Linear Optimization: Column Generation

Brady Hunsaker

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- ▶ Recall from the simplex algorithm in matrix notation:
 - ► The dual values associated with a solution are given by the vector $y^T = c_B^T B^{-1}$
 - ► The reduced cost of a column A_j is given by $c_i c_R^T B^{-1} A_i = c_i y^T A_i$
- So given y, we must determine whether there exists a column A_i such that $y^T A_i$ is favorable.



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- ▶ This is equivalent to minimizing the total waste.



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Really we should have integer values, but in practice the numbers are mostly large enough that rounding gives a good solution.

Formulating the pricing problem

We need to find values a_i for $i \in I$ such that the values form a feasible pattern and the reduced cost is favorable.

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- ▶ We mentioned dynamic programming before, since it is also an efficient way to solve many shortest-path instances.

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 - The easy constraints may have a special structure, such as a graph algorithm, which can be solved quickly using a special algorithm.
- ► The idea is to solve the easy constraints separately (and repeatedly, as it turns out).



Extreme points and extreme rays

Consider a set of linear inequalities: $\sum_j a_{ij}x_j \leq b_i$. The feasible region for this system has a set of extreme points x_1^*, \ldots, x_s^* and extreme rays d_1^*, \ldots, d_t^* .

Theorem: Any point in the feasible region defined by the set of linear constraints above may be expressed in the form

$$\sum_{i=1}^{s} \alpha_i x_i^* + \sum_{j=1}^{t} \beta_j d_j^*,$$

where $\alpha_i, \beta_j \geq 0$ and $\sum_{i=1}^s \alpha_i = 1$.

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The main idea of Dantzig-Wolfe decomposition is to replace the system of inequalities with this expression and generate the columns x_i^* or d_i^* as needed using column generation.

