Parallel Sort

Parallel and Distributed Computing

Department of Computer Science and Engineering (DEI) Instituto Superior Técnico

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Outline

Parallel Sort

- Hyperquicksort
- PSRS, Parallel Sorting by Regular Sampling
- Odd-Even Transposition Sort

Sorting Problem

Sorting Problem

Given an unordered sequence, obtain an ordered one through permutations of the elements in the sequence.

Typically the value being sorted (key) is part of record with additional values (satellite data).

Efficiency of sorting is particularly important as it is used as part of many algorithms.

Sorting Algorithms

Name	Average	Worst	Memory	Stable	
Bubble sort	$O(n^2)$	$O(n^2)$	O(1)	Yes	
Selection sort	$O(n^2)$	$O(n^2)$	O(1)	No	
Insertion sort	$O(n^2)$	$O(n^2)$	O(1)	Yes	
Merge sort	$O(n \log n)$	$O(n \log n)$	O(n)	Yes	
Heapsort	$O(n \log n)$	$O(n \log n)$	O(1)	No	
Quicksort	$O(n \log n)$	$O(n^2)$	$O(n \log n)$	No	

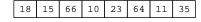
Sorting Algorithms

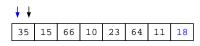
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Merge sort	$O(n \log n)$	$O(n \log n)$	O(n)	Yes		
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Quicksort	$O(n \log n)$	$O(n^2)$	$O(n \log n)$	No		

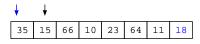
Smaller hidden constants in Quicksort make it popular.

```
procedure quicksort(array, left, right)
  if right > left
    select a pivot index (e.g. pivotIndex := left)
    pivotNewIndex := partition(array, left, right, pivotIndex)
    quicksort(array, left, pivotNewIndex - 1)
    quicksort(array, pivotNewIndex + 1, right)
```

