Analýza robustnosti spojitých dynamických systémů v distribuovaném prostředí



Jan Papoušek

Dynamické systémy

soustava diferenciálních rovnic

$$\frac{\mathbf{y}}{dt} = f(\mathbf{y})$$

$$t \geq t_o, \mathbf{y}(t_o) = y_0$$



Chování dynamického systému

numerická simulace

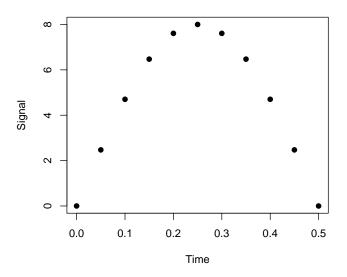
$$t_{n+1}=t_n+h$$

$$\mathbf{y}_n \sim \mathbf{y}(t_n)$$

(trejektorie chování, signál)

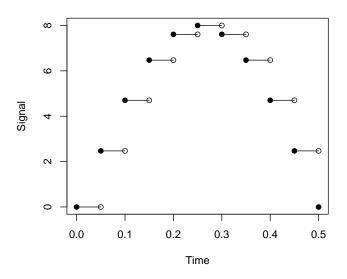


Chování dynamického systému





Chování dynamického systému





$$U = \{\mu_1, \mu_2, \dots, \mu_k\}$$

$$\mu_i : \mathbb{R}^n \to \{T, F\}$$



$$U = \{\mu_1, \mu_2, \dots, \mu_k\}$$

$$\mu_i : \mathbb{R}^n \to \{T, F\}$$

atomické propozice

$$P = \{1, \ldots, k\}$$



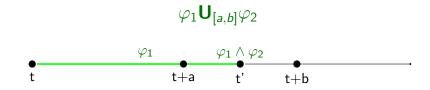
$$\varphi := T \mid p \mid \neg \varphi \mid \varphi_1 \wedge \varphi_2 \mid \varphi_1 \mathbf{U}_{[a,b]} \varphi_2$$



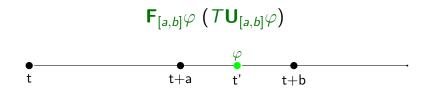
$$\varphi := T \mid p \mid \neg \varphi \mid \varphi_1 \land \varphi_2 \mid \varphi_1 \mathbf{U}_{[a,b]} \varphi_2$$

$$\begin{aligned} (\mathbf{y},t) &\models \rho &\iff \mu_{p}(\mathbf{y}(t)) = T \\ (\mathbf{y},t) &\models \neg \varphi &\iff (\mathbf{y},t) \not\models \varphi \\ (\mathbf{y},t) &\models \varphi_{1} \land \varphi_{2} &\iff (\mathbf{y},t) \models \varphi_{1} \text{ a současně } (\mathbf{y},t) \models \varphi_{2} \\ (\mathbf{y},t) &\models \varphi_{1} \mathbf{U}_{[a,b]} \varphi_{2} &\iff \exists t' \in [t+a,t+b].(\mathbf{y},t') \models \varphi_{2} \\ &\text{a současně } \forall t'' \in [t,t'].(\mathbf{y},t'') \models \varphi_{1} \end{aligned}$$

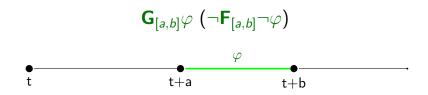














Parametry

$$\frac{dY_1}{dt} = \nu Y_1 - \alpha Y_1 \cdot Y_2 \qquad \frac{dY_2}{dt} = \alpha Y_1 \cdot Y_2 - \mu Y_2$$

proměnné (Y_1, Y_2) – počáteční hodnoty **koeficienty** (μ, ν, α)



