

Documentation: MODEL_FRBA_full

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1 Model

Suppose that there are a vector of four latent variables $x_t = (x_{1t}, x_{2t}, x_{3t})'$ and v_t that drive nominal and real yields as well as inflation. Their dynamics under the physical measure is

$$dx_t = \mathcal{K}(\mu - x_t) dt + \Sigma dW_{x,t} \quad (1)$$

$$dv_t = \kappa_v(\mu_v - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t} + \rho dW_{\perp,t} \right) \quad (2)$$

and

$$d\delta_t = \kappa_\delta(\mu_\delta - \delta_t) dt + \sigma_\delta dW_{\delta,t} \quad (3)$$

$$ds_t = \left(r_t^N - \delta_t - \frac{1}{2}\sigma_s^2 + \sigma_s \Lambda_{\delta,t}^N \right) dt + \sigma_s dW_{\delta,t} \quad (4)$$

The nominal pricing kernel takes the form

$$dM_t^N / M_t^N = -r_t^N dt - \Lambda_{x,t}^{N'} dW_{x,t} - \Lambda_{v,t}^N dW_{v,t} - \Lambda_{\perp,t}^N dW_{\perp,t} - \Lambda_{\delta,t}^N dW_{\delta,t} \quad (5)$$

where the nominal short rate is

$$r_t^N = \rho_0^N + \rho_x^{N'} x_t + \rho_v^N v_t + \rho_\delta^N \delta_t + \rho_s^N s_t \quad (6)$$

and the vector of prices of risk is given by

$$\Lambda_{x,t}^N = \lambda_{0,x}^N + \lambda_x^N x_t$$

$$\Lambda_{v,t}^N = \gamma_v \sqrt{v_t}$$

$$\Lambda_{\perp,t}^N = \gamma_v^\perp \sqrt{v_t}$$

$$\Lambda_{\delta,t}^N = \lambda_{0,\delta}^N + \lambda_\delta^N \delta_t$$

Let $q_t \equiv \log Q_t$ denote the log price level. The price level evolves as follows:

$$dq_t = \pi_t dt + \sigma_q' dW_{x,t} + \sqrt{v_t} dW_{\perp,t} \quad (7)$$

where the instantaneous expected inflation rate is given by

$$\pi_t = \rho_0^\pi + \rho_x^{\pi'} x_t + \rho_v^\pi v_t + \rho_\delta^\pi \delta_t + \rho_s^\pi s_t \quad (8)$$

Under the risk-neutral measure,

$$\begin{aligned} d\delta_t &= \kappa_\delta(\mu_\delta - \delta_t) dt + \sigma_\delta dW_{\delta,t} \\ &= \kappa_\delta(\mu_\delta - \delta_t) dt + \sigma_\delta (dW_{\delta,t}^* - \Lambda_{\delta,t}^N dt) \\ &\equiv \kappa_\delta^*(\mu_\delta^* - \delta_t) dt + \sigma_\delta dW_{\delta,t}^* \end{aligned}$$

and

$$\begin{aligned}
ds_t &= \left(r_t^N - \delta_t - \frac{1}{2}\sigma_s^2 + \sigma_s \Lambda_{\delta,t}^N \right) dt + \sigma_s dW_{\delta,t} \\
&\equiv (\phi_0 + \phi'_x x_t + \phi_v v_t + \phi_\delta \delta_t + \phi_s s_t) dt + \sigma_s dW_{\delta,t} \\
&\equiv (\phi_0^* + \phi_x^{*'} x_t + \phi_v^* v_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s dW_{\delta,t}^*
\end{aligned}$$

where

$$\begin{aligned}
\kappa_\delta^* &= \kappa_\delta + \sigma_\delta \lambda_\delta^N \\
\kappa_\delta^* \mu_\delta^* &= \kappa_\delta \mu_\delta - \sigma_\delta \lambda_{0,\delta}^N
\end{aligned}$$

and

$$\begin{aligned}
\phi_0 &= \rho_0^N - \frac{1}{2}\sigma_s^2 + \sigma_s \lambda_{0,\delta}^N \\
\phi_x &= \rho_x^N \\
\phi_v &= \rho_v^N \\
\phi_\delta &= \rho_\delta^N - 1 + \sigma_s \lambda_\delta^N \\
\phi_s &= \rho_s^N
\end{aligned}$$

and

$$\begin{aligned}
\phi_0^* &= \rho_0^N - \frac{1}{2}\sigma_s^2 = \phi_0 - \sigma_s \lambda_{0,\delta}^N \\
\phi_x^* &= \rho_x^N \\
\phi_v^* &= \rho_v^N \\
\phi_\delta^* &= \rho_\delta^N - 1 = \phi_\delta - \sigma_s \lambda_\delta^N \\
\phi_s^* &= \rho_s^N
\end{aligned}$$

Remark. We initialize λ_δ^N so that $\phi_\delta = 0 = \rho_\delta^N - 1 + \sigma_s \lambda_\delta^N$, or $\lambda_\delta^N = (1 - \rho_\delta^N) / \sigma_s$. Furthermore, as we show later, the long run mean of s_t is

$$s_\infty \equiv -\frac{1}{\phi_s} (\phi_0 + \phi'_x \mu + \phi_v \mu_v + \phi_\delta \mu_\delta)$$

Given the other parameters including ϕ_s , we can initialize $\lambda_{0,\delta}^N$ by matching sample mean of s_t , denoted by \widehat{s} , to its long run mean s_∞ . Given that $\phi_\delta = 0$ via initialization and $\mu = 0$ by normalization and $\phi_v = \rho_v^N = 0$ by restriction, we have

$$\begin{aligned}
\phi_0 &= -(\phi_v \mu_v + \phi_s \widehat{s}) = \rho_0^N - \frac{1}{2}\sigma_s^2 + \sigma_s \lambda_{0,\delta}^N \\
\Rightarrow \lambda_{0,\delta}^N &= -\frac{\phi_v \mu_v + \phi_s \widehat{s} + \rho_0^N - \frac{1}{2}\sigma_s^2}{\sigma_s} \\
\Rightarrow \lambda_{0,\delta}^N &= -\frac{\phi_s \widehat{s} + \rho_0^N - \frac{1}{2}\sigma_s^2}{\sigma_s}
\end{aligned}$$

NOTE:

$$dx_t = \mathcal{K}^*(\mu^* - x_t) dt + \Sigma dW_{x,t}^* \quad (9)$$

$$dv_t = \kappa_v^*(\mu_v^* - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t}^* + \rho dW_{\perp,t}^* \right) \quad (10)$$

$$d\delta_t = \kappa_\delta^*(\mu_\delta^* - \delta_t) dt + \sigma_\delta dW_{\delta,t}^* \quad (11)$$

$$ds_t = (\phi_0^* + \phi_x^{*'} x_t + \phi_v^* v_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s dW_{\delta,t}^* \quad (12)$$

Oil futures. Let $s_t \equiv \log(S_t)$ denote the spot oil price.

$$\begin{aligned} F_{t,\tau}^{oil} &= E_t^* [\exp(s_{t+\tau})] \\ &\equiv \exp(A_\tau^{oil} + B_\tau^{oil} x_t + C_\tau^{oil} v_t + D_\tau^{oil} \delta_t + E_\tau^{oil} s_t) \end{aligned}$$

where

$$\begin{aligned} \dot{A}_\tau^{oil} &= (\mathcal{K}^* \mu^*)' B_\tau^{oil} + (\kappa_v^* \mu_v^*) C_\tau^{oil} + (\kappa_\delta^* \mu_\delta^*) D_\tau^{oil} + \phi_0^* E_\tau^{oil} \\ &\quad + \frac{1}{2} B_\tau^{oil'} \Sigma \Sigma' B_\tau^{oil} + \frac{1}{2} \sigma_\delta^2 (D_\tau^{oil})^2 + \frac{1}{2} \sigma_s^2 (E_\tau^{oil})^2 \\ \dot{B}_\tau^{oil} &= -(\mathcal{K}^*)' B_\tau^{oil} + \phi_x^* E_\tau^{oil} \\ \dot{C}_\tau^{oil} &= -\kappa_v^* C_\tau^{oil} + \frac{1}{2} \sigma_v^2 (C_\tau^{oil})^2 + \phi_v^* E_\tau^{oil} \\ \dot{D}_\tau^{oil} &= -\kappa_\delta^* D_\tau^{oil} + \phi_\delta^* E_\tau^{oil} \\ \dot{E}_\tau^{oil} &= \phi_s^* E_\tau^{oil} \end{aligned}$$

and the initial conditions are: $A_0^{oil} = B_0^{oil} = C_0^{oil} = D_0^{oil} = 0$ and $E_0^{oil} = 1$.

For simplicity, we assume

$$\rho_v^N = 0 \tag{13}$$

which implies $\phi_v^* = \phi_v = 0$.

