Handover trajectory in shared frame, n = 5, Robot: Taker

Legend:
- Human position (green solid, circle markers)
- Human plan (green dashed, x markers)
- Robot position (red solid, circle markers)
- Robot plan (red dashed, x markers)
- True human position (pink dashed)
- True robot position (blue dashed)
- Predicted handover, K8 = 0.01 (black dashed)