

ELECTIONS AND CLIMATE ATTITUDES: HOW DO PEOPLE'S VIEWS ON CLIMATE CHANGE AND POLICIES SHIFT DURING AN ELECTION?

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ABSTRACT

This thesis examines the impact of elections on climate change attitudes and policy support. Using a data set of 5,667 survey responses collected over 3 waves, we apply two complementary temporal methods: a PVAR model (panel vector autoregression) and the PCMCi+ (Peter and Clark Momentary Conditional Independence). Although PVAR models the linear dynamic structure of climate-related attitudes, PCMCi+ enables the data-driven discovery of causal links over time. By comparing their results, we assess how climate perceptions, willingness to pay for climate solutions, and support for specific climate policies evolve around the 2020 US elections. Our findings show that climate views stay mostly stable, but some changes in perceived harm and policy support happen around elections. Political beliefs also shape how much people are willing to pay for climate action. The study contributes to understanding how politics shape public opinion on climate issues, offering insights for policymakers and researchers.

CCS CONCEPTS

• Mathematics of computing → Time series analysis.

KEYWORDS

climate change, elections, causal data science, PCMCi+, PVAR

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GITHUB REPOSITORY

The code used for the analysis in this thesis is available at: <https://github.com/paraskevasleivadaros/climate-opinions-and-elections>

1 INTRODUCTION

This paper explores the relationship between political events, policies, and society's attitudes toward climate change. Climate change is one of the most important global challenges at the moment. For this reason, understanding how elections and policies shape public opinion is crucial. This knowledge is important for policy makers and researchers who need to get the public involved in tackling climate change.

How Do People's Views on Climate Change and Policies Change During an Election?

The research question can be answered by examining people's opinions towards climate change and related policies during the 2020 US elections. The following sub-questions will guide our analysis:

RQ1. Does support for climate policies (like carbon taxes or emissions standards) change during elections? And is this support influenced by personal or community-level perceptions of climate harm?

RQ2. Does willingness to pay for climate solutions vary during elections and what factors influence it?

RQ3. Does political ideology moderate the relationship between perceptions of harm and willingness to pay?

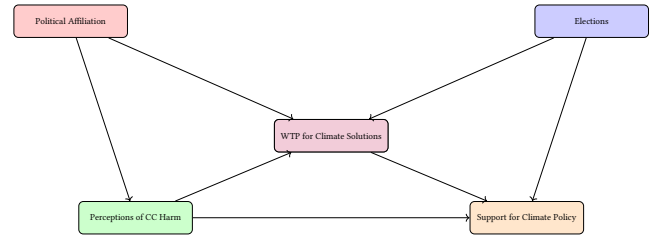


Figure 1: Conceptual Model: Key Relationships Based on Research Questions

2 RELATED WORK

This section reviews previous research on the relationship between elections, climate perceptions, and policy support.

Hahnel et al., 2020 [2] found that when political leaders frame climate change as a divisive issue, public opinion becomes polarized on perceptions of climate harm. Similarly, Fisher (2022) [3] found that different ideologies influence how different parties assess climate risks, with left-leaning voters more likely to express concern for vulnerable populations (e.g., poor communities) than right-leaning voters. Given these findings, our study examines whether perceived harm to poor or wealthy communities changes during elections.

Fisher also found that ideological polarization influences whether people translate perceptions of climate risk into policy preferences. Studies on voter behavior suggest that Democrats are more likely to convert climate concern into higher WTP for solutions compared to Republicans. Based on this, our study investigates whether political affiliation moderates the effect of perceived harm on WTP during elections.

Schulze et al. (2021) [10] found that willingness to pay (WTP) for climate policies declines in pre-election periods, as voters become more sensitive to financial costs. Research suggests that conservatives are generally less supportive of costly interventions, but may express higher WTP when policies are framed as benefiting local communities or economic stability. Ogami (2024) [7] found that voters tend to prioritize low-cost climate solutions closer to elections due to economic concerns influenced by campaign rhetoric. Based on these findings, our study examines whether elections shape WTP for climate solutions.

The CIRES study on the opinions on climate change during elections [1] found that Democrats consistently express greater support for climate policies, such as carbon taxes, while Republicans remain more resistant. Similarly, Ogami explains that politicians often avoid promoting polarizing policies, such as carbon taxes, in the lead-up to elections to minimize losing voters. The CIRES study also found that people experiencing direct climate impacts, such as extreme weather events, tend to support pro-climate candidates and policy measures. Based on this, our study examines whether support for specific policies changes during elections and whether these shifts are influenced by political affiliation or perceptions of family health and economic well-being.

3 METHODOLOGY

3.1 Resources

Previous research has shown that elections influence climate attitudes and policy support, but the direction and magnitude of these effects are unclear. This study addresses that gap by applying two temporal methods: PVAR and the PCMCi+ algorithm. Although PVAR captures dynamic interdependencies among variables over time under parametric assumptions, PCMCi+ offers a data-driven approach to uncover causal relationships from time series. Using the Tigramite Python package [8], we will try to identify the causal impact of elections on climate perceptions, WTP and support for climate policies.

The primary resource for this study is a longitudinal data set consisting of survey responses from 1,889 participants collected over 3 waves from June 2020 to August 2021. Table 1 provides an overview of the key variables included in the dataset and groups them according to their thematic role in the analysis.

Variable	Description
Climate Change Perception (cc4_*)	
cc4_world	Perceived harm of climate change on the world
cc4_wealthUS	Perceived harm on wealthy U.S. communities
cc4_poorUS	Perceived harm on poor U.S. communities
cc4_comm	Perceived harm on local communities
cc4_famheal	Perceived harm on family health
cc4_famecon	Perceived harm on family economy
WTP (ccSolve*)	
ccSolve100	Support for policies at \$100/month
ccSolve50	Support for policies at \$50/month
ccSolve10	Support for policies at \$10/month
ccSolve1	Support for policies at \$1/month
ccSolve0	Support for policies (no cost specified)
Climate Policy Support (cc_pol_*)	
cc_pol_tax	Support for a carbon tax
cc_pol_car	Support for stricter car emissions
Political Affiliation and Ideology (pol_*)	
pol_party	Political party identification (Rep, Dem, Ind)
pol_lean	Political party leaning (Lean Rep, Lean Dem)
pol_ideology	Political ideology (Conservative, Moderate, Liberal)
Demographics (dem_*)	
dem_income	Respondent's reported income level
dem_male	Respondent's gender
dem_age	Respondent's age
dem_educ	Respondent's education level

Table 1: Description of Key Variables (raw data)

Table 2 summarizes the response options and coding for key variables used in the analysis.

