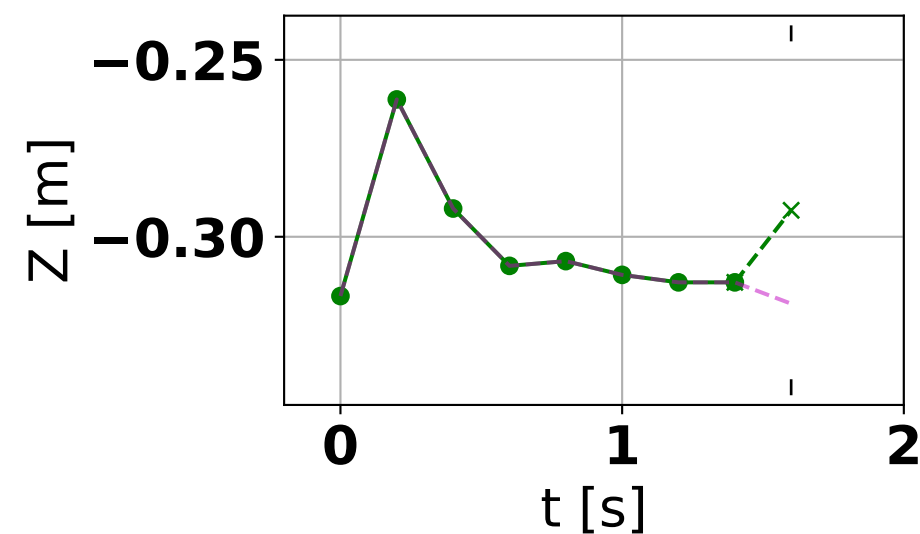Handover trajectory in shared frame, n = 7, Robot: Taker
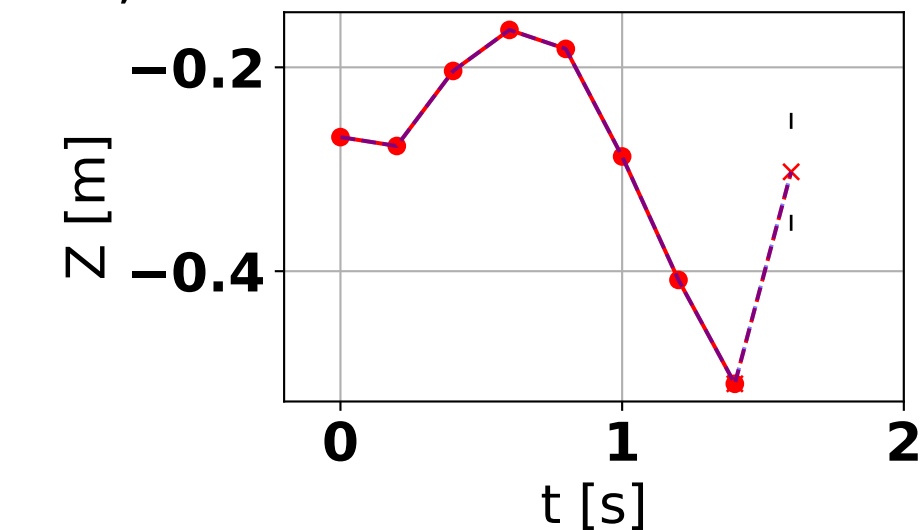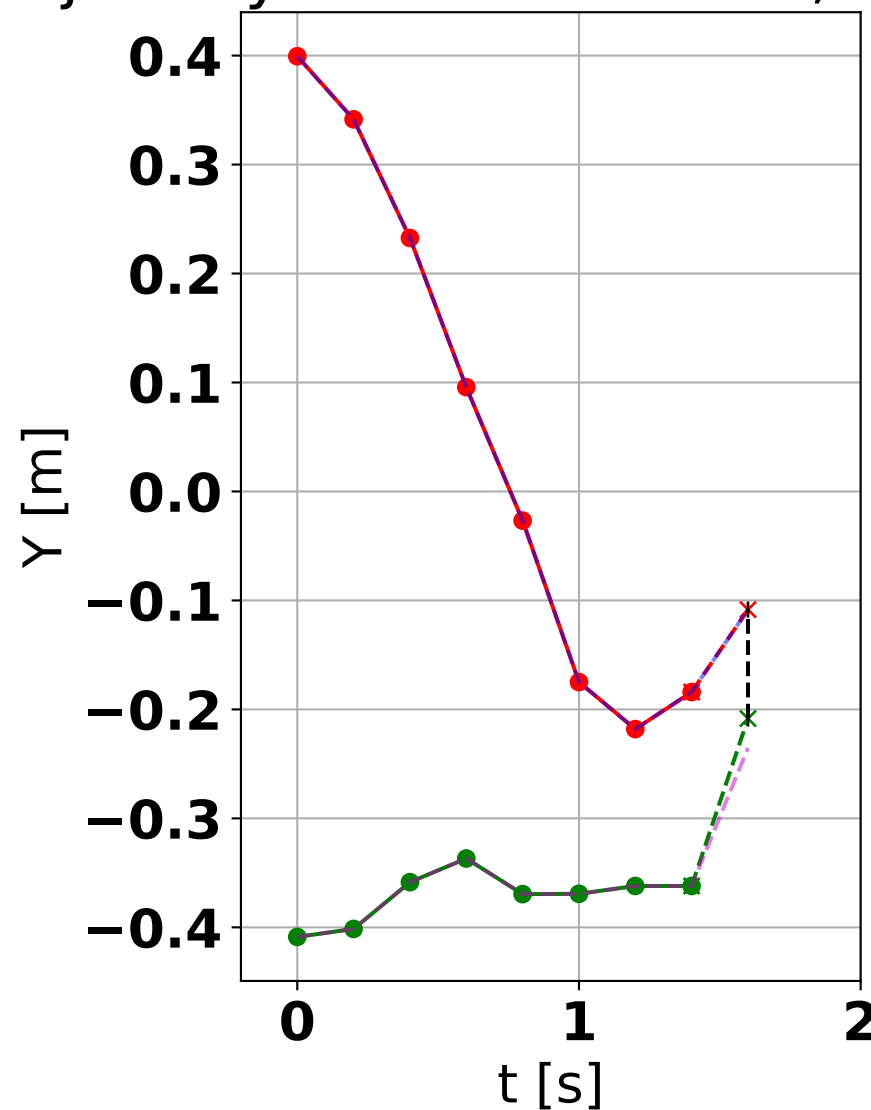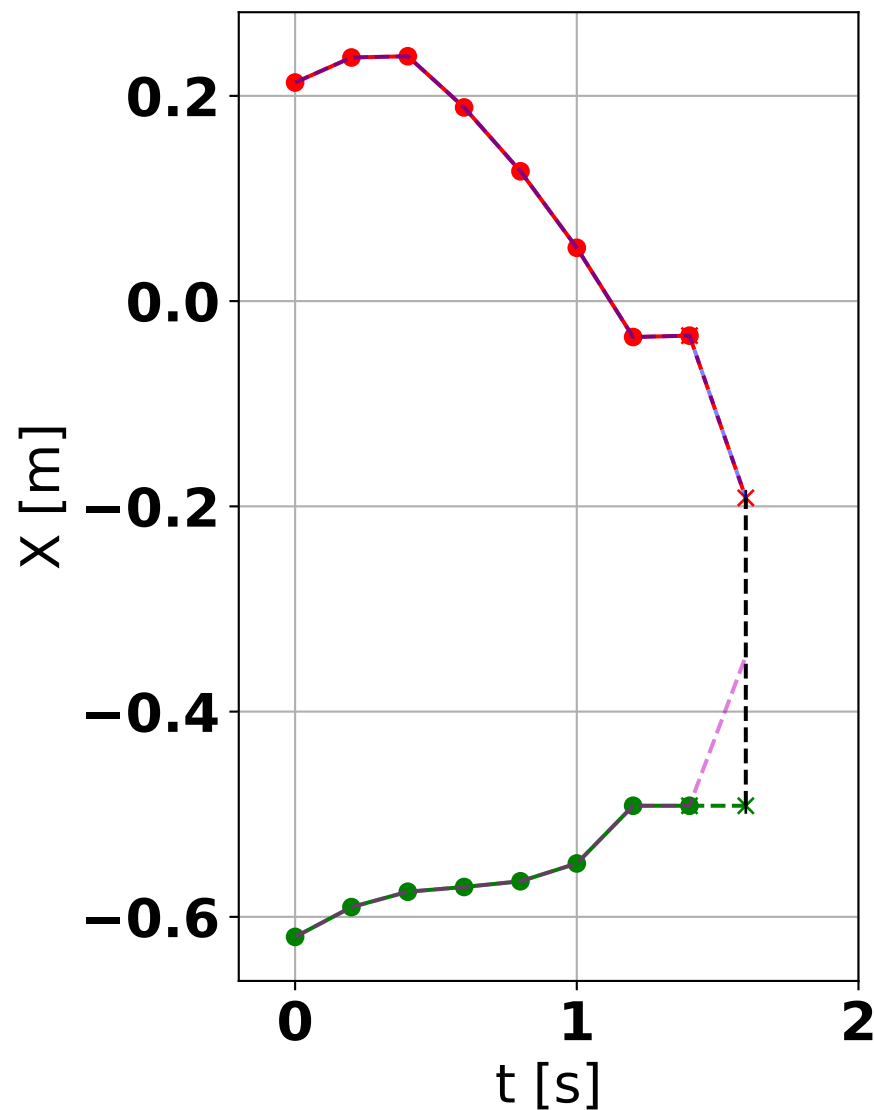
Legend:
- Human position (green solid line with circles)
- Human plan (green dashed line with x markers)
- Robot position (red solid line with circles)
- Robot plan (red dashed line with x markers)
- True human position (magenta dashed line)
- True robot position (blue dashed line)
- Predicted handover, K8 = 0.01 (black dashed line with + markers)