Handover trajectory in world frame, n = 7, Robot: Taker

Legend:
- **Human position** — green solid line with dots
- **Human plan** — green dashed line with x markers
- **Robot position** — red solid line with dots
- **Robot plan** — red dashed line with x markers
- **True human position** — magenta dashed line
- **True robot position** — blue dashed line
- **Predicted handover, K8 = 0.01** — black dashed line with + markers