

Documentation: MODEL_FRBA_oil

Nikolay Gospodinov and Bin Wei

May 27, 2015

1 Model

Suppose that there are a vector of four latent variables $x_t = (x_{1t}, x_{2t}, x_{3t})'$ that drive nominal and real yields as well as inflation. Their dynamics under the physical measure is

$$dx_t = \mathcal{K}(\mu - x_t)dt + \Sigma dW_{x,t} \quad (1)$$

and

$$d\delta_t = \kappa_\delta(\mu_\delta - \delta_t)dt + \sigma_\delta dW_{\delta,t} \quad (2)$$

$$ds_t = \left(r_t^N - \delta_t - \frac{1}{2}\sigma_s^2 + \sigma_s \Lambda_{\delta,t}^N \right) dt + \sigma_s dW_{\delta,t} \quad (3)$$

The nominal pricing kernel takes the form

$$dM_t^N / M_t^N = -r_t^N dt - \Lambda'_{x,t} dW_{x,t} - \Lambda_{\delta,t} dW_{\delta,t} \quad (4)$$

where the nominal short rate is

$$r_t^N = \rho_0^N + \rho_x^{N'} x_t + \rho_\delta^N \delta_t + \rho_s^N s_t \quad (5)$$

and the vector of prices of risk is given by

$$\Lambda_{x,t}^N = \lambda_{0,x}^N + \lambda_x^N x_t \quad (6)$$

$$\Lambda_{\delta,t}^N = \lambda_{0,\delta}^N + \lambda_\delta^N \delta_t \quad (7)$$

Let $q_t \equiv \log Q_t$ denote the log price level. The price level evolves as follows:

$$dq_t = \pi_t dt + \sigma_q' dW_{x,t} + \sigma_q^\perp dW_{\perp,t} \quad (8)$$

where the instantaneous expected inflation rate is given by

$$\pi_t = \rho_0^\pi + \rho_x^{\pi'} x_t + \rho_\delta^\pi \delta_t + \rho_s^\pi s_t \quad (9)$$

Under the risk-neutral measure,

$$\begin{aligned} d\delta_t &= \kappa_\delta(\mu_\delta - \delta_t)dt + \sigma_\delta dW_{\delta,t} \\ &= \kappa_\delta(\mu_\delta - \delta_t)dt + \sigma_\delta(dW_{\delta,t}^* - \Lambda_{\delta,t}^N dt) \\ &\equiv \kappa_\delta^*(\mu_\delta^* - \delta_t)dt + \sigma_\delta dW_{\delta,t}^* \end{aligned}$$

and

$$\begin{aligned}
ds_t &= \left(r_t^N - \delta_t - \frac{1}{2}\sigma_s^2 + \sigma_s \Lambda_{\delta,t}^N \right) dt + \sigma_s dW_{\delta,t} \\
&\equiv (\phi_0 + \phi'_x x_t + \phi_\delta \delta_t + \phi_s s_t) dt + \sigma_s dW_{\delta,t} \\
&\equiv (\phi_0^* + \phi_x^{*'} x_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s dW_{\delta,t}^*
\end{aligned}$$

where

$$\begin{aligned}
\kappa_\delta^* &= \kappa_\delta + \sigma_\delta \lambda_\delta^N \\
\kappa_\delta^* \mu_\delta^* &= \kappa_\delta \mu_\delta - \sigma_\delta \lambda_{0,\delta}^N
\end{aligned}$$

$$\begin{aligned}
\phi_0 &= \rho_0^N - \frac{1}{2}\sigma_s^2 + \sigma_s \lambda_{0,\delta}^N \\
\phi_x &= \rho_x^N \\
\phi_\delta &= \rho_\delta^N - 1 + \sigma_s \lambda_\delta^N \\
\phi_s &= \rho_s^N
\end{aligned}$$

and

$$\begin{aligned}
\phi_0^* &= \rho_0^N - \frac{1}{2}\sigma_s^2 = \phi_0 - \sigma_s \lambda_{0,\delta}^N \\
\phi_x^* &= \rho_x^N \\
\phi_\delta^* &= \rho_\delta^N - 1 = \phi_\delta - \sigma_s \lambda_\delta^N \\
\phi_s^* &= \rho_s^N
\end{aligned}$$

Remark. We initialize λ_δ^N so that $\phi_\delta = 0 = \rho_\delta^N - 1 + \sigma_s \lambda_\delta^N$, or $\lambda_\delta^N = (1 - \rho_\delta^N) / \sigma_s$. Furthermore, as we show later, the long run mean of s_t is

$$s_\infty \equiv -\frac{1}{\phi_s} (\phi_0 + \phi'_x \mu + \phi_v \mu_v + \phi_\delta \mu_\delta)$$