Cíl analýzy



Lokální robustnost

$$U' = \{\mu'_1, \mu'_2, \dots, \mu'_k\}$$

$$\mu'_i : \mathbb{R}^n \to \mathbb{R}$$



Jan Papoušek Parasim 12

Lokální robustnost

$$U' = \{\mu'_1, \mu'_2, \dots, \mu'_k\}$$

$$\mu'_i : \mathbb{R}^n \to \mathbb{R}$$

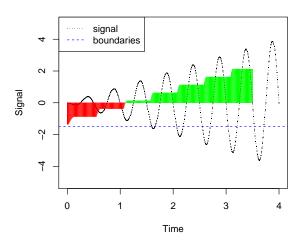
$$\begin{split} &\rho(p,\mathbf{y},t) &= \mu_p'(\mathbf{y}(t)) \\ &\rho(\neg\varphi,\mathbf{y},t) &= -\rho(\varphi,\mathbf{y},t) \\ &\rho(\varphi_1 \land \varphi_2,\mathbf{y},t) &= \min\left(\rho(\varphi_1,\mathbf{y},t),\rho(\varphi_1,\mathbf{y},t)\right) \\ &\rho(\varphi_1 \mathbf{U}_{[a,b]}\varphi_2,\mathbf{y},t) &= \max_{t' \in [t+a,t+b]} \min\left(\rho(\varphi_2,\mathbf{y},t'), \min_{t'' \in [t,t']} \rho(\varphi_1,\mathbf{y},t'')\right) \end{split}$$

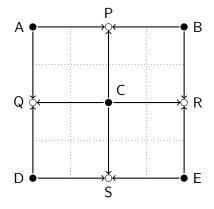


Jan Papoušek Parasim

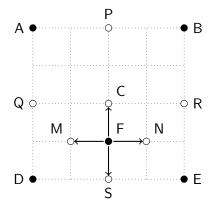
Lokální robustnost

$$\mathbf{F}_{[0,\frac{1}{2}]}x \le -k$$

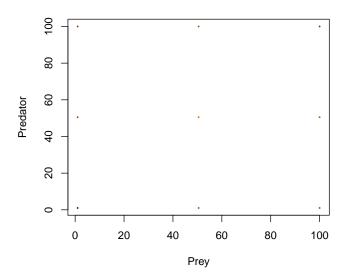




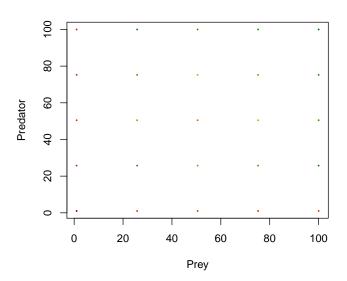




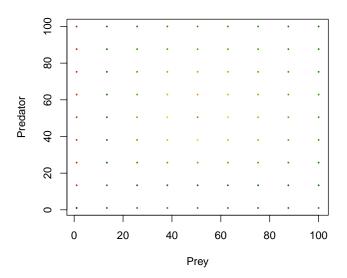




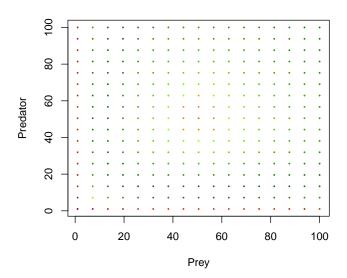




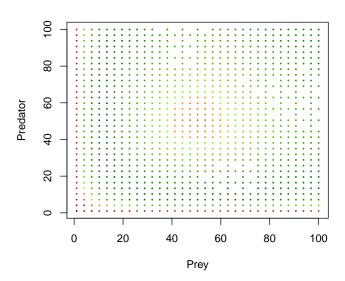




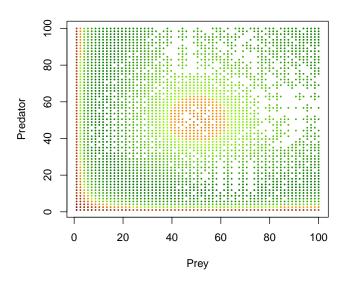




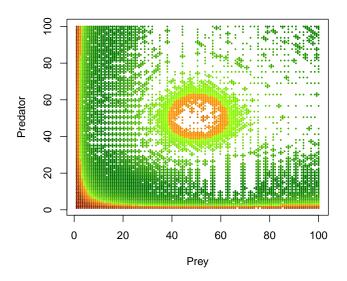














Implementace



Systém rozšíření



Výpočetní model



Měření