Variable	Coding	Response Scale
cc4_*	1 to 4	Not at all to A great deal
ccSolve*	1 to 5	Strongly disapprove to Strongly approve
cc_pol_*	1 to 5	Strongly oppose to Strongly support
pol_party	1 to 3	Republican, Democrat, Independent
pol_lean	1 to 4	Leaning Rep., Leaning Dem., Neither
pol_ideology	1 to 5	Very conservative to Very liberal
dem_income	1 to 6	<\$25k to >\$200k
dem_educ	1 to 6	<High School to Advanced degree
dem_age	18 to 99	Age in years
dem_male	0, 1, 77	Female, Male, Self-described

Table 2: Variable coding and response scales (raw data)

Table 3 provides summary statistics for all variables in the dataset prior to filtering. For each variable, the table reports the number and percentage of missing values, as well as key distribution metrics: mean, standard deviation, and the five-number summary (minimum, 25th percentile, median, 75th percentile, and maximum).

Variable	NA%	Mean	SD	P0	P25	P50	P75	P100
cc4_world	0.00%	2.971	0.994	1	2	3	4	4
cc4_wealthUS	0.00%	2.336	1.010	1	2	2	3	4
cc4_poorUS	0.00%	2.797	1.053	1	2	3	4	4
cc4_comm	0.00%	2.464	0.988	1	2	2	3	4
cc4_famheal	0.00%	2.262	1.010	1	1	2	3	4
cc4_famecon	0.00%	1.959	1.021	1	1	2	3	4
ccSolve100	79.78%	2.469	1.261	1	1	2.5	3	5
ccSolve50	80.04%	2.606	1.287	1	1	3	4	5
ccSolve10	80.27%	2.959	1.327	1	2	3	4	5
ccSolve1	80.15%	3.309	1.367	1	3	3	4	5
ccSolve0	79.76%	3.402	1.275	1	3	4	4	5
cc_pol_tax	0.44%	3.193	1.314	1	2	3	4	5
cc_pol_car	0.44%	3.717	1.230	1	3	4	5	5
pol_party	0.00%	2.016	0.789	1	1	2	3	3
pol_lean	68.08%	2.758	1.265	1	2	2	4	4
pol_ideology	0.00%	2.887	1.068	1	2	3	3	5
dem_income	0.00%	3.314	1.543	1	2	3	5	6
dem_educ	0.00%	3.611	1.601	1	2	3	5	6
dem_age	0.00%	54.28	15.16	18	42	56	67	93
dem_male	0.00%	0.617	3.250	0	0	0	1	77

Table 3: Data Summary (raw data)

To complement the summary statistics above, Figure 2 visualizes the distribution of key variables (raw data).

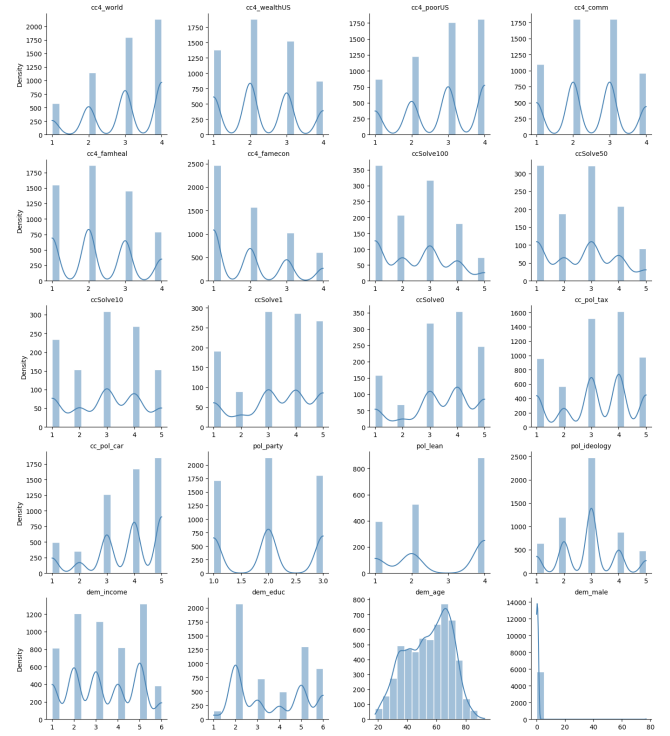


Figure 2: Distributions with Density Overlay (raw data)

3.2 Approach

To analyze how climate attitudes change during elections, we apply two complementary time series methods: a PVAR model [4] and the PCMCI+ causal discovery algorithm [9].

PVAR models are well suited for analyzing systems of interdependent variables in panel data. Each variable is modeled as a function of its own lag and the lags of all other variables. This allows us to capture bidirectional feedback dynamics across time, making it ideal for understanding how climate concern, policy support, and political attitudes influence one another longitudinally [6].

PCMCI+ is a constraint-based causal discovery method designed for time series data. It relies on conditional independence (CI) testing to infer the presence or absence of lagged causal relationships between variables. While PCMCI+ supports nonparametric CI tests such as GPDC or CMlknn, we use linear partial correlation (Par-Corr) tests, given the short panel length ($T = 3$) in our data [9].

Traditional approaches, such as pooled OLS or fixed-effects regressions, assume unidirectional influence and do not account for dynamic feedback loops. They may estimate average associations over time but cannot adequately model temporal causality or mutual interdependence among variables. By contrast, both PVAR and PCMCI+ allow for bidirectional, time-lagged relationships that better reflect the evolving nature of public opinion during elections.

This thesis contributes methodologically by combining a dynamic system-based model (PVAR) with a causal graph discovery framework (PCMCI+) - a combination not previously applied in the context of climate policy attitudes shifts in election periods.

The PVAR model produces directed graphs that represent significant lagged effects between variables. PCMCI+ outputs a causal graph based on conditional independence tests. We compare these two graphs qualitatively to assess the robustness of temporal relationships.

Table 4 maps each survey wave to the research questions it informs.

Wave	Research Questions Addressed
Wave 2	Provides baseline values for all lagged predictors
Wave 3	Captures dynamics during the election
Wave 4	Allows continued observation of attitudes after election

Table 4: Timeline structure and relevance of each wave

The implementation relied entirely on open-source Python packages. Table 5 lists the key packages used throughout the analysis.

Tool/Library	Purpose
graphviz	Rendering directed acyclic graphs (DAGs)
matplotlib	Static plotting
networkx	Construction and layout of causal graphs
numpy	Numerical operations and array handling
pandas	Data manipulation and panel structuring
plotly	Interactive network visualizations
seaborn	Statistical graphics for EDA
skimpy	Quick summaries and data diagnostics
statsmodels	PVAR estimation
tigramite	Time-lagged causal discovery (PCMCI+)

Table 5: Software Tools Used in the Analysis

3.3 Steps

The process begins with preparing the panel dataset and estimating PVAR models to explore the temporal dynamics of climate attitudes followed by the application of a causal graph algorithm in the final step. An overview of these main stages is provided in Figure 3.