Given the other parameters including ϕ_s , we can initialize $\lambda_{0,\delta}^N$ by matching sample mean of s_t , denoted by \widehat{s} , to its long run mean s_∞ . Given that $\phi_\delta = 0$ via initialization and $\mu = 0$ by normalization and $\phi_v = \rho_v^N = 0$ by restriction, we have

$$\begin{aligned}
\phi_0 &= -(\phi_v \mu_v + \phi_s \widehat{s}) = \rho_0^N - \frac{1}{2}\sigma_s^2 + \sigma_s \lambda_{0,\delta}^N \\
\Rightarrow \lambda_{0,\delta}^N &= -\frac{\phi_v \mu_v + \phi_s \widehat{s} + \rho_0^N - \frac{1}{2}\sigma_s^2}{\sigma_s} \\
\Rightarrow \lambda_{0,\delta}^N &= -\frac{\phi_s \widehat{s} + \rho_0^N - \frac{1}{2}\sigma_s^2}{\sigma_s}
\end{aligned}$$

NOTE:

$$dx_t = \mathcal{K}^* (\mu^* - x_t) dt + \Sigma dW_{x,t}^* \quad (10)$$

$$d\delta_t = \kappa_\delta^* (\mu_\delta^* - \delta_t) dt + \sigma_\delta dW_{\delta,t}^* \quad (11)$$

$$ds_t = (\phi_0^* + \phi_x^{*'} x_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s dW_{\delta,t}^* \quad (12)$$

Oil futures. Let $s_t \equiv \log(S_t)$ denote the spot oil price.

$$\begin{aligned} F_{t,\tau}^{oil} &= E_t^*[\exp(s_{t+\tau})] \\ &\equiv \exp(A_\tau^{oil} + B_\tau^{oil} x_t + D_\tau^{oil} \delta_t + E_\tau^{oil} s_t) \end{aligned}$$

where

$$\begin{aligned} \dot{A}_\tau^{oil} &= (\mathcal{K}^* \mu^*)' B_\tau^{oil} + (\kappa_\delta^* \mu_\delta^*) D_\tau^{oil} + \phi_0^* E_\tau^{oil} \\ &\quad + \frac{1}{2} B_\tau^{oil} \Sigma \Sigma' B_\tau^{oil} + \frac{1}{2} \sigma_\delta^2 (D_\tau^{oil})^2 + \frac{1}{2} \sigma_s^2 (E_\tau^{oil})^2 \\ \dot{B}_\tau^{oil} &= -(\mathcal{K}^*)' B_\tau^{oil} + \phi_x^* E_\tau^{oil} \\ \dot{D}_\tau^{oil} &= -\kappa_\delta^* D_\tau^{oil} + \phi_\delta^* E_\tau^{oil} \\ \dot{E}_\tau^{oil} &= \phi_s^* E_\tau^{oil} \end{aligned}$$

and the initial conditions are: $A_0^{oil} = B_0^{oil} = D_0^{oil} = 0$ and $E_0^{oil} = 1$.

Consider the transformation

$$\begin{aligned} \mathcal{A} &= A_\tau^{oil} \\ \mathcal{B} &= \begin{pmatrix} B_\tau^{oil} \\ D_\tau^{oil} \\ E_\tau^{oil} - 1 \end{pmatrix} \end{aligned}$$

Then $\mathcal{A}(0) = \mathcal{B}(0) = \mathcal{C}(0) = 0$ and

$$\begin{aligned} \dot{\mathcal{A}} &= \left(\phi_0^* + \frac{1}{2} \sigma_s^2 \right) + \begin{pmatrix} \mathcal{K}^* \mu^* \\ \kappa_\delta^* \mu_\delta^* \\ \phi_0^* + \sigma_s^2 \end{pmatrix}' \mathcal{B} + \frac{1}{2} \mathcal{B}' \begin{pmatrix} \Sigma \Sigma' & & \\ & \sigma_\delta^2 & \\ & & \sigma_s^2 \end{pmatrix} \mathcal{B} \\ \dot{\mathcal{B}} &= \begin{pmatrix} \phi_x^* \\ \phi_\delta^* \\ \phi_s^* \end{pmatrix} + \begin{pmatrix} -(\mathcal{K}^*)' & 0 & \phi_x^* \\ 0 & -\kappa_\delta^* & \phi_\delta^* \\ 0 & 0 & \phi_s^* \end{pmatrix} \mathcal{B} \end{aligned}$$

