## Part 4: Advanced Binary Choice

Chris Conlon

Panel Data Econometrics

March 28, 2019

## Binary Choice: Overview

Many problems we are interested in look at discrete rather than continuous outcomes.

- We are familiar with limitations of the linear probability model (LPM)
  - ightharpoonup Predictions outside of [0,1]
  - Estimates of marginal effects need not be consistent.
- ▶ What about the case where *Y* is binary and a regressor *X* is endogenous?
  - The usual 2SLS estimator is NOT consistent.
  - Or we can ignore the fact that Y is binary...
  - Neither seems like a good option
- Suppose we have panel data on repeated binary choices
  - lacktriangle When N is large and T is small.
  - Adding FE to the logit/probit model produces biased (and inconsistent) estimates.

#### Problem #1: Fixed Effects and Incidental Parameters

Threshold Crossing / Latent Variable Model:

$$y_{it} = \mathbf{1}(X_{it}\beta + \epsilon_{it} \ge 0)$$

- ▶ Goal is not usually  $\hat{\beta}$  or it's CI, but rather  $P(y_{it} = 1 | x_{it})$  or  $\frac{\partial P[y_{it} = 1 | x_{it}]}{\partial x_{it}}$  (marginal effects).
- $\blacktriangleright$  What about if we want to add FE  $\alpha_i$

$$y_{it} = \mathbf{1}(X_{it}\beta + \alpha_i + \epsilon_{it} \ge 0)$$

Best case scenario  $E[\epsilon_{it}|x_{i1},\ldots,x_{iT},\alpha_i]=0.$ 

#### Fixed Effects and Incidental Parameters

Let's try and difference out (within transform) the FE:

$$E[y_{it} - y_{i,t-1}|X_i, \alpha_i] = E[F(X_{i,t}\beta + \alpha_i) - F(X_{i,t-1}\beta + \alpha_i)|X_i]$$

- We can't difference out the FE anymore!
- $ightharpoonup \alpha_i$  doesn't have the interpretation as  $\overline{y}_i$ .
- ▶ The effect of  $\alpha_i$  will now depend on  $X_{i,t}$ .
- We need to estimate N parameters  $\alpha_1, \ldots, \alpha_N$ .

#### Fixed Effects and Incidental Parameters

- ▶ FE requires maximizing LL over  $\alpha_i, \beta$ .
- ▶ FE model inconsistent as  $N \to \infty$  as T fixed.
- ▶ Under OLS we have a consistent estimator of  $\alpha_i$ , as N gets big, random noise in  $\alpha_i$  washes out.
- ▶ Under Logit/Probit/etc. now we only have *T* observations.
- ▶ Under logit/probit bias in  $\hat{\beta}$  can be pretty bad.
- ▶ Under probit, bias in marginal effects tends not to be as bad Hahn and Newey (2004) as bias in  $\hat{\beta}$ .

#### Two Solutions

#### Two possible solutions:

- Conditional Logit. Exploit a sufficient statistic formulation (Chamberlain)
- 2. Work out an analytic expression for the bias and subtract it off: analytic bias correction.

#### Conditional MLE

Imagine a sufficient statistic  $S_i$ :

$$f(Y_i|X_i, S_i, \theta, \alpha_i) = f(Y_i|X_i, S_i, \theta)$$
$$\hat{\theta} = \arg\max_{\theta} \sum_{i=1}^{n} f(Y_i|X_i, S_i, \theta)$$

These are hard to find, but examples:

- Binary Logit
- Gaussian linear model
- Poisson
- (and as we have seen) PH model for durations

#### Approach #2: Estimate the FE, Fix the Bias

#### What does bife do?

- Estimate the model with the FE in there as parameters (dummy variables).
- This model is biased and inconsistent.
- ▶ It is a big pain to estimate if N becomes large (lots of parameters, lots of derivatives, etc.)
  - Exploits the sparsity of the Hessian.
- Fix the bias on the back end by working out an analytic expression or jackknife: Hahn and Newey (2004).

