4[C:突际计算得到的解;

 $\Rightarrow \|\widehat{u} - u\| \leq \|\% \|u\|$

 $||f(t)|| \leq ||f(t)|| \leq ||f(t)||$

 $\Rightarrow ||\hat{u} - u|| \leq \frac{e^{200}}{100} ||f||$

U: Xf确解;

05t 52

$$\frac{\partial}{\partial t} \left| \hat{u} \right|^2 = 0.$$

$$\frac{\partial}{\partial t} \left| \hat{u} \right|^2 = 0.$$

$$\frac{\partial}{\partial t} \left| \hat{u} \right|^2 = \left(2\omega A + B \right) \hat{u}$$

$$\frac{\partial}{\partial t} \left| \hat{u} \right|^2 = \left(4\omega A + B \right) \hat{u}$$

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$$\begin{array}{ll}
\text{Res} & u_t = (2\omega A + B) u \\
\text{Fith} & \frac{\partial}{\partial t} |u|^2 = \langle u_t , u \rangle + \langle u, u_t \rangle \\
&= \langle (2\omega A + B) u , u \rangle + \langle u \rangle
\end{array}$$

$$= \langle (i\omega A + B) \hat{u}, \hat{u} \rangle + \langle \hat{u}, (i\omega A + B) \hat{u} \rangle$$

$$= \langle \hat{u}, (-i\omega A^* + B^*) \hat{u} \rangle + \langle \hat{u}, (i\omega A + B) \hat{u} \rangle$$

$$= \langle \hat{u}, (i\omega A^* + B^*) \hat{u} \rangle + \langle \hat{u}, (i\omega A + B) \hat{u} \rangle$$

$$= \langle \hat{u}, (i\omega (A - A^*) + (B + B^*)) \hat{u} \rangle$$

$$= \langle u, (2w(A-A^*) + (B+B^*)) u \rangle$$

$$= 0$$

$$\Rightarrow A^* = A, B^* = -B.$$

Att-
$$\Re$$
 \Re , $\chi(x,0) = f(x) = \int_{\infty}^{\infty} \int_{\infty}$

$$L(x,t) = \int_{2\pi} \lesssim e^{i\omega x} \hat{u}(\omega,t) \qquad \Rightarrow \hat{u}(\omega,o) = \hat{f}(\omega)$$
由 Parse $u_0(x,t) = \int_{2\pi} \hat{u}(\omega,t) = \int_{2$

亦即要求 A*=A, B*--B.

 $= -\omega^{2} \left(\langle A\hat{u}, \hat{u} \rangle + \langle \hat{u}, A\hat{u} \rangle \right)$ $= -\omega^{2} \left(\langle \hat{u}, A^{\dagger}\hat{u} \rangle + \langle \hat{u}, A\hat{u} \rangle \right)$ $= -\omega^{2} \left(\langle \hat{u}, A^{\dagger}\hat{u} \rangle + \langle \hat{u}, A\hat{u} \rangle \right)$ $= -\omega^{2} \langle \hat{u}, (A+A^{\dagger})\hat{u} \rangle$ $\leq -\omega^{2} \delta |\hat{u}|^{2} , \text{ If } (4) \text{ Local Line But Afficiently } \delta, K 使得 不對成立.$

$$\begin{split} u(\mathbf{x},t) &= \sqrt{\mathbf{x}} \stackrel{>}{\lesssim} e^{i\omega \mathbf{x}} \widehat{\mathbf{x}}(\omega,t) \quad \widehat{\mathbf{x}}(\omega,\rho) = \widehat{\mathbf{f}}(\omega) \\ \Rightarrow u_{\mathbf{x}}(\mathbf{x},t) &= \sqrt{\mathbf{x}} \stackrel{>}{\lesssim} i\omega e^{i\omega \mathbf{x}} \widehat{\mathbf{x}}(\omega,t) \\ &= \frac{1}{2} |\widehat{\mathbf{x}}(\omega,t)|^2 \\ &= \frac{1}{2} |\widehat{\mathbf{x}}(\omega,t)|^2 \\ &= \frac{1}{2} |\widehat{\mathbf{x}}(\omega,t)|^2 \\ \Rightarrow \widehat{\mathbf{x}}\widehat{\mathbf{x}}\widehat{\mathbf{x}} \\ &= |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 \\ &= |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 \\ &= |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 \\ &= |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 \\ &= |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}}(\omega,t)|^2 \\ &= |\widehat{\mathbf{x}}(\omega,t)|^2 + |\widehat{\mathbf{x}$$

対般解, U(X,o)=f(x)= 元をwxf(w)

25.2.
$$\theta$$
 Scheme: $\frac{V_{j}^{m+1} V_{j}^{n}}{K} = \theta \frac{V_{jn}^{m+1} V_{j-1}^{m+1}}{h^{2}} + (1-\theta) \frac{V_{jn}^{n} \frac{2}{2} V_{j}^{m+1}}{h^{2}}$

$$\exists N V_{j}^{n} = \overline{\int_{N}^{\infty}} V_{j}^{n}(\omega) e^{2\omega X_{j}^{n}}$$

$$\Rightarrow V_{j}^{m+1} - V_{j}^{n}(\omega) = \lambda \left(e^{2\omega h} - 2 + e^{2\omega h} \right) \left(\theta V_{j}^{n+1} + (1-\theta) V_{j}^{n}(n) \right), \lambda = \frac{k}{h^{2}}$$

$$2(\cos s - 1) \quad s = \omega h$$

$$\frac{1}{4 \sin^{2} \frac{s}{2}}$$

$$\Rightarrow V_{j}^{m+1} - \frac{1 - 4(1-\theta) \lambda \sin^{2} \frac{s}{2}}{1 + \theta + \lambda \sin^{2} \frac{s}{2}} V_{j}^{n}(\omega) = \theta V_{j}^{n}(\omega)$$

$$\theta = \frac{1 - \frac{4 \lambda \sin^{2} \frac{s}{2}}{1 + \theta + \lambda \sin^{2} \frac{s}{2}} \cdot 1 + \theta + \lambda \sin^{2} \frac{s}{2}}{1 + \theta + \lambda \sin^{2} \frac{s}{2}} \cdot 1 + \theta + \lambda \sin^{2} \frac{s}{2} \cdot 1 + \theta$$