Based on the observation $M_t^R = M_t^N Q_t$, we have

$$\begin{aligned} dM_t^R/M_t^R &= dM_t^N/M_t^N + dQ_t/Q_t + (dM_t^N/M_t^N) \cdot (dQ_t/Q_t) \\ &= -r_t^N dt - \Lambda_{x,t}^{N'} dW_{x,t} - \Lambda_{\delta,t}^N dW_{\delta,t} \\ &\quad + \left[\pi_t + \frac{1}{2} \left(\sigma_q' \sigma_q + (\sigma_q^\perp)^2 \right) - \sigma_q' \Lambda_{x,t}^N \right] dt + \sigma_q' dW_{x,t} + \sigma_q^\perp dW_{\perp,t} \\ &\equiv -r_t^R dt - \Lambda_{x,t}^{R'} dW_{x,t} - \Lambda_{\delta,t}^R dW_{\delta,t} \end{aligned}$$

where

$$\begin{aligned} r_t^R &= r_t^N - \left[\pi_t + \frac{1}{2} \left(\sigma_q' \sigma_q + (\sigma_q^\perp)^2 \right) \right] + \sigma_q' \Lambda_{x,t}^N \equiv \rho_0^R + \rho_x^R x_t + \rho_\delta^R \delta_t + \rho_s^R s_t \\ \Lambda_{x,t}^R &= \Lambda_{x,t}^N - \sigma_q \equiv \lambda_{0,x}^R + \lambda_x^R x_t \\ \Lambda_{\delta,t}^R &= \Lambda_{\delta,t}^N \equiv \lambda_{0,\delta}^R + \lambda_\delta^R \delta_t \end{aligned}$$

and

$$\begin{aligned}\rho_0^R &= \rho_0^N - \rho_0^\pi - \frac{1}{2} \left(\sigma_q' \sigma_q + (\sigma_q^\perp)^2 \right) + \lambda_{0,x}' \sigma_q \\ \rho_x^R &= \rho_x^N - \rho_x^\pi + \lambda_x^{N'} \sigma_q \\ \rho_\delta^R &= \rho_\delta^N - \rho_\delta^\pi \\ \rho_s^R &= \rho_s^N - \rho_s^\pi\end{aligned}$$

and

$$\begin{aligned}\lambda_{0,x}^R &= \lambda_{0,x}^N - \sigma_q, \text{ and } \lambda_x^R = \lambda_x^N \\ \lambda_{0,\delta}^R &= \lambda_{0,\delta}^N, \text{ and } \lambda_\delta^R = \lambda_\delta^N\end{aligned}$$

1.1 Dynamics under the Risk-Neutral Measure and Bond Pricing

Let

$$\Lambda_t^N \equiv \begin{pmatrix} \Lambda_{x,t}^N \\ \Lambda_{\delta,t}^N \end{pmatrix}, W_t \equiv \begin{pmatrix} W_{x,t} \\ W_{\delta,t} \end{pmatrix}.$$

Then, the Radon-Nikodym derivative of the risk neutral measure \mathbb{P}^* with respect to the physical measure \mathbb{P} is given by

$$\left(\frac{d\mathbb{P}^*}{d\mathbb{P}} \right)_{t,T} = \exp \left[-\frac{1}{2} \int_t^T \Lambda_s^{N'} \Lambda_s^N ds - \int_t^T \Lambda_s^{N'} dW_s \right] \quad (13)$$

By the Girsanov theorem, $dW_t^* = dW_t + \Lambda_t^N dt$ is a standard Brownian motion under the risk-neutral probability measure \mathbb{P}^* . It implies that under the risk neutral measure,

$$\begin{aligned}dW_{x,t}^* &= dW_{x,t} + \Lambda_{x,t}^N dt \\ dW_{\delta,t}^* &= dW_{\delta,t} + \Lambda_{\delta,t}^N dt\end{aligned}$$

Therefore,

$$\begin{aligned}dx_t &= \mathcal{K}(\mu - x_t) dt + \Sigma dW_{x,t} \\ &= \mathcal{K}(\mu - x_t) dt + \Sigma (dW_{x,t}^* - \Lambda_{x,t}^N dt) \\ &= \left[\left(\mathcal{K}\mu - \Sigma \lambda_0^N \right) - \left(\mathcal{K} + \Sigma \lambda_x^N \right) x_t \right] dt + \Sigma dW_{x,t}^* \\ &\equiv \mathcal{K}^*(\mu^* - x_t) dt + \Sigma dW_{x,t}^*,\end{aligned}$$

$$\begin{aligned}d\delta_t &= \kappa_\delta^*(\mu_\delta^* - \delta_t) dt + \sigma_\delta dW_{\delta,t}^* \\ ds_t &= (\phi_0^* + \phi_x^{*'} x_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s dW_{\delta,t}^*\end{aligned}$$

