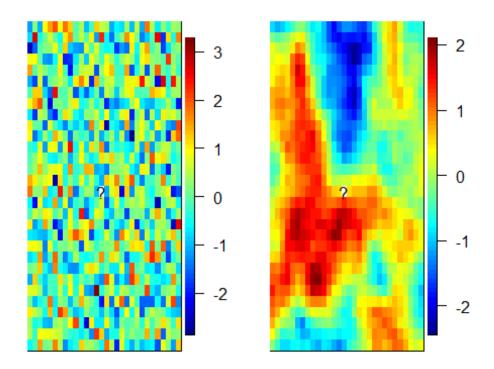
# **Spatial Statistics 1**

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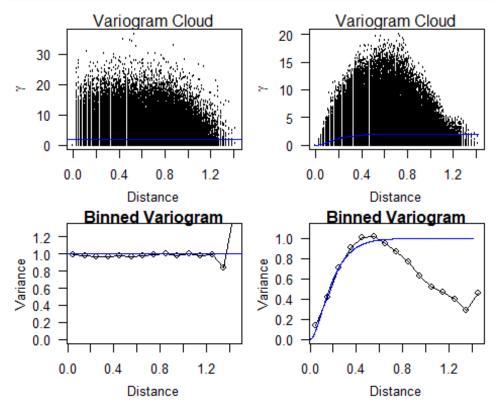
## **Toy Examples**

```
N = 30
xg \leftarrow yg \leftarrow seq(0, 1, length = N)
locs <- expand.grid(xg, yg)</pre>
par(mfrow = c(1, 2), mar = c(2, 2, 1, 0.6),
    mgp = c(2.4, 1, 0), las = 1)
## Case 1: No Spatial Pattern
set.seed(123)
y1 \leftarrow array(rnorm(n = N^2), dim = c(N, N))
y1[N / 2, N / 2] <- NA
which(is.na(y1) == 1)
## [1] 435
library(fields)
image.plot(xg, yg, y1, xlab = "", ylab = "", xaxt = "n", yaxt = "n")
text(xg[N / 2], yg[N / 2], "?")
## Case 2: A Smooth Spatial Image
library(MASS)
cov.Matern <- function(h, pars) Matern(h, phi = pars[1], range = pars[2],</pre>
smoothness = pars[3])
dist <- rdist(locs)</pre>
Sigma_Matern <- cov.Matern(dist, c(1, 0.1, 1.5))
set.seed(123)
y2 \leftarrow array(mvrnorm(n = 1, rep(0, N^2), Sigma Matern), dim = c(N, N))
y2[N / 2, N / 2] <- NA
which(is.na(y2) == 1)
## [1] 435
image.plot(xg, yg, y2, xlab = "", ylab = "", xaxt = "n", yaxt = "n")
text(xg[N / 2], yg[N / 2], "?")
```



# Using Variogram Cloud and (Binned) Variogram to Examine the Spatial Dependency

```
gamma1 <- array(dim = c(N^2, N^2))
system.time(for (i in 1:N^2) {
  for (j in 1:N^2) {
    gamma1[i, j] \leftarrow (c(y1)[i] - c(y1)[j])^2
 }
})
##
      user system elapsed
##
      3.82
              1.94
                      5.80
system.time(gamma1 <- outer(c(y1), c(y1), FUN = "-")^2)
##
      user system elapsed
##
      0.02
              0.00
                      0.01
gamma2 \leftarrow outer(c(y2), c(y2), FUN = "-")^2
par(mfrow = c(2, 2), mar = c(3.6, 3.6, 1, 0.6),
    mgp = c(2.4, 1, 0), las = 1)
plot(dist, gamma1, cex = 0.2, xlab = "Distance", ylab = expression(gamma))
abline(h = 2 * 1, col = "blue")
mtext("Variogram Cloud")
plot(dist, gamma2, cex = 0.2, xlab = "Distance", ylab = expression(gamma))
```