Consider the transformation

$$\begin{aligned} \mathcal{A} &= A_\tau^{oil} \\ \mathcal{B} &= \begin{pmatrix} B_\tau^{oil} \\ D_\tau^{oil} \\ E_\tau^{oil} - 1 \end{pmatrix} \\ \mathcal{C} &= C_\tau^{oil} \end{aligned}$$

Then $\mathcal{A}(0) = \mathcal{B}(0) = \mathcal{C}(0) = 0$ and

$$\begin{aligned} \dot{\mathcal{A}} &= \left(\phi_0^* + \frac{1}{2} \sigma_s^2 \right) + \begin{pmatrix} \mathcal{K}^* \mu^* \\ \kappa_\delta^* \mu_\delta^* \\ \phi_0^* + \sigma_s^2 \end{pmatrix}' \mathcal{B} + (\kappa_v^* \mu_v^*) \mathcal{C} + \frac{1}{2} \mathcal{B}' \begin{pmatrix} \Sigma \Sigma' & & \\ & \sigma_\delta^2 & \\ & & \sigma_s^2 \end{pmatrix} \mathcal{B} \\ \dot{\mathcal{B}} &= \begin{pmatrix} \phi_x^* \\ \phi_\delta^* \\ \phi_s^* \end{pmatrix} + \begin{pmatrix} -(\mathcal{K}^*)' & 0 & \phi_x^* \\ 0 & -\kappa_\delta^* & \phi_\delta^* \\ 0 & 0 & \phi_s^* \end{pmatrix} \mathcal{B} \\ \dot{\mathcal{C}} &= -\kappa_v^* \mathcal{C} + \frac{1}{2} \sigma_v^2 \mathcal{C}^2 \end{aligned}$$

Based on the observation $M_t^R = M_t^N Q_t$, we have

$$\begin{aligned} dM_t^R / M_t^R &= dM_t^N / M_t^N + dQ_t / Q_t + (dM_t^N / M_t^N) \cdot (dQ_t / Q_t) \\ &= -r_t^N dt - \Lambda_{x,t}^{N'} dW_{x,t} - \Lambda_{v,t}^N dW_{v,t} - \Lambda_{\perp,t}^N dW_{\perp,t} - \Lambda_{\delta,t}^N dW_{\delta,t} \\ &\quad + \left[\pi_t + \frac{1}{2} (\sigma_q' \sigma_q + v_t) - \sigma_q' \Lambda_{x,t}^N - \sqrt{v_t} \Lambda_{\perp,t}^N \right] dt + \sigma_q' dW_{x,t} + \sqrt{v_t} dW_{\perp,t} \\ &\equiv -r_t^R dt - \Lambda_{x,t}^{R'} dW_{x,t} - \Lambda_{v,t}^R dW_{v,t} - \Lambda_{\perp,t}^R dW_{\perp,t} - \Lambda_{\delta,t}^R dW_{\delta,t} \end{aligned}$$

where

$$\begin{aligned}
r_t^R &= r_t^N - \left[\pi_t + \frac{1}{2} (\sigma'_q \sigma_q + v_t) \right] + \sigma'_q \Lambda_{x,t}^N + \sqrt{v_t} \Lambda_{\perp,t}^N \\
&= r_t^N - \left[\pi_t + \frac{1}{2} (\sigma'_q \sigma_q + v_t) \right] + \sigma'_q (\lambda_{0,x}^N + \lambda_x^{N'} x_t) + \gamma_v^\perp v_t \\
&\equiv \rho_0^R + \rho_x^{R'} x_t + \rho_v^R v_t + \rho_\delta^R \delta_t + \rho_s^R s_t \\
\Lambda_{x,t}^R &= \Lambda_{x,t}^N - \sigma_q \equiv \lambda_{0,x}^R + \lambda_x^{R'} x_t \\
\Lambda_{v,t}^R &= \Lambda_{v,t}^N = \gamma_v \sqrt{v_t}, \\
\Lambda_{\perp,t}^R &= \Lambda_{\perp,t}^N - \sqrt{v_t} = (\gamma_v^\perp - 1) \sqrt{v_t} \\
\Lambda_{\delta,t}^R &= \Lambda_{\delta,t}^N \equiv \lambda_{0,\delta}^R + \lambda_\delta^R \delta_t
\end{aligned}$$

and

$$\begin{aligned}
\rho_0^R &= \rho_0^N - \rho_0^\pi - \frac{1}{2} \sigma'_q \sigma_q + \lambda_{0,x}' \sigma_q \\
\rho_x^R &= \rho_x^N - \rho_x^\pi + \lambda_x^{N'} \sigma_q \\
\rho_v^R &= \rho_v^N - \rho_v^\pi + \gamma_v^\perp - \frac{1}{2} \\
\rho_\delta^R &= \rho_\delta^N - \rho_\delta^\pi \text{ and } \rho_s^R = \rho_s^N - \rho_s^\pi
\end{aligned}$$

and

$$\begin{aligned}
\lambda_{0,x}^R &= \lambda_{0,x}^N - \sigma_q, \text{ and } \lambda_x^R = \lambda_x^N \\
\lambda_{0,\delta}^R &= \lambda_{0,\delta}^N, \text{ and } \lambda_\delta^R = \lambda_\delta^N
\end{aligned}$$

1.1 Dynamics under the Risk-Neutral Measure and Bond Pricing

Let

$$\Lambda_t^N \equiv \begin{pmatrix} \Lambda_{x,t}^N \\ \Lambda_{v,t}^N \\ \Lambda_{\perp,t}^N \\ \Lambda_{\delta,t}^N \end{pmatrix}, W_t \equiv \begin{pmatrix} W_{x,t} \\ W_{v,t} \\ W_{\perp,t} \\ W_{\delta,t} \end{pmatrix}.$$

Then, the Radon-Nikodym derivative of the risk neutral measure \mathbb{P}^* with respect to the physical measure \mathbb{P} is given by

$$\left(\frac{d\mathbb{P}^*}{d\mathbb{P}} \right)_{t,T} = \exp \left[-\frac{1}{2} \int_t^T \Lambda_s^{N'} \Lambda_s^N ds - \int_t^T \Lambda_s^{N'} dW_s \right] \quad (14)$$

By the Girsanov theorem, $dW_t^* = dW_t + \Lambda_t^N dt$ is a standard Brownian motion under the risk-neutral probability measure \mathbb{P}^* . It implies that under the risk neutral measure,

$$\begin{aligned}
dW_{x,t}^* &= dW_{x,t} + \Lambda_{x,t}^N dt \\
dW_{v,t}^* &= dW_{v,t} + \Lambda_{v,t}^N dt \\
dW_{\perp,t}^* &= dW_{\perp,t} + \Lambda_{\perp,t}^N dt \\
dW_{\delta,t}^* &= dW_{\delta,t} + \Lambda_{\delta,t}^N dt
\end{aligned}$$

Therefore,

$$\begin{aligned}
dx_t &= \mathcal{K}(\mu - x_t) dt + \Sigma dW_{x,t} \\
&= \mathcal{K}(\mu - x_t) dt + \Sigma (dW_{x,t}^* - \Lambda_{x,t}^N dt) \\
&= \left[(\mathcal{K}\mu - \Sigma\lambda_0^N) - (\mathcal{K} + \Sigma\lambda_x^N) x_t \right] dt + \Sigma dW_{x,t}^* \\
&\equiv \mathcal{K}^*(\mu^* - x_t) dt + \Sigma dW_{x,t}^*,
\end{aligned}$$

$$\begin{aligned}
dv_t &= \kappa_v(\mu_v - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t} + \rho dW_{\perp,t} \right) \\
&= \kappa_v(\mu_v - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} (dW_{v,t}^* - \Lambda_{v,t}^N dt) + \rho (dW_{\perp,t}^* - \Lambda_{\perp,t}^N dt) \right) \\
&= \left(\kappa_v \mu_v - \left[\kappa_v + \sqrt{1 - \rho^2} \sigma_v \gamma_v + \rho \sigma_v \gamma_{\perp} \right] v_t \right) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t}^* + \rho dW_{\perp,t}^* \right) \\
&\equiv \kappa_v^*(\mu_v^* - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t}^* + \rho dW_{\perp,t}^* \right)
\end{aligned}$$

$$\begin{aligned}
d\delta_t &= \kappa_{\delta}^*(\mu_{\delta}^* - \delta_t) dt + \sigma_{\delta} dW_{\delta,t}^* \\
ds_t &= (\phi_0^* + \phi_x^* x_t + \phi_v^* v_t + \phi_{\delta}^* \delta_t + \phi_s^* s_t) dt + \sigma_s dW_{\delta,t}^*
\end{aligned}$$

and

$$\begin{aligned}
dq_t &= \pi_t dt + \sigma'_q dW_{x,t} + \sqrt{v_t} dW_{\perp,t} \\
&= (\rho_0^{\pi} + \rho_x^{\pi'} x_t + \rho_v^{\pi} v_t + \rho_{\delta}^{\pi} \delta_t + \rho_s^{\pi} s_t) dt + \sigma'_q (dW_{x,t}^* - \Lambda_{x,t}^N dt) + \sqrt{v_t} (dW_{\perp,t}^* - \Lambda_{\perp,t}^N dt) \\
&= \left(\rho_0^{\pi} + \rho_x^{\pi'} x_t + \rho_v^{\pi} v_t + \rho_{\delta}^{\pi} \delta_t + \rho_s^{\pi} s_t - \sigma'_q (\lambda_0^N + \lambda_x^N x_t) - \gamma_{\perp} v_t \right) dt + \sigma'_q dW_{x,t}^* + \sqrt{v_t} dW_{\perp,t}^* \\
&= \left(\rho_0^{\pi} - \lambda_0^{N'} \sigma_q + (\rho_x^{\pi} - \lambda_x^{N'} \sigma_q)' x_t + (\rho_v^{\pi} - \gamma_{\perp}) v_t + \rho_{\delta}^{\pi} \delta_t + \rho_s^{\pi} s_t \right) dt + \sigma'_q dW_{x,t}^* + \sqrt{v_t} dW_{\perp,t}^* \\
&\equiv (\rho_0^{\pi*} + \rho_x^{\pi*'} x_t + \rho_v^{\pi*} v_t + \rho_{\delta}^{\pi*} \delta_t + \rho_s^{\pi*} s_t) dt + \sigma'_q dW_{x,t}^* + \sqrt{v_t} dW_{\perp,t}^*,
\end{aligned}$$