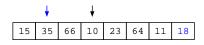
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         pivotNewIndex := partition(array, left, right, pivotIndex)
         quicksort(array, left, pivotNewIndex - 1)
         quicksort(array, pivotNewIndex + 1, right)
function partition(array, left, right, pivotIndex)
     pivotValue := array[pivotIndex]
     swap array[pivotIndex] and array[right] // Move pivot to end
     storeIndex := left
     for i from left to right - 1
         if array[i] <= pivotValue</pre>
             swap array[i] and array[storeIndex]
             storeIndex := storeIndex + 1
     // Move pivot to its final place
     swap array[storeIndex] and array[right]
     return storeIndex
```

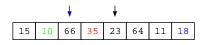




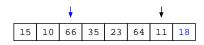




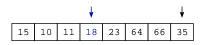


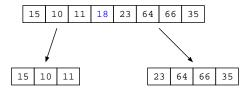


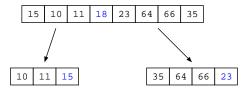


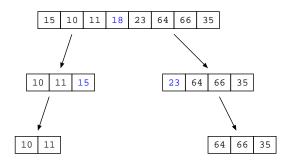


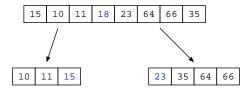


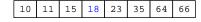




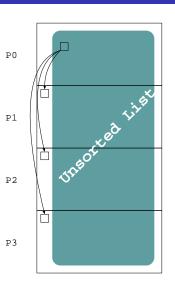




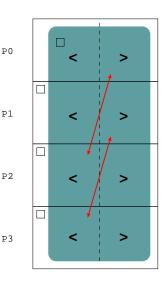




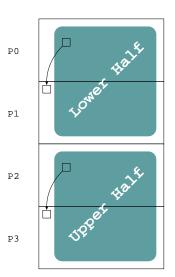
one process broadcast initial pivot to all processes



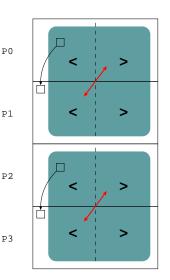
- one process broadcast initial pivot to all processes
- each process in the upper half swaps with a partner in the lower half



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- 3 recurse on each half



- one process broadcast initial pivot to all processes
- each process in the upper half swaps with a partner in the lower half
- recurse on each half
- swap among partners in each half



one process broadcast initial pivot to all processes

each process in the upper half swaps with a partner in the lower half

recurse on each half

swap among partners in each half

 each process uses quicksort on local elements

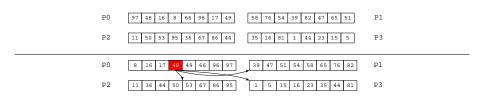
1st quarter P02nd quarter Р1 3rd quarter P2 4th quarter P3

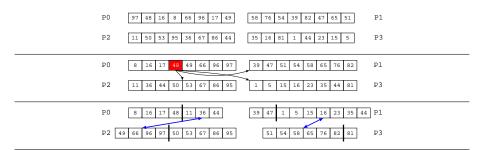
Limitation of parallel quicksort: poor balancing of list sizes.

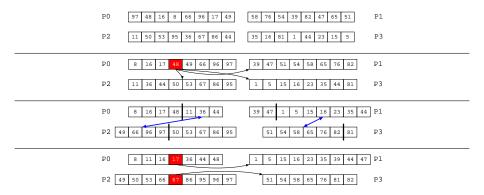
Hyperquicksort: sort elements before broadcasting pivot.

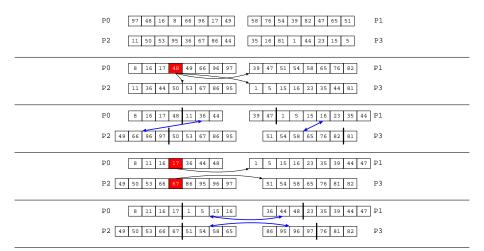
- sort elements in each process
- 2 select median as pivot element and broadcast it
- each process in the upper half swaps with a partner in the lower half
- recurse on each half

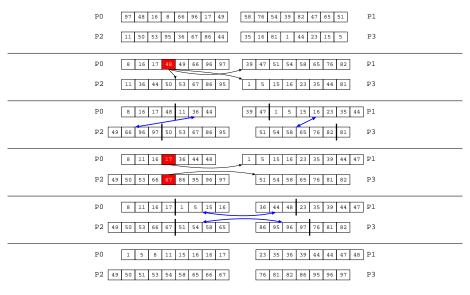
P0	97	48	16	8	66	96	17	49	58	76	54	39	82	47	65	51	P1
P2	11	50	53	95	36	67	86	44	35	16	81	1	44	23	15	5	Р3











Complexity Analysis of Hyperquicksort

- sort elements in each process
- select median as pivot element and broadcast it
- each process in the upper half swaps with a partner in the lower half
- recurse on each half

Computation complexity:

initial quicksort step:

Complexity Analysis of Hyperquicksort

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- select median as pivot element and broadcast it
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- recurse on each half

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- remaining sorts:

- sort elements in each process
- select median as pivot element and broadcast it
- each process in the upper half swaps with a partner in the lower half
- recurse on each half

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- remaining sorts: $O(\frac{n}{p})$

Communication time:

• pivot broadcast:

- sort elements in each process
- select median as pivot element and broadcast it
- each process in the upper half swaps with a partner in the lower half
- recurse on each half

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- remaining sorts: $O(\frac{n}{p})$

Communication time:

- pivot broadcast: $O(\log p)$
- array exchange:

- sort elements in each process
- select median as pivot element and broadcast it
- each process in the upper half swaps with a partner in the lower half
- recurse on each half

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- remaining sorts: $O(\frac{n}{p})$

Communication time:

- pivot broadcast: $O(\log p)$
- array exchange: $O(\frac{n}{p})$

Number of iterations:



- sort elements in each process
- select median as pivot element and broadcast it
- each process in the upper half swaps with a partner in the lower half
- recurse on each half

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- remaining sorts: $O(\frac{n}{p})$

Communication time:

- pivot broadcast: $O(\log p)$
- array exchange: $O(\frac{n}{p})$

Number of iterations: $\log p$

Total time: $O(\frac{n}{p} \log n)$ $n \gg p$



Isoefficiency analysis: $T(n,1) \ge CT_0(n,p)$