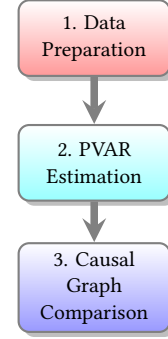


Figure 3: Overview of the main analytical steps in the study

3.3.1 Data Preparation. Several variables of harm perception were originally recorded on different Likert scales (some 1–4, others 1–6). These were linearly transformed to a common scale of 1 to 5 so that all predictors could be compared on the same scale.

The `pol_party` and `pol_lean` variables were merged into a single `pol_score` variable to create a continuous scale of political alignment from left to right. This scale ranges from -2 (strong Democrat) to 2 (strong Republican). For those who identified as Independents (`pol_party = 3`), their placement depended on their lean: those leaning Democrat (`pol_lean = 2`) received a score of -1, those leaning Republican (`pol_lean = 1`) received a 1, and those who leaned neither way (`pol_lean = 4`) were assigned a neutral score of 0.

Missing values in the two policy support variables (`cc_pol_tax`, `cc_pol_car`) were filled with the neutral midpoint (value 3). WTP variables (`ccSolve100`, `ccSolve50`, etc.) were combined into a single, scaled measure (`ccSolve`), rescaled to a 1–5 scale based on dollar weighting. Rows with no WTP response were excluded.

To enable comparisons between subgroups, three demographic variables were recoded into binary format, as shown in Table 6.

Variable	Binary Recoding Rule
<code>dem_income</code>	Low income (1–4) recoded as 0 High income (5–6) recoded as 1
<code>dem_educ</code>	Non-advanced degrees (1–5) recoded as 0 Advanced degree (6) recoded as 1
<code>dem_male</code>	Female (0) and self-described (77) recoded as 0 Male (1) recoded as 1

Table 6: Binary Recoding of Demographic Variables

The data set was reshaped into a long format indexed by respondent ID and wave number (2, 3, and 4). Lagged versions of all time-varying variables were created for PVAR and causal modeling.

Table 7 summarizes the descriptive statistics of the key variables in the data set after filtering.

Variable	NA%	Mean	SD	P0	P25	P50	P75	P100
cc4_world	0.00%	3.643	1.308	1	2.33	3.67	5.00	5
cc4_wealthUS	0.00%	2.767	1.350	1	2.33	2.33	3.67	5
cc4_poorUS	0.00%	3.401	1.407	1	2.33	3.67	5.00	5
cc4_comm	0.00%	2.932	1.310	1	2.33	2.33	3.67	5
cc4_famheal	0.00%	2.664	1.321	1	1.00	2.33	3.67	5
cc4_famecon	0.00%	2.245	1.337	1	1.00	2.33	3.67	5
ccSolve	0.00%	1.732	0.9707	1	1.00	1.00	2.00	5
cc_pol_tax	0.00%	3.182	1.299	1	2.00	3.00	4.00	5
cc_pol_car	0.00%	3.713	1.218	1	3.00	4.00	5.00	5
pol_score	0.00%	-0.1754	1.697	-2	-2.00	0.00	2.00	2
pol_ideology	0.00%	2.886	1.054	1	2.00	3.00	3.00	5
dem_income	0.00%	0.3043	0.4602	0	0.00	0.00	1.00	1
dem_educ	0.00%	0.1409	0.348	0	0.00	0.00	0.00	1
dem_age	0.00%	55.47	14.80	19	43.00	58.00	67.00	93
dem_male	0.00%	0.4766	0.4995	0	0.00	0.00	1.00	1

Table 7: Data Summary (after filtering)

To complement the summary statistics above, Figure 4 visualizes the distribution of key variables (after filtering).

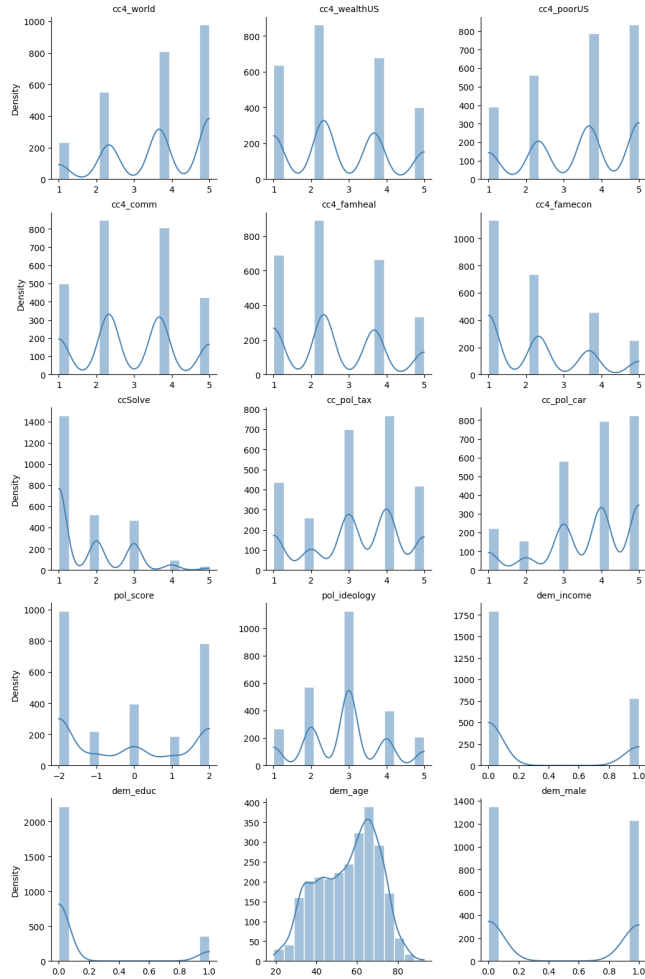


Figure 4: Distributions with Density Overlay (after filtering)

While the dataset includes 861 respondents in three waves, it may not fully represent the broader US population. To mitigate potential bias in age, income and education, demographic variables were inspected for distributional imbalances, and binary groups were constructed to ensure that each category reflected balanced splits. This reduces the risk of biased estimates due to skewed sampling. Although demographic controls are included in the analysis, the results should be viewed as indicative of broader trends rather than as fully generalizable to the national population.

3.3.2 PVAR Estimation. Estimate global PVAR(1) models. The model for *RQ1* (whether support for climate policies changes during elections and whether it is influenced by harm perception) focuses on policy support (cc_pol_tax, cc_pol_car) as dependent variables and uses all the variables as predictors (including the dependent variables). The model for *RQ2* (how WTP is shaped by related attitudes over time) focuses on WTP (cc_Solve) as the dependent variable and uses all the variables as predictors (including the dependent variable).