where

$$\begin{aligned}
\mathcal{K}^* &= \mathcal{K} + \Sigma \lambda_x^N \\
\mathcal{K}^* \mu^* &= \mathcal{K} \mu - \Sigma \lambda_0^N \\
\kappa_v^* &= \kappa_v + \sqrt{1 - \rho^2} \sigma_v \gamma_v + \rho \sigma_v \gamma_{\perp} \\
\kappa_v^* \mu_v^* &= \kappa_v \mu_v \\
\kappa_{\delta}^* &= \kappa_{\delta} + \sigma_{\delta} \lambda_{\delta}^N \\
\kappa_{\delta}^* \mu_{\delta}^* &= \kappa_v \mu_v - \sigma_{\delta} \lambda_{0,\delta}^N \\
\pi_t^* &= \rho_0^{\pi*} + \rho_x^{\pi*'} x_t + \rho_v^{\pi*} v_t + \rho_{\delta}^{\pi*} \delta_t + \rho_s^{\pi*} s_t \\
\rho_0^{\pi*} &= \rho_0^{\pi} - \lambda_0^{N'} \sigma_q \\
\rho_x^{\pi*} &= \rho_x^{\pi} - \lambda_x^{N'} \sigma_q \\
\rho_v^{\pi*} &= \rho_v^{\pi} - \gamma_{\perp} \\
\rho_{\delta}^{\pi*} &= \rho_{\delta}^{\pi} \text{ and } \rho_s^{\pi*} = \rho_s^{\pi}
\end{aligned}$$

We first establish a well-known result of affine-form of nominal yields in Proposition 1 below.

Proposition 1 Under this model, nominal and real bond prices take the exponential-affine form

$$P_{t,\tau}^i = \exp \left(A_\tau^i + B_\tau^{i'} x_t + C_\tau^i v_t + D_\tau^i \delta_t + E_\tau^i s_t \right), \quad i = N, R \quad (15)$$

and nominal and real yields take the affine form

$$y_{t,\tau}^i = a_\tau^i + b_\tau^{i'} x_t + c_\tau^i v_t + d_\tau^i \delta_t + e_\tau^i s_t, \quad i = N, R \quad (16)$$

where $a_\tau^i \equiv -A_\tau^i/\tau$, $b_\tau^i \equiv -B_\tau^i/\tau$, $c_\tau^i \equiv -C_\tau^i/\tau$, $d_\tau^i \equiv -D_\tau^i/\tau$ and $e_\tau^i \equiv -E_\tau^i/\tau$, and A_τ^i , B_τ^i , C_τ^i , D_τ^i , E_τ^i ($i = N, R$) satisfy the following system of ODEs:

$$\begin{aligned} \frac{dA_\tau^i}{d\tau} &= -\rho_0^i + (\mathcal{K}\mu - \Sigma\lambda_0^i)' B_\tau^i + \kappa_v^* \mu_v^* C_\tau^i + \kappa_\delta^* \mu_\delta^* D_\tau^i + \phi_0^* E_\tau^i + \frac{1}{2} B_\tau^{i'} \Sigma \Sigma' B_\tau^i + \frac{1}{2} \sigma_\delta^2 (D_\tau^i)^2 + \frac{1}{2} \sigma_s^2 (E_\tau^i)^2, \text{ with } A_0^i = 0 \\ \frac{dB_\tau^i}{d\tau} &= -\rho_x^i - (\mathcal{K} + \Sigma\lambda_x^i)' B_\tau^i + \phi_x^* E_\tau^i, \text{ with } B_0^i = 0 \\ \frac{dC_\tau^i}{d\tau} &= -\rho_v^i - \kappa_v^* C_\tau^i + \frac{1}{2} \sigma_v^2 (C_\tau^i)^2 + \phi_v^* E_\tau^i, \text{ with } C_0^i = 0 \\ \frac{dD_\tau^i}{d\tau} &= -\rho_\delta^i - \kappa_\delta^* D_\tau^i + \phi_\delta^* E_\tau^i, \text{ with } D_0^i = 0 \\ \frac{dE_\tau^i}{d\tau} &= -\rho_s^i + \phi_s^* E_\tau^i, \text{ with } E_0^i = 0 \end{aligned}$$

Consider the transformation

$$\begin{aligned} \mathcal{A} &= A_\tau^i \\ \mathcal{B} &= \begin{pmatrix} B_\tau^i \\ D_\tau^i \\ E_\tau^i \end{pmatrix} \\ \mathcal{C} &= C_\tau^i \end{aligned}$$

Then

$$\begin{aligned} \dot{\mathcal{A}} &= -\rho_0^i + \begin{pmatrix} \mathcal{K}\mu - \Sigma\lambda_0^i \\ \kappa_\delta^* \mu_\delta^* \\ \phi_0^* \end{pmatrix}' \mathcal{B} + (\kappa_v^* \mu_v^*) \mathcal{C} + \frac{1}{2} \mathcal{B}' \begin{pmatrix} \Sigma \Sigma' & & \\ & \sigma_\delta^2 & \\ & & \sigma_s^2 \end{pmatrix} \mathcal{B} \\ \dot{\mathcal{B}} &= \begin{pmatrix} -\rho_x^i \\ -\rho_\delta^i \\ -\rho_s^i \end{pmatrix} + \begin{pmatrix} -(\mathcal{K} + \Sigma\lambda_x^i)' & 0 & \phi_x^* \\ 0 & -\kappa_\delta^* & \phi_\delta^* \\ 0 & 0 & \phi_s^* \end{pmatrix} \mathcal{B} \\ \dot{\mathcal{C}} &= -\rho_v^i - \kappa_v^* \mathcal{C} + \frac{1}{2} \sigma_v^2 \mathcal{C}^2 \end{aligned}$$

Survey Yield Forecast. To calculate survey yield forecasts, we need the following results:

$$\begin{aligned} E_t[x_{t+\tau}] &= \mu + \exp(-\kappa\tau)(x_t - \mu) \\ E_t[v_{t+\tau}] &= \mu_v + \exp(-\kappa_v\tau)(v_t - \mu_v) \\ E_t[\delta_{t+\tau}] &= \mu_\delta + \exp(-\kappa_\delta\tau)(\delta_t - \mu_\delta) \end{aligned}$$

Next we calculate, $E_t[s_{t+\tau}]$. Note that

$$\begin{aligned} ds_t &= (\phi_0 + \phi_x' x_t + \phi_v v_t + \phi_\delta \delta_t + \phi_s s_t) dt + \sigma_s dW_{\delta,t} \\ d[\exp(-\phi_s t) s_t] &= \exp(-\phi_s t) [(\phi_0 + \phi_x' x_t + \phi_v v_t + \phi_\delta \delta_t) dt + \sigma_s dW_{\delta,t}] \end{aligned}$$

and

$$\begin{aligned} & \exp(-\phi_s(t+\tau))s_{t+\tau} - \exp(-\phi_s t)s_t \\ = & \int_t^{t+\tau} \exp(-\phi_s u) (\phi_0 + \phi'_x x_u + \phi_v v_u + \phi_\delta \delta_u) du + \exp(-\phi_s u) \sigma_s dW_{\delta,u} \end{aligned}$$

implying

$$\begin{aligned} & \exp(-\phi_s(t+\tau))E_t[s_{t+\tau}] - \exp(-\phi_s t)s_t \\ = & \int_t^{t+\tau} \exp(-\phi_s u) \begin{pmatrix} \phi_0 + \phi'_x([\mu + \exp(-\kappa(u-t))(x_t - \mu)]) \\ + \phi_v([\mu_v + \exp(-\kappa_v(u-t))(v_t - \mu_v)]) \\ + \phi_\delta([\mu_\delta + \exp(-\kappa_\delta(u-t))(\delta_t - \mu_\delta)]) \end{pmatrix} du \\ = & \frac{1}{\phi_s} (\exp(-\phi_s t) - \exp(-\phi_s(t+\tau))) (\phi_0 + \phi'_x \mu + \phi_v \mu_v + \phi_\delta \mu_\delta) \\ & + \exp(-\phi_s t) \phi'_x (\kappa + \phi_s I)^{-1} (I - \exp(-(\kappa + \phi_s I)\tau)) (x_t - \mu) \\ & + \exp(-\phi_s t) \phi_v (\kappa_v + \phi_s)^{-1} (1 - \exp(-(\kappa_v + \phi_s)\tau)) (v_t - \mu_v) \\ & + \exp(-\phi_s t) \phi_\delta (\kappa_\delta + \phi_s)^{-1} (1 - \exp(-(\kappa_\delta + \phi_s)\tau)) (\delta_t - \mu_\delta) \end{aligned}$$

or

$$\begin{aligned} & E_t[s_{t+\tau}] \\ = & \exp(\phi_s \tau) s_t + \frac{1}{\phi_s} (\exp(\phi_s \tau) - 1) (\phi_0 + \phi'_x \mu + \phi_v \mu_v + \phi_\delta \mu_\delta) \\ & + \phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s \tau) I - \exp(-\kappa \tau)) (x_t - \mu) \\ & + \phi_v (\kappa_v + \phi_s)^{-1} (\exp(\phi_s \tau) - \exp(-\kappa_v \tau)) (v_t - \mu_v) \\ & + \phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s \tau) - \exp(-\kappa_\delta \tau)) (\delta_t - \mu_\delta) \end{aligned}$$

and

$$Var_t[s_{t+\tau}] = E_t \left[\int_{-\tau}^0 \exp(-2\phi_s u) \sigma_s^2 du \right] = \frac{1}{2\phi_s} (\exp(2\phi_s \tau) - 1) \sigma_s^2$$