(T(n,1) sequential time; $T_0(n,p)$ parallel overhead)

Sequential time complexity: $T(n,1) = O(n \log n)$

Parallel overhead dominated by exchanges: $O(\frac{n}{p} \log p)$

$$T_0(n,p) = p \times O(\frac{n}{p}\log p) = O(n\log p)$$

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 $n \log n \ge C n \log p \quad \Rightarrow \quad n \ge p^C$

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Scalability function:
$$M(f(p))/p$$

$$M(n) = n \quad \Rightarrow \quad \frac{M(p^C)}{p} = p^{C-1}$$

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 \Rightarrow Scalability is only good for $C \leq 2$.



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 \Rightarrow Scalability is only good for $C \leq 2$.

$$C = \frac{\varepsilon(n,p)}{1-\varepsilon(n,p)} \le 2 \Rightarrow \varepsilon(n,p) \le \frac{2}{3}$$

Cannot maintain high efficiency!



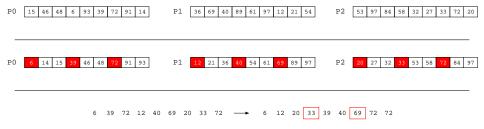
Limitations on the Scalability of Hyperquicksort

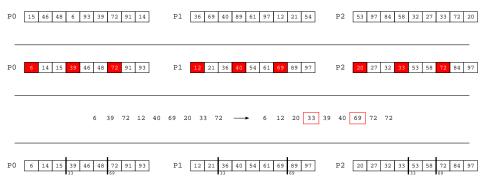
- analysis assumes lists remain balanced
- as p increases, each processor's share of list decreases
- hence, as p increases, likelihood of lists becoming unbalanced increases
- unbalanced lists lowers efficiency

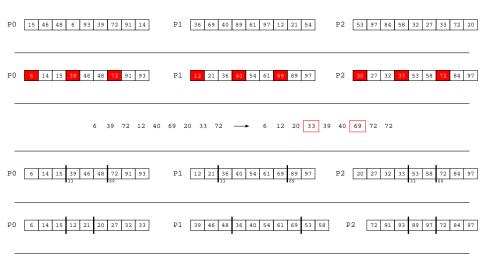
A better solution is to get sample values from all processes before choosing median.

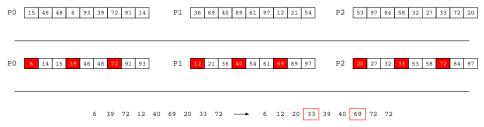
- each process sorts its share of elements
- each process selects regular samples of sorted list
- one process gathers and sorts samples, chooses pivot values from sorted sample list, and broadcasts these pivot values
- each process partitions its list into p pieces, using pivot values
- each process sends partitions to other processes
- each process merges its partitions

PO 15 46 48 6 93 39 72 91 14 P1 36 69 40 89 61 97 12 21 54 P2 53 97 84 58 32 27 33 72 20









- P1 12 21 36 40 54 61 69 89 97 P2 20 27 32 33 53 58 72 84 97 6 14 15 39 46 48 72 91 93
- P1 39 46 48 36 40 54 61 69 53 58 P2 72 91 93 89 97 72 84 97 P0 6 14 15 12 21 20 27 32 33

Computation complexity:

initial quicksort step:

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- sorting samples:

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- sorting samples: $O(p^2 \log p)$
- merging subarrays:

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- sorting samples: $O(p^2 \log p)$
- merging subarrays: $O(\frac{n}{p} \log p)$

Communication time:

gather samples:

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- sorting samples: $O(p^2 \log p)$
- merging subarrays: $O(\frac{n}{p} \log p)$

Communication time:

- gather samples: $O(p \log p)$
- pivot broadcast:

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- sorting samples: $O(p^2 \log p)$
- merging subarrays: $O(\frac{n}{p} \log p)$

Communication time:

- gather samples: $O(p \log p)$
- pivot broadcast: $O(p \log p)$
- array exchange:

Computation complexity:

- initial quicksort step: $O(\frac{n}{p}\log \frac{n}{p})$
- sorting samples: $O(p^2 \log p)$
- merging subarrays: $O(\frac{n}{p} \log p)$

Communication time:

- gather samples: $O(p \log p)$
- pivot broadcast: $O(p \log p)$
- array exchange: $O(\frac{n}{p})$

Total time: $O(\frac{n}{p} \log n)$

Isoefficiency Analysis of PSRS

Isoefficiency analysis: $T(n,1) \ge CT_0(n,p)$

Sequential time complexity: $T(n, 1) = O(n \log n)$

Parallel overhead:

communication dominated by exchanges: $O(\frac{n}{p})$ redundant computation of last merge: $O(\frac{n}{p}\log p)$

$$T_0(n,p) = p \times O(\frac{n}{p}\log p) = O(n\log p)$$

$$n \log n \ge C n \log p \quad \Rightarrow \quad n \ge p^C$$

Scalability function: M(f(p))/p

$$M(n) = n \quad \Rightarrow \quad \frac{M(p^{C})}{p} = p^{C-1}$$

⇒ Same scalability as hyperquicksort.



Comparison of Parallel QuickSorting Algorithms

Three parallel algorithms based on quicksort.

Keeping list sizes balanced:

- Parallel quicksort: poor
- Hyperquicksort: better
- PSRS algorithm: excellent

Average number of times each key moved:

- ullet Parallel quicksort and hyperquicksort: $\frac{\log p}{2}$
- PSRS algorithm: $\frac{p-1}{p}$

Odd-Even Transposition Sort

- Based on Bubble Sort
- Consists of two distinct phases:

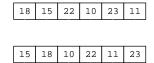
```
Even phase compare and swaps are executed on pairs (a[0],a[1]); (a[2],a[3]); (a[4],a[5]);...
```

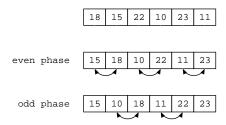
Odd phase

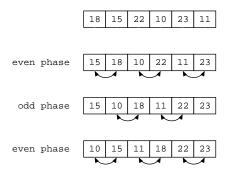
```
compare and swaps are executed on pairs (a[1],a[2]); (a[3],a[4]); (a[5],a[6]);...
```

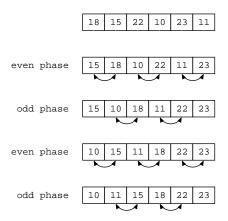
• Sorting is complete after at most *n* phases

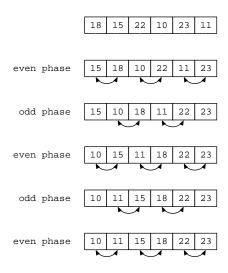
18 15 22 10 23 11











Odd-Even Transposition Sort Program