3.3.3 Causal Graph Comparison. Apply the PCMCi+ algorithm using the Tigramite Python package. This method identifies potential causal links through time-lagged conditional independence tests, providing a complementary, data-driven perspective to the PVAR results.

3.4 Evaluation

The evaluation of results is organized around 3 research questions and uses a combination of global PVAR(1) models and causal graph discovery. These models allow us to examine how climate attitudes, political identity, and demographic factors influence support for climate policies and WTP over time, including the elections.

Policy Support Shifts (RQ1): First, estimate global PVAR(1) models where the dependent variables are support for carbon taxes and emissions standards (cc_pol_tax, cc_pol_car). Second, include as predictors the lagged values of all the variables such as harm perception variables (cc4_*), WTP (ccSolve), political identity (pol_score), and demographic controls (dem_income, dem_male, dem_age, dem_educ). Third, estimate all variables as jointly endogenous within each equation, using pooled OLS with clustered standard errors. Finally, assess how policy support evolves over time and whether it is influenced by perceptions of harm.

WTP Over Time (RQ2): First, estimate a global PVAR(1) model where ccSolve is the dependent variable and is regressed due to its own lag, lagged policy support, perception of harm, political identity, and demographics. Second, evaluate the stability of the WTP over time and whether it changes throughout the election period. Third, identify which predictors (e.g., policy support, perception of global harm, ideology) consistently explain variation in WTP.

Ideological Moderation (RQ3): First, estimate a pooled OLS model with interaction terms between political ideology and each harm perception variable. Second, assess whether the strength of the relationship between perceived climate harm and WTP varies by ideological group. Third, determine if liberals, moderates, or conservatives respond differently to perceived climate threats when forming their willingness to financially support solutions.

Cross-Method Comparison: Start by applying the PCMCi+ algorithm using the Tigramite package to estimate a time-lagged causal graph from the panel data. And finish by comparing the structure and direction of key paths (e.g. harm \rightarrow support, ideology \rightarrow WTP) with those found in the PVAR models to assess consistency and gain deeper insight into causal structure.

To assess the reliability of our causal estimates, we performed bootstrapping checks. Since algorithms like PCMCi+ can be sensitive to small changes in the data, we reran it on bootstrapped subsets to test the stability of the discovered links. Similarly, for PVAR, we used bootstrapping to validate the consistency of estimated coefficients, addressing concerns related to the limited number of time points ($T = 3$).

4 RESULTS

4.1 RQ1 – Drivers of Support for Climate Policy

To investigate whether support for climate policies fluctuates during elections, and whether such support is shaped by perceptions of climate-related harm, we estimated a reduced-form panel vector autoregression (PVAR(1)) model. The analysis focused on two outcome variables: support for carbon taxes (cc_pol_tax) and support for vehicle emissions standards (cc_pol_car). Each regression included lagged values of 15 predictors, and standard errors were clustered at the respondent level. Figure 5 displays the estimated coefficients using dot-whisker plots, highlighting statistically significant predictors at the $p < 0.01$ level with 99% confidence intervals.

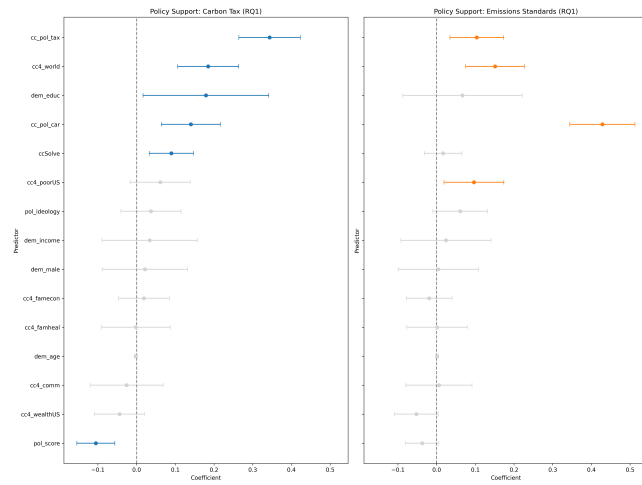


Figure 5: Predictors of support for carbon taxes and emissions standards. The figure displays results from two reduced-form PVAR(1) regressions using dot-whisker plots. Each dot represents a regression coefficient estimate, and the horizontal lines denote 99% confidence intervals. Predictors are ordered by the size and direction of their effects, with statistically significant results ($p < 0.01$) shown in color and non-significant ones in gray. A vertical line at zero indicates no effect. This visualization helps identify which attitudinal, demographic, and political variables are most strongly associated with support for climate policies during election periods.

Support for climate policies remains stable over time. Prior support for either carbon taxes or emissions standards is a significant and positive predictor of subsequent support for the same policy, indicating that individuals tend to maintain stable preferences. There is also evidence of cross-policy spillover, with prior support for emissions standards (cc_pol_car) significantly predicting later support for carbon taxes and vice versa. These findings show that people’s views on climate policies remain mostly the same, even during election time.

Support for carbon taxes is significantly influenced by several attitudinal and demographic predictors. Individuals who perceive that climate change harms the world (cc4_world) are more likely to support carbon taxation. This global perception of harm emerges as a robust positive driver of support, highlighting the role of broader environmental concern. Interestingly, personal perceptions of climate harm — such as concern for one’s own community (cc4_comm) or family health (cc4_famheal) — do not significantly influence support for carbon taxes at the stricter $p < 0.01$ threshold. Education level (dem_educ) is also positively associated with support, suggesting that more educated respondents are more receptive to market-based climate solutions. Furthermore, the willingness to financially contribute to climate solutions (ccSolve) significantly predicts support for carbon taxes. In contrast, political orientation (pol_score) exhibits a negative significant relationship, with more conservative individuals being less supportive of carbon taxes.

The emission standards model reveals a somewhat different set of predictors. Again, global harm perception (cc4_world) remains a significant and positive predictor of support. In addition, concern for the impact of climate change on the poor in the United States (cc4_poorUS) is positively associated with support. This suggests that concerns about fairness, especially how climate change affects poorer people in the country, influence support for climate rules. As with the carbon tax model, both autoregressive and cross-policy predictors are significant. Past support for emissions standards (cc_pol_car) and carbon taxes (cc_pol_tax) each positively influence current support for emissions standards. Demographic characteristics do not reach statistical significance in this model. This shows that personal values and beliefs matter more than things like age, income, or education when it comes to supporting climate rules. Unlike carbon taxes, emission standards appear less ideologically polarized, as political orientation does not emerge as a significant predictor.