Therefore,

$$\begin{aligned} E_t^{svy}[y_{t+\tau,3m}^N] &= E_t^{mkt}[y_{t+\tau,3m}^N] + \epsilon_{t,\tau}^f \\ &= E_t[a_{3m}^N + b_{3m}^{N'} x_{t+\tau} + c_{3m}^N v_{t+\tau} + d_{3m}^N \delta_{t+\tau} + e_{3m}^N s_{t+\tau}] + \epsilon_{t,\tau}^f \\ &= a_{3m}^N + b_{3m}^{N'} [\mu + \exp(-\kappa \tau) (x_t - \mu)] \\ &\quad + c_{3m}^N [\mu_v + \exp(-\kappa_v \tau) (v_t - \mu_v)] \\ &\quad + d_{3m}^N [\mu_\delta + \exp(-\kappa_\delta \tau) (\delta_t - \mu_\delta)] \\ &\quad + e_{3m}^N \left[\exp(\phi_s \tau) s_t + \frac{1}{\phi_s} (\exp(\phi_s \tau) - 1) (\phi_0 + \phi'_x \mu + \phi_v \mu_v + \phi_\delta \mu_\delta) \right. \\ &\quad \left. + \phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s \tau) I - \exp(-\kappa \tau)) (x_t - \mu) \right. \\ &\quad \left. + \phi_v (\kappa_v + \phi_s)^{-1} (\exp(\phi_s \tau) - \exp(-\kappa_v \tau)) (v_t - \mu_v) \right. \\ &\quad \left. + \phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s \tau) - \exp(-\kappa_\delta \tau)) (\delta_t - \mu_\delta) \right] + \epsilon_{t,\tau}^f \\ &\equiv a_\tau^f + b_\tau^{f'} x_t + c_\tau^f v_t + d_\tau^f \delta_t + e_\tau^f s_t + \epsilon_{t,\tau}^f \end{aligned}$$

where

$$\begin{aligned}
a_\tau^f &= a_{3m}^N + b_{3m}^{N'} [I - \exp(-\kappa\tau)] \mu + c_{3m}^N [1 - \exp(-\kappa_v\tau)] \mu_v + d_{3m}^N [1 - \exp(-\kappa_\delta\tau)] \mu_\delta \\
&\quad + e_{3m}^N \begin{bmatrix} \frac{1}{\phi_s} (\exp(\phi_s\tau) - 1) (\phi_0 + \phi'_x\mu + \phi_v\mu_v + \phi_\delta\mu_\delta) \\ -\phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s\tau) I - \exp(-\kappa\tau)) \mu \\ -\phi_v (\kappa_v + \phi_s)^{-1} (\exp(\phi_s\tau) - \exp(-\kappa_v\tau)) \mu_v \\ -\phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s\tau) - \exp(-\kappa_\delta\tau)) \mu_\delta \end{bmatrix}
\end{aligned}$$

and

$$\begin{aligned}
b_\tau^{f'} &= b_{3m}^{N'} \exp(-\kappa\tau) + e_{3m}^N \phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s\tau) I - \exp(-\kappa\tau)) \\
c_\tau^f &= c_{3m}^N \exp(-\kappa_v\tau) + e_{3m}^N \phi_v (\kappa_v + \phi_s)^{-1} (\exp(\phi_s\tau) - \exp(-\kappa_v\tau)) \\
d_\tau^f &= d_{3m}^N \exp(-\kappa_\delta\tau) + e_{3m}^N \phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s\tau) - \exp(-\kappa_\delta\tau)) \\
e_\tau^f &= e_{3m}^N \exp(\phi_s\tau)
\end{aligned}$$

Lastly, we turn to the long-range forecast: $E_t^{mkt} [\bar{y}_{3m, T_1, T_2}^N]$ as follows. Note that

$$\begin{aligned}
&E_t \left[\frac{1}{T_2 - T_1} \int_{t+T_1}^{t+T_2} s_u du \right] \\
&= \frac{1}{T_2 - T_1} \int_{T_1}^{T_2} \begin{bmatrix} \exp(\phi_s u) s_t + \frac{1}{\phi_s} (\exp(\phi_s u) - 1) (\phi_0 + \phi'_x\mu + \phi_v\mu_v + \phi_\delta\mu_\delta) \\ +\phi'_x (\kappa + \phi_s I)^{-1} (\exp(\phi_s u) I - \exp(-\kappa u)) (x_t - \mu) \\ +\phi_v (\kappa_v + \phi_s)^{-1} (\exp(\phi_s u) - \exp(-\kappa_v u)) (v_t - \mu_v) \\ +\phi_\delta (\kappa_\delta + \phi_s)^{-1} (\exp(\phi_s u) - \exp(-\kappa_\delta u)) (\delta_t - \mu_\delta) \end{bmatrix} du \\
&= W_{T_1, T_2}^s s_t + \frac{1}{\phi_s} (W_{T_1, T_2}^s - 1) (\phi_0 + \phi'_x\mu + \phi_v\mu_v + \phi_\delta\mu_\delta) \\
&\quad + \phi'_x (\kappa + \phi_s I)^{-1} (W_{T_1, T_2}^s I - W_{T_1, T_2}^x) (x_t - \mu) \\
&\quad + \phi_v (\kappa_v + \phi_s)^{-1} (W_{T_1, T_2}^s - W_{T_1, T_2}^v) (v_t - \mu_v) \\
&\quad + \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1, T_2}^s - W_{T_1, T_2}^\delta) (\delta_t - \mu_\delta)
\end{aligned}$$

where

$$\begin{aligned}
W_{T_1, T_2}^x &= \frac{1}{T_2 - T_1} \int_{T_1}^{T_2} \exp(-\kappa s) ds = \frac{1}{T_2 - T_1} \kappa^{-1} (\exp(-\kappa T_1) - \exp(-\kappa T_2)) \\
W_{T_1, T_2}^v &= \frac{1}{T_2 - T_1} \kappa_v^{-1} (\exp(-\kappa_v T_1) - \exp(-\kappa_v T_2)) \\
W_{T_1, T_2}^\delta &= \frac{1}{T_2 - T_1} \kappa_\delta^{-1} (\exp(-\kappa_\delta T_1) - \exp(-\kappa_\delta T_2)) \\
W_{T_1, T_2}^s &= \frac{1}{T_2 - T_1} \int_{T_1}^{T_2} \exp(\phi_s u) du = \frac{1}{T_2 - T_1} \phi_s^{-1} (\exp(\phi_s T_2) - \exp(\phi_s T_1))
\end{aligned}$$

Therefore,

$$\begin{aligned}
E_t^{svy} [\bar{y}_{3m,T_1,T_2}^N] &= E_t^{mkt} [\bar{y}_{3m,T_1,T_2}^N] + \epsilon_{t,LT}^f = E_t \left[\frac{1}{T_2 - T_1} \int_{T_1}^{T_2} y_{s,3m}^N ds \right] + \epsilon_{t,LT}^f \\
&= E_t \left[\frac{1}{T_2 - T_1} \int_{T_1}^{T_2} (a_{3m}^N + b_{3m}^{N'} x_s + c_{3m}^N v_s + d_{3m}^N \delta_s + e_{3m}^N s_s) ds \right] + \epsilon_{t,LT}^f \\
&= a_{3m}^N + b_{3m}^{N'} (I - W_{T_1,T_2}) \mu + b_{3m}^{N'} W_{T_1,T_2} x_t \\
&\quad + c_{3m}^N [(1 - W_{T_1,T_2}^v) \mu_v + W_{T_1,T_2}^v v_t] + d_{3m}^N [(1 - W_{T_1,T_2}^\delta) \mu_\delta + W_{T_1,T_2}^\delta \delta_t] \\
&\quad + e_{3m}^N \left[\begin{aligned} &W_{T_1,T_2}^s s_t + \frac{1}{\phi_s} (W_{T_1,T_2}^s - 1) (\phi_0 + \phi'_x \mu + \phi_v \mu_v + \phi_\delta \mu_\delta) \\ &+ \phi'_x (\kappa + \phi_s I)^{-1} (W_{T_1,T_2}^s I - W_{T_1,T_2}^x) (x_t - \mu) \\ &+ \phi_v (\kappa_v + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^v) (v_t - \mu_v) \\ &+ \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^\delta) (\delta_t - \mu_\delta) \end{aligned} \right] + \epsilon_{t,LT}^f \\
&\equiv a_{LT}^f + b_{LT}^{f'} x_t + c_{LT}^f v_t + d_{LT}^f \delta_t + \epsilon_{t,LT}^f
\end{aligned}$$

where

$$\begin{aligned}
a_{LT}^f &= a_{3m}^N + b_{3m}^{N'} (I - W_{T_1,T_2}^x) \mu + c_{3m}^N (1 - W_{T_1,T_2}^v) \mu_v + d_{3m}^N (1 - W_{T_1,T_2}^\delta) \mu_\delta \\
&\quad + e_{3m}^N \left[\begin{aligned} &\frac{1}{\phi_s} (W_{T_1,T_2}^s - 1) (\phi_0 + \phi'_x \mu + \phi_v \mu_v + \phi_\delta \mu_\delta) - \phi'_x (\kappa + \phi_s I)^{-1} (W_{T_1,T_2}^s I - W_{T_1,T_2}^x) \mu \\ &- \phi_v (\kappa_v + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^v) \mu_v - \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^\delta) \mu_\delta \end{aligned} \right]
\end{aligned}$$

and

$$\begin{aligned}
b_{LT}^{f'} &= b_{3m}^{N'} W_{T_1,T_2}^x + e_{3m}^N \phi'_x (\kappa + \phi_s I)^{-1} (W_{T_1,T_2}^s I - W_{T_1,T_2}^x) \\
c_{LT}^f &= c_{3m}^N W_{T_1,T_2}^v + e_{3m}^N \phi_v (\kappa_v + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^v) \\
d_{LT}^f &= d_{3m}^N W_{T_1,T_2}^\delta + e_{3m}^N \phi_\delta (\kappa_\delta + \phi_s)^{-1} (W_{T_1,T_2}^s - W_{T_1,T_2}^\delta) \\
e_{LT}^f &= e_{3m}^N W_{T_1,T_2}^s
\end{aligned}$$

