Handover trajectory in world frame, n = 2, Robot: Taker

Legend:
- Human position (green, solid with dots)
- Human plan (green, dashed with x)
- Robot position (red, solid with dots)
- Robot plan (red, dashed with x)
- True human position (pink, dashed)
- True robot position (blue, dashed)
- Predicted handover, K8 = 0.01 (black, dashed)