and

$$\begin{aligned}dq_t &= \pi_t dt + \sigma_q' dW_{x,t} + \sigma_q^\perp dW_{\perp,t} \\ &= (\rho_0^\pi + \rho_x^{\pi'} x_t + \rho_\delta^\pi \delta_t + \rho_s^\pi s_t) dt + \sigma_q' (dW_{x,t}^* - \Lambda_{x,t}^N dt) + \sigma_q^\perp dW_{\perp,t}^* \text{ (suppose } dW_{\perp,t}^* = dW_{\perp,t}) \\ &= \left(\rho_0^\pi + \rho_x^{\pi'} x_t + \rho_\delta^\pi \delta_t + \rho_s^\pi s_t - \sigma_q' \left(\lambda_{0,x}^N + \lambda_x^N x_t \right) \right) dt + \sigma_q' dW_{x,t}^* + \sigma_q^\perp dW_{\perp,t}^* \\ &= \left(\rho_0^\pi - \lambda_{0,x}^{N'} \sigma_q + \left(\rho_x^\pi - \lambda_x^{N'} \sigma_q \right)' x_t + \rho_\delta^\pi \delta_t + \rho_s^\pi s_t \right) dt + \sigma_q' dW_{x,t}^* + \sigma_q^\perp dW_{\perp,t}^* \\ &\equiv (\rho_0^{\pi*} + \rho_x^{\pi*'} x_t + \rho_\delta^{\pi*} \delta_t + \rho_s^{\pi*} s_t) dt + \sigma_q' dW_{x,t}^* + \sqrt{v_t} dW_{\perp,t}^*,\end{aligned}$$

where

$$\begin{aligned}
\mathcal{K}^* &= \mathcal{K} + \Sigma \lambda_x^N \\
\mathcal{K}^* \mu^* &= \mathcal{K} \mu - \Sigma \lambda_{0,x}^N \\
\kappa_\delta^* &= \kappa_\delta + \sigma_\delta \lambda_\delta^N \\
\kappa_\delta^* \mu_\delta^* &= \kappa_v \mu_v - \sigma_\delta \lambda_{0,\delta}^N \\
\pi_t^* &= \rho_0^{\pi*} + \rho_x^{\pi*'} x_t + \rho_\delta^{\pi*} \delta_t + \rho_s^{\pi*} s_t \\
\rho_0^{\pi*} &= \rho_0^\pi - \lambda_{0,x}^{N'} \sigma_q \\
\rho_x^{\pi*} &= \rho_x^\pi - \lambda_x^{N'} \sigma_q \\
\rho_\delta^{\pi*} &= \rho_\delta^\pi \text{ and } \rho_s^{\pi*} = \rho_s^\pi
\end{aligned}$$

We first establish a well-known result of affine-form of nominal yields in Proposition 1 below.

Proposition 1 *Under this model, nominal and real bond prices take the exponential-affine form*

$$P_{t,\tau}^i = \exp \left(A_\tau^i + B_\tau^{i'} x_t + D_\tau^i \delta_t + E_\tau^i s_t \right), \quad i = N, R \quad (14)$$

and nominal and real yields take the affine form

$$y_{t,\tau}^i = a_\tau^i + b_\tau^{i'} x_t + d_\tau^i \delta_t + e_\tau^i s_t, \quad i = N, R \quad (15)$$

where $a_\tau^i \equiv -A_\tau^i/\tau$, $b_\tau^i \equiv -B_\tau^i/\tau$, $d_\tau^i \equiv -D_\tau^i/\tau$, and $e_\tau^i \equiv -E_\tau^i/\tau$, and A_τ^i , B_τ^i , D_τ^i , E_τ^i ($i = N, R$) satisfy the following system of ODEs:

$$\begin{aligned}
\frac{dA_\tau^i}{d\tau} &= -\rho_0^i + (\mathcal{K} \mu - \Sigma \lambda_0^i)' B_\tau^i + \kappa_\delta^* \mu_\delta^* D_\tau^i + \phi_0^* E_\tau^i + \frac{1}{2} B_\tau^{i'} \Sigma \Sigma' B_\tau^i + \frac{1}{2} \sigma_\delta^2 (D_\tau^i)^2 + \frac{1}{2} \sigma_s^2 (E_\tau^i)^2, \text{ with } A_0^i = 0 \\
\frac{dB_\tau^i}{d\tau} &= -\rho_x^i - (\mathcal{K} + \Sigma \lambda_x^i)' B_\tau^i + \phi_x^* E_\tau^i, \text{ with } B_0^i = 0 \\
\frac{dD_\tau^i}{d\tau} &= -\rho_\delta^i - \kappa_\delta^* D_\tau^i + \phi_\delta^* E_\tau^i, \text{ with } D_0^i = 0 \\
\frac{dE_\tau^i}{d\tau} &= -\rho_s^i + \phi_s^* E_\tau^i, \text{ with } E_0^i = 0
\end{aligned}$$

Consider the transformation

$$\begin{aligned}
\mathcal{A} &= A_\tau^i \\
\mathcal{B} &= \begin{pmatrix} B_\tau^i \\ D_\tau^i \\ E_\tau^i \end{pmatrix}
\end{aligned}$$