Demographic variables such as dem_educ_lag, dem_income_lag, and dem_male_lag show the highest standard errors in both the carbon tax and emissions standards models. These predictors contribute disproportionately to overall model uncertainty, as evidenced by their wide confidence intervals in the dot-whisker plots (Figure 5) and elevated standard errors (Figure 6).

Several factors may explain this imprecision. First, demographic characteristics like gender and education are largely time-invariant, offering limited within-subject variation across survey waves. Second, small subgroup sizes — particularly combinations of traits like income and gender — may reduce the model’s ability to detect robust effects. Worth mentioning, variance inflation factors (VIFs) [5] for these variables are low (Table 8), indicating that multicollinearity is not the primary driver of uncertainty. These considerations

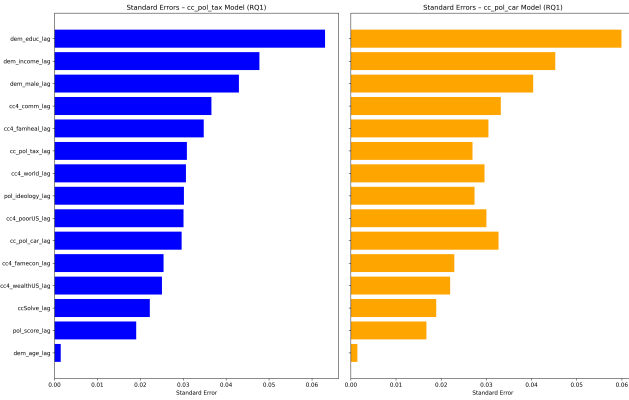


Figure 6: Standard errors for predictors in the carbon tax model (cc_pol_tax, left) and emissions standards model (cc_pol_car, right). In both cases, the demographic variables — education, income, and gender — exhibit the highest standard errors

suggest that demographic predictors should be interpreted with caution in this analysis.

Table 8: Variance Inflation Factors (VIF) - RQ1

Variable	VIF	Interpretation
cc4_comm_lag	4.66	Some correlation (acceptable)
cc4_famheal_lag	4.22	Some correlation (acceptable)
cc4_poorUS_lag	3.94	Some correlation (acceptable)
cc4_world_lag	3.60	Some correlation (acceptable)
cc4_famecon_lag	2.44	Some correlation (acceptable)
cc4_wealthUS_lag	2.38	Some correlation (acceptable)
cc_pol_car_lag	2.17	Some correlation (acceptable)
cc_pol_tax_lag	2.16	Some correlation (acceptable)
pol_score_lag	1.99	Low correlation (no multicollinearity)
pol_ideology_lag	1.94	Low correlation (no multicollinearity)
dem_income_lag	1.15	Low correlation (no multicollinearity)
dem_educ_lag	1.13	Low correlation (no multicollinearity)
ccSolve_lag	1.07	Low correlation (no multicollinearity)
dem_age_lag	1.06	Low correlation (no multicollinearity)
dem_male_lag	1.06	Low correlation (no multicollinearity)

Together, these results suggest that support for climate policy during elections is primarily shaped by global environmental concern, policy consistency, and — especially in the case of emissions standards — concern for social fairness. In contrast, perceptions of local or familial harm do not play a statistically significant role in shaping support, contrary to some expectations in the literature. The difference in how political views affect support for the two policies suggests that carbon taxes are more politically divisive than policies like emissions standards.

Overall, the analysis shows that people’s views on climate policies don’t change during short-term political events like elections. Instead, people’s views are based on long-lasting values and past opinions. This is important for understanding how likely climate action is to succeed, especially during elections when politicians are more likely to listen to voters.

4.2 RQ2 – Drivers of WTP for Climate Solutions

The reduced-form PVAR(1) model for ccSolve (willingness to pay for climate action) reveals that attitudes remain highly stable across the election period. Among all lagged predictors, only one variable — prior support for a carbon tax (cc_pol_tax) — emerges as a statistically significant predictor at the $p < 0.01$ level. This finding indicates that individuals who previously expressed support for carbon pricing are more likely to report a willingness to pay for broader climate solutions in subsequent waves. Figure 7 displays the estimated coefficients using dot-whisker plots, highlighting statistically significant predictors at the $p < 0.01$ level with 99% confidence intervals.

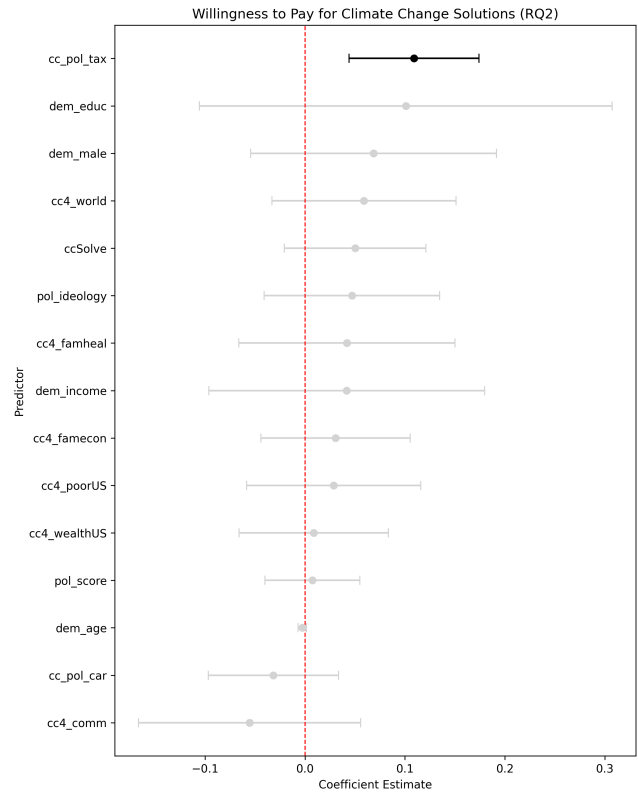


Figure 7: Predictors of willingness to pay for climate change solutions (ccSolve). Dot-whisker plots show coefficient estimates with 99% confidence intervals. Only prior support for carbon tax (cc_pol_tax) is statistically significant ($p < 0.01$), shown in black.

An inspection of standard errors reveals that dem_educ_lag, dem_income_lag, and dem_male_lag exhibit the largest standard errors among all predictors (see Figure 8). These three demographic variables contribute most to overall model uncertainty, making their estimated effects less precise. This is visually reflected in the long whiskers observed in the dot-whisker plot (Figure 7), particularly for dem_educ_lag, which had the widest confidence interval despite being conceptually important.

