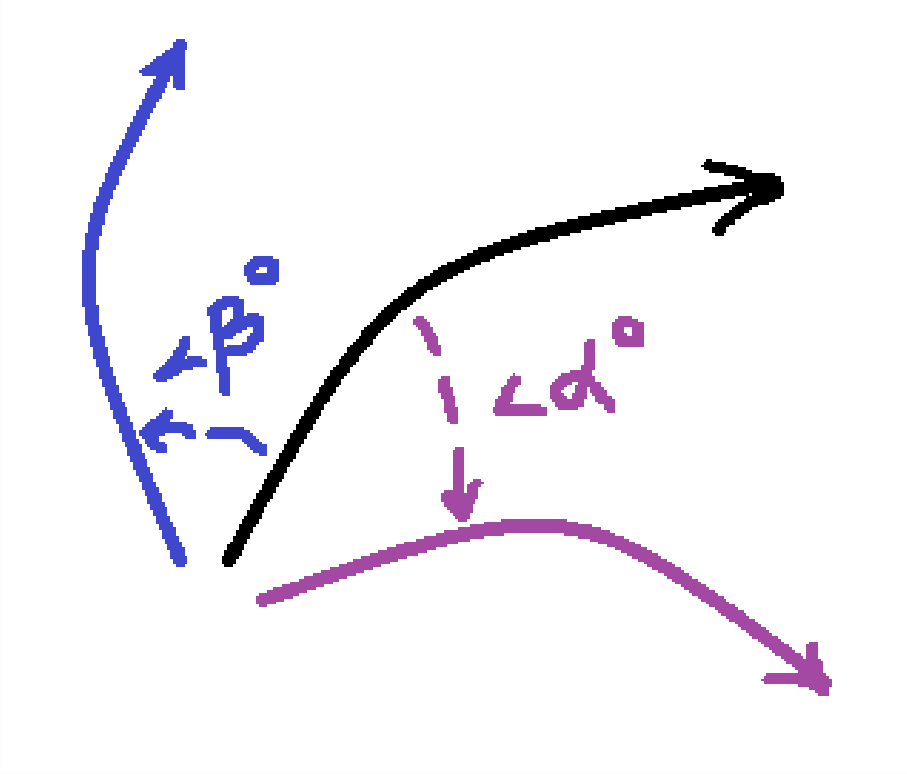
1

1,5

Medium ADE

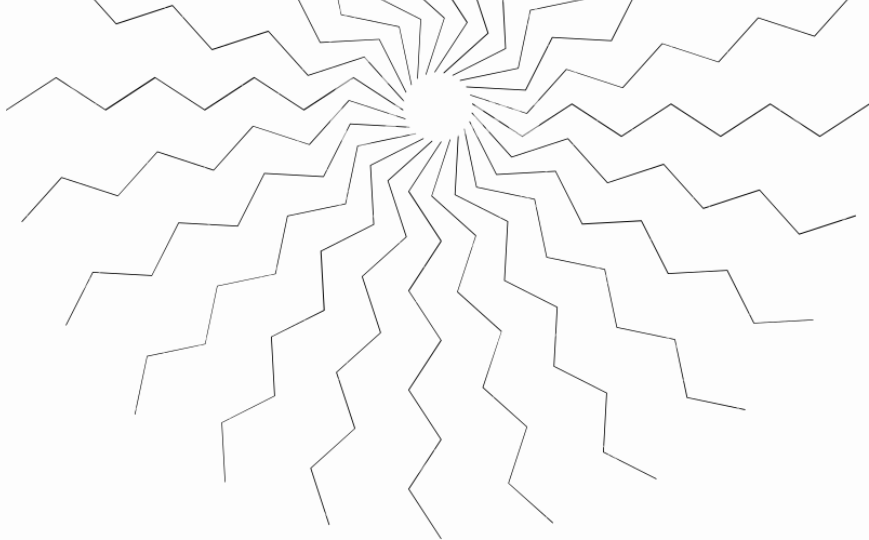
The smaller the ADE,
the better

A turn on a random angle
proved to be the best