# Conditional Logit (Chamberlain 1984/1992)

Here  $S_i = \sum_t y_{it}$ . Assume that T = 2 to make things clear

$$E[y_{i1}|X_i, \alpha_i, y_{i1} + y_{i2} = 1]$$

Consider the  $\sum_t y_{it} = 1$  case:

$$\Pr(y_{i1} + y_{i2} = 1) = \Pr(y_{i1} = 0, y_{i2} = 1) + \Pr(y_{i1} = 1, y_{i2} = 0)$$

And then we can write:

$$Pr(y_{i1} = 1) = \exp(\alpha_i + x'_{it}\beta) / [1 + \exp(\alpha_i + x'_{it}\beta)]$$

$$Pr(y_{i1} = 0) = 1 - \exp(\alpha_i + x'_{it}\beta) / [1 + \exp(\alpha_i + x'_{it}\beta)]$$

$$= 1 / [1 + \exp(\alpha_i + x'_{it}\beta)]$$

# Conditional Logit (Chamberlain 1984/1992)

$$\begin{split} \Pr\left(y_{i1} = 1, y_{i2} = 0\right) &= \frac{\exp\left(\alpha_{i} + x_{i1}'\beta\right)}{1 + \exp\left(\alpha_{i} + x_{i1}'\beta\right)} \cdot \frac{1}{1 + \exp\left(\alpha_{i} + x_{i2}'\beta\right)} \\ \Pr\left(y_{i1} = 0, y_{i2} = 1\right) &= \frac{1}{1 + \exp\left(\alpha_{i} + x_{i1}'\beta\right)} \cdot \frac{\exp\left(\alpha_{i} + x_{i2}'\beta\right)}{1 + \exp\left(\alpha_{i} + x_{i2}'\beta\right)} \end{split}$$

#### Putting it together

$$\begin{split} \Pr\left(y_{i1} + y_{i2} = 1\right) &= \Pr\left(y_{i1} = 0, y_{i2} = 1\right) + \Pr\left(y_{i1} = 1, y_{i2} = 0\right) \\ &= \frac{\exp\left(\alpha_i + x_{i1}'\beta\right) + \exp\left(\alpha_i + x_{i2}'\beta\right)}{\left(1 + \exp\left(\alpha_i + x_{i1}'\beta\right)\right)\left(1 + \exp\left(\alpha_i + x_{i2}'\beta\right)\right)} \end{split}$$

#### And the conditional:

$$\begin{split} \Pr\left(y_{i1} = 1, y_{i2} = 0 \middle| y_{i1} + y_{i2} = 1\right) &= \frac{\Pr\left(y_{i1} = 1, y_{i2} = 0\right)}{\Pr\left(y_{i1} + y_{i2} = 1\right)} \\ \frac{\exp\left(\alpha_i + x_{i1}'\beta\right)}{\exp\left(\alpha_i + x_{i1}'\beta\right) + \exp\left(\alpha_i + x_{i2}'\beta\right)} &= \frac{\exp\left(x_{i1}'\beta\right)}{\exp\left(x_{i1}'\beta\right) + \exp\left(x_{i2}'\beta\right)} \end{split}$$



# Eliminating the FE (Chamberlain 1984/1992)

Notice that we've now eliminated the FE!

$$Pr(y_{i1} = 1, y_{i2} = 0 | y_{i1} + y_{i2} = 1) = \frac{1}{1 + \exp(x_{i2} - x_{i1})' \beta}$$

$$Pr(y_{i1} = 1, y_{i2} = 0 | y_{i1} + y_{i2} = 1) = \frac{\exp(x_{i2} - x_{i1})' \beta}{1 + \exp(x_{i2} - x_{i1})' \beta}$$

- $\blacktriangleright$  As per usual if  $x_{it}$  doesn't vary over t it drops out too.
- ▶ We can skip the  $y_{i1} + y_{i2} = 2$  and  $y_{i1} + y_{i2} = 0$  case, why?
  - ▶ The FE  $\alpha_i \to \pm \infty$

## Problem #2: Endogeneity

Four possible solutions (maybe there are more?)

