Handover trajectory in shared frame, n = 5, Robot: Taker

Legend:
- Human position (green solid with dots)
- Human plan (green dashed with x)
- Robot position (red solid with dots)
- Robot plan (red dashed with x)
- True human position (magenta dashed)
- True robot position (blue dashed)
- Predicted handover, K8 = 0.01 (black dash-dot with +)