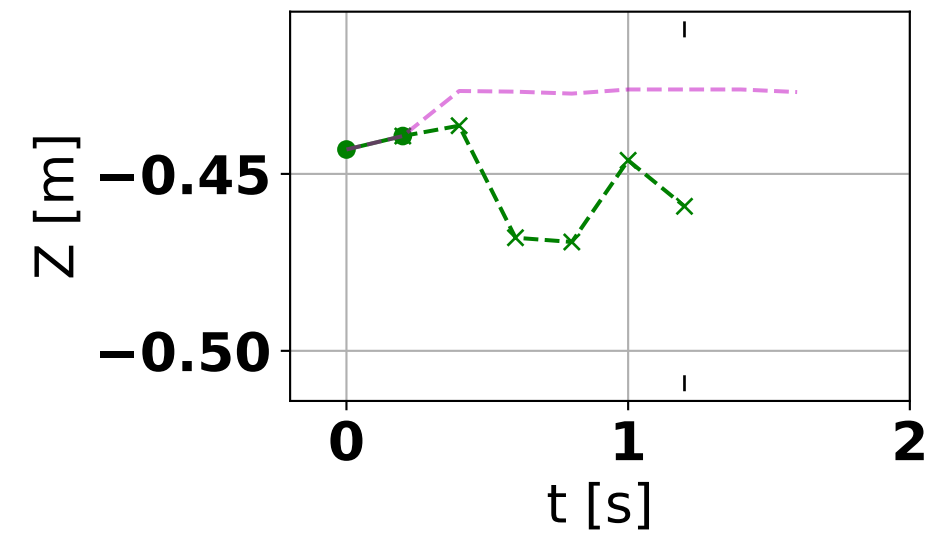
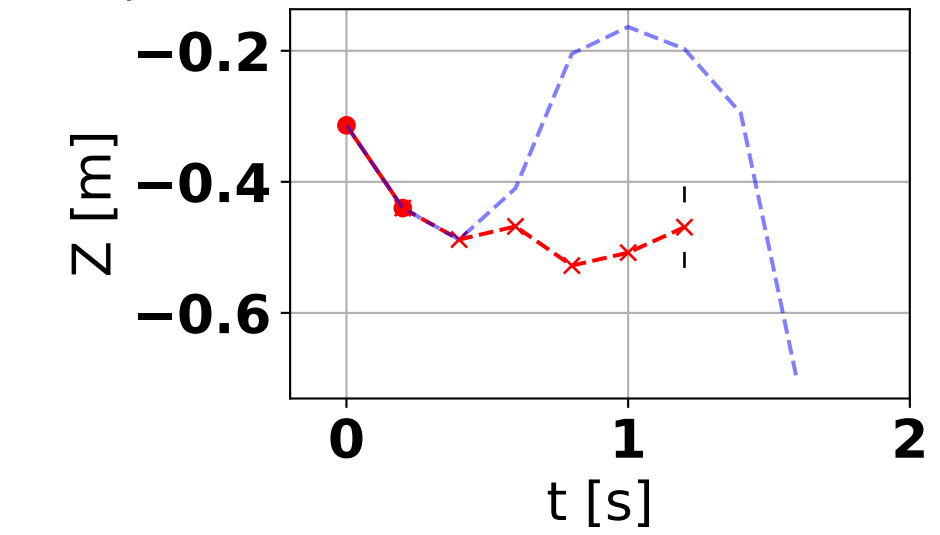
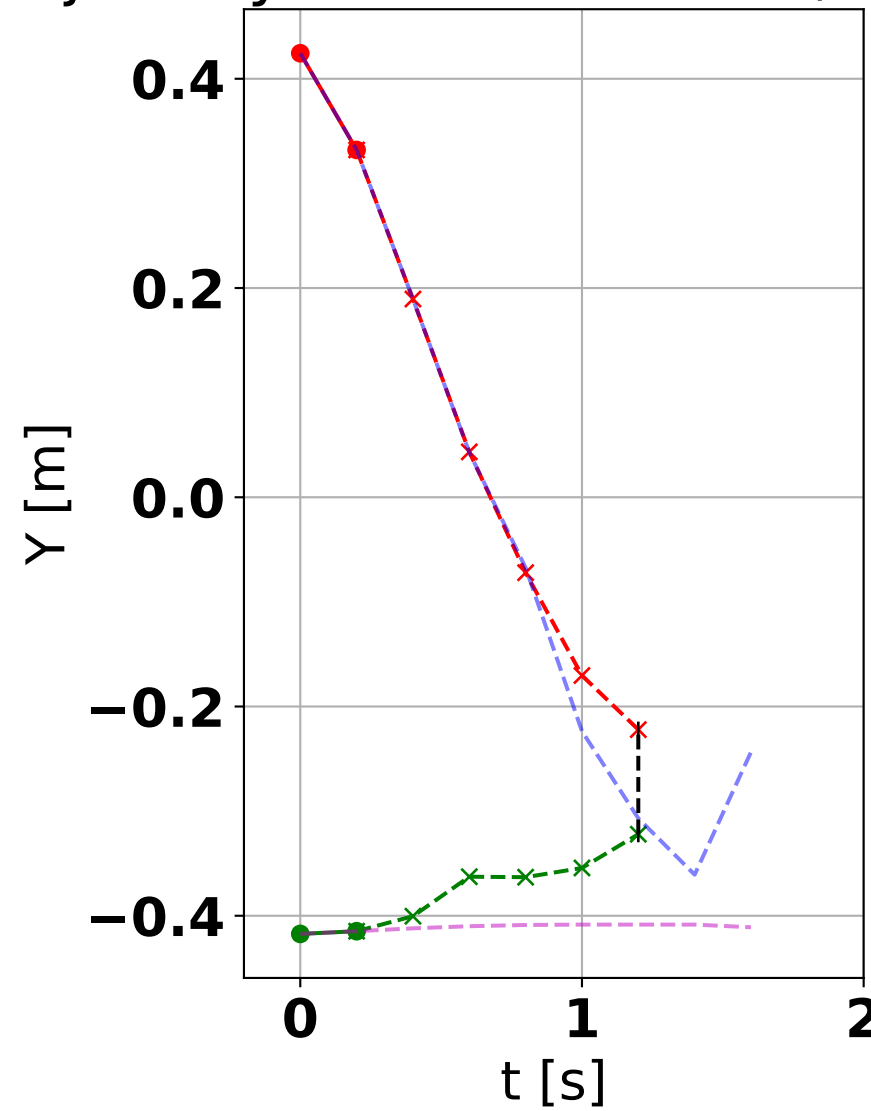
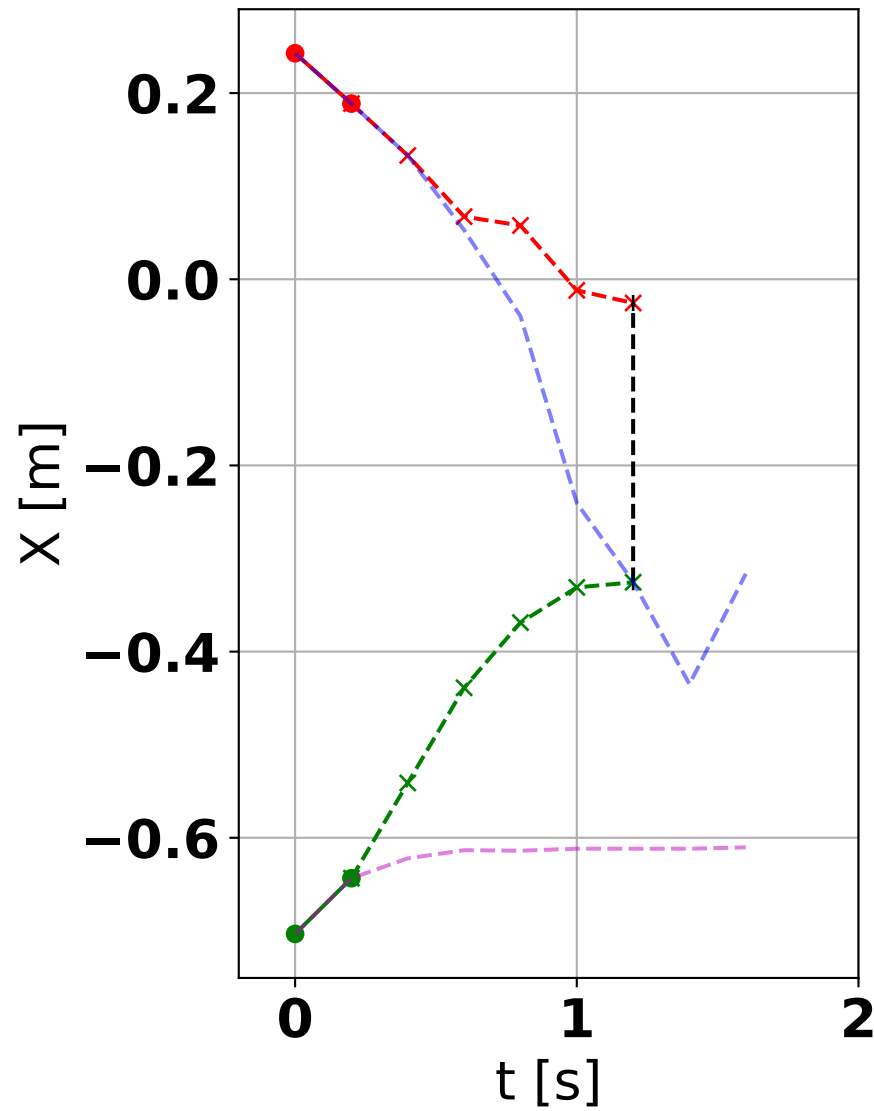





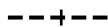



Handover trajectory in shared frame, $n = 1$, Robot: Taker



- | | | | |
|---|-----------------------|---|---|
|  | Human position |  | True human position |
|  | Human plan |  | True robot position |
|  | Robot position |  | Predicted handover, $K6 = 0.01$ |
|  | Robot plan | | |