- 1. Close eyes, run the LPM with instruments (Suggested by MHE).
- Specify the distribution of errors in first and second stage and do MLE (biprobit in STATA).
- 3. Control Function Estimation
- 4. 'Special Regressor' Methods

## Problem #1: Endogeneity

#### Setup:

- ▶ Binary variable *D*: the outcome of interest
- lacktriangleq X is a vector of observed regressors with coefficient eta
  - (Can think about  $X^e$ : endogenous and  $X^0$ : exogenous).
  - In an treatment model we might have that T is a binary treatment indicator within X
- lacktriangleright  $\epsilon$  is unobserved error. Specifying f(e) can give logit/probit.
- Threshold Crossing / Latent Variable Model:

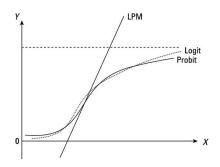
$$D = \mathbf{1}(X\beta + \epsilon \ge 0)$$

▶ Goal is not usually  $\hat{\beta}$  or it's CI, but rather P(D=1|X) or  $\frac{\partial P[D=1|x]}{\partial X}$  (marginal effects).

#### Linear Probability Model

Consider the LPM with a single continuous regressor

- lackbox LPM prediction departs greatly from CDF long before [0,1] limits.
- ▶ We get probabilities that are too extreme even for  $X\hat{\beta}$  "in bounds".
- Some (MHE) argue that though  $\hat{Y}$  is flawed, constant marginal effects are still OK.



#### Some well known textbooks

#### (Baby) Wooldrige:

"Even with these problems, the linear probability model is useful and often applied in economics. It usually works well for values of the independent variables that are near the averages in the sample." (2009, p. 249)

▶ Mentions heteroskedasticity of error (which is binomial given *X*) but does not address the violation of the first LSA.

#### Some well known textbooks

#### Angrist and Pischke (MHE)

several examples where marginal effects of probit and LPM are "indistinguishable".

...while a nonlinear model may fit the CEF (conditional expectation function) for LDVs (limited dependent variable models) more closely than a linear model, when it comes to marginal effects, this probably matters little. This optimistic conclusion is not a theorem, but as in the empirical example here, it seems to be fairly robustly true.(2009, p. 107)

#### and continue...

...extra complexity comes into the inference step as well, since we need standard errors for marginal effects. (ibid.)

## Linear Probability Model

How does the LPM work?

$$D = X\beta + \varepsilon$$

- **E**stimated  $\hat{\beta}$  are the MFX.
- ▶ With exogenous X we have  $E[D|X] = Pr[D = 1|X] = X\beta$ .
- If some elements of X (including treatment indicators) are endogenous or mismeasured they will be correlated with E.
- ► In that case we can do IV via 2SLS or IV-GMM given some instruments Z.
- ▶ We need the usual  $E[\varepsilon|X] = 0$  or  $E[\varepsilon|Z] = 0$ .

## Linear Probability Model

How does the LPM work?

$$D = X\beta + \varepsilon$$

- **E**stimated  $\hat{\beta}$  are the MFX.
- ▶ With exogenous X we have  $E[D|X] = Pr[D = 1|X] = X\beta$ .
- If some elements of X (including treatment indicators) are endogenous or mismeasured they will be correlated with E.
- ► In that case we can do IV via 2SLS or IV-GMM given some instruments Z.
- ▶ We need the usual  $E[\varepsilon|X] = 0$  or  $E[\varepsilon|Z] = 0$ .
- An obvious flaw: Given any  $\varepsilon|X$  must equal either  $1-X\beta$  or  $-X\beta$  which are functions of X
- Only the trivial binary X with no other regressors satisfies this!



