Handover trajectory in world frame, n = 3, Robot: Taker

Legend:
- Human position (green, solid line with dots)
- Human plan (green, dashed line with x markers)
- Robot position (red, solid line with dots)
- Robot plan (red, dashed line with x markers)
- True human position (magenta, dashed line)
- True robot position (blue, dashed line)
- Predicted handover, K7 = 0.01 (black, dashed line with + markers)