1.2 Dynamics under the Forward Measure and Inflation Option Pricing

Under the forward measure, we have

$$\left(\frac{d\tilde{\mathbb{P}}}{d\mathbb{P}^*} \right)_{t,T} = \frac{\exp \left(- \int_t^T r_s^N ds \right)}{P_{t,\tau}^N}$$

and

$$\Psi_t \equiv E_t^{\mathbb{P}^*} \left[\left(\frac{d\tilde{\mathbb{P}}}{d\mathbb{P}^*} \right)_{0,T} \right] = E_t^{\mathbb{P}^*} \left[\frac{\exp \left(- \int_0^T r_s^N ds \right)}{P_{0,T}^N} \right] = \frac{P_{t,\tau}^N}{P_{0,T}^N} \exp \left(- \int_0^t r_s^N ds \right)$$

We have

$$\begin{aligned}
d\Psi_t &= \frac{\exp \left(- \int_0^t r_s^N ds \right)}{P_{0,T}^N} [dP_{t,\tau}^N - r_t^N P_{t,\tau}^N dt] \\
&= \Psi_t \left[B_\tau^{N'} \Sigma dW_{x,t} + C_\tau^N \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t} + \rho dW_{\perp,t} \right) + (D_\tau^N \sigma_\delta + E_\tau^N \sigma_s) dW_{\delta,t} \right]
\end{aligned}$$

By Girsanov's Theorem, we have

$$d\tilde{W}_t = dW_t^* - \frac{d\Psi_t}{\Psi_t} \cdot dW_t^*$$

or

$$\begin{aligned} d\tilde{W}_{x,t} &= dW_t^* - \Sigma' B_\tau^N dt \\ d\tilde{W}_{v,t} &= dW_{v,t}^* - \sqrt{1 - \rho^2} \sigma_v C_\tau^N \sqrt{v_t} dt \\ d\tilde{W}_{\perp,t} &= dW_{\perp,t}^* - \rho \sigma_v C_\tau^N \sqrt{v_t} dt. \\ d\tilde{W}_{\delta,t} &= dW_{\delta,t}^* - (\sigma_\delta D_\tau^N + \sigma_s E_\tau^N) dt \end{aligned}$$

The dynamics of the state variables under the risk neutral measure is given by

$$\begin{aligned} dx_t &= [\mathcal{K}^*(\mu^* - x_t)] dt + \Sigma dW_{x,t}^* \\ dv_t &= \kappa_v^*(\mu_v^* - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t}^* + \rho dW_{\perp,t}^* \right) \\ dq_t &= (\rho_0^{\pi^*} + \rho_x^{\pi^*} x_t + \rho_v^{\pi^*} v_t + \rho_\delta^{\pi^*} v_t) dt + \sigma'_q dW_{x,t}^* + \sqrt{v_t} dW_{\perp,t}^* \\ d\delta_t &= \kappa_\delta^*(\mu_\delta^* - \delta_t) dt + \sigma_\delta dW_{\delta,t}^* \end{aligned}$$

Therefore,

$$\begin{aligned} d\delta_t &= \kappa_\delta^*(\mu_\delta^* - \delta_t) dt + \sigma_\delta dW_{\delta,t}^* \\ &= \kappa_\delta^*(\mu_\delta^* - \delta_t) dt + \sigma_\delta \left(d\tilde{W}_{\delta,t} + (\sigma_\delta D_\tau^N + \sigma_s E_\tau^N) dt \right) \\ &= (\kappa_\delta^* \mu_\delta^* + \sigma_\delta (\sigma_\delta D_\tau^N + \sigma_s E_\tau^N) - \kappa_\delta^* \delta_t) dt + \sigma_\delta d\tilde{W}_{\delta,t} \\ &\equiv \tilde{\kappa}_\delta (\tilde{\mu}_\delta - \delta_t) dt + \sigma_\delta d\tilde{W}_{\delta,t} \\ \\ dx_t &= [\mathcal{K}^*(\mu^* - x_t)] dt + \Sigma \left(d\tilde{W}_{x,t} + \Sigma' B_\tau^N dt \right) \\ &= (\mathcal{K}^* \mu^* + \Sigma \Sigma' B_\tau^N - \mathcal{K}^* x_t) dt + \Sigma d\tilde{W}_{x,t} \\ &\equiv \tilde{\mathcal{K}} (\tilde{\mu} - x_t) dt + \Sigma d\tilde{W}_{x,t}, \\ \\ dv_t &= \kappa_v^*(\mu_v^* - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} dW_{v,t}^* + \rho dW_{\perp,t}^* \right) \\ &= [\kappa_v^* \mu_v^* - (\kappa_v^* - \sigma_v^2 C_\tau^N) v_t] dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} d\tilde{W}_{v,t} + \rho d\tilde{W}_{\perp,t} \right) \\ &\equiv \tilde{\kappa}_v (\tilde{\mu}_v - v_t) dt + \sigma_v \sqrt{v_t} \left(\sqrt{1 - \rho^2} d\tilde{W}_{v,t} + \rho d\tilde{W}_{\perp,t} \right) \\ \\ ds_t &= (\phi_0^* + \phi_x^* x_t + \phi_v^* v_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s dW_{\delta,t}^* \\ &= (\phi_0^* + \phi_x^* x_t + \phi_v^* v_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s \left(d\tilde{W}_{\delta,t} + (\sigma_\delta D_\tau^N + \sigma_s E_\tau^N) dt \right) \\ &= ([\phi_0^* + \sigma_s (\sigma_\delta D_\tau^N + \sigma_s E_\tau^N)] + \phi_x^* x_t + \phi_v^* v_t + \phi_\delta^* \delta_t + \phi_s^* s_t) dt + \sigma_s d\tilde{W}_{\delta,t} \\ &\equiv (\tilde{\phi}_0 + \tilde{\phi}_x^* x_t + \tilde{\phi}_v^* v_t + \tilde{\phi}_\delta^* \delta_t + \tilde{\phi}_s^* s_t) dt + \sigma_s d\tilde{W}_{\delta,t} \end{aligned}$$

and

$$\begin{aligned}
dq_t &= (\rho_0^{\pi*} + \rho_x^{\pi*'} x_t + \rho_v^{\pi*} v_t + \rho_\delta^{\pi*} \delta_t + \rho_s^{\pi*} s_t) dt + \sigma_q' dW_{x,t}^* + \sqrt{v_t} dW_{\perp,t}^* \\
&= ([\rho_0^{\pi*} + \sigma_q' \Sigma' B_\tau^N] + \rho_x^{\pi*'} x_t + [\rho_v^{\pi*} + \rho \sigma_v C_\tau^N] v_t + \rho_\delta^{\pi*} \delta_t + \rho_s^{\pi*} s_t) dt + \sigma_q' d\tilde{W}_{x,t} + \sqrt{v_t} d\tilde{W}_{\perp,t} \\
&\equiv (\tilde{\rho}_0^\pi + \tilde{\rho}_x^{\pi'} x_t + \tilde{\rho}_v^\pi v_t + \tilde{\rho}_\delta^{\pi*} \delta_t + \tilde{\rho}_s^{\pi*} s_t) dt + \sigma_q' d\tilde{W}_{x,t} + \sqrt{v_t} d\tilde{W}_{\perp,t}
\end{aligned}$$

where

$$\begin{aligned}
\tilde{\mathcal{K}} &= \mathcal{K}^* = \mathcal{K} + \Sigma \lambda_1^N, \\
\tilde{\mathcal{K}} \tilde{\mu} &= \mathcal{K}^* \mu^* + \Sigma \Sigma' B_\tau^N = \mathcal{K} \mu - \Sigma \lambda_0^N + \Sigma \Sigma' B_\tau^N, \\
\tilde{\kappa}_v &= \kappa_v^* - \sigma_v^2 C_\tau^N = \kappa_v + \sqrt{1 - \rho^2} \sigma_v \gamma_v + \rho \sigma_v \gamma_\perp - \sigma_v^2 C_\tau^N, \\
\tilde{\kappa}_v \tilde{\mu}_v &= \kappa_v^* \mu_v^* = \kappa_v \mu_v, \\
\tilde{\kappa}_\delta &= \kappa_\delta^* = \kappa_\delta + \sigma_\delta \lambda_\delta^N \\
\tilde{\kappa}_\delta \tilde{\mu}_\delta &= \kappa_\delta^* \mu_\delta^* + \sigma_\delta (\sigma_\delta D_\tau^N + \sigma_s E_\tau^N) = \kappa_v \mu_v - \sigma_\delta \lambda_{0,\delta}^N + \sigma_\delta (\sigma_\delta D_\tau^N + \sigma_s E_\tau^N) \\
\tilde{\pi}_t &= \tilde{\rho}_0^\pi + \tilde{\rho}_x^{\pi'} x_t + \tilde{\rho}_v^\pi v_t + \tilde{\rho}_\delta^{\pi*} \delta_t + \tilde{\rho}_s^{\pi*} s_t, \\
\tilde{\rho}_0^\pi &= \rho_0^{\pi*} + \sigma_q' \Sigma' B_\tau^N = \rho_0^\pi - \lambda_0^{N'} \sigma_q + \sigma_q' \Sigma' B_\tau^N, \\
\tilde{\rho}_x^\pi &= \rho_x^{\pi*} = \rho_x^\pi - \lambda_x^{N'} \sigma_q, \\
\tilde{\rho}_v^\pi &= \rho_v^{\pi*} + \rho \sigma_v C_\tau^N = \rho_v^\pi - \gamma_\perp + \rho \sigma_v C_\tau^N. \\
\tilde{\rho}_\delta^{\pi*} &= \rho_\delta^{\pi*} \text{ and } \tilde{\rho}_s^{\pi*} = \rho_s^{\pi*}
\end{aligned}$$