# Alarming Example: Lewbel Dong and Yang (2012)

- ► LPM is not just about taste and convenience.
- ▶ Three treated observations, three untreated
- lacktriangle Assume that  $f(\varepsilon) \sim N(0,\sigma^2)$

$$D = I(1 + Treated + R + \varepsilon \ge 0)$$

Each individual treatment effect given by:

$$I(2+R+\varepsilon \ge 0) - I(1+R+\varepsilon \ge 0) = I(0 \le 1+R+\varepsilon \le 1)$$

- ▶ All treatment effects are positive for all  $(R, \varepsilon)$ .
- Construct a sample where true effect = 1 for 5th individual, 0 otherwise.  $ATE = \frac{1}{6}$ .

## Alarming Example: Lewbel Dong and Yang (2012)

```
. list
              Treated
      -1.8
       -.9
      -.92
 4. | -2.1
 5. | -1.92
. reg D Treated R, robust
Linear regression
                                               Number of obs
                                               F(2, 3)
                                                                        1.02
                                               Prob > F
                                                                      0.4604
                                               R-squared
                                                                      0.1704
                                               Root MSE
                                                                       .60723
                            Robust
          DΙ
                   Coef.
                           Std. Err.
                                               P>ItI
                                                         [95% Conf. Interval]
```

						_
+						
Treated	1550841	.5844637	-0.27	0.808	-2.015108	1.70494
R	.0484638	.0419179	1.16	0.331	0849376	.1818651
_cons	.7251463	.3676811	1.97	0.143	4449791	1.895272
. nlcom _b[Treat _nl_1:	ted]/_b[R] _b[Treated]/	/_b[R]	_			
D		Std. Err.		P> z	[95% Conf.	Interval]
_nl_1	-3.2	10.23042	-0.31	0.754	-23.25125	16.85125

## Alarming Example: Lewbel Dong and Yang (2012)

- ► That went well, except that:
  - ightharpoonup we got the wrong sign of  $\beta_T$
  - $ightharpoonup eta_1/eta_2$  was the wrong sign and three times too big.
- ▶ this is not because of small sample size or  $\beta_1 \approx 0$ .
- ▶ As  $n \to \infty$  we can get an arbitrarily precise wrong answer.
- We don't even get the sign right!

. expand 30

► This is still in OLS (not much hope for 2SLS).

```
. reg D Treated R. robust
Linear regression
                                        Number of obs =
                                                             180
                                        F(2, 177)
                                                     = 59.93
                                        Prob > F
                                                             0.0000
                                        R-squared
                                                             0.1704
                                         Root MSE
                                                               .433
                        Robust
                       Std. Err.
                                      P>|t| [95% Conf. Interval]
    Treated | -.1550841 .0760907
                                 -2.04
                                        0.043
                                                -.3052458 -.0049224
             .0484638 .0054572
                                 8.88
                                        0.000
                                                 .0376941 .0592334
                       .047868
      cons | .7251463
                                  15.15
                                        0.000
                                                 .6306808
                                                           .8196117
```

#### Solution #0: LPM

#### Advantages

- Just like 2SLS.
- ► Computationally easy (no numerical searches)
- ▶ Missing Z is about efficiency not consistency.
- $ightharpoonup X^e$  can be discrete or continuous (same estimator)
- allows general heteroskedasticity (random coefficients)

#### Disadvantages

- $\hat{F}_D$  is linear not S-shaped, approximation valid for small range of X.
- $ightharpoonup \hat{F}_D$  can be outside [0,1].
- ▶ no element of X can have  $\infty$  support (e.g. no normally distributed regressors).
- ightharpoonup arepsilon not independent of any regressors (even the exogenous ones). How do we also get  $E[X^0arepsilon]=0$  ? = 0

## Solution #1: MLE

$$D = I(X'\beta + \varepsilon \geq 0) \quad \text{and} \quad X^e = G(Z,\theta,e)$$

- ► Fully specified G (could be vector). Could be linear if X<sup>e</sup> continuous or probit if X<sup>e</sup> binary.
- ▶ Need to fully specify distribution of  $(\varepsilon, e, |Z)$ , parametrized.
- Implementation (see book), biprobit for joint normal in Stata.

