Handover trajectory in shared frame, n = 3, Robot: Taker

Legend:
- Human position (green solid, circle marker)
- Human plan (green dashed, x marker)
- Robot position (red solid, circle marker)
- Robot plan (red dashed, x marker)
- True human position (magenta dashed)
- True robot position (blue dashed)
- Predicted handover, K8 = 0.00 (black dashed, + marker)