Handover trajectory in shared frame, n = 0, Robot: Taker
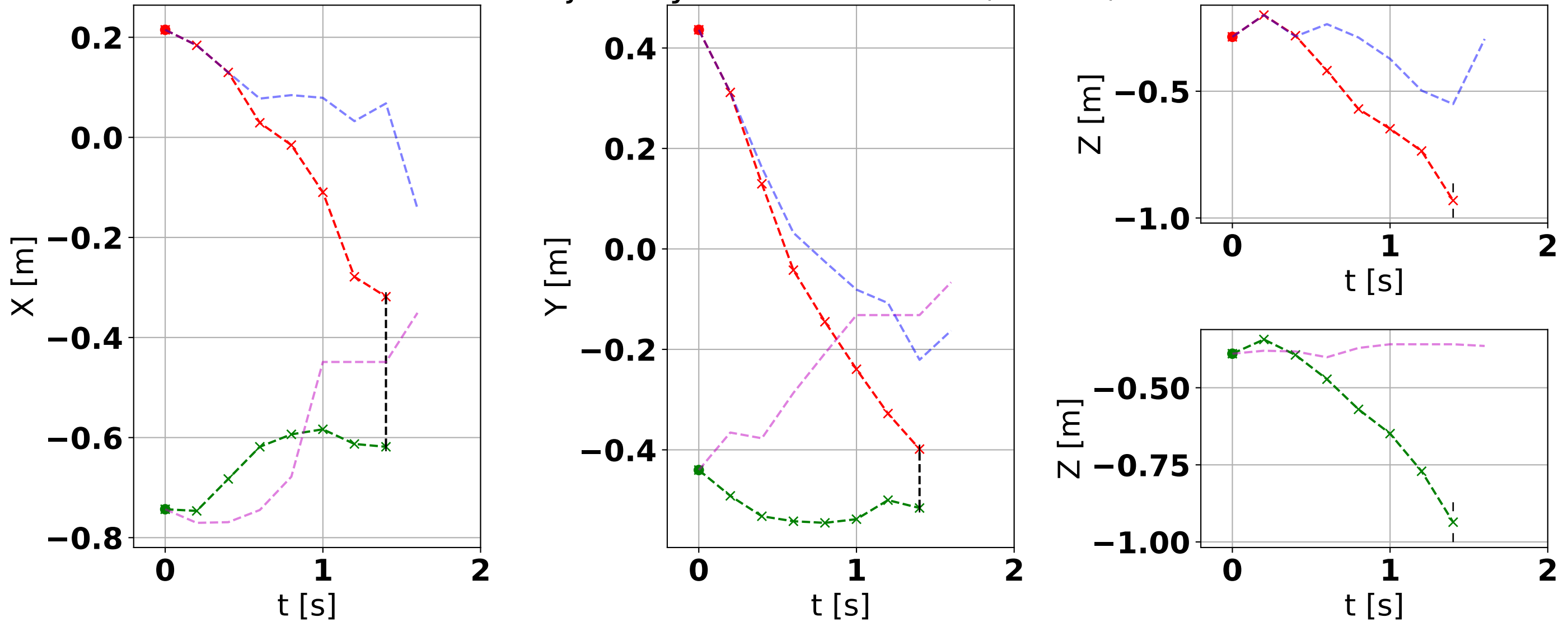
Legend:
- Human position (green, solid with circle markers)
- Human plan (green, dashed with x markers)
- Robot position (red, solid with circle markers)
- Robot plan (red, dashed with x markers)
- True human position (magenta, dashed)
- True robot position (blue, dashed)
- Predicted handover, K7 = 0.02 (black, dash-dot)