## Solution #1: MLE

#### Advantages

- ▶ Nests logit, probit, etc. as special cases.
- ightharpoonup Can have any kind of  $X^e$
- Allows heteroskedasticity, random coefficients
- Asymptotically efficient (if correctly specified)

#### Disadvantages

- Need to parametrize everything G,  $F_{\varepsilon,e|Z}$ .
- Numerical optimization issues
- Many nusiance parameters, sometimes poorly identified, especially with discrete  $X^e$ , correlation between latent  $(\varepsilon, e)$ .
- Need to know all required instruments Z. Omitting just one Z causes inconsistency in G. (Not sure if something is exogenous, too bad!).



## Solution #2 : Control Functions

$$\begin{array}{lcl} D &=& I(X'\beta+\varepsilon\geq 0) \quad \text{and} \\ X^e &=& G(Z)+e \quad \text{or} \quad X^e=G(Z,e) \quad \text{identified and invertible in } e \\ \varepsilon &=& \lambda'e+U \quad \text{or} \quad \varepsilon=H(U,e) \quad \text{with conditions and } U\bot Z,e. \end{array}$$

#### Simple Case:

- Estimate a vector of functions G in the  $X^e$  models, get estimated errors  $\hat{e}$ .
- Estimate the D model including  $\hat{e}$  as additional regressors in addition to X.
- ► This "cleans" the errors in U.

## Solution #2 : Control Functions (Stata Version)

- ivprobit assumes that G(Z,e) is linear, and  $(e,\varepsilon)$  jointly normal, independent of Z.
- not exactly the semi-parametric flexibility we were looking for...
- It is actually Control Function not IV

$$D = I(X^e \beta_e + X^0 \beta_0 + \varepsilon \ge 0)$$
  
$$X^e = \gamma Z + e$$

Run first-stage OLS and get residuals  $\hat{e}$ . Then plug into

$$D = I(X^e \beta_e + X^0 \beta_0 + \lambda \hat{e} + U \ge 0)$$

and do a conventional probit estimator.

- ▶ If you forget a  $Z_2$  the resulting model isn't even probit!
- ▶ God help you if  $X^e$  isnt continuous.



## Solution #2 : Control Functions

$$D = I(X'\beta + \varepsilon \ge 0), \quad X^e = G(Z, e), \varepsilon = H(U, e), \quad U \perp X, e.$$

#### Much stronger requirements that 2SLS

- Must be able to solve for errors e in  $X^e$  equations (not just orthogonality)
- ▶ Endogeneity must be caused only by  $\varepsilon$  relation to e so after conditioning on e must be that  $f(\varepsilon|e,X^e)=f(\varepsilon|e)$ .
- ▶ I need a consistent estimator for *e* which means nothing is omitted.

#### Not Quite MLE

- ► First stage can be semi/non-parametric .
- ▶ Don't need to fully specify joint distribution of  $(\varepsilon, e)$  (Stata does though!).

#### Solution #2 : Control Functions

#### Advantages

- ► Nests logit, probit, etc. as special cases
- Requires less parametric information than MLE
- Some versions are computationally easy without numerical optimization (Bootstrap!)
- ► Less efficient than MLE due to less restrictions, but can be semiparametrically efficient given information.

# Solution #2 : Control Functions (Disadvantages: Not well known)

- Only allows limited heteroskedasticity
- Need to correctly specify vector G(Z,e) including all Z. Omitting a Z or misspecified G causes inconsistency because we need to have joint conditions on  $(\varepsilon,e)$ .
- Generally inconsistent for X<sup>e</sup> that is discrete, censored, limited, or not continuous.
- If you cannot solve for a latent e in G(Z, e) then you can't get  $\hat{e}$  for the censored observations (e.g.:  $X^e = \max(0, Z'\gamma + e)$ .
- An observable e is  $e = X^e E[X^e|Z]$  but for discontinuous  $X^e$  that e violates assumptions (except in very strange cases)
  - Ex:  $\varepsilon = [X^e E[X^e|Z]]\lambda + U$  satisfies CF, but if  $X^e$  is discrete then e has some strange distribution that depends on regressors.
  - Hard to generate a model of behavior that justifies this!