Then

$$\begin{aligned}
\dot{\mathcal{A}} &= -\rho_0^i + \begin{pmatrix} \mathcal{K} \mu - \Sigma \lambda_0^i \\ \kappa_\delta^* \mu_\delta^* \\ \phi_0^* \end{pmatrix}' \mathcal{B} + \frac{1}{2} \mathcal{B}' \begin{pmatrix} \Sigma \Sigma' & & \\ & \sigma_\delta^2 & \\ & & \sigma_s^2 \end{pmatrix} \mathcal{B} \\
\dot{\mathcal{B}} &= \begin{pmatrix} -\rho_x^i \\ -\rho_\delta^i \\ -\rho_s^i \end{pmatrix} + \begin{pmatrix} -(\mathcal{K} + \Sigma \lambda_x^i)' & 0 & \phi_x^* \\ 0 & -\kappa_\delta^* & \phi_\delta^* \\ 0 & 0 & \phi_s^* \end{pmatrix} \mathcal{B}
\end{aligned}$$

Survey Yield Forecast. To calculate survey yield forecasts, we need the following results:

$$\begin{aligned} E_t [x_{t+\tau}] &= \mu + \exp(-\kappa\tau) (x_t - \mu) \\ E_t [\delta_{t+\tau}] &= \mu_\delta + \exp(-\kappa_\delta\tau) (\delta_t - \mu_\delta) \end{aligned}$$

Next we calculate, $E_t [s_{t+\tau}]$. Note that

$$\begin{aligned} ds_t &= (\phi_0 + \phi'_x x_t + \phi_\delta \delta_t + \phi_s s_t) dt + \sigma_s dW_{\delta,t} \\ d[\exp(-\phi_s t) s_t] &= \exp(-\phi_s t) [(\phi_0 + \phi'_x x_t + \phi_\delta \delta_t) dt + \sigma_s dW_{\delta,t}] \end{aligned}$$

and

$$\begin{aligned} &\exp(-\phi_s(t+\tau)) s_{t+\tau} - \exp(-\phi_s t) s_t \\ &= \int_t^{t+\tau} [\exp(-\phi_s u) (\phi_0 + \phi'_x x_u + \phi_\delta \delta_u) du + \exp(-\phi_s u) \sigma_s dW_{\delta,u}] \end{aligned}$$

implying

$$\begin{aligned} &\exp(-\phi_s(t+\tau)) E_t [s_{t+\tau}] - \exp(-\phi_s t) s_t \\ &= \int_t^{t+\tau} \exp(-\phi_s u) \left(\begin{aligned} &\phi_0 + \phi'_x ([\mu + \exp(-\kappa(u-t))(x_t - \mu)]) \\ &+ \phi_\delta ([\mu_\delta + \exp(-\kappa_\delta(u-t))(\delta_t - \mu_\delta)]) \end{aligned} \right) du \\ &= \frac{1}{\phi_s} (\exp(-\phi_s t) - \exp(-\phi_s(t+\tau))) (\phi_0 + \phi'_x \mu + \phi_\delta \mu_\delta) \\ &\quad + \exp(-\phi_s t) \phi'_x (\kappa + \phi_s I)^{-1} (I - \exp(-(\kappa + \phi_s I)\tau)) (x_t - \mu) \\ &\quad + \exp(-\phi_s t) \phi_\delta (\kappa_\delta + \phi_s)^{-1} (1 - \exp(-(\kappa_\delta + \phi_s)\tau)) (\delta_t - \mu_\delta) \end{aligned}$$

or

$$\begin{aligned} &E_t [s_{t+\tau}] \\ &= \exp(\phi_s \tau) s_t + \frac{1}{\phi_s} (\exp(\phi_s \tau) - 1) (\phi_0 + \phi'_x \mu + \phi_\delta \mu_\delta) \\ &\quad + \phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s \tau) I - \exp(-\kappa\tau)) (x_t - \mu) \\ &\quad + \phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s \tau) - \exp(-\kappa_\delta\tau)) (\delta_t - \mu_\delta) \end{aligned}$$

and

$$Var_t [s_{t+\tau}] = E_t \left[\int_{-\tau}^0 \exp(-2\phi_s u) \sigma_s^2 du \right] = \frac{1}{2\phi_s} (\exp(2\phi_s \tau) - 1) \sigma_s^2$$

