# Parakh M. Gupta

Visiting Scholar, Kumar Lab, Pennovation Center, University of Pennsylvania, – Philadelphia, PA, 19104.

□ +1 267-879-7081 • □ pmg95@seas.upenn.edu • www.parakhmgupta.com

### **Areas of interest**

vehicular robotics, legged robotics, aerial robotics, marine robotics, control algorithms, autonomous systems, flight controllers, mechanism design, CAD, internet-of-things, circuit design, microcontrollers, sensor interfacing.

### **Education**

### **BITS Pilani Hyderabad Campus**

Mechanical Engineering, B.E.(Hons.)

Thesis | ModQuad : Self-assembling modular flying robots.

**BITS Pilani Hyderabad Campus** 

Physics, M.Sc.(Hons.)

Thesis | ModQuad : Flying modular structure that can self-reconfigure in midair.

Hyderabad, India 2014 - 2019

Hyderabad, India

2014 - 2019

# **Work Experience**

# Kumar Lab, GRASP Labs, University of Pennsylvania

Philadelphia

Visiting Student Intern

July 2018-Present

- o ModQuad 2.0: A novel flying modular structure capable of self-reconfiguring mid-air.
- o **Position controller for DJI Tello :** A ROS-based position controller for DJI Tello using Tello SDK and Vicon motion capture system.
- o **LiDAR-based SLAM on Unmanned Ground Vehicle**: A ROS-based SLAM implementation using Google Cartographer coupled with Velodyne VLP-16 LiDAR on Clearpath Jackal.
- **165mm quadrotor platform**: Pixhawk based quadrotor capable of holding position using PX4Flow and a forward facing camera.

### **Publication and Posters**

- D. Saldaña, P. M. Gupta, V. Kumar, "An Inflight Self-disassembly Method for Aerial Modular Robots", RA-L/IROS, 2019 - under review.
- V. Sai, P. M. Gupta, S. Khandelwal, L. Modi, S. Wani, Sri Raj, Saumitra, "Anterior chamber depth and corneal thickness quantification using a slit-lamp and van herrick's technique." Srujana Center for Innovation Open House, Engineering the Eye Hackathon, (July 2, 2017) - Awarded 1st Prize.

### **Achievements and Awards**

- o MIT MediaLabs Hackathon Engineering the EYE '17: Winner.
- o Named in 25 under 25 by Campus Diaries : Science and Technology Category.
- o Mantra Innovator of the Year 2018 : BITS Alumni Association.

- o Whiz Kid 2014 Batch: Bon Voyage Awards, BITS Pilani Hyderabad Campus.
- o Indian Oil Start-up Fund : Finalist.
- o Ink Makers Makeathon Regional Round : Second Runner-up.
- Magneto Competition, IIT-Bombay : Finalist.
- LAW Follower Competition, BITS Pilani Hyderabad Campus: Second Runner-up(2014), Second Runner-up(2015).
- o iNavigate Competition, BITS Pilani Hyderabad Campus: Runner-up(2015).

### **Projects**

### Aerial Systems and Robots....

### **Quadrotor Flight Controller**

**BITS Hyderabad** 

A fully-custom flight controller capable of holding altitude and auto-levelling

Personal

Implementing  $I^2C$  to fetch IMU data, data fusion using complementary filter, PID control loop, tuning on custom-built rig.

### **Autonomous Pesticide Spraying Drone**

**BITS Hyderabad** 

An Ardupilot based quadrotor platform capable of spraying pesticide Guided by Dr. Kurra Suresh Analysis of spray nozzle and pump setup for optimum atomization, pressure, spray-width, and flow-rate

Thrust test on motor-propeller combinations | Configuring APM with Ardupilot and GPS Trajectory planning.

# Marine Robotics.

### Clearpath Heron: Unmanned Surface Vehicle

Scalar Lab

Trajectory planning, PID control, and depth data logging from river-bed. University of Pennsylvania Custom ROS package for trajectory planning, position control, and data logging for the robot to autonomously follow a trajectory and collect data for reconstruction of river-bed using Micron Echosounder.

#### Legged and Vehicular Robotics.....

#### **Dextroid the Biped**

**BITS Hyderabad** 

Bipedal robot capable of detecting and avoiding obstacles. Mechanical Dept. and Physics Dept.

Design and testing of mechanical structure, electrical circuits for power delivery, component selection, and writing walking algorithm.

#### The Magneto Robot

BITS Hyderabad

Wireless mobile robot capable of collecting and shooting balls

Personal

Design and construction of chassis, manipulator arm | Design and soldering of circuits for transmitter, receiver, motor-drive and control units.

### Biomedical Devices.

Anterior Chamber Depth and Corneal thickness measurement device(ACDC)

Hyderabad

MIT MediaLabs - ETE'17, Srujana Centre for Innovation

Hackathon

Design, rapid-prototyping, and fabrication of optical setup, lens holder, and face-mask to sit on user's head for focusing a narrow slit.

#### Low-cost Handheld Pneumonia monitor for Rural Children

BITS Hyderabad

Collaboration with MediCiti Hospitals, and Indian Council of Medical Research Under Prof. M. B. Srinivas Designing and testing of 16-bit ADC data sampling at 4 KHz, first-stage amplifier using trans-impedance op-amp, second-stage amplifier using op-amp for 20x amplification, filtering circuit, SPI-based flash storage for rapid storage.

### Other Projects.....

- o Online temperature logger for automatic monitoring and cooling of solar panel.
- o Wirelessly controlled room lock using ESP8266 module.
- o PID control algorithm based self-balancing two-wheeled ground-robot.
- o Ising model simulation for a square ferromagnetic lattice using the Metropolis algorithm on MATLAB.

### **Technical skills**

- Programming: Arduino (Advanced), C (Intermediate), MATLAB (Intermediate), Python (Beginner), ROS (Intermediate).
- o Industry Software: SolidWorks (Intermediate), EagleCAD (Beginner).
- o Hardware Skills: Sensor Interfacing (Advanced), Circuit Design (Advanced), PCB Design (Beginner).
- Other Skills: Awesome soldering skills.

## Position of Responsibility

- o Mentor: Student Mentorship Program Robotics, BITS Pilani Hyderabad Campus.
- o Co-Founder: Automation and Robotics Club, BITS Pilani Hyderabad Campus.
- o Co-Founder: Aero Club, BITS Pilani Hyderabad Campus.
- o Founder: Technopedia Documentation Blog, BITS Pilani Hyderabad Campus.
- o Recording Team Lead: Dept. of Visual Effects, BITS Pilani Hyderabad Campus.