Handover trajectory in world frame, n = 5, Robot: Taker

Legend:
- **Human position** (green line with dots)
- **Human plan** (green dashed line with x markers)
- **Robot position** (red line with dots)
- **Robot plan** (red dashed line with x markers)
- **True human position** (magenta dashed line)
- **True robot position** (blue dashed line)
- **Predicted handover, K8 = 0.01** (black dashed line with + markers)