Next, we compute the expected values of the state variables over the period t to $t + \tau$ under the forward measure. First, similar to the calculations under the risk neutral measure, we have

$$E_t^{\tilde{\mathbb{P}}}(x_s) = \tilde{\mu} + \exp(-\tilde{\mathcal{K}}(s-t))(x_t - \tilde{\mu})$$

and

$$\begin{aligned}
\frac{1}{\tau} E_t^{\tilde{\mathbb{P}}} \left[\int_t^{t+\tau} x_s ds \right] &= \frac{1}{\tau} \left[\int_t^{t+\tau} (\tilde{\mu} + \exp(-\tilde{\mathcal{K}}(s-t))(x_t - \tilde{\mu})) ds \right] \\
&= \tilde{\mu} + \widetilde{W}_{0,\tau}^x (x_t - \tilde{\mu}) \equiv \tilde{a}_\tau^x + \tilde{b}_\tau^x x_t
\end{aligned}$$

where $\widetilde{W}_{T_1, T_2}^x$ is defined similarly as W_{T_1, T_2}^x except that dynamics under the forward measure is used instead, and

$$\tilde{a}_\tau^x = (I - \widetilde{W}_{0,\tau}^x) \tilde{\mu} \text{ and } \tilde{b}_\tau^x = \widetilde{W}_{0,\tau}^x \equiv (\tilde{\mathcal{K}} \tau)^{-1} (I - \exp(-\tilde{\mathcal{K}} \tau))$$

Similarly (the results for δ_t are very similar and thus omitted), we have

$$\begin{aligned}
E_t^{\tilde{\mathbb{P}}}(v_s) &= \tilde{\mu}_v + \exp(-\tilde{\kappa}_v(s-t))(v_t - \tilde{\mu}_v) \\
\frac{1}{\tau} E_t^{\tilde{\mathbb{P}}} \left[\int_t^{t+\tau} v_s ds \right] &= \tilde{\mu}_v + \widetilde{W}_{0,\tau}^v (v_t - \tilde{\mu}_v) \equiv \tilde{a}_\tau^v + \tilde{b}_\tau^v v_t
\end{aligned}$$

where

$$\tilde{a}_\tau^v = \tilde{\mu}_v [1 - \widetilde{W}_{0,\tau}^v] \text{ and } \tilde{b}_\tau^v = \widetilde{W}_{0,\tau}^v \equiv (\tilde{\kappa}_v \tau)^{-1} (1 - \exp(-\tilde{\kappa}_v \tau)).$$

Furthermore,

$$\begin{aligned}
& E_t^{\tilde{\mathbb{P}}} [s_s] \\
&= \exp \left(\tilde{\phi}_s (s-t) \right) s_t + \frac{1}{\tilde{\phi}_s} \left(\exp \left(\tilde{\phi}_s (s-t) \right) - 1 \right) \left(\tilde{\phi}_0 + \tilde{\phi}'_x \mu + \tilde{\phi}_v \mu_v + \tilde{\phi}_\delta \mu_\delta \right) \\
&\quad + \tilde{\phi}'_x \left(\kappa + \tilde{\phi}_s I \right)^{-1} \left(\exp \left(\tilde{\phi}_s (s-t) \right) I - \exp (-\kappa (s-t)) \right) (x_t - \mu) \\
&\quad + \tilde{\phi}_v \left(\kappa_v + \tilde{\phi}_s \right)^{-1} \left(\exp \left(\tilde{\phi}_s (s-t) \right) - \exp (-\kappa_v (s-t)) \right) (v_t - \mu_v) \\
&\quad + \tilde{\phi}_\delta \left(\kappa_\delta + \tilde{\phi}_s \right)^{-1} \left(\exp \left(\tilde{\phi}_s (s-t) \right) - \exp (-\kappa_\delta (s-t)) \right) (\delta_t - \mu_\delta)
\end{aligned}$$

and

$$\begin{aligned}
& E_t^{\tilde{\mathbb{P}}} \left[\frac{1}{T_2 - T_1} \int_{t+T_1}^{t+T_2} s_u du \right] \\
&= \frac{1}{T_2 - T_1} \int_{T_1}^{T_2} \left[\begin{aligned} & \exp \left(\tilde{\phi}_s u \right) s_t + \frac{1}{\tilde{\phi}_s} \left(\exp \left(\tilde{\phi}_s u \right) - 1 \right) \left(\tilde{\phi}_0 + \tilde{\phi}'_x \mu + \tilde{\phi}_v \mu_v + \tilde{\phi}_\delta \mu_\delta \right) \\ & + \tilde{\phi}'_x \left(\kappa + \tilde{\phi}_s I \right)^{-1} \left(\exp \left(\tilde{\phi}_s u \right) I - \exp (-\kappa u) \right) (x_t - \mu) \\ & + \tilde{\phi}_v \left(\kappa_v + \tilde{\phi}_s \right)^{-1} \left(\exp \left(\tilde{\phi}_s u \right) - \exp (-\kappa_v u) \right) (v_t - \mu_v) \\ & + \tilde{\phi}_\delta \left(\kappa_\delta + \tilde{\phi}_s \right)^{-1} \left(\exp \left(\tilde{\phi}_s u \right) - \exp (-\kappa_\delta u) \right) (\delta_t - \mu_\delta) \end{aligned} \right] du \\
&= \widetilde{W}_{T_1, T_2}^s s_t + \frac{1}{\tilde{\phi}_s} \left(\widetilde{W}_{T_1, T_2}^s - 1 \right) \left(\tilde{\phi}_0 + \tilde{\phi}'_x \mu + \tilde{\phi}_v \mu_v + \tilde{\phi}_\delta \mu_\delta \right) \\
&\quad + \tilde{\phi}'_x \left(\kappa + \tilde{\phi}_s I \right)^{-1} \left(\widetilde{W}_{T_1, T_2}^s I - \widetilde{W}_{T_1, T_2}^x \right) (x_t - \mu) \\
&\quad + \tilde{\phi}_v \left(\kappa_v + \tilde{\phi}_s \right)^{-1} \left(\widetilde{W}_{T_1, T_2}^s - \widetilde{W}_{T_1, T_2}^v \right) (v_t - \mu_v) \\
&\quad + \tilde{\phi}_\delta \left(\kappa_\delta + \tilde{\phi}_s \right)^{-1} \left(\widetilde{W}_{T_1, T_2}^s - \widetilde{W}_{T_1, T_2}^\delta \right) (\delta_t - \mu_\delta)
\end{aligned}$$

implying

$$E_t^{\tilde{\mathbb{P}}} \left[\frac{1}{\tau} \int_t^{t+\tau} s_u du \right] \equiv \tilde{a}_\tau^s + \tilde{b}_\tau^{s,x} x_t + \tilde{b}_\tau^{s,v} v_t + \tilde{b}_\tau^{s,\delta} v_t + \tilde{b}_\tau^{s,s} s_t$$

where

$$\begin{aligned}
\tilde{a}_\tau^s &\equiv \frac{1}{\tilde{\phi}_s} \left(\widetilde{W}_{0,\tau}^s - 1 \right) \left(\tilde{\phi}_0 + \tilde{\phi}'_x \mu + \tilde{\phi}_v \mu_v + \tilde{\phi}_\delta \mu_\delta \right) \\
&\quad - \tilde{\phi}'_x \left(\kappa + \tilde{\phi}_s I \right)^{-1} \left(\widetilde{W}_{0,\tau}^s I - \widetilde{W}_{0,\tau}^x \right) \mu \\
&\quad - \tilde{\phi}_v \left(\kappa_v + \tilde{\phi}_s \right)^{-1} \left(\widetilde{W}_{0,\tau}^s - \widetilde{W}_{0,\tau}^v \right) \mu_v \\
&\quad - \tilde{\phi}_\delta \left(\kappa_\delta + \tilde{\phi}_s \right)^{-1} \left(\widetilde{W}_{0,\tau}^s - \widetilde{W}_{0,\tau}^\delta \right) \mu_\delta
\end{aligned}$$

and

$$\begin{aligned}
\tilde{b}_\tau^{s,x} &\equiv \tilde{\phi}'_x \left(\kappa + \tilde{\phi}_s I \right)^{-1} \left(\tilde{W}_{0,\tau}^s I - \tilde{W}_{0,\tau}^x \right) \\
\tilde{b}_\tau^{s,v} &\equiv \tilde{\phi}'_v \left(\kappa_v + \tilde{\phi}_s \right)^{-1} \left(\tilde{W}_{0,\tau}^s - \tilde{W}_{0,\tau}^v \right) \\
\tilde{b}_\tau^{s,\delta} &\equiv \tilde{\phi}'_\delta \left(\kappa_\delta + \tilde{\phi}_s \right)^{-1} \left(\tilde{W}_{0,\tau}^s - \tilde{W}_{0,\tau}^\delta \right) \\
\tilde{b}_\tau^{s,s} &\equiv \tilde{W}_{0,\tau}^s
\end{aligned}$$

