Handover trajectory in world frame, n = 3, Robot: Taker

Legend:
- **Human position** (green solid line with circles)
- **Human plan** (green dashed line with x markers)
- **Robot position** (red solid line with circles)
- **Robot plan** (red dashed line with x markers)
- **True human position** (pink dashed line)
- **True robot position** (blue dashed line)
- **Predicted handover, K4 = 0.10** (black dashed line with + markers)