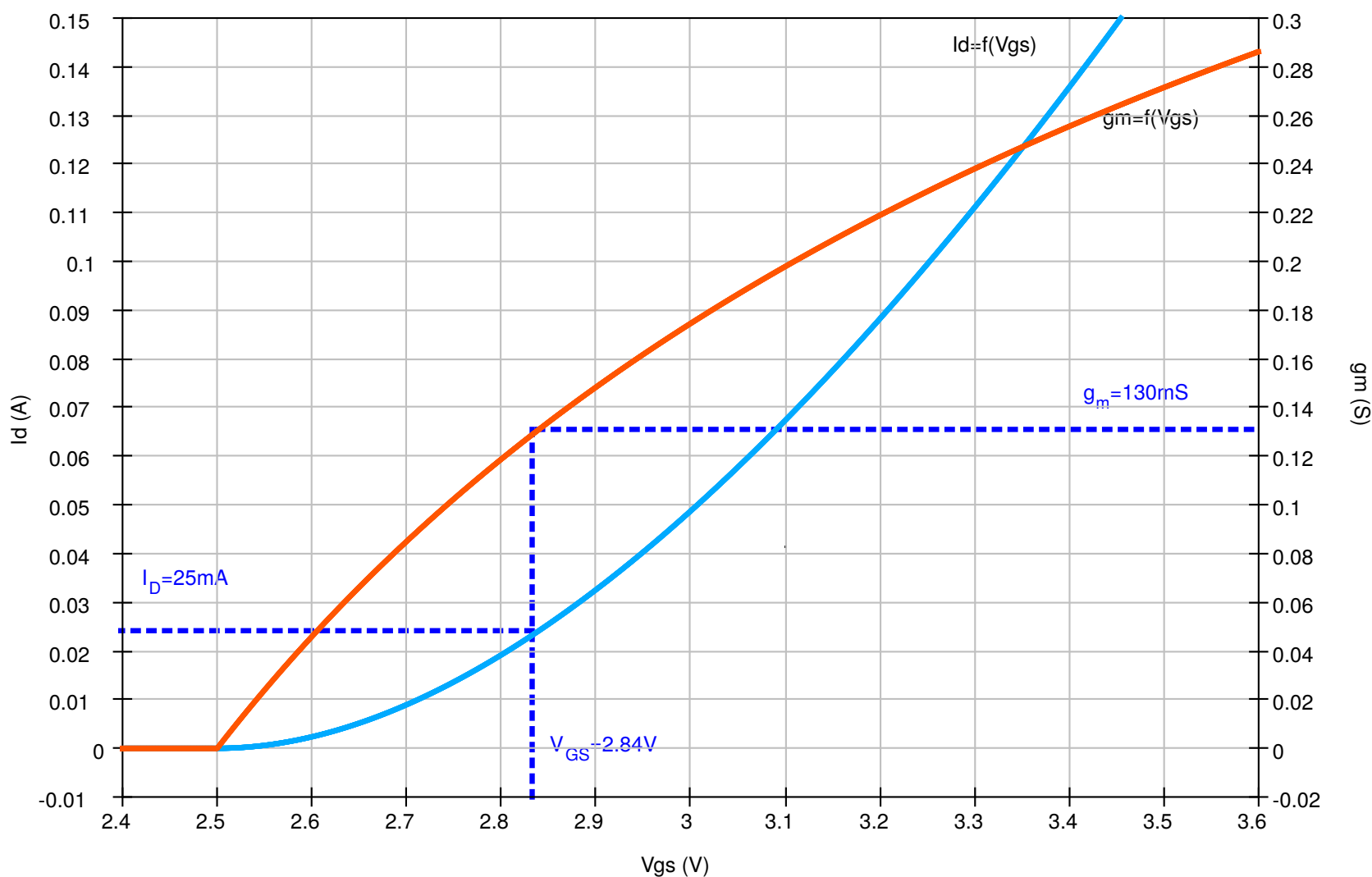


$I_d=f(V_{gs}); g_m=f(V_{gs})$



$I_d=f(V_{ds})@V_{gs}=ct$