Therefore,

$$\begin{aligned} E_t^{svy} [y_{t+\tau,3m}^N] &= E_t^{mkt} [y_{t+\tau,3m}^N] + \epsilon_{t,\tau}^f \\ &= E_t [a_{3m}^N + b_{3m}^{N'} x_{t+\tau} + d_{3m}^N \delta_{t+\tau} + e_{3m}^N s_{t+\tau}] + \epsilon_{t,\tau}^f \\ &= a_{3m}^N + b_{3m}^{N'} [\mu + \exp(-\kappa\tau) (x_t - \mu)] \\ &\quad + d_{3m}^N [\mu_\delta + \exp(-\kappa_\delta\tau) (\delta_t - \mu_\delta)] \\ &\quad + e_{3m}^N \left[\begin{aligned} &\exp(\phi_s \tau) s_t + \frac{1}{\phi_s} (\exp(\phi_s \tau) - 1) (\phi_0 + \phi'_x \mu + \phi_\delta \mu_\delta) \\ &+ \phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s \tau) I - \exp(-\kappa\tau)) (x_t - \mu) \\ &+ \phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s \tau) - \exp(-\kappa_\delta\tau)) (\delta_t - \mu_\delta) \end{aligned} \right] + \epsilon_{t,\tau}^f \\ &\equiv a_\tau^f + b_\tau^{f'} x_t + d_\tau^f \delta_t + e_\tau^f s_t + \epsilon_{t,\tau}^f \end{aligned}$$

where

$$\begin{aligned} a_\tau^f &= a_{3m}^N + b_{3m}^{N'} [I - \exp(-\kappa\tau)] \mu + d_{3m}^N [1 - \exp(-\kappa_\delta\tau)] \mu_\delta \\ &\quad + e_{3m}^N \begin{bmatrix} \frac{1}{\phi_s} (\exp(\phi_s\tau) - 1) (\phi_0 + \phi'_x\mu + \phi_\delta\mu_\delta) \\ -\phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s\tau) I - \exp(-\kappa\tau)) \mu \\ -\phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s\tau) - \exp(-\kappa_\delta\tau)) \mu_\delta \end{bmatrix} \end{aligned}$$

and

$$\begin{aligned} b_\tau^{f'} &= b_{3m}^{N'} \exp(-\kappa\tau) + e_{3m}^N \phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s\tau) I - \exp(-\kappa\tau)) \\ d_\tau^f &= d_{3m}^N \exp(-\kappa_\delta\tau) + e_{3m}^N \phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s\tau) - \exp(-\kappa_\delta\tau)) \\ e_\tau^f &= e_{3m}^N \exp(\phi_s\tau) \end{aligned}$$

Lastly, we turn to the long-range forecast: $E_t^{mkt} [\bar{y}_{3m, T_1, T_2}^N]$ as follows. Note that

$$\begin{aligned} &E_t \left[\frac{1}{T_2 - T_1} \int_{t+T_1}^{t+T_2} s_u du \right] \\ &= \frac{1}{T_2 - T_1} \int_{T_1}^{T_2} \begin{bmatrix} \exp(\phi_s u) s_t + \frac{1}{\phi_s} (\exp(\phi_s u) - 1) (\phi_0 + \phi'_x\mu + \phi_\delta\mu_\delta) \\ + \phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s u) I - \exp(-\kappa u)) (x_t - \mu) \\ + \phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s u) - \exp(-\kappa_\delta u)) (\delta_t - \mu_\delta) \end{bmatrix} du \\ &= W_{T_1, T_2}^s s_t + \frac{1}{\phi_s} (W_{T_1, T_2}^s - 1) (\phi_0 + \phi'_x\mu + \phi_\delta\mu_\delta) \\ &\quad + \phi'_x (\kappa + \phi_s I)^{-1} (W_{T_1, T_2}^s I - W_{T_1, T_2}^x) (x_t - \mu) \\ &\quad + \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1, T_2}^s - W_{T_1, T_2}^\delta) (\delta_t - \mu_\delta) \end{aligned}$$

where

$$\begin{aligned} W_{T_1, T_2}^x &= \frac{1}{T_2 - T_1} \int_{T_1}^{T_2} \exp(-\kappa s) ds = \frac{1}{T_2 - T_1} \kappa^{-1} (\exp(-\kappa T_1) - \exp(-\kappa T_2)) \\ W_{T_1, T_2}^\delta &= \frac{1}{T_2 - T_1} \kappa_\delta^{-1} (\exp(-\kappa_\delta T_1) - \exp(-\kappa_\delta T_2)) \\ W_{T_1, T_2}^s &= \frac{1}{T_2 - T_1} \int_{T_1}^{T_2} \exp(\phi_s u) du = \frac{1}{T_2 - T_1} \phi_s^{-1} (\exp(\phi_s T_2) - \exp(\phi_s T_1)) \end{aligned}$$