```
void Odd_even_sort(int a[], int n)
  int phase, i;
  for (phase = 0; phase < n; phase++)</pre>
    if (phase % 2 == 0) /* even phase */
      for (i = 1; i < n; i += 2)
        if (a[i-1] > a[i])
          swap(&a[i], &a[i-1]);
    else /* odd phase */
      for (i = 1; i < n-1; i += 2)
        if (a[i] > a[i+1])
          swap(&a[i], &a[i+1]);
```

Odd-Even Transposition Sort Program

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Complexity of sequencial algorihtm:

Odd-Even Transposition Sort Program

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          swap(&a[i], &a[i+1]);
}
```

Complexity of sequencial algorihtm: $O(n^2)$

Can we do better in the parallel algorithm?

Partitioning:

Partitioning:

Primitive task is to determine value of a[i] at the end of each phase

Partitioning:

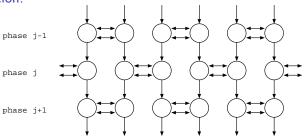
Primitive task is to determine value of a[i] at the end of each phase

Communication:

Partitioning:

Primitive task is to determine value of a[i] at the end of each phase

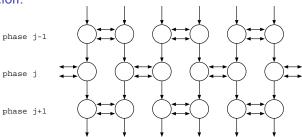
Communication:



Partitioning:

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Communication:

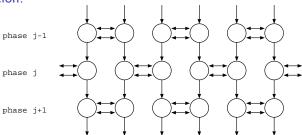


Aglomeration and Mapping:

Partitioning:

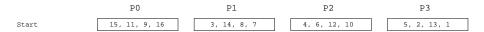
Primitive task is to determine value of a[i] at the end of each phase

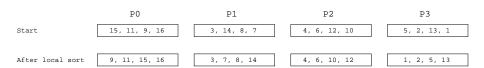
Communication:

