Handover trajectory in shared frame, n = 0, Robot: Taker
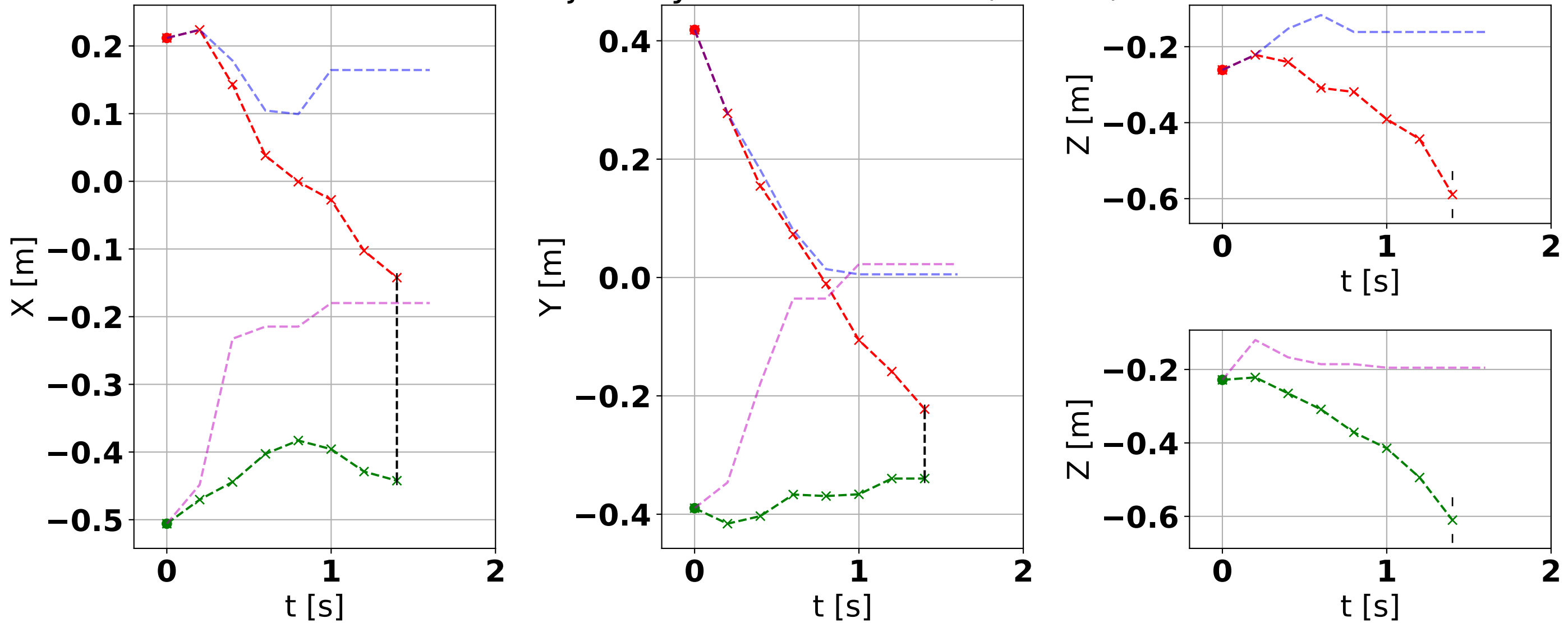
Legend:
- **Human position** (green solid with circle)
- **Human plan** (green dashed with x)
- **Robot position** (red solid with circle)
- **Robot plan** (red dashed with x)
- **True human position** (magenta dashed)
- **True robot position** (blue dashed)
- **Predicted handover, K7 = 0.04** (black dash-dot)