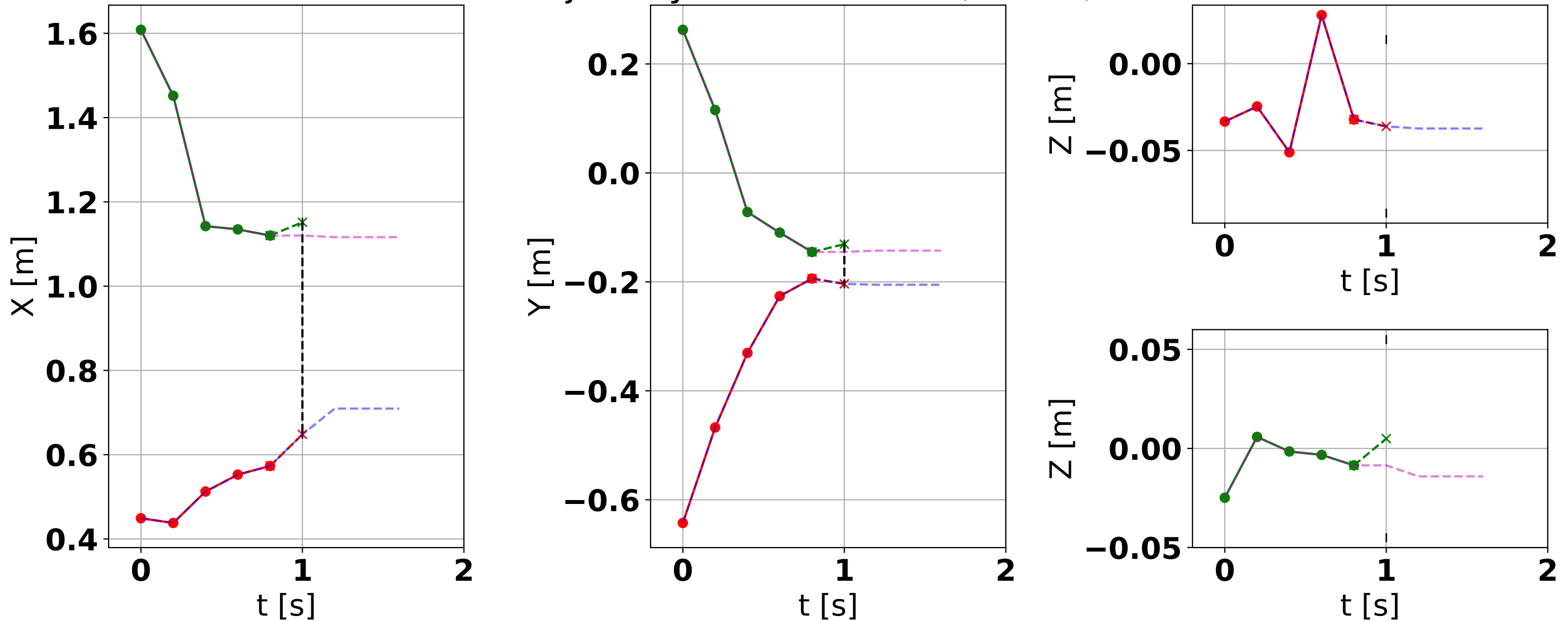


Handover trajectory in world frame,  $n = 4$ , Robot: Taker



- |  |                       |  |   |
|--|-----------------------|--|---|
|  | <b>Human position</b> |  | <b>True human position</b>                        |
|  | <b>Human plan</b>     |  | <b>True robot position</b>                        |
|  | <b>Robot position</b> |  | <b>Predicted handover, <math>K5 = 0.10</math></b> |
|  | <b>Robot plan</b>     |  |   |