Therefore,

$$\begin{aligned}
E_t^{svy} [\bar{y}_{3m,T_1,T_2}^N] &= E_t^{mkt} [\bar{y}_{3m,T_1,T_2}^N] + \epsilon_{t,LT}^f \\
&= E_t \left[\frac{1}{T_2 - T_1} \int_{T_1}^{T_2} y_{s,3m}^N ds \right] + \epsilon_{t,LT}^f \\
&= E_t \left[\frac{1}{T_2 - T_1} \int_{T_1}^{T_2} (a_{3m}^N + b_{3m}^{N'} x_s + d_{3m}^N \delta_s + e_{3m}^N s_s) ds \right] + \epsilon_{t,LT}^f \\
&= a_{3m}^N + b_{3m}^{N'} [(I - W_{T_1,T_2}^x) \mu + W_{T_1,T_2}^x x_t] \\
&\quad + d_{3m}^N [(1 - W_{T_1,T_2}^\delta) \mu_\delta + W_{T_1,T_2}^\delta \delta_t] \\
&\quad + e_{3m}^N \left[\begin{aligned} &W_{T_1,T_2}^s s_t + \frac{1}{\phi_s'} (W_{T_1,T_2}^s - 1) (\phi_0 + \phi_x' \mu + \phi_\delta \mu_\delta) \\ &+ \phi_x' (\kappa + \phi_s I)^{-1} (W_{T_1,T_2}^s I - W_{T_1,T_2}^x) (x_t - \mu) \\ &+ \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^\delta) (\delta_t - \mu_\delta) \end{aligned} \right] + \epsilon_{t,LT}^f \\
&\equiv a_{LT}^f + b_{LT}^{f'} x_t + d_{LT}^f \delta_t + \epsilon_{t,LT}^f
\end{aligned}$$

where

$$\begin{aligned}
a_{LT}^f &= a_{3m}^N + b_{3m}^{N'} (I - W_{T_1,T_2}^x) \mu + d_{3m}^N (1 - W_{T_1,T_2}^\delta) \mu_\delta \\
&\quad + e_{3m}^N \left[\begin{aligned} &\frac{1}{\phi_s'} (W_{T_1,T_2}^s - 1) (\phi_0 + \phi_x' \mu + \phi_\delta \mu_\delta) \\ &- \phi_x' (\kappa + \phi_s I)^{-1} (W_{T_1,T_2}^s I - W_{T_1,T_2}^x) \mu \\ &- \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^\delta) \mu_\delta \end{aligned} \right]
\end{aligned}$$

and

$$\begin{aligned}
b_{LT}^{f'} &= b_{3m}^{N'} W_{T_1,T_2}^x + e_{3m}^N \phi_x' (\kappa + \phi_s I)^{-1} (W_{T_1,T_2}^s I - W_{T_1,T_2}^x) \\
d_{LT}^f &= d_{3m}^N W_{T_1,T_2}^\delta + e_{3m}^N \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^\delta) \\
e_{LT}^f &= e_{3m}^N W_{T_1,T_2}^s
\end{aligned}$$

1.2 State Dynamics

We first consider the discrete-time dynamics of the state variable q_t between time $t - \Delta t$ and t . From $dq_t = \pi_t dt + \sigma_q' dW_{x,t} + \sqrt{v_t} dW_{\perp,t}$, we have

$$q_t = q_{t-\Delta t} + (\rho_0^\pi \Delta t + (\rho_x^\pi \Delta t) x_t + (\rho_\delta^\pi \Delta t) \delta_t + (\rho_s^\pi \Delta t) s_t) + \eta_t^q$$

where $\eta_t^q \equiv \int_{t-\Delta t}^t (\sigma_q' dW_{x,s} + \sigma_q^\perp dW_{\perp,s}) \sim N(0, \Omega^q)$ and

$$\Omega^q \equiv \text{Var}_{t-\Delta t}(\eta_t^q) = (\sigma_q' \sigma_q + (\sigma_q^\perp)^2) \Delta t$$

Similarly, for the state variable x_t we have

$$x_t = \exp(-\mathcal{K} \Delta t) x_{t-\Delta t} + (I - \exp(-\mathcal{K} \Delta t)) \mu + \eta_t^x,$$

where $\eta_t^x = \int_0^{\Delta t} \exp(-\kappa s) \Sigma dW_{x,s} \sim N(0, \Omega^x)$ and

$$\Omega^x \equiv \text{Var}_{t-\Delta t}(\eta_t^x) = \int_0^{\Delta t} \exp(-\mathcal{K} s) \Sigma \Sigma' \exp(-\mathcal{K}' s) ds = N \Xi N',$$

with $\mathcal{K} = NDN^{-1}$, $D = \text{diag}([d_1, \dots, d_N])$, and $\Xi_{i,j} = [(N^{-1}\Sigma)(N^{-1}\Sigma)']_{i,j} \frac{1 - \exp[-(d_i + d_j) \cdot t]}{(d_i + d_j)}$. The covariance matrix between η_t^x and η_t^q is given by

$$\Omega^{xq} = \text{Cov}_{t-\Delta t}[\eta_t^x, \eta_t^q] = \int_0^{\Delta t} \exp(-\mathcal{K}s) \Sigma \sigma_q ds = \mathcal{K}^{-1} (I - \exp(-\mathcal{K}\Delta t)) \Sigma \sigma_q.$$

where I signifies the identity matrix.