2,5,3. Ut = UXX. $= \left(\left(\left(\mathcal{U}_{t} \right)_{j}^{n+1} - \frac{k}{2} \left(\mathcal{U}_{t} \right)_{j}^{n+1} + \mathcal{O}(k^{2}) \right) - \left(\left(\mathcal{U}_{XX} \right)_{j}^{n+1} + \frac{h^{2}}{12} \left(\mathcal{U}^{(4)} \right)_{i}^{n+1} + \mathcal{O}(h^{4}) \right)$ $= (\mu_1 - \lambda_{XX})^{n+1} + O(\lambda^2 + k) = O(\lambda^2 + k)$

(Uxx); ~ Q_1 Uj-1 + Qo Uj + Q1 Uj+1

$$U_{j\pm 1} = U_{j} + h(U_{x})_{j} + \frac{h^{2}}{2}(U_{xx})_{j} + \frac{h^{3}}{3!}(U_{xxx})_{j} + \frac{h^{4}}{4!}(U^{(4)})_{j} + \dots$$

$$\Rightarrow a_{-1} u_{j-1} + u_{0} u_{j} + a_{1} u_{j+1} = (a_{-1} + a_{0} + a_{1}) u_{j} + (a_{-1} + a_{1}) h (u_{x})_{j} + (a_{1} + a_{1}) h (u_{x})_{j} + (a_{1} + a_{1}) \frac{h^{2}}{2} (u_{xx})_{j} + (a_{-1} + a_{1}) \frac{h^{3}}{3!} (u_{xxx})_{j} + (a_{-1} + a_{1}) \frac{h^{4}}{4!} (u^{(4)})_{j} + \cdots$$

$$\begin{cases} a_{-1} + a_{0} + a_{1} = 0 \\ -a_{-1} + a_{1} = 0 \end{cases} \qquad a_{1} = a_{1} = \frac{1}{h^{2}} \quad a_{0} = \frac{-2}{h^{2}}$$

$$\begin{cases} a_{-1} + a_{1} - a_{1} = 0 \\ a_{-1} + a_{1} = 0 \end{cases} \qquad a_{1} = a_{1} = \frac{1}{h^{2}} \quad a_{0} = \frac{-2}{h^{2}}$$

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只有 2 附,縱是 3 阶或更高.

2. 针对 (1+= 11xx ,基于其在控制体 [tn-1, tn+1] x [xj-1, xj-1] L的积分形式构造有限体积格式。参考书: [.6.2节.

 $= (u_{xx})_j + O(h^2)$

小则2, $4 = 6(x,t) u_{xx}$ FTCS格式,整体误差。

根据性:
$$\frac{V_{j}^{n+1} - V_{j}^{n}}{K} = b_{j}^{n} \cdot \frac{V_{j+1}^{n} - 2V_{j}^{n} + V_{j-1}^{n}}{h^{2}}$$
 $\int_{K}^{n} = \frac{u_{j}^{n+1} - u_{j}^{n}}{K} - b_{j}^{n} \cdot \frac{u_{j+1}^{n} - 2u_{j}^{n} + u_{j-1}^{n}}{h^{2}}$

 $= \left(\left(l_{t} \right)_{j}^{n} + \frac{k}{2} \left(l_{tb} \right)_{j}^{n} + 0 \left(k^{2} \right) - b_{j}^{n} \left(\left(l_{xx} \right)_{j}^{n} + \frac{h^{2}}{12} \left(l_{u}^{(u)} \right)_{j}^{n} + 0 \left(h^{4} \right) \right)$ $= \left(l_{t} - b_{u}^{2} l_{xx} \right)_{j}^{n} + 0 \left(h^{2} + k \right)$

 $= D(h^2+k)$

総成性.

$$\lambda = \frac{k}{n^2}$$
 , $\xi = \omega h$
 $Y_j^n = \sqrt{2} p^n (\omega) e^{i\omega X_j}$
 $\Rightarrow \hat{y}^{n+1} = ([-b_j^n, 4\lambda s_{in}^{-1} \frac{1}{2}) p^n = Q p^n$
 $\beta \in \{ = \omega_j^n, 4\lambda s_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_{j-1}^n) + k l_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_{j-1}^n) + k l_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_j^n - 2\lambda_j^n + \lambda_j^n + \lambda_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_j^n - 2\lambda_j^n + \lambda_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_j^n - 2\lambda_j^n + \lambda_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_j^n - 2\lambda_j^n + \lambda_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_j^n - 2\lambda_j^n + \lambda_j^n (\lambda_j^n - 2\lambda_j^n + \lambda_j^n - 2\lambda_j^n + \lambda_j^n - 2\lambda_j^n + \lambda_j^n (\lambda_j^n - 2\lambda_j^n - 2\lambda_j^$