Handover trajectory in shared frame, n = 4, Robot: Taker

Legend:
- Human position (green solid with circles)
- Human plan (green dashed with x)
- Robot position (red solid with circles)
- Robot plan (red dashed with x)
- True human position (magenta dashed)
- True robot position (blue dashed)
- Predicted handover, K8 = 0.01 (black dashed)