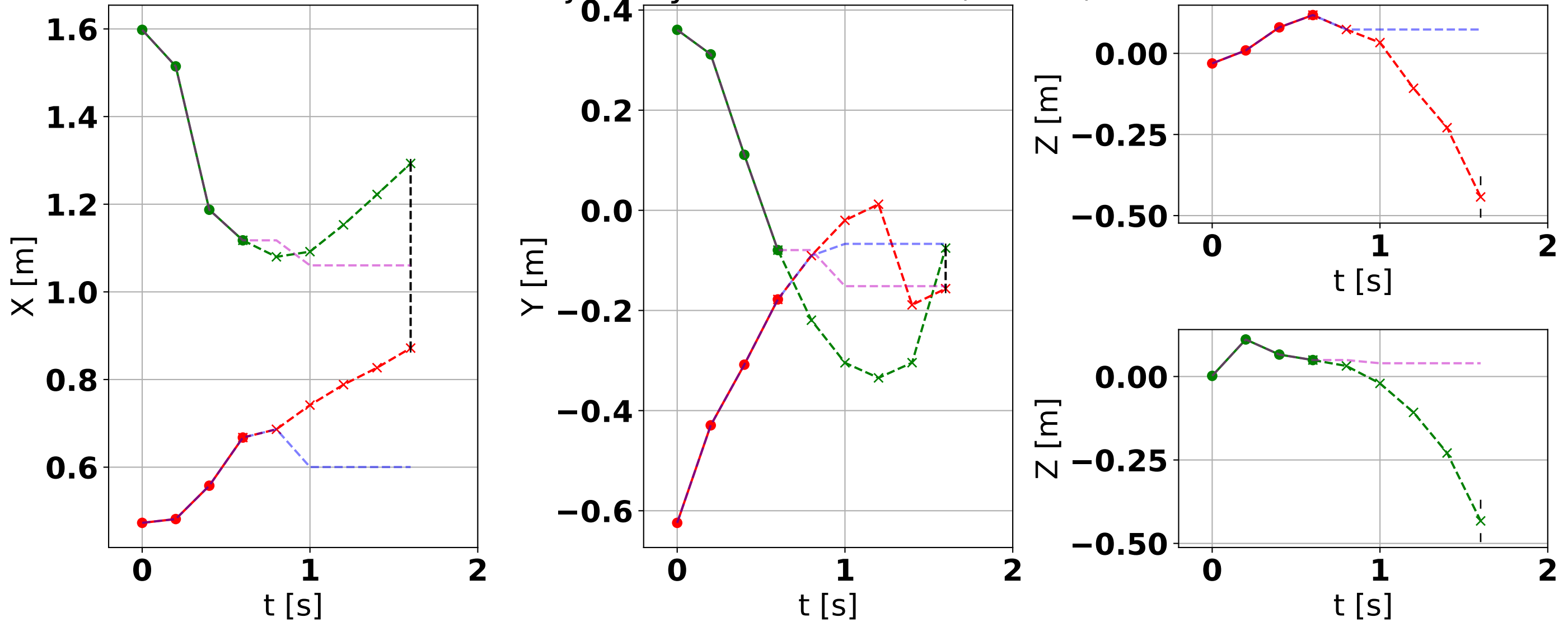


Handover trajectory in world frame,  $n = 3$ , Robot: Taker



- |   |  |
|---|--|
| <span style="color: green;">—●—</span> Human position   | <span style="color: magenta;">- - -</span> True human position               |
| <span style="color: green;">- - x - -</span> Human plan | <span style="color: blue;">- - -</span> True robot position                  |
| <span style="color: red;">—●—</span> Robot position     | <span style="color: black;">- - + - -</span> Predicted handover, $K8 = 0.01$ |
| <span style="color: red;">- - x - -</span> Robot plan   |  |