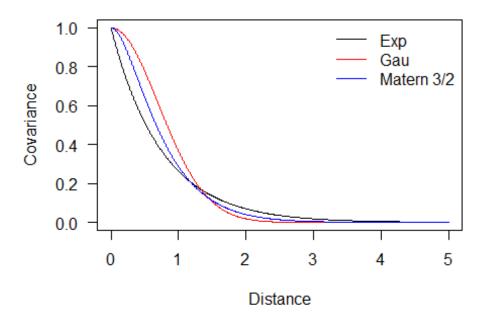
#### **Covariance Functions and Their Realizations**

```
# Commonly Used Covariance Functions
cov.exp <- function(h, pars) pars[1] * exp(-h / pars[2])
cov.doubleExp <- function(h, pars) pars[1] * exp(-(h / pars[2])^2)

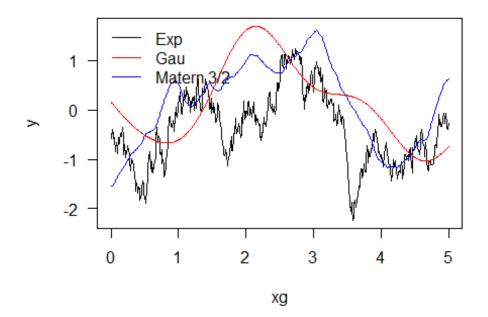
xg <- seq(0, 5, 0.01)
c_exp <- cov.exp(xg, c(1, 0.75))
c_doubleExp <- cov.doubleExp(xg, c(1, 1))
c_Matern <- cov.Matern(xg, c(1, 0.4, 1.5))

plot(xg, c_exp, type = "l", ylab = "Covariance", xlab = "Distance", las = 1)
lines(xg, c_doubleExp, col = "red")
lines(xg, c_Matern, col = "blue")</pre>
```

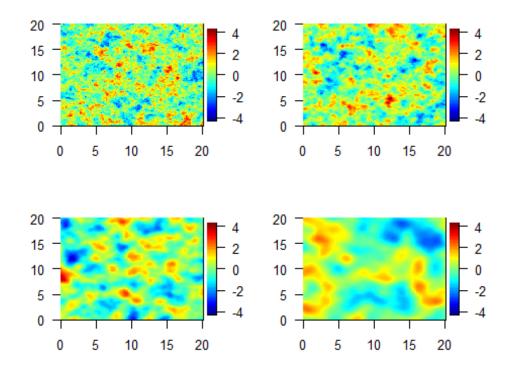
```
legend("topright", legend = c("Exp", "Gau", "Matern 3/2"),
        col = c("black", "red", "blue"), lty = 1, bty = "n")
```



```
Sigma_exp \leftarrow cov.exp(rdist(xg), c(1, 0.75))
Sigma_doubleExp <- cov.doubleExp(rdist(xg), c(1, 1))</pre>
Sigma Matern <- cov.Matern(rdist(xg), c(1, 0.4, 1.5))
library(MASS)
set.seed(123)
sim_exp_1d \leftarrow mvrnorm(n = 1, rep(0, 501), Sigma_exp)
set.seed(123)
sim_doubleExp_1d <- mvrnorm(n = 1, rep(0, 501), Sigma_doubleExp)</pre>
set.seed(123)
sim_Matern_1d <- mvrnorm(n = 1, rep(0, 501), Sigma_Matern)</pre>
plot(xg, sim_exp_1d, type = "l", ylim = range(sim_exp_1d, sim_doubleExp_1d,
                                                 sim_Matern_1d),
     ylab = "y", las = 1)
lines(xg, sim doubleExp 1d, col = "red")
lines(xg, sim_Matern_1d, col = "blue")
legend("topleft", legend = c("Exp", "Gau", "Matern 3/2"),
       col = c("black", "red", "blue"), lty = 1, bty = "n")
```



