Handover trajectory in shared frame, n = 3, Robot: Taker

Legend:
- Human position (green, solid with dots)
- Human plan (green, dashed with x)
- Robot position (red, solid with dots)
- Robot plan (red, dashed with x)
- True human position (magenta, dashed)
- True robot position (blue, dashed)
- Predicted handover, K6 = 0.01 (black, dashed)