We can now calculate inflation expectation and variance as follows:

$$\begin{aligned}
E_t^{\tilde{\mathbb{P}}} \left[\log \left(\frac{Q_{t+\tau}}{Q_t} \right) \right] &= E_t^{\tilde{\mathbb{P}}} \left[\int_t^{t+\tau} \tilde{\pi}_s ds \right] = E_t^{\tilde{\mathbb{P}}} \left[\int_t^{t+\tau} \left(\tilde{\rho}_0^\pi + \tilde{\rho}_x^{\pi'} x_s + \tilde{\rho}_v^\pi v_s + \tilde{\rho}_\delta^\pi \delta_s + \tilde{\rho}_s^\pi s_s \right) ds \right] \\
&= \tau \left(\begin{aligned} &\tilde{\rho}_0^\pi + \tilde{\rho}_x^{\pi'} \left(\tilde{a}_\tau^x + \tilde{b}_\tau^x x_t \right) + \tilde{\rho}_v^\pi \left(\tilde{a}_\tau^v + \tilde{b}_\tau^v v_t \right) + \tilde{\rho}_\delta^\pi \left(\tilde{a}_\tau^\delta + \tilde{b}_\tau^\delta \delta_t \right) \\ &+ \tilde{\rho}_s^\pi \left(\tilde{a}_\tau^s + \tilde{b}_\tau^{s,x} x_t + \tilde{b}_\tau^{s,v} v_t + \tilde{b}_\tau^{s,\delta} \delta_t + \tilde{b}_\tau^{s,s} s_t \right) \end{aligned} \right) \\
&\equiv \tau \left(\tilde{a}_\tau^\pi + \tilde{b}_\tau^{\pi'} x_t + \tilde{c}_\tau^\pi v_t + \tilde{c}_\tau^{\pi} \delta_t + \tilde{c}_\tau^{\pi} s_t \right)
\end{aligned}$$

and

$$Var_t^{\tilde{\mathbb{P}}} \left[\log \left(\frac{Q_{t+\tau}}{Q_t} \right) \right] = E_t^{\tilde{\mathbb{P}}} \left[\int_t^{t+\tau} \left(\sigma'_q \sigma_q + v_s \right) ds \right] = \tau \left(\sigma'_q \sigma_q + \tilde{a}_\tau^v + \tilde{b}_\tau^v v_t \right) \equiv \tau \left(\tilde{d}_\tau^\pi + \tilde{e}_\tau^\pi v_t \right),$$

where

$$\begin{aligned}
\tilde{a}_\tau^\pi &= \tilde{\rho}_0^\pi + \tilde{\rho}_x^{\pi'} \tilde{a}_\tau^x + \tilde{\rho}_v^\pi \tilde{a}_\tau^v + \tilde{\rho}_\delta^\pi \tilde{a}_\tau^\delta + \tilde{\rho}_s^\pi \tilde{a}_\tau^s, \\
\tilde{b}_\tau^\pi &= \tilde{b}_\tau^{x'} \tilde{\rho}_x^\pi + \tilde{b}_\tau^{s,x'} \tilde{\rho}_s^\pi, \\
\tilde{c}_\tau^\pi &= \tilde{\rho}_v^\pi \tilde{b}_\tau^v + \tilde{\rho}_s^\pi \tilde{b}_\tau^{s,v}, \\
\tilde{c}_\tau^{\pi} &= \tilde{\rho}_\delta^\pi \tilde{b}_\tau^\delta + \tilde{\rho}_s^\pi \tilde{b}_\tau^{s,\delta}, \\
\tilde{c}_\tau^{\pi} &= \tilde{\rho}_s^\pi \tilde{b}_\tau^{s,s}, \\
\tilde{d}_\tau^\pi &= \sigma'_q \sigma_q + \tilde{a}_\tau^v \\
\tilde{e}_\tau^\pi &= \tilde{b}_\tau^v.
\end{aligned}$$

Finally, we turn to inflation option pricing. The price of a τ -maturity inflation cap with strike K is given by

$$\begin{aligned}
P_{t,\tau,K}^{CAP} &= \exp \left(-\tau y_{t,\tau}^N \right) E_t^{\tilde{\mathbb{P}}} \left[\left(\frac{Q_{t+\tau}}{Q_t} - (1+K)^\tau \right)^+ \right] \\
&= \exp \left(-\tau y_{t,\tau}^N \right) E_t^{\tilde{\mathbb{P}}} \left[\left(\exp \left(\log \left(\frac{Q_{t+\tau}}{Q_t} \right) \right) - (1+K)^\tau \right)^+ \right] \\
&= \exp \left(-\tau y_{t,\tau}^N \right) \left[\exp \left(\tau \left(\left(\tilde{a}_\tau^\pi + \frac{\tilde{d}_\tau^\pi}{2} \right) + \tilde{b}_\tau^{\pi'} x_t + \left(\tilde{c}_\tau^\pi + \frac{\tilde{e}_\tau^\pi}{2} \right) v_t + \tilde{c}_\tau^{\pi} \delta_t + \tilde{c}_\tau^{\pi} s_t \right) \right) \right. \\
&\quad \times \Phi \left(\frac{\tau}{\sigma} \left[-\ln(1+K) + \left(\tilde{a}_\tau^\pi + \tilde{d}_\tau^\pi \right) + \tilde{b}_\tau^{\pi'} x_t + \left(\tilde{c}_\tau^\pi + \tilde{e}_\tau^\pi \right) v_t + \tilde{c}_\tau^{\pi} \delta_t + \tilde{c}_\tau^{\pi} s_t \right] \right) \\
&\quad \left. - (1+K)^\tau \Phi \left(\frac{\tau}{\sigma} \left[-\ln(1+K) + \tilde{a}_\tau^\pi + \tilde{b}_\tau^{\pi'} x_t + \tilde{c}_\tau^\pi v_t + \tilde{c}_\tau^{\pi} \delta_t + \tilde{c}_\tau^{\pi} s_t \right] \right) \right],
\end{aligned}$$

and the price of a τ -maturity inflation cap with strike K is given by

$$\begin{aligned}
P_{t,\tau,K}^{FLO} &= \exp(-\tau y_{t,\tau}^N) E_t^{\tilde{\mathbb{P}}} \left[\left((1+K)^\tau - \frac{Q_{t+\tau}}{Q_t} \right)^+ \right] \\
&= \exp(-\tau y_{t,\tau}^N) E_t^{\tilde{\mathbb{P}}} \left[\left((1+K)^\tau - \exp \left(\log \left(\frac{Q_{t+\tau}}{Q_t} \right) \right) \right)^+ \right] \\
&= \exp(-\tau y_{t,\tau}^N) \left[-\exp \left(\tau \left(\left(\tilde{a}_\tau^\pi + \frac{\tilde{d}_\tau^\pi}{2} \right) + \tilde{b}_\tau^{\pi'} x_t + \left(\tilde{c}_\tau^\pi + \frac{\tilde{e}_\tau^\pi}{2} \right) v_t \right) \right) \right. \\
&\quad \times \Phi \left(-\frac{\tau}{\sigma} \left[-\ln(1+K) + \left(\tilde{a}_\tau^\pi + \frac{\tilde{d}_\tau^\pi}{2} \right) + \tilde{b}_\tau^{\pi'} x_t + (\tilde{c}_\tau^\pi + \tilde{e}_\tau^\pi) v_t \right] \right) \\
&\quad \left. + (1+K)^\tau \Phi \left(-\frac{\tau}{\sigma} \left[-\ln(1+K) + \tilde{a}_\tau^\pi + \tilde{b}_\tau^{\pi'} x_t + \tilde{c}_\tau^\pi v_t \right] \right) \right]
\end{aligned}$$

where we used the fact that for a normal random variable $\tilde{z} \sim N(\mu, \sigma^2)$,

$$\begin{aligned}
E \left[(ae^{\tilde{z}} - b)^+ \right] &= a \exp \left(\mu + \frac{\sigma^2}{2} \right) \Phi \left(\frac{\ln(a/b) + (\mu + \sigma^2)}{\sigma} \right) - b \Phi \left(\frac{\ln(a/b) + \mu}{\sigma} \right), \\
E \left[(b - ae^{\tilde{z}})^+ \right] &= -a \exp \left(\mu + \frac{\sigma^2}{2} \right) \Phi \left(-\frac{\ln(a/b) + (\mu + \sigma^2)}{\sigma} \right) + b \Phi \left(-\frac{\ln(a/b) + \mu}{\sigma} \right).
\end{aligned}$$

Remark. We can derive option-implied inflation expectations as follows:

$$\begin{aligned}
P_{t,\tau,K}^{CAP} - P_{t,\tau,K}^{FLO} &= \exp(-\tau y_{t,\tau}^N) E_t^{\tilde{\mathbb{P}}} \left[\left(\frac{Q_{t+\tau}}{Q_t} - (1+K)^\tau \right)^+ \right] - \exp(-\tau y_{t,\tau}^N) E_t^{\tilde{\mathbb{P}}} \left[\left((1+K)^\tau - \frac{Q_{t+\tau}}{Q_t} \right)^+ \right] \\
&= \exp(-\tau y_{t,\tau}^N) E_t^{\tilde{\mathbb{P}}} \left[\frac{Q_{t+\tau}}{Q_t} - (1+K)^\tau \right]
\end{aligned}$$