### **Simulate 2D Realizations**



# **Spatial Interpolation**

Here we assume  $m(s) = 0 \quad \forall s \in \mathcal{S}$ 

# **Predicting One Location**

$$\hat{y}_0 = k^T \Sigma^{-1} \mathbf{y}$$
 
$$Var(\hat{y}_0) = \sigma^2 - k^T \Sigma^{-1} k$$

```
Sigma_Matern <- cov.Matern(dist, c(1, 0.1, 1.5))
set.seed(123)
y2 <- array(mvrnorm(n = 1, rep(0, N^2), Sigma_Matern), dim = c(N, N))
y2[N / 2, N / 2] <- NA

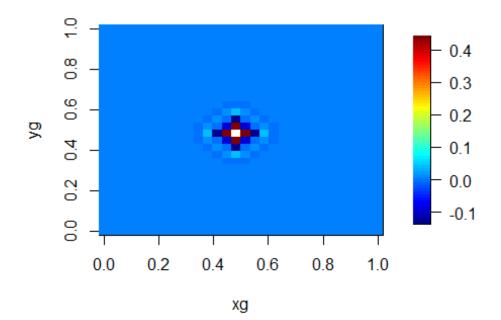
# k Vector
k <- Sigma_Matern[435, -435]

# Sigma Matrix
Sigma <- Sigma_Matern[-435, -435]

# y Vector
y <- y2[-435]

## Prediction
system.time(y0_hat <- t(k) %*% solve(Sigma) %*% y)</pre>
```

```
##
      user system elapsed
##
       0.5
                        0.5
                0.0
system.time(y0_hat_faster <- t(k) %*% solve(Sigma, y))</pre>
##
      user system elapsed
##
      0.14
               0.00
                       0.14
## Prediction Uncertainty
system.time(var_y0_hat <- Sigma_Matern[435, 435] - t(k) %*% solve(Sigma) %*%</pre>
k)
##
      user system elapsed
      0.47
##
               0.00
                       0.47
system.time(Sigma_Matern[435, 435] - t(k) %*% solve(Sigma, k))
##
      user system elapsed
##
      0.14
               0.00
                       0.14
w <- t(k) %*% solve(Sigma)</pre>
weight_map <- array(c(w[1, 1:434], NA, w[1, 435:899]),</pre>
                     dim = c(30, 30)
xg \leftarrow yg \leftarrow seq(0, 1, length = N)
image.plot(xg, yg, weight_map)
```



```
Predicting Multiple Locations
```

```
N = 30
xg \leftarrow yg \leftarrow seq(0, 1, length = N)
locs <- expand.grid(xg, yg); dist <- rdist(locs)</pre>
Sigma_Matern <- cov.Matern(dist, c(1, 0.1, 1.5))
set.seed(123)
y2 \leftarrow array(mvrnorm(n = 1, rep(0, N^2), Sigma_Matern), dim = c(N, N))
y2_vec <- c(y2)
set.seed(123)
rm \leftarrow sample(1:(N^2), 0.5 * N^2)
y2_{vec[rm]} \leftarrow NA
y2_rm \leftarrow array(y2_vec, dim = c(N, N))
# k Matrix
k <- Sigma_Matern[-rm, rm]</pre>
# Sigma Matrix
Sigma <- Sigma_Matern[-rm, -rm]</pre>
# y Vector
y \leftarrow y2_rm[-rm]
## Prediction
system.time(y0 hat <- t(k) %*% solve(Sigma) %*% y)</pre>
##
      user system elapsed
##
      0.13
               0.00
                        0.13
system.time(y0_hat_faster <- t(k) %*% solve(Sigma, y))</pre>
##
      user system elapsed
##
      0.03
               0.00
                        0.03
## Prediction Uncertainty
system.time(var_y0 hat <- Sigma_Matern[rm, rm] - t(k) %*% solve(Sigma) %*% k)</pre>
##
      user system elapsed
##
      0.19
               0.00
                        0.20
system.time(Sigma_Matern[rm, rm] - t(k) %*% solve(Sigma, k))
##
      user system elapsed
##
      0.21
               0.00
                        0.22
par(mfrow = c(1, 3), mar = c(0, 1.6, 1.2, 0),
    mgp = c(2.4, 1, 0), las = 1)
image.plot(xg, yg, y2_rm, xlab = "", ylab = "", xaxt = "n", yaxt = "n",
horizontal = T, legend.width = 0.8,
            legend.line = 1)
mtext("Observed")
```

