Handover trajectory in shared frame, n = 0, Robot: Taker
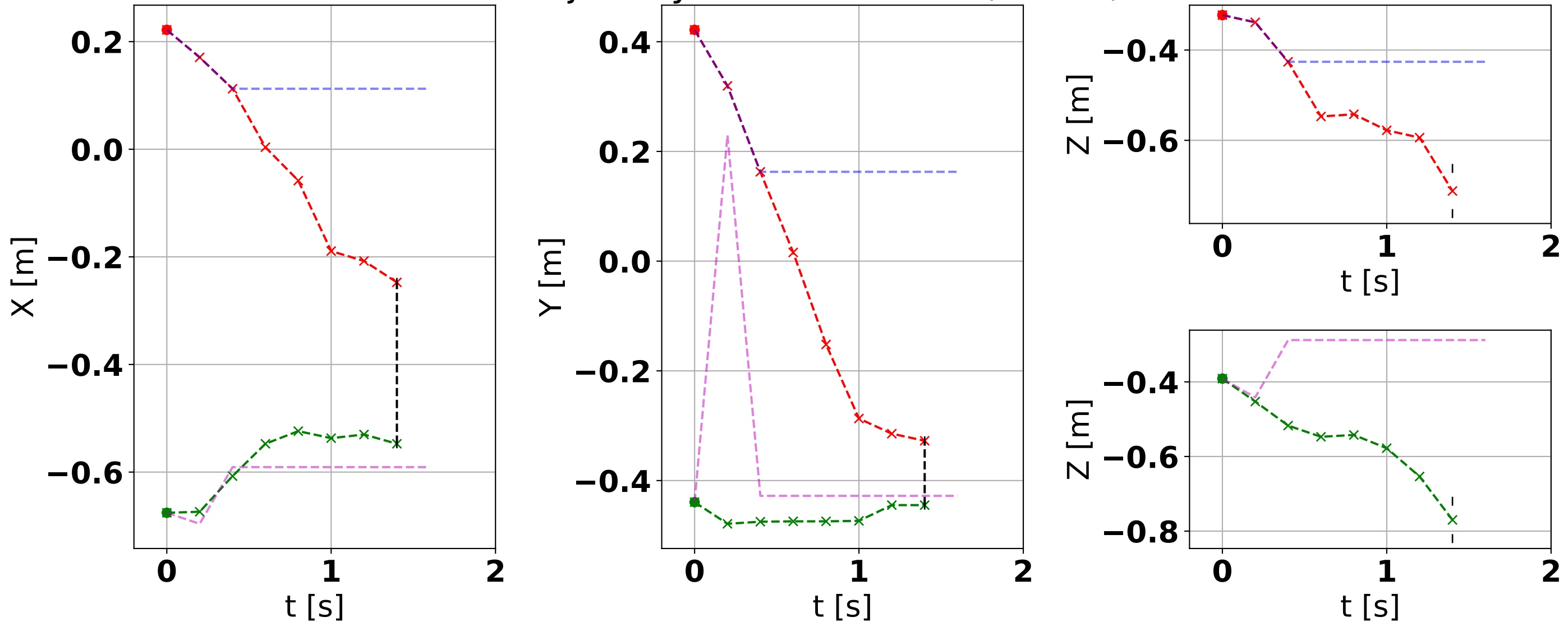
Legend:
- Human position
- Human plan
- Robot position
- Robot plan
- True human position
- True robot position
- Predicted handover, K7 = 0.07