#### Solution #2 : Control Functions Generalized Residuals

What if  $X^e$  isn't continuous? Technically possible...

- Given the probit estimate in first stage we could construct a generalized residual (see Imbens and Wooldridge notes)
- $e^g \propto E[\varepsilon|Z,e]$ . An estimate  $\hat{e}^g$  of  $e^g$  can be included as a regressor in the model to fix the endogeneity problem, just as  $\hat{e}$  would have been used if the endogenous regressor were continuous.

Why would you ever want to do this..

- In the linear model we should just do IV with far fewer restrictions
- ▶ In the nonlinear model,  $\hat{e}^g$  requires almost as many assumptions as MLE which is efficient!

# Solution #3 : Special Regressor

This approach draws on these two papers:

- ► Lewbel (JoE 2002)
- ▶ Dong and Lewbel (Econometric Reviews 2015)

$$D = I(X'\beta + V + \varepsilon \ge 0)$$

Special Regressor V has three properties

- $\qquad \qquad \textbf{Exogenous} \ E[\varepsilon|V] = 0$
- Additively separable in the model
- Continuous distribution and large support (such as Normal)
- ▶ Helpful to have thick-tails (kurtosis). Why? We want to trace Pr(D|V) from [0,1].

#### Learn about SR

Binary, ordered, and multinomial choice, censored regression, selection, and treatment models (Lewbel 1998, 2000, 2007a), truncated regression models (Khan and Lewbel 2007), binary panel models with FE (Honore and Lewbel 2002), dynamic choice models (Heckman and Navarro 2007, Abbring and Heckman 2007), contingent valuation models (Lewbel, Linton, and McFadden 2008), market equilibrium models of multinomial choice (Berry and Haile 2009a, 2009b), models with (partly) nonseparable errors (Lewbel 2007b, Matzkin 2007, Briesch, Chintagunta, and Matzkin 2009).

Other empirical applications: Anton, Fernandez Sainz, and Rodriguez-Poo (2002), Cogneau and Maurin (2002), Goux and Maurin (2005), Stewart (2005), Lewbel and Schennach (2007), and Tiwari, Mohnen, Palm, and van der Loeff (2007).

Precursors: Matzkin (1992, 1994) and Lewbel (1997).

Recent theory: Magnac and Maurin (2007, 2008), Jacho-Ch·vez (2009), Khan and Tamer (2010), and Khan and Nekipelov (2010a, 2010b).

## Solution #3 : Special Regressor

#### Requirements:

$$D = I(X'\beta + V + \varepsilon \ge 0)$$

- Exogenous  $E[\varepsilon|V] = 0$  (Strict Exogeneity) This is the key!
- Additively separable in the model
- Continuous distribution and large support (such as Normal)
- NOT interacted with other regressors.
- ightharpoonup enters LINEARLY, e.g. V must be continuously distributed after conditioning on other regressors
- ► Can normalize its coefficient to 1
- ▶ 2SLS Assumptions:  $E[\varepsilon|Z] = 0$  and E[Z'X] is full rank.

## Solution #3 : Special Regressor: How it works

- 1. Demean or center V at zero.
- 2. Assume that  $f_v(V|Z,X^e)=f_v(V|Z)$  and let  $\hat{f}_v(V|Z)$  be a nonparametric kernel estimator of  $f_v(V|Z)$ . Or just use a kernel of the whole thing  $\hat{f}_v(V|Z,X^e)$
- 3. For each observation i, Construct  $\hat{T}_i = I[D_i I(V_i \ge 0)]/\hat{f}_v(V_i|Z_i)$
- 4. Linear 2SLS regression of  $\hat{T}$  on X using instruments Z to get the estimated coefficients  $\hat{\beta}$ .

Here  $\hat{f}_v(V|Z)$  is high dimensional. So will consider some simpler parametric or semi-parametric version of  $f_v$ .

By properly adjusting  $T_i$  we guarantee to stay in [0,1].