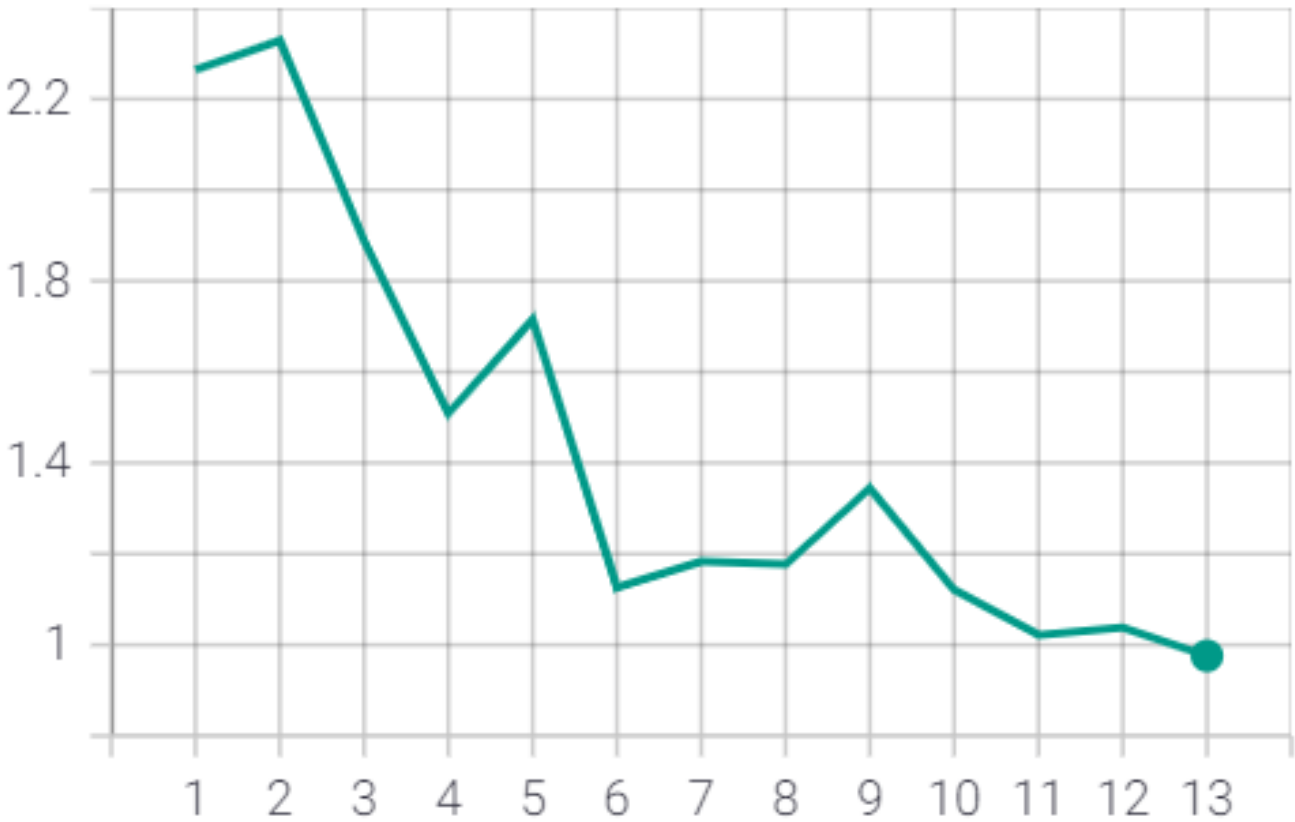
Best solution

Score on validation



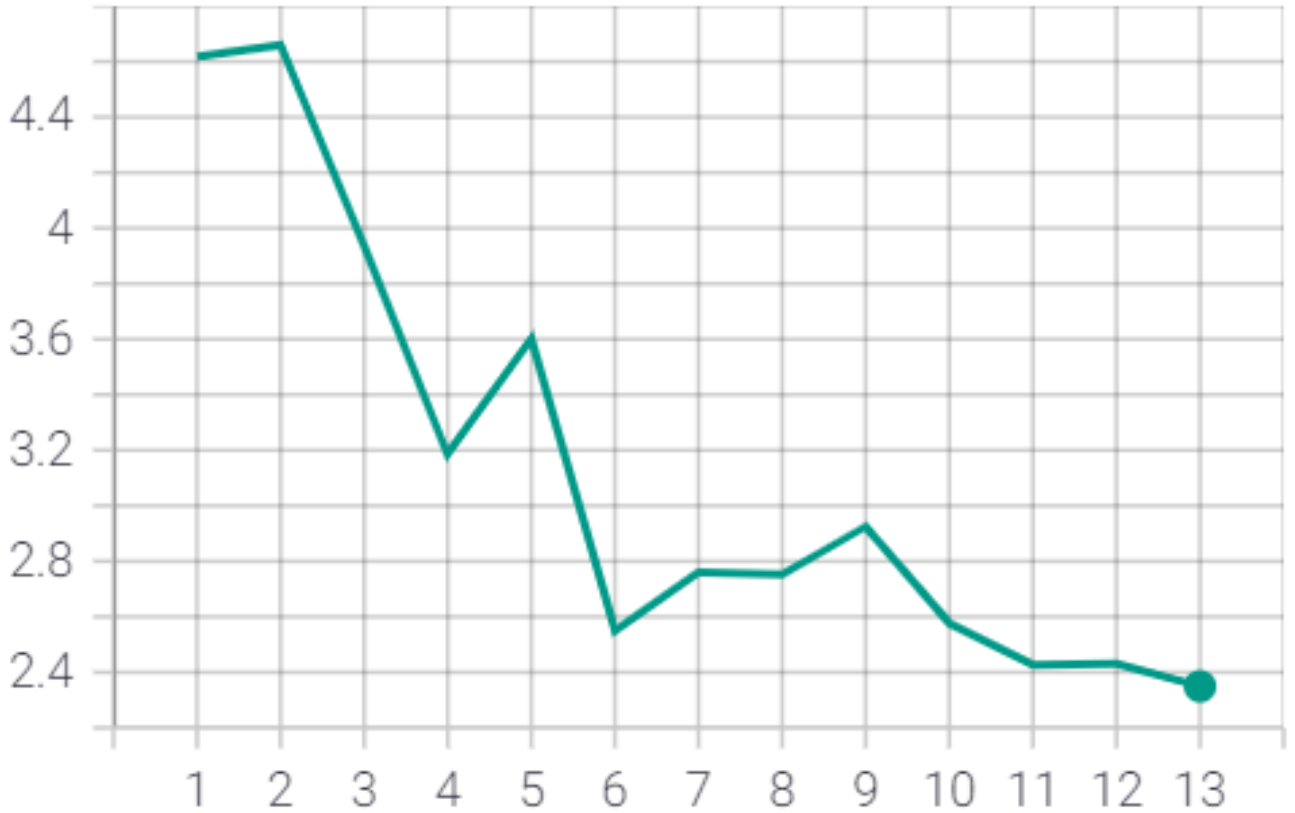
	Name	Smoothed	Value	Step
●	Trajectory rotation	0.9761	0.9761	13