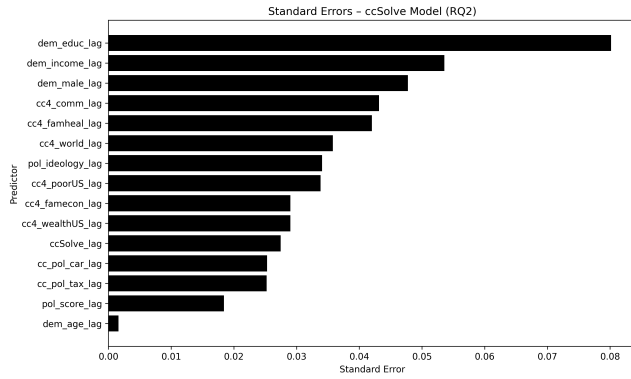


Figure 8: Standard errors of predictors in the ccSolve model. Variables with the highest uncertainty are shown at the top.

Several factors likely contribute to this uncertainty. First, there may be limited variation or small sample sizes within certain demographic subgroups. Second, demographic characteristics such as education and gender tend to remain constant across survey waves, reducing within-subject variability. Notably, the variance inflation factors (VIFs) for these predictors are low (see Table 9), indicating that multicollinearity is not a primary concern in this model.

Table 9: Variance Inflation Factors (VIF) - RQ2

Variable	VIF	Interpretation
cc4_comm_lag	4.66	Some correlation (acceptable)
cc4_famheal_lag	4.22	Some correlation (acceptable)
cc4_poorUS_lag	3.94	Some correlation (acceptable)
cc4_world_lag	3.60	Some correlation (acceptable)
cc4_famecon_lag	2.44	Some correlation (acceptable)
cc4_wealthUS_lag	2.38	Some correlation (acceptable)
cc_pol_car_lag	2.17	Some correlation (acceptable)
cc_pol_tax_lag	2.16	Some correlation (acceptable)
pol_score_lag	1.99	Low correlation (no multicollinearity)
pol_ideology_lag	1.94	Low correlation (no multicollinearity)
dem_income_lag	1.15	Low correlation (no multicollinearity)
dem_educ_lag	1.13	Low correlation (no multicollinearity)
ccSolve_lag	1.07	Low correlation (no multicollinearity)
dem_age_lag	1.06	Low correlation (no multicollinearity)
dem_male_lag	1.06	Low correlation (no multicollinearity)

4.3 RQ3 – Moderating Role of Political Ideology

To explore this question, we extended the PVAR(1) model to include interaction terms between perceived climate harms and respondents' political ideology. The aim was to test whether the effect of harm perceptions on willingness to financially support climate solutions varies across the ideological spectrum.

Figure 9 presents the results of the full interaction model. Among all predictors and interaction terms, the only variable that is statistically significant at the $p < 0.01$ level is prior support for a carbon tax (cc_pol_tax). This confirms a consistent pattern seen in previous models: individuals who already support specific climate policies are more likely to express a willingness to pay for climate solutions in general.

None of the interaction terms between harm perceptions and political ideology — such as cc4_world × pol_ideology, cc4_poorUS

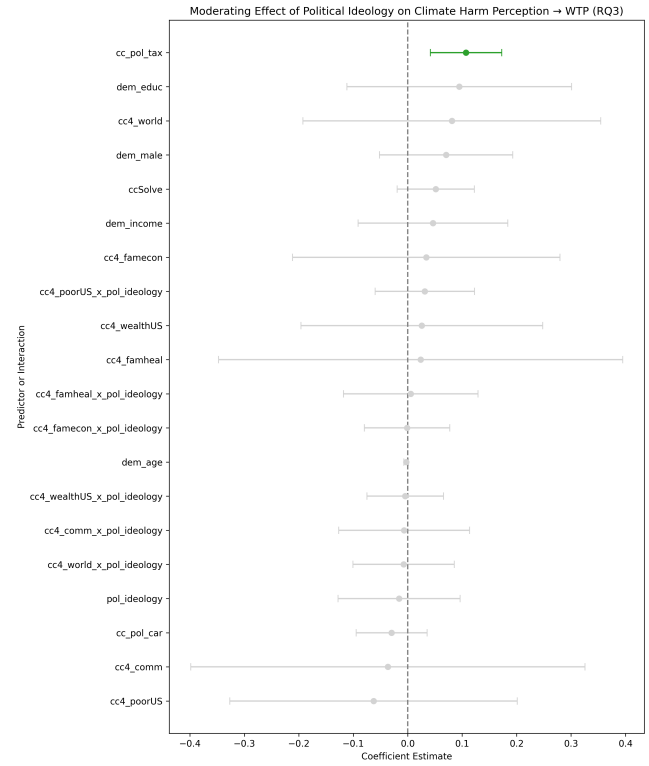


Figure 9: Moderation model with interaction terms between harm perceptions and political ideology. Only prior support for a carbon tax is significant ($p < 0.01$).

× pol_ideology, or cc4_famheal × pol_ideology — achieve statistical significance. This suggests that political ideology does not meaningfully alter how people translate climate risk perceptions into willingness to act financially.

The full interaction model exhibits substantial multicollinearity, especially between harm perception variables and their interaction terms. Standard errors for main harm predictors such as cc4_famheal, cc4_comm, and cc4_world exceed 0.10, with variance inflation factors (VIFs) for interaction terms ranging from 40 to 80 — well above acceptable thresholds (see Table 10). This collinearity inflates standard errors, reduces statistical power, and makes it difficult to isolate individual effects (see Figure 10).

To address multicollinearity, we constructed a harm_index to summarize all six harm perception variables into a single factor, which was then interacted with political ideology. The simplified specification resulted in improved model stability. All variance inflation factors (VIFs) for the harm index model remained below the conventional threshold of 10 (see Table 11), and standard errors for key predictors and interaction terms were substantially reduced (see Figure 11).

Figure 12 presents the results of the simplified moderation model using the harm_index.