## Solution #3 : Special Regressor Advantages

- ▶ Unlike LPM it stays "in bounds" and is consistent with threshold crossing models.
- Unlike MLE and CF, does not require correctly specified first stage model: any valid set of instruments may be used, with only efficiency at stake.
- Unlike MLE, the SR method has a linear form, not requiring iterative search
- lackbox Unlike CF, the SR method can be used when endogenous regressors  $X^e$  are discrete or limited; unlike ML there is a single estimation method, regardless of the characteristics of  $X^e$
- Unlike MLE, the SR method permits unknown heteroskedasticity in the model errors.

# Solution #3 : Special Regressor Disadvantages

$$D = I(X'\beta + V + \varepsilon \ge 0)$$

- ▶ Because assumptions are weaker we give up a lot of potential efficiency (larger SEs).
- Of course this presumes the assumptions were valid and alternatives were consistent.
- ► SR Methods are generally valid under more general conditions.

## The average index function (AIF)/ Propensity Score

In the original problem

$$D = I(X'\beta + \varepsilon \ge 0)$$

- ightharpoonup V is part of X with coefficient =1
- When  $\varepsilon \perp x$  write the propensity score:  $E[D|X] = E[D|X\beta] = F_{-\varepsilon}(X\beta) = Pr(-\varepsilon \leq X\beta).$
- ▶ Under independence  $X \perp \varepsilon$  these are the same, under endogeneity or even heteroskedasticity they are not.

## The average index function (AIF)/ Propensity Score

- ▶ Blundell and Powell (ReStud 2004, this is actually the most important control function paper) use the average structural function (ASF) =  $F_{-\varepsilon}(X\beta)$  to summarize choice probabilities. But when  $\varepsilon \bot X$  is violated then they have to compute  $F_{-\varepsilon \mid X}(X\beta)$  which is quite difficult (especially semiparametrically).
- Lewbel, Dong and Tang (CJE 2012) propose using the AIF estimator  $E[D|X\beta]$  instead.
- Like ASF the AIF is based on the estimated index  $X\beta$  and is equal to the propensity score if  $\varepsilon \bot X$ . However, when this is violated (endogeneity, heteroskedasticity) the AIF is easier to estimate, via unidimensional nonparametric regression of D on  $X\beta$ .

#### What is the difference

Propensity Score: Conditions on ALL covariates using  $F_{-\varepsilon|X}$ .

ASF: Conditions on no covariates using  $F_{-\varepsilon}$ .

AIF: Conditions on index only using  $F_{-\varepsilon|X\beta}$ .

- Unlike ASF, AIF is always identified and easy to estimate.
- ▶ Unlike Propensity score AIF uses  $\beta$  and isn't high dimensional
- ASF, AIF and propensity score all coincide under exogeneity.

## Marginal Effects

- ▶ With exogenous X: MFX are  $m(X) = p'(X) = \frac{\partial E[D|X\beta]}{\partial X}$ .
- Let  $f_{-\varepsilon}$  be marginal pdf of  $-\varepsilon$ . If  $D = I(X'\beta + \varepsilon \ge 0)$  with  $\varepsilon \perp X$  then:

$$m(X\beta)\beta = \frac{\partial E[D|X]}{\partial X} = \frac{\partial E[D|X\beta]}{\partial X'\beta}\beta = f_{-\varepsilon}(X'\beta)\beta$$

#### With endogenous X:

- Propensity Score marginal effects are  $m(X) = p'(X) = \frac{\partial E[D|X]}{\partial X}$ .
- ▶ ASF marginal effects are  $m(X) = \frac{\partial ASF(X'\beta)}{\partial X'\beta}\beta = f_{-\varepsilon}(X'\beta)\beta$ .
- ▶ AIF marginal effects are  $m(X) = \frac{\partial ASF(X'\beta)}{\partial X'\beta}\beta = \frac{\partial E[D|X'\beta]}{\partial X'\beta}\beta$

Given  $\hat{\beta}$  ASF and AIF mfx require just one dimensional index derivative.

