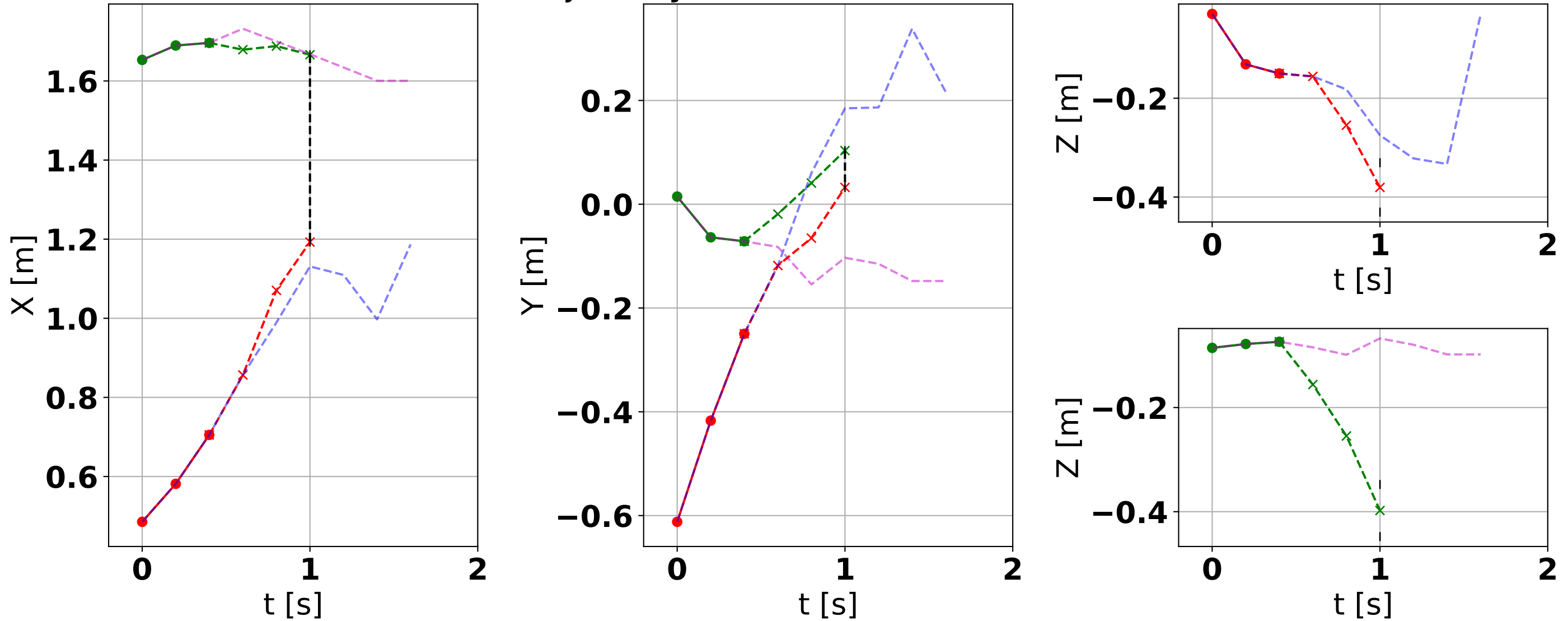


Handover trajectory in world frame,  $n = 2$ , Robot: Taker



- |  |  |
|--|--|
| <span style="color: green;">—●—</span> <b>Human position</b>   | <span style="color: magenta;">- - -</span> <b>True human position</b>                          |
| <span style="color: green;">- - x - -</span> <b>Human plan</b> | <span style="color: blue;">- - -</span> <b>True robot position</b>                             |
| <span style="color: red;">—●—</span> <b>Robot position</b>     | <span style="color: black;">- - + - -</span> <b>Predicted handover, <math>K5 = 0.06</math></b> |
| <span style="color: red;">- - x - -</span> <b>Robot plan</b>   |  |