The results from both the full interaction and simplified harm index models suggest that political ideology does not significantly moderate the relationship between climate harm perceptions and

Table 10: VIF - Full Interaction Model (RQ3)

Variable	VIF	Interpretation
cc4_comm_x_pol_ideology	87.39	High multicollinearity (problematic)
cc4_famheal_x_pol_ideology	78.85	High multicollinearity (problematic)
cc4_poorUS_x_pol_ideology	73.07	High multicollinearity (problematic)
cc4_world_x_pol_ideology	66.68	High multicollinearity (problematic)
cc4_comm	47.98	High multicollinearity (problematic)
cc4_famheal	43.39	High multicollinearity (problematic)
cc4_wealthUS_x_pol_ideology	38.33	High multicollinearity (problematic)
cc4_famecon_x_pol_ideology	34.82	High multicollinearity (problematic)
cc4_poorUS	31.96	High multicollinearity (problematic)
cc4_world	25.22	High multicollinearity (problematic)
cc4_wealthUS	23.99	High multicollinearity (problematic)
cc4_famecon	23.80	High multicollinearity (problematic)
pol_ideology	4.03	Some correlation (acceptable)
cc_pol_car	2.18	Some correlation (acceptable)
cc_pol_tax	2.16	Some correlation (acceptable)
dem_income	1.15	Low correlation (no multicollinearity)
dem_educ	1.14	Low correlation (no multicollinearity)
ccSolve	1.08	Low correlation (no multicollinearity)
dem_age	1.07	Low correlation (no multicollinearity)
dem_male	1.06	Low correlation (no multicollinearity)

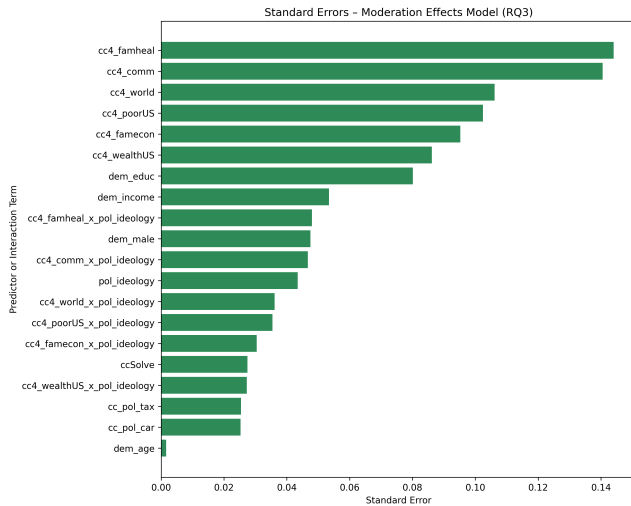


Figure 10: Standard errors for predictors in the full interaction model (RQ3). Harm perception variables and their interaction terms exhibit the largest uncertainty.

Table 11: VIF - Harm Index Moderation Model (RQ3)

Variable	VIF	Interpretation
harm_index × pol_ideology	8.64	Moderate multicollinearity (monitor)
harm_index	4.80	Some correlation (acceptable)
pol_ideology	3.66	Some correlation (acceptable)
cc_pol_tax	2.13	Some correlation (acceptable)
cc_pol_car	2.04	Some correlation (acceptable)
dem_income	1.14	Low correlation (no multicollinearity)
dem_educ	1.13	Low correlation (no multicollinearity)
ccSolve	1.07	Low correlation (no multicollinearity)
dem_male	1.05	Low correlation (no multicollinearity)
dem_age	1.04	Low correlation (no multicollinearity)

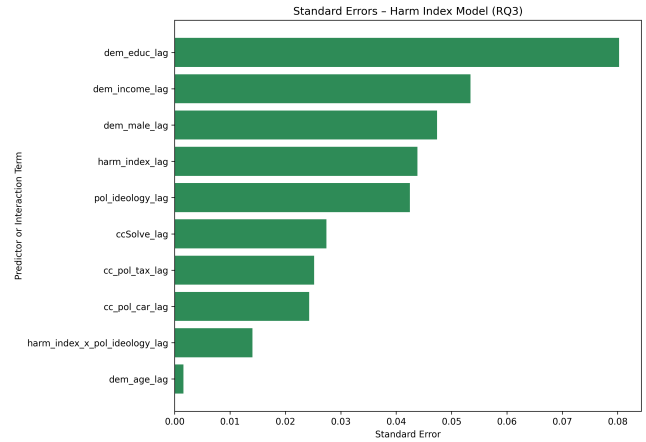


Figure 11: Standard errors in the simplified harm index model. The interaction term is more stable, with reduced uncertainty.

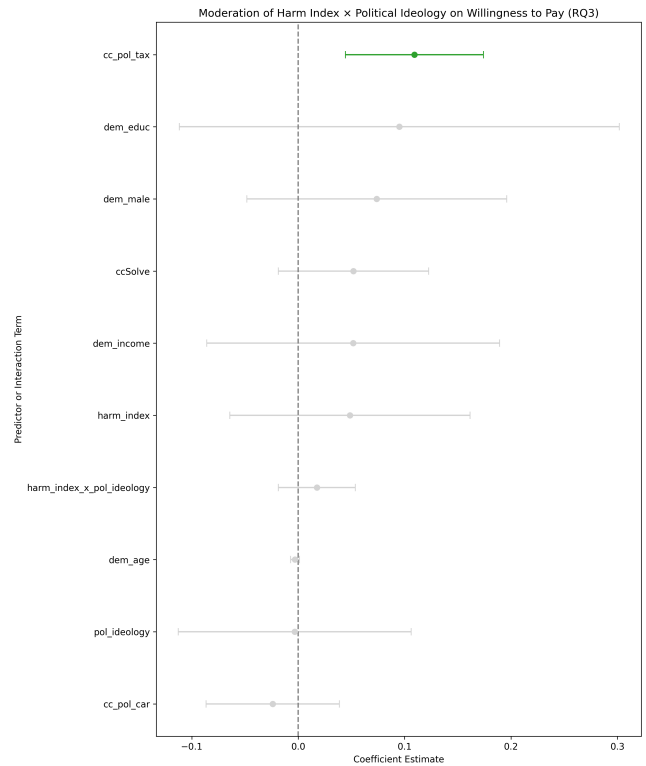


Figure 12: Moderation model using a composite harm index. Interaction with political ideology is not significant, but more precisely estimated.

willingness to pay. However, simplifying the model structure substantially improved the statistical clarity. The harm index approach

yielded lower multicollinearity, narrower confidence intervals while preserving the conclusion that prior climate policy support remains the strongest and most consistent predictor of financial engagement with climate solutions.

4.4 PVAR and PCMCI+ Graphs Comparison

To better understand the temporal and causal structure of climate attitudes, we compare two modeling approaches: lagged Panel Vector Autoregression (PVAR) and the causal discovery algorithm PCMCI+. Both rely on longitudinal panel data, but differ in their underlying assumptions and inference logic.

Figure 13 displays the PVAR lagged-effects graph, capturing statistically significant ($p < 0.01$) predictive links from time $t - 1$ to t . Each edge represents a standardized regression coefficient, with green and red indicating positive and negative effects, respectively. Political orientation variables (pol_score , pol_ideology) act as influential sources, sending predictive signals to a variety of downstream nodes. Climate harm perceptions such as comm , famheal , and world strongly shape policy attitudes like support for a carbon tax (pol_tax) and car regulations (pol_car). By contrast, demographic variables (dem_age , dem_male , etc.) exhibit only self-predictive (autoregressive) effects, playing a limited role in driving broader attitudinal change.