Next, we consider the state variable δ_t . From $d\delta_t = \kappa_\delta (\mu_\delta - \delta_t) dt + \sigma_\delta dW_{\delta,t}$, we have

$$\delta_t = e^{-\kappa_\delta \Delta t} \delta_{t-\Delta t} + \mu_\delta (1 - e^{-\kappa_\delta \Delta t}) + \eta_t^\delta$$

where $\eta_t^\delta = \sigma_\delta \int_{t-\Delta t}^t e^{\kappa_\delta(u-t)} dW_{\delta,u} \sim N(0, \Omega^\delta)$ and

$$\Omega^\delta = E_{t-\Delta t} \left[\sigma_\delta^2 \int_{t-\Delta t}^t e^{2\kappa_\delta(s-t)} ds \right] = \sigma_\delta^2 \frac{1 - e^{-2\kappa_\delta \Delta t}}{2\kappa_\delta}$$

Last, we consider the state variable s_t . Note

$$d[\exp(-\phi_s t) s_t] = \exp(-\phi_s t) [(\phi_0 + \phi'_x x_t + \phi_\delta \delta_t) dt + \sigma_s dW_{\delta,t}]$$

we have

$$\begin{aligned} s_t &= e^{\phi_s \Delta t} s_{t-\Delta t} + (\phi_0 + \phi'_x x_{t-\Delta t} + \phi_\delta \delta_{t-\Delta t}) \frac{\exp(\phi_s \Delta t) - 1}{\phi_s} + \eta_t^s \\ &\approx (1 + \phi_s \Delta t) s_{t-\Delta t} + (\phi_0 \Delta t + (\phi'_x \Delta t) x_{t-\Delta t} + (\phi_\delta \Delta t) \delta_{t-\Delta t}) + \eta_t^s \end{aligned}$$

where $\eta_t^s = \sigma_s \int_{t-\Delta t}^t \exp(-\phi_s(u-t)) dW_{\delta,u} \sim N(0, \Omega^s)$ and

$$\Omega^s = E_{t-\Delta t} \left[\sigma_s^2 \int_{t-\Delta t}^t e^{2(-\phi_s)(u-t)} du \right] = \sigma_s^2 \frac{e^{2\phi_s \Delta t} - 1}{2\phi_s}$$

and

$$\begin{aligned} \Omega^{\delta s} &= \sigma_\delta \sigma_s E_{t-\Delta t} \left[\int_{t-\Delta t}^t e^{\kappa_\delta(u-t)} dW_{\delta,u} \int_{t-\Delta t}^t e^{-\phi_s(u-t)} dW_{\delta,u} \right] \\ &= \sigma_\delta \sigma_s E_{t-\Delta t} \left[\int_{t-\Delta t}^t e^{(\kappa_\delta - \phi_s)(u-t)} du \right] \\ &= \sigma_\delta \sigma_s \frac{1 - e^{-(\kappa_\delta - \phi_s)\Delta t}}{\kappa_\delta - \phi_s} \end{aligned}$$

In summary, the dynamics of the state vector $Z_t = (q_t, x'_t, \delta_t, s_t)'$ follows the VAR process

$$Z_t = \mathcal{A} + \mathcal{B}Z_{t-\Delta t} + \eta_t$$

$$\text{where } \mathcal{A} = \begin{bmatrix} \rho_0^\pi \Delta t \\ (I - \exp(-\mathcal{K}\Delta t)) \mu \\ (1 - e^{-\kappa_\delta \Delta t}) \mu_\delta \\ \phi_0 \Delta t \end{bmatrix}, \mathcal{B} = \begin{bmatrix} 1 & \rho_x^{\pi'} \Delta t & \rho_\delta^\pi \Delta t & \rho_s^\pi \Delta t \\ 0 & \exp(-\mathcal{K}\Delta t) & 0 & 0_{3 \times 1} \\ 0 & 0_{1 \times 3} & e^{-\kappa_\delta \Delta t} & 0 \\ 0 & \phi'_x \Delta t & \phi_\delta \Delta t & 1 + \phi_s \Delta t \end{bmatrix}, \eta_t = \begin{pmatrix} \eta_t^q \\ \eta_t^x \\ \eta_t^\delta \\ \eta_t^s \end{pmatrix} \sim N(0, \Omega) \text{ and } \Omega = \begin{bmatrix} \Omega^q & \Omega^{xq'} & & \\ \Omega^{xq} & \Omega^x & & \\ & & \Omega^\delta & \Omega^{\delta s} \\ & & \Omega^{\delta s} & \Omega^s \end{bmatrix}.$$