Handover trajectory in shared frame, n = 3, Robot: Taker

Legend:
- **Human position** (green solid line with dots)
- **Human plan** (green dashed line with x)
- **Robot position** (red solid line with dots)
- **Robot plan** (red dashed line with x)
- **True human position** (pink dashed line)
- **True robot position** (blue dashed line)
- **Predicted handover, K7 = 0.10** (black dashed line)