1.3 State Dynamics

We first consider the discrete-time dynamics of the state variable q_t between time $t - \Delta t$ and t . From $dq_t = \pi_t dt + \sigma'_q dW_{x,t} + \sqrt{v_t} dW_{\perp,t}$, we have

$$q_t = q_{t-\Delta t} + (\rho_0^\pi \Delta t + (\rho_x^{\pi'} \Delta t) x_t + (\rho_v^\pi \Delta t) v_t + (\rho_\delta^\pi \Delta t) \delta_t + (\rho_s^\pi \Delta t) s_t) + \eta_t^q$$

where $\eta_t^q \equiv \int_{t-\Delta t}^t (\sigma'_q dW_{x,s} + \sqrt{v_s} dW_{\perp,s}) \sim N(0, \Omega_{t-\Delta t}^q)$ and

$$\begin{aligned}
\Omega_{t-\Delta t}^q &\equiv \text{Var}_{t-\Delta t}(\eta_t^q) = \sigma'_q \sigma_q \Delta t + E_{t-\Delta t} \left[\int_{t-\Delta t}^t v_s ds \right] \\
&= \sigma'_q \sigma_q \Delta t + \left[\int_0^{\Delta t} (\mu_v (1 - e^{-\kappa_v s}) + e^{-\kappa_v s} v_{t-\Delta t}) ds \right] \\
&= \sigma'_q \sigma_q \Delta t + \mu_v \Delta t + (v_{t-\Delta t} - \mu_v) \frac{1 - \exp(-\kappa_v \Delta t)}{\kappa_v}.
\end{aligned}$$

Similarly, for the state variable x_t we have

$$x_t = \exp(-\mathcal{K}\Delta t) x_{t-\Delta t} + (I - \exp(-\mathcal{K}\Delta t)) \mu + \eta_t^x,$$

where $\eta_t^x = \int_0^{\Delta t} \exp(-\kappa s) \Sigma dW_{x,s} \sim N(0, \Omega_{t-\Delta t}^x)$ and

$$\Omega_{t-\Delta t}^x \equiv \text{Var}_{t-\Delta t}(\eta_t^x) = \int_0^{\Delta t} \exp(-\mathcal{K}s) \Sigma \Sigma' \exp(-\mathcal{K}'s) ds = N \Xi N',$$

with $\mathcal{K} = NDN^{-1}$, $D = \text{diag}([d_1, \dots, d_N])$, and $\Xi_{i,j} = [(N^{-1}\Sigma)(N^{-1}\Sigma)']_{i,j} \frac{1 - \exp[-(d_i + d_j) \cdot t]}{(d_i + d_j)}$. The covariance matrix between η_t^x and η_t^q is given by

$$\Omega_{t-\Delta t}^{xq} = \text{Cov}_{t-\Delta t}[\eta_t^x, \eta_t^q] = \int_0^{\Delta t} \exp(-\mathcal{K}s) \Sigma \sigma_q ds = \mathcal{K}^{-1} (I - \exp(-\mathcal{K}\Delta t)) \Sigma \sigma_q.$$

where I signifies the identity matrix.

Next, we consider the state variable v_t . From $dv_t = \kappa_v (\mu_v - v_t) dt + \sigma_v \sqrt{v_t} (\sqrt{1 - \rho^2} dW_{v,t} + \rho dW_{\perp,t})$, we have

$$v_t = e^{-\kappa_v \Delta t} v_{t-\Delta t} + \mu_v (1 - e^{-\kappa_v \Delta t}) + \eta_t^v$$

where $\eta_t^v = \sigma_v \int_{t-\Delta t}^t e^{\kappa_v(s-t)} \sqrt{v_s} (\sqrt{1 - \rho^2} dB_s^v + \rho dB_s^\perp) \sim N(0, \Omega_{t-1}^v)$ and

$$\begin{aligned} \Omega_{t-\Delta t}^v &= E_{t-\Delta t} \left[\sigma_v^2 \int_{t-\Delta t}^t e^{2\kappa_v(s-t)} v_s ds \right] \\ &= \mu_v \sigma_v^2 \frac{(1 - e^{-\kappa_v \Delta t})^2}{2\kappa_v} + v_{t-1} \sigma_v^2 \frac{e^{-\kappa_v \Delta t} - e^{-2\kappa_v \Delta t}}{\kappa_v} \end{aligned}$$

The covariance between η_t^v and η_t^x is zero by construction while the covariance between the inflation and volatility innovation terms is

$$\begin{aligned} \Omega_{t-\Delta t}^{vq} &= \text{Cov}_{t-\Delta t}[\eta_t^v, \eta_t^q] = \rho \sigma_v E_{t-\Delta t} \left[\int_{t-\Delta t}^t e^{\kappa_v(s-t)} v_s ds \right] \\ &= \rho \sigma_v \left[\mu_v \frac{(1 - e^{-\frac{\kappa_v}{2} \Delta t})^2}{\kappa_v} + v_{t-\Delta t} \frac{e^{-\frac{\kappa_v}{2} \Delta t} - e^{-\kappa_v \Delta t}}{\kappa_v/2} \right]. \end{aligned}$$

Next, we consider the state variable δ_t . From $d\delta_t = \kappa_\delta (\mu_\delta - \delta_t) dt + \sigma_\delta dW_{\delta,t}$, we have

$$\delta_t = e^{-\kappa_\delta \Delta t} \delta_{t-\Delta t} + \mu_\delta (1 - e^{-\kappa_\delta \Delta t}) + \eta_t^\delta$$

where $\eta_t^\delta = \sigma_\delta \int_{t-\Delta t}^t e^{\kappa_\delta(u-t)} dW_{\delta,u} \sim N(0, \Omega_{t-\Delta t}^\delta)$ and

$$\Omega_{t-\Delta t}^\delta = E_{t-\Delta t} \left[\sigma_\delta^2 \int_{t-\Delta t}^t e^{2\kappa_\delta(s-t)} ds \right] = \sigma_\delta^2 \frac{1 - e^{-2\kappa_\delta \Delta t}}{2\kappa_\delta}$$

Last, we consider the state variable s_t .

$$s_t - s_{t-\Delta t} = (\phi_0 \Delta t + (\phi_x \Delta t)' x_{t-\Delta t} + \phi_v \Delta t v_{t-\Delta t} + \phi_\delta \Delta t \delta_{t-\Delta t} + \phi_s \Delta t s_{t-\Delta t}) + \eta_t^s$$

where $\eta_t^s = \sigma_s \int_{t-\Delta t}^t \exp(-\phi_s(u-t)) dW_{\delta,u} \sim N(0, \Omega_{t-\Delta t}^s)$ and

$$\Omega_{t-\Delta t}^s = E_{t-\Delta t} \left[\sigma_s^2 \int_{t-\Delta t}^t e^{2(-\phi_s)(u-t)} du \right] = \sigma_s^2 \frac{e^{2\phi_s \Delta t} - 1}{2\phi_s}$$

and

$$\begin{aligned}
\Omega_{t-\Delta t}^{\delta s} &= \sigma_\delta \sigma_s E_{t-\Delta t} \left[\int_{t-\Delta t}^t e^{\kappa_\delta(u-t)} dW_{\delta,u} \int_{t-\Delta t}^t e^{-\phi_s(u-t)} dW_{\delta,u} \right] \\
&= \sigma_\delta \sigma_s E_{t-\Delta t} \left[\int_{t-\Delta t}^t e^{(\kappa_\delta - \phi_s)(u-t)} du \right] \\
&= \sigma_\delta \sigma_s \frac{1 - e^{-(\kappa_\delta - \phi_s)\Delta t}}{\kappa_\delta - \phi_s}
\end{aligned}$$

In summary, the dynamics of the state vector $Z_t = (q_t, x'_t, v_t, \delta_t, s_t)'$ follows the VAR process

$$\begin{aligned}
Z_t &= \mathcal{A} + \mathcal{B}Z_{t-\Delta t} + \eta_t \\
\text{where } \mathcal{A} &= \begin{bmatrix} \rho_0^\pi \Delta t \\ (I - \exp(-\mathcal{K}\Delta t)) \mu \\ \begin{pmatrix} 1 - e^{-\kappa_v \Delta t} \\ 1 - e^{-\kappa_\delta \Delta t} \end{pmatrix} \mu_v \\ \phi_0 \Delta t \end{bmatrix}, \quad \mathcal{B} = \begin{bmatrix} 1 & \rho_x^{\pi'} \Delta t & \rho_v^\pi \Delta t & \rho_\delta^\pi \Delta t & \rho_s^\pi \Delta t \\ 0 & \exp(-\mathcal{K}\Delta t) & & & \\ 0 & 0_{1 \times 3} & e^{-\kappa_v \Delta t} & & \\ 0 & 0_{1 \times 3} & 0 & e^{-\kappa_\delta \Delta t} & \\ 0 & \phi'_x \Delta t & \phi_v \Delta t & \phi_\delta \Delta t & 1 + \phi_s \Delta t \end{bmatrix}, \quad \eta_t = \\
\begin{pmatrix} \eta_t^q \\ \eta_t^x \\ \eta_t^v \\ \eta_t^\delta \\ \eta_t^s \end{pmatrix} &\sim N(0, \Omega_{t-\Delta t}) \text{ and } \Omega_{t-\Delta t} = \begin{bmatrix} \Omega_{t-\Delta t}^q & \Omega_{t-\Delta t}^{xq'} & \Omega_{t-\Delta t}^{vq} & & \\ \Omega_{t-\Delta t}^{xq} & \Omega_{t-\Delta t}^x & & & \\ \Omega_{t-\Delta t}^{vq} & & \Omega_{t-\Delta t}^v & & \\ & & & \Omega_{t-\Delta t}^\delta & \Omega_{t-\Delta t}^{\delta s} \\ & & & \Omega_{t-\Delta t}^{\delta s} & \Omega_{t-\Delta t}^s \end{bmatrix}.
\end{aligned}$$