

$$1. (x - x_*)^T A (x - x_*) = x^T A x + x_*^T A x_* - 2x_*^T A x$$

Since  $Ax_* = b \quad \Leftarrow \quad = x^T A x + x_*^T A x_* - 2b^T x = \text{LHS}$

$$2. \varphi(x_k) = \varphi(x_{k-1}) - \frac{(r_{k-1}^T r_{k-1})^2}{r_{k-1}^T A r_{k-1}}$$

$$\therefore r_{k-1}^T A^{-1} r_{k-1} = (b - Ax_{k-1})^T A^{-1} (b - Ax_{k-1}) = b^T A^{-1} b + \varphi(x_{k-1}) \geq \varphi(x_{k-1})$$

$$\therefore \varphi(x_k) \leq \varphi(x_{k-1}) - \frac{(r_{k-1}^T r_{k-1})^2}{r_{k-1}^T A r_{k-1}} \cdot \frac{\varphi(x_{k-1})}{r_{k-1}^T A^{-1} r_{k-1}} = \varphi(x_{k-1}) \left[ 1 - \frac{1}{\kappa_2(A)} \right]$$

3. 即  $x_* = x_k + \frac{r_k^T r_k}{r_k^T A r_k} \cdot r_k \rightarrow \text{记为 } c$

$$\Rightarrow b = Ax_* = Ax_k + Ar_k \cdot c$$

$$\Rightarrow \cancel{r_k} \quad r_k = b - Ax_k = A \cancel{A} \cdot r_k \cdot c$$

4. 方程的系数矩阵为  $B = \begin{pmatrix} r_k^T A r_k & r_k^T A p_{k-1} \\ r_k^T A p_{k-1} & p_{k-1}^T A p_{k-1} \end{pmatrix}$

$$\therefore B \text{ 正定} \Leftrightarrow (x_1 r_k + x_2 p_{k-1})^T A (x_1 r_k + x_2 p_{k-1}) = 0 \quad \text{相 当 且 仅 当 } x_1 = x_2 = 0$$

$$\Leftrightarrow r_k \text{ 与 } p_{k-1} \text{ 线性无关 (显然)}$$

$$\therefore B \text{ 正定} \Rightarrow B \text{ 可逆} \Rightarrow \text{解唯一} \quad (\text{亦可用归约法证 } B \text{ 可逆})$$

5 反证: 若  $\exists \alpha_i$  不全为 0,  $\sum_{i=1}^k \alpha_i \vec{p}_i = 0$

$$\Rightarrow 0 = \vec{p}_i^T A \left( \sum_{i=1}^k \alpha_i \vec{p}_i \right) = \alpha_i \vec{p}_i^T A \vec{p}_i \neq 0 \Rightarrow \alpha_i = 0 \quad \forall i = 1, 2, \dots, k$$

矛盾

6. 令  $\frac{d \varphi(y_{i-1} + t e_i)}{dt} = 0 \Rightarrow t = \frac{1}{a_{ii}} (b - Ay_{i-1})^T e_i$

$$\Rightarrow y_i = y_{i-1} + \frac{1}{a_{ii}} (b - Ay_{i-1})^T e_i \quad \text{仅第 } i \text{ 行发生改变}$$

而对 G-S 迭代,  $x_i^{(k+1)} = \frac{1}{a_{ii}} (b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k+1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k)})$

$$\therefore x_i^{(k+1)} - x_i^{(k)} = \frac{1}{a_{ii}} (b_i - (b - Ay_{i-1})^T e_i)$$

故经过  $n$  次相当于做一次 G-S 迭代



7.  $A$  实对称  $\Rightarrow A$  可对角化  $\Rightarrow \chi_A(\lambda)$  无重根

$$\Rightarrow d_A(\lambda) = \prod_{i=1}^k (\lambda - \lambda_k) \Rightarrow \deg d_A(\lambda) = k$$

$$\Rightarrow \dim \text{span} \{r, \dots, A^{k-1}r\} = \dim \text{span} \{r, \dots, A^{k-1}r\} \leq k$$

8. 由定理 5.2.2 与上题结论显然

9.  $A = A^T \Rightarrow A$  可经相似到对角阵

设  $A = P \Sigma P^T$ ,  $P \in \mathbb{R}^n$ ,  $\Sigma = \text{diag}(\lambda_1, \dots, \lambda_n)$ ,  $\lambda_i \geq \lambda_{i+1} > 0$

$$\therefore \|x\|_A^2 = x^T A x = x^T P \Sigma P^T x =: y^T \Sigma y = \sum_{i=1}^n \lambda_i y_i^2 \quad (\text{令 } \bar{y} = P^T x)$$

$$\therefore \lambda_n \|x\|_2^2 = \lambda_n \sum_{i=1}^n y_i^2 \leq \|x\|_A^2 \leq \lambda_1 \sum_{i=1}^n y_i^2 = \lambda_1 \|x\|_2^2, \quad \forall x \in \mathbb{R}^n$$

易得  $\|A\|_2 = \sqrt{\lambda_1}$ ,  $\|A^{-1}\|_2 = \frac{1}{\sqrt{\lambda_n}}$ , 代入上式及定理 5.3.2 得证

11.  $x_k$  极小化  $\|x - A^{-1}b\|_A \Leftrightarrow \forall w \in \mathcal{X}, \frac{d}{d\alpha} \|x_k + \alpha w - A^{-1}b\|_A^2 \big|_{\alpha=0} = 0$

$$\Leftrightarrow w^T A (x_k - A^{-1}b) = 0 \quad \forall w \in \mathcal{X}$$

$$\Leftrightarrow A x_k - b \perp \mathcal{X}$$

12 略

