Handover trajectory in shared frame, n = 1, Robot: Taker
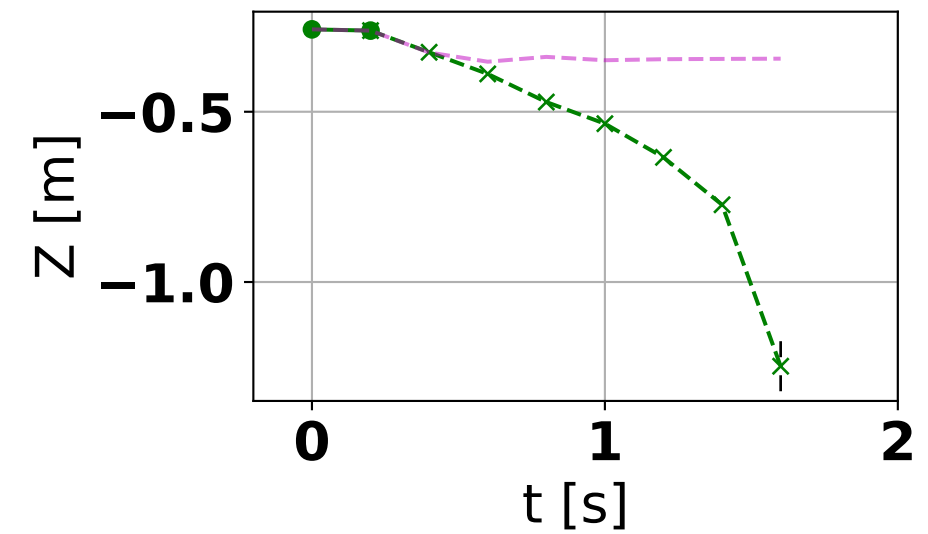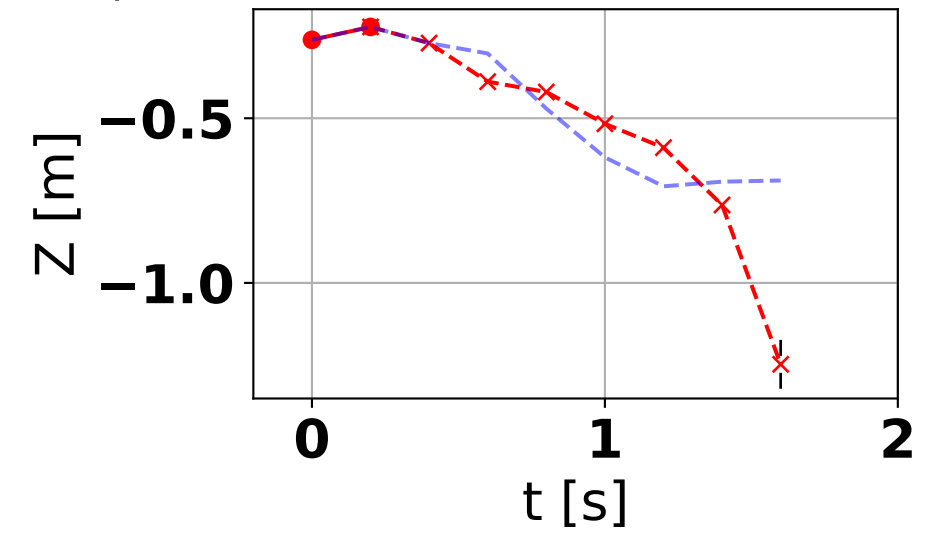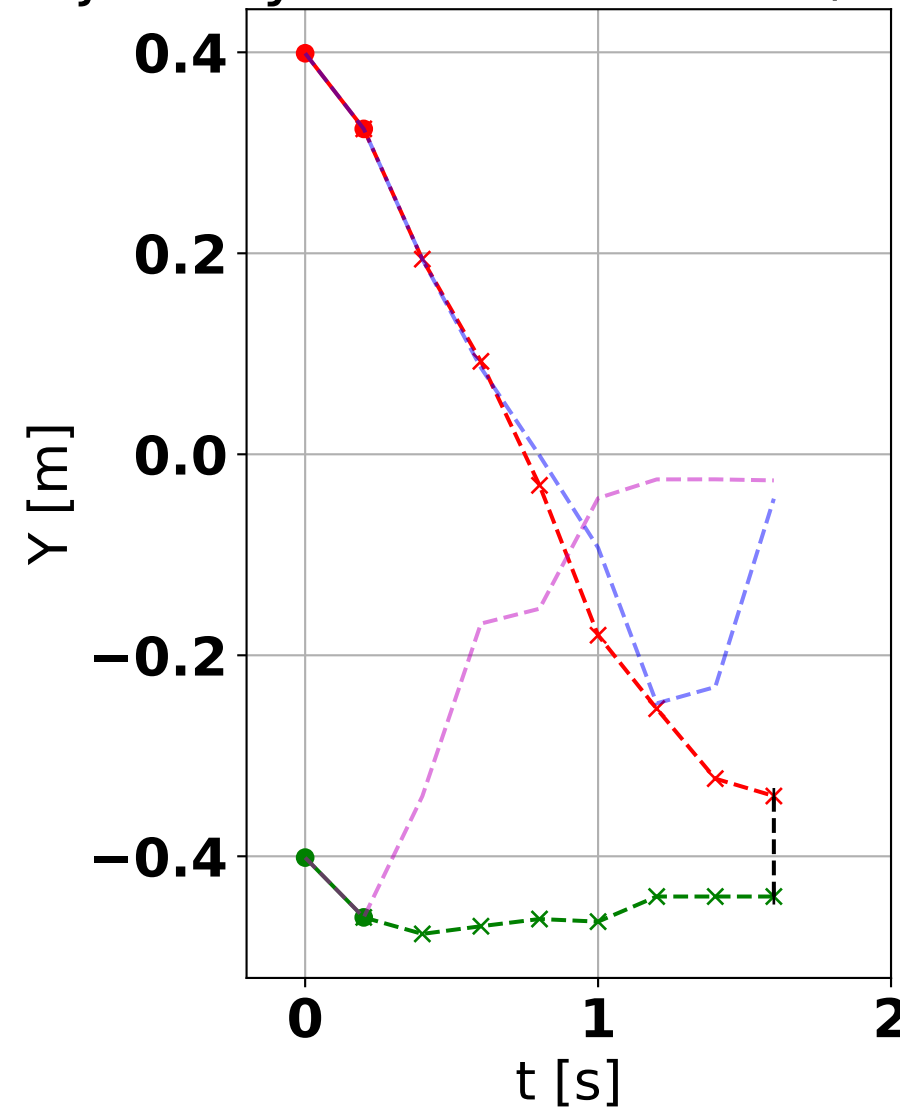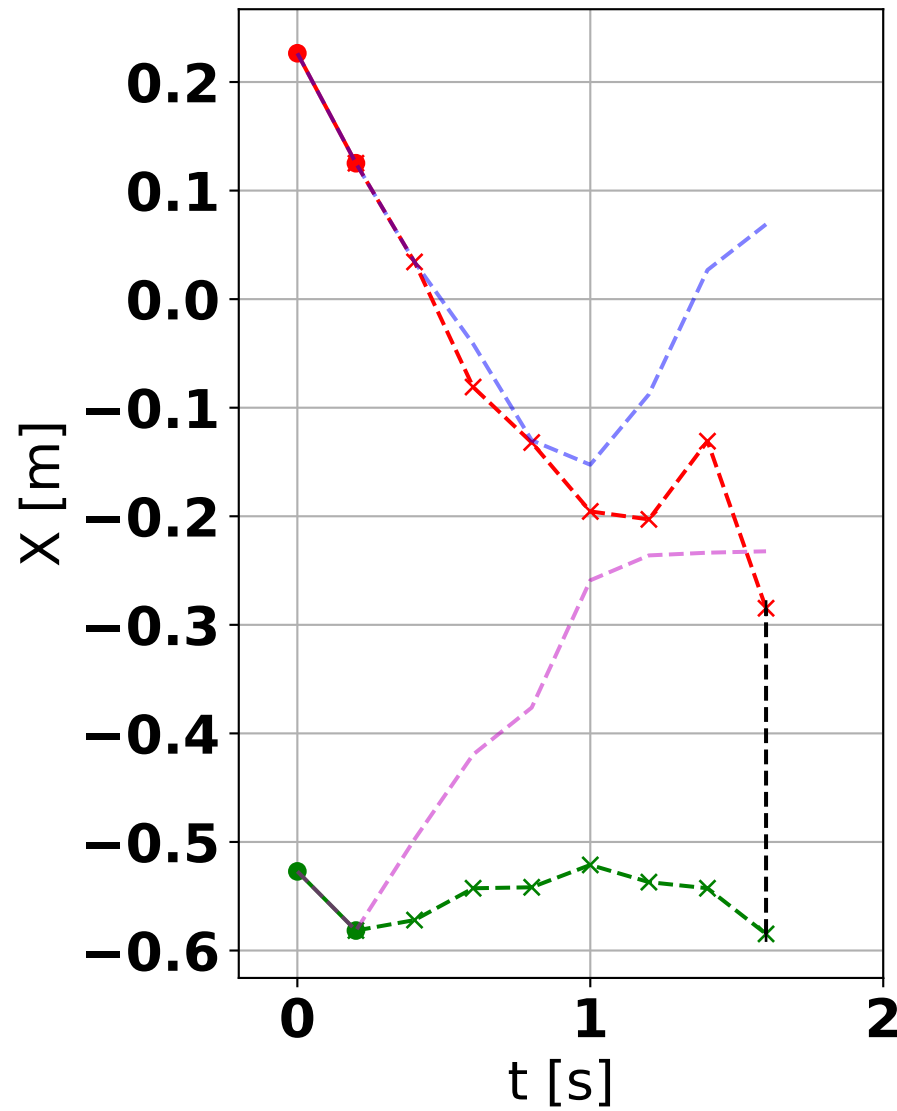
Legend:
- **Human position** (green solid line with dots)
- **Human plan** (green dashed line with x markers)
- **Robot position** (red solid line with dots)
- **Robot plan** (red dashed line with x markers)
- **True human position** (magenta dashed line)
- **True robot position** (blue dashed line)
- **Predicted handover, K8 = 0.00** (black dashed line with + markers)