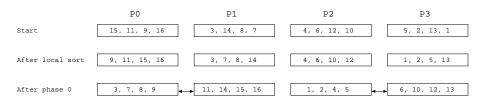


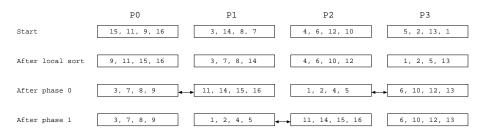
Aglomeration and Mapping:

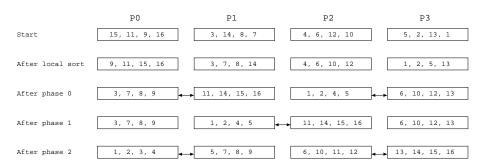
Distibute values of array through processors

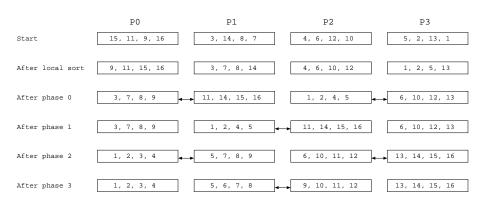












- sort elements in each process
- send/receive values to/from partner process
- if rank of process is smaller than rank of partner then keep smaller values
- otherwise keep larger values

Computational complexity:

• initial quicksort:

- sort elements in each process
- send/receive values to/from partner process
- if rank of process is smaller than rank of partner then keep smaller values
- otherwise keep larger values

Computational complexity:

- initial quicksort: $O(\frac{n}{p}\log\frac{n}{p})$
- sorting smaller/larger values in each phase:

- sort elements in each process
- send/receive values to/from partner process
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Computational complexity:

- initial quicksort: $O(\frac{n}{p}\log\frac{n}{p})$
- sorting smaller/larger values in each phase: $O(\frac{n}{p})$

Communication time:

Sending/receving values in each phase:

- sort elements in each process
- send/receive values to/from partner process
- if rank of process is smaller than rank of partner then keep smaller values
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Computational complexity:

- initial quicksort: $O(\frac{n}{p}\log\frac{n}{p})$
- sorting smaller/larger values in each phase: $O(\frac{n}{p})$

Communication time:

• Sending/receving values in each phase: $O(\frac{n}{p})$

Number of phases:



- sort elements in each process
- send/receive values to/from partner process
- if rank of process is smaller than rank of partner then keep smaller values
- otherwise keep larger values

Computational complexity:

- initial quicksort: $O(\frac{n}{p}\log\frac{n}{p})$
- sorting smaller/larger values in each phase: $O(\frac{n}{p})$

Communication time:

• Sending/receving values in each phase: $O(\frac{n}{p})$

Number of phases: p

Total time: $O(\frac{n}{n}\log n + n)$



Isoefficiency Analysis of Odd-Even Sort

Isoefficiency analysis: $T(n,1) \ge CT_0(n,p)$

Sequential time complexity: $T(n,1) = O(n \log n)$

Parallel overhead dominated by exchanges: O(n)

$$T_0(n,p) = p \times O(n) = O(pn)$$

$$n \log n \ge Cpn \quad \Rightarrow \quad n \ge e^{Cp}$$

Scalability function: M(f(p))/p

$$M(n) = n \quad \Rightarrow \quad \frac{M(e^{Cp})}{p} = \frac{e^{Cp}}{p}$$

⇒ Poor scalability.



Comparison of Parallel Sorting Algorithms

Hyperquicksort

Total time: $O(\frac{n}{p} \log n)$

Scalability function: p^{C-1}

 \Rightarrow Scalability is only good for $C \leq 2$.

PSRS

Total time: $O(\frac{n}{p} \log n)$

Scalability function: p^{C-1}

⇒ Same scalability as hyperquicksort.

Odd-Even Sort

Total time: $O(\frac{n}{p} \log n + n)$

Scalability function: $\frac{e^{Cp}}{p}$

⇒ Poor scalability.

Review

Parallel Sort

- Hyperquicksort
- PSRS, Parallel Sorting by Regular Sampling
- Odd-Even Transposition Sort

Next Class

• Efficient parallelization of numerical algorithms