## Binary Choice with Endogenous Regressors

- Linear probability models, Maximum Likelihood, and Control functions (including ivprobit have more drawbacks and limitations than are usually recognized.
- Special Regressor estimators are a viable alternative (or at least they have completely different drawbacks and may be more generally applicable than has been recognized).
- In practice, best might be to try all estimators and check robustness of results. Can use marginal effects to normalize them the same when comparing.
- Average Index Functions can be used to construct estimated probabilities and comparable marginal effects across estimators, often simpler to calculate than Average Structural Functions.
- Implementation of special regressor in Stata is done in sspecialreg.

- ▶ Binary dependent variable: does *i* migrate from one state to another.
- ightharpoonup Special Regressor  $V_i$ : age. Human capital theory suggests it should appear linearly (or at least monotonic) in a threshold crossing model
- Migration is drive by maximizing expected lifetime income and potential gain from a permanent change in income declines linearly in age.
- $ightharpoonup V_i$  is defined as negative of age, demeaned so that coefficient is positive with mean zero.
- ▶ Other endogenous regressors: family income pre migration, home ownership.

As a reminder, normally we would be in trouble here:

- MLE would be very complicated with multiple endogenous variables
- Control functions ivprobit won't work with 0/1 homeowner variable.

#### 1990 PSID

- male head of household (23-59 years), completed education and not-retired (key!)
- ▶ D = 1 indicates migration during 1991-1993.
- ▶ 4689 Individuals, 807 migrants.
- Exogenous regressors: years of education, # of children, white, disabled, married.
- Instruments: level of govt benefits in 1989-1990, state median residential tax rate.

#### Specifications

- Special Regressors: kernel density vs. sorted data density.
- Special Regressor: homoskedastic vs. heteroskedastic errors.
- ► LPM vs 2SLS
- Probit (assuming exogeneity)
- Control Function (ivprobit) misspecified for homeowner endogenous binary variable.

## Empirical Example

Table: Marginal effects: binary outcome, binary endogenous regressor

	kdens	sortdens	kdens_hetero	sortdens_hetero	IV-LPM	probit	ivprobi
age	0.0146	0.0112	0.0071	0.0104	-0.0010	0.0019	-0.0005
	(0.003)***	(0.003)***	(0.003)*	(0.003)***	(0.002)	(0.001)**	(0.007)
log income	-0.0079	0.0024	0.0382	0.0176	0.0550	-0.0089	0.1406
	(0.028)	(0.027)	(0.024)	(0.026)	(0.080)	(0.007)	(0.286)
homeowner	0.0485	-0.0104	-0.0627	-0.0111	-0.3506	-0.0855	-1.0647
	(0.072)	(0.065)	(0.059)	(0.061)	(0.204)	(0.013)***	(0.708)
white	0.0095	0.0021	0.0021	0.0011	0.0086	-0.0099	0.0134
	(0.008)	(0.010)	(0.007)	(800.0)	(0.018)	(0.012)	(0.065
disabled	0.1106	0.0730	0.0908	0.0916	0.0114	-0.0122	0.0104
	(0.036)**	(0.042)	(0.026)***	(0.037)*	(0.055)	(0.033)	(0.203
education	-0.0043	-0.0023	-0.0038	-0.0036	0.0015	0.0004	0.0047
	(0.002)*	(0.003)	(0.002)*	(0.002)	(0.004)	(0.002)	(0.015
married	0.0628	0.0437	0.0258	0.0303	0.0322	-0.0064	0.0749
	(0.020)**	(0.028)	(0.013)	(0.020)	(0.031)	(0.017)	(0.114
nr. children	-0.0169	-0.0117	0.0006	-0.0021	0.0137	0.0097	0.0502
	(0.005)***	(0.005)*	(0.002)	(0.003)	(0.006)*	(0.005)*	(0.023)

Note: bootstrapped standard errors in parentheses (100 replications)

- ▶ SEs of MFX are computed from 100 bootstrap replications
- MFX of special regressor (age) is estimated as positive and significant but LPM and ivprobit estimate negative effects!
- household income and home ownership status do not seem to play significant roles in migration decision.
- Kernel density estimator seems to give most significant results.