Handover trajectory in world frame, n = 5, Robot: Taker

Human position ● (green solid line)
Human plan ✕ (green dashed line)
Robot position ● (red solid line)
Robot plan ✕ (red dashed line)
True human position (magenta dashed line)
True robot position (blue dashed line)
Predicted handover, K7 = 0.07 (black dashed line)