Medium ADE



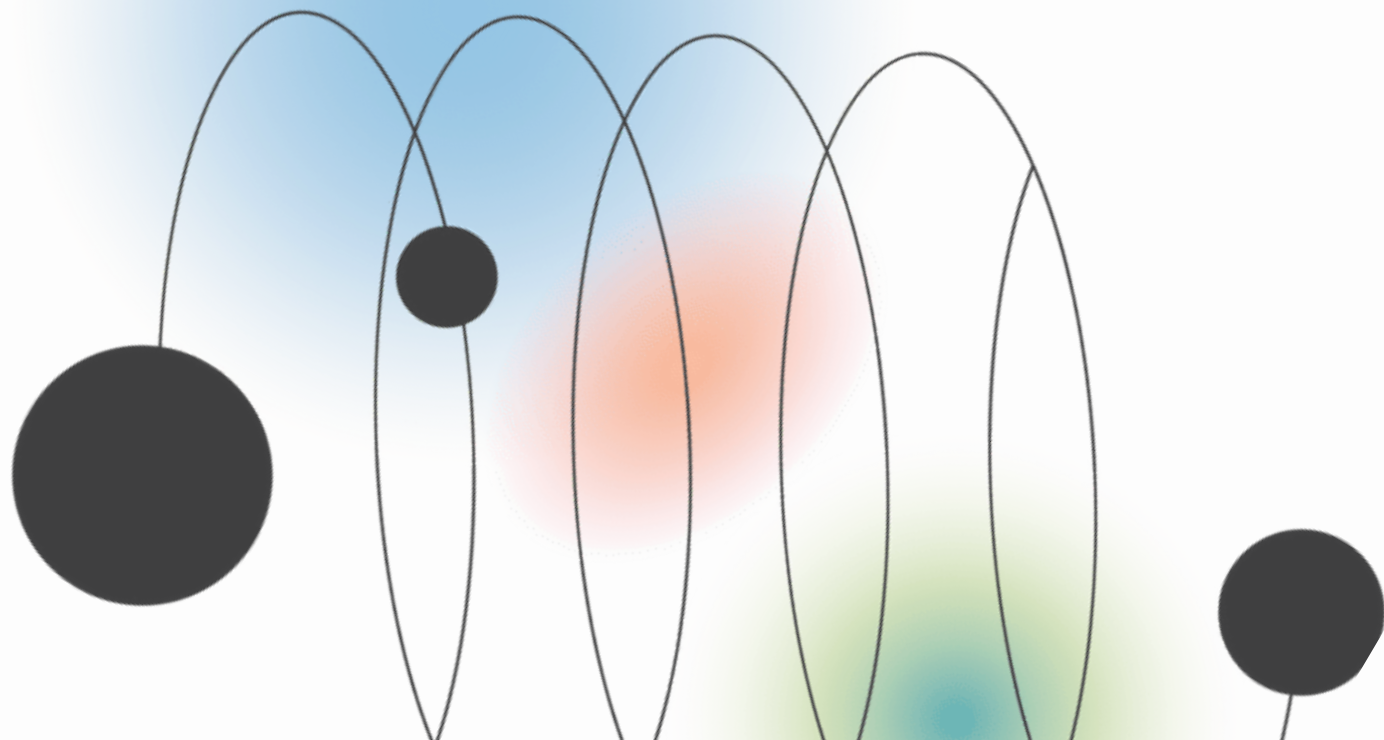
	Name	Smoothed	Value	Step
●	Trajectory rotation	2.349	2.349	13

Medium FDE



What's Next

- Study of special augmentation methods for trajectories
- Deep analysis of the dataset and the use of other techniques to improve the result
- Research of information on motion planning on top of motion prediction



**Thank you
for your attention!**

