Handover trajectory in shared frame, n = 0, Robot: Taker
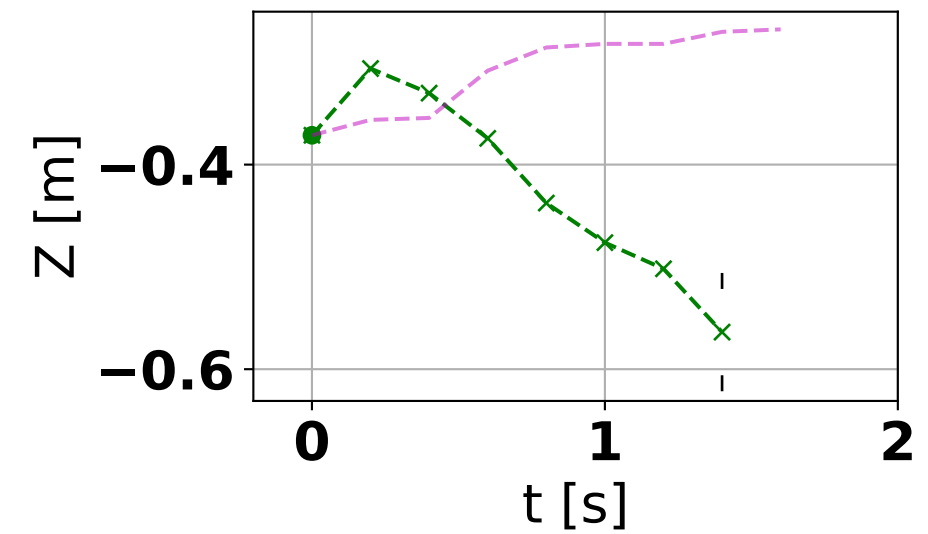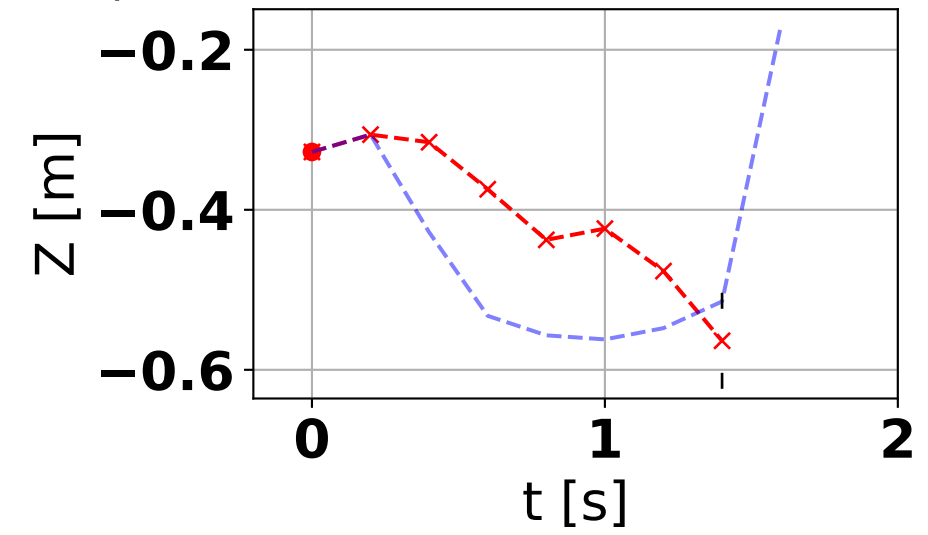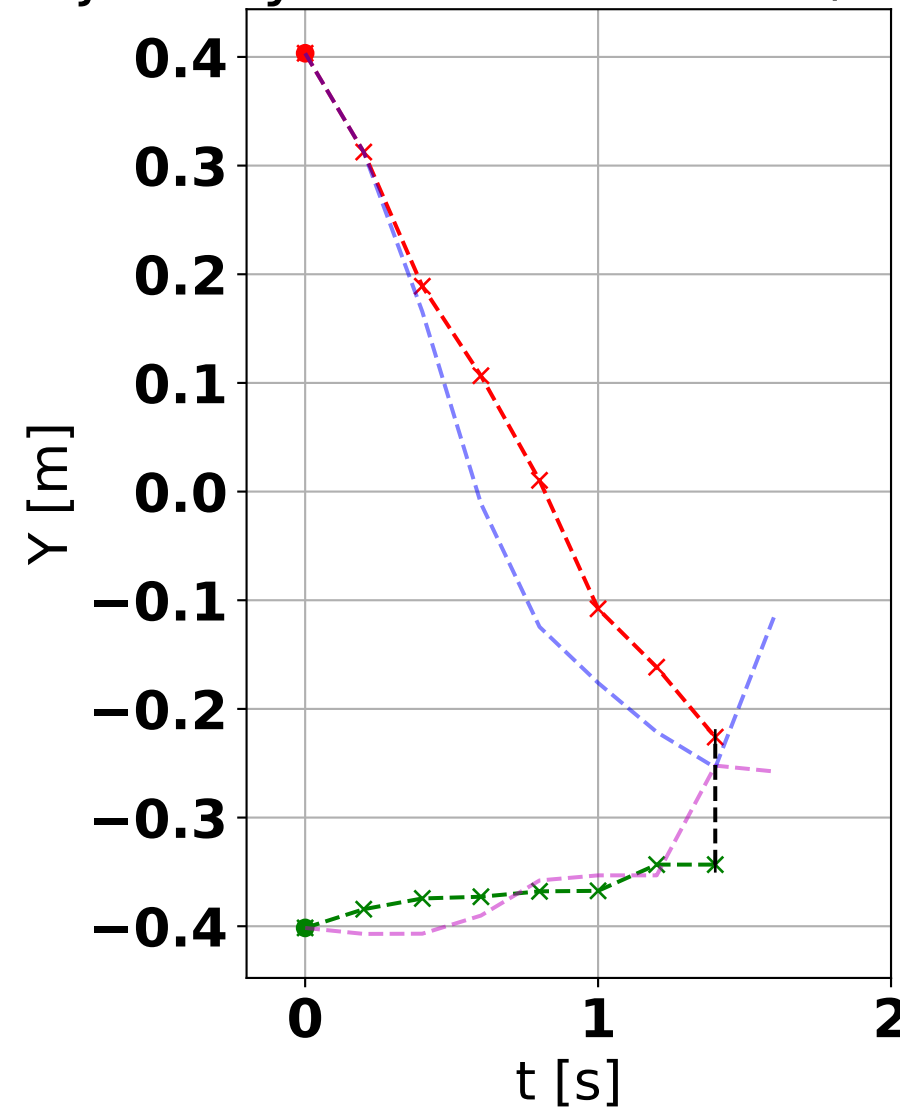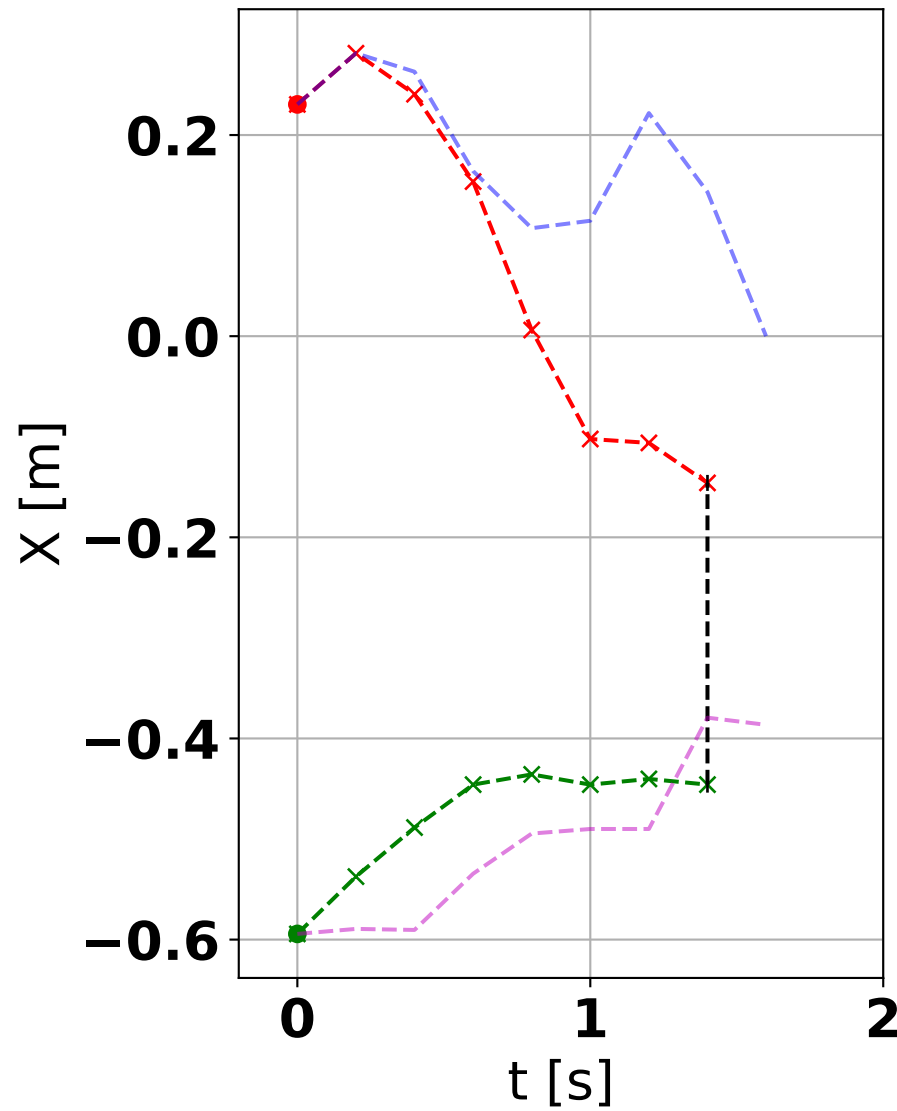
Legend:
- **Human position** (green, solid with dots)
- **Human plan** (green, dashed with x markers)
- **Robot position** (red, solid with dots)
- **Robot plan** (red, dashed with x markers)
- **True human position** (magenta, dashed)
- **True robot position** (blue, dashed)
- **Predicted handover, K7 = 0.02** (black, dashed)