Handover trajectory in shared frame, n = 2, Robot: Taker

Legend:
- Human position (solid green with dots)
- Human plan (dashed green with x)
- Robot position (solid red with dots)
- Robot plan (dashed red with x)
- True human position (dashed magenta)
- True robot position (dashed blue)
- Predicted handover, K6 = 0.01 (dashed black)