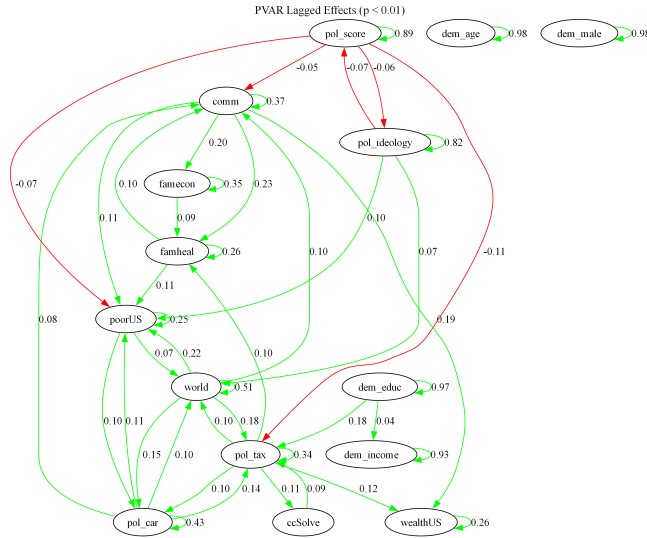


Figure 13: PVAR Lagged Effects ($p < 0.01$). Edge labels indicate standardized coefficients from lagged OLS models. Green = positive, Red = negative effects.

Figure 14 shows the graph generated by PCMCI+, which uses conditional independence testing to isolate direct, potentially non-linear causal links. Edge weights reflect momentary conditional information (MCI), with thicker edges indicating stronger dependencies. PCMCI+ reveals a more clustered and sparse structure, consistent with its stricter criteria for causal discovery.

Despite methodological differences, both models highlight the importance of political orientation and climate harm perceptions. PVAR offers interpretable effect sizes and directionality, while PCMCI+ emphasizes statistically valid, direct relationships by filtering out confounding paths. To directly compare results, Figure 15 presents a matrix of lag-1 edges detected by each method at $\alpha = 0.01$. PVAR identifies 46 links, while PCMCI+ finds just 5, consistent with its conservative approach.

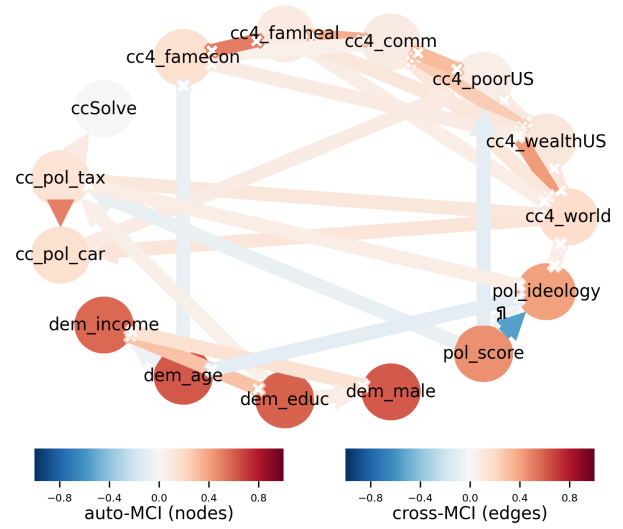


Figure 14: PCMCI+ causal graph. Nodes are colored by auto-MCI (self-dependence), and edges reflect cross-variable causal strength.

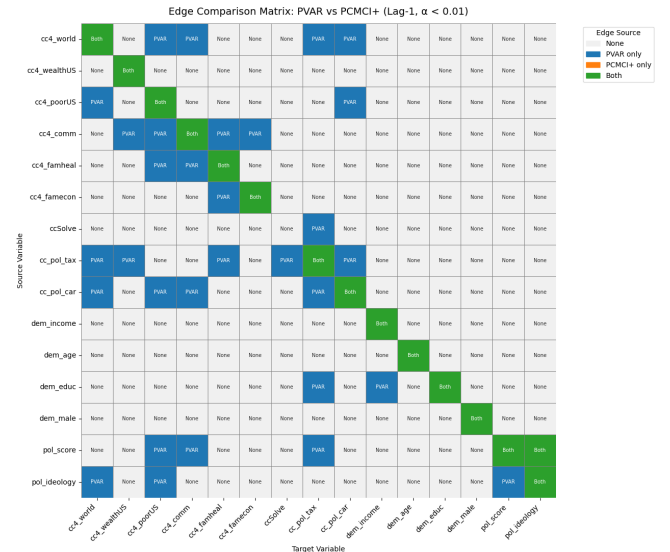


Figure 15: Edge Comparison Matrix: Directed lag-1 edges detected by PVAR and PCMCI+. Only statistically significant links at $\alpha < 0.01$ are displayed.

The edge from pol_score to pol_ideology is detected by both methods, suggesting a consistent directional influence from party alignment to ideology.

Many additional edges in the PVAR graph connect climate harm variables to each other or to policy outcomes. PCMCI+ filters out most of these, likely treating them as redundant or non-causal once controlling for confounders. This difference illustrates the trade-off between model interpretability and statistical significance.

5 DISCUSSION

6 CONCLUSION

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Appendix A RISK ASSESSMENT

A.1 Data Quality and Completeness

Risk: While the dataset is largely complete, there are missing values in 7 out of the 20 key variables. Although these are considered insignificant, unexpected data quality issues may arise during analysis.

Mitigation: Perform detailed exploratory data analysis early in the project. Prepare multiple imputation methods for the missing data.

Plan B: If data quality issues persist, focus analysis on the most complete variables and consider omitting the variables that have missing data.

A.2 Computational Challenges with PCMCI+

Risk: The PCMCI+ algorithm can be computationally intensive, especially with large datasets and multiple time lags.

Mitigation: Start with a subset of data to test and optimize the PCMCI+ implementation. Use cloud computing resources if necessary or the Snellius Dutch National supercomputer.

Plan B: If computational issues persist, consider simplifying the model or using alternative causal inference methods such as Granger causality or vector autoregression (VAR) models.

A.3 Software Dependencies

Risk: The Tigramite package or its dependencies may have compatibility problems or bugs.

Mitigation: Set up the software environment early and run multiple tests.

Plan B: Search for alternative Python packages as backups.

A.4 Ethical Considerations

Risk: Potential misuse of the findings for political purposes or biased interpretations.

Mitigation: Clearly state the limitations of the study and provide guidelines for ethical use of the results in the thesis and repository documentation.

Plan B: Include an "Ethical Use" section in the documentation, outlining specific scenarios of appropriate and inappropriate use of the findings.