



developerWorks Technical topics Linux Technical library

Inside the Linux boot process

Take a guided tour from the Master Boot Record to the first user-space application

The process of booting a Linux® system consists of a number of stages. But whether you're booting a standard x86 desktop or a deeply embedded PowerPC® target, much of the flow is surprisingly similar. This article explores the Linux boot process from the initial bootstrap to the start of the first user-space application. Along the way, you'll learn about various other boot-related topics such as the boot loaders, kernel decompression, the initial RAM disk, and other elements of Linux boot.

Share:

M. Tim Jones is an embedded software architect and the author of GNU/Linux Application Programming, AI Application Programming, and BSD Sockets Programming from a Multilanguage Perspective. His engineering background ranges from the development of kernels for geosynchronous spacecraft to embedded systems architecture and networking protocols development. Tim is a Consultant Engineer for Emulex Corp. in Longmont, Colorado.

31 May 2006

Also available in [Russian](#) [Portuguese](#)

In the early days, bootstrapping a computer meant feeding a paper tape containing a boot program or manually loading a boot program using the front panel address/data/control switches. Today's computers are equipped with facilities to simplify the boot process, but that doesn't necessarily make it simple.

Let's start with a high-level view of Linux boot so you can see the entire landscape. Then we'll review what's going on at each of the individual steps. Source references along the way will help you navigate the kernel tree and dig in further.



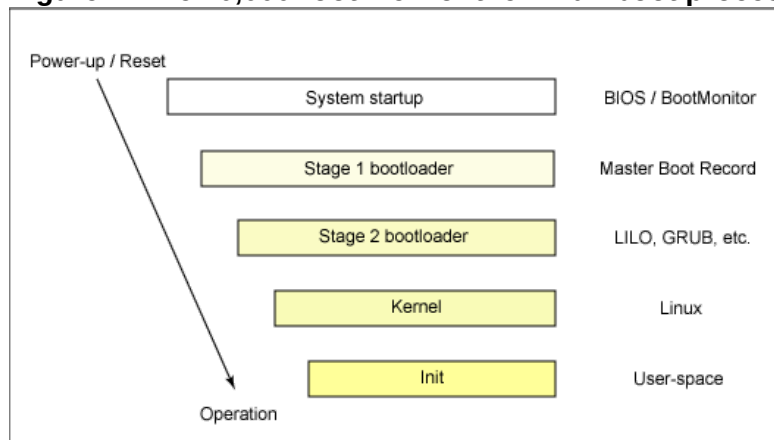
Develop and deploy your
next
app on the IBM Bluemix
cloud platform.

Start building for free

Overview

Figure 1 gives you the 20,000-foot view.

Figure 1. The 20,000-foot view of the Linux boot process



When a system is first booted, or is reset, the processor executes code at a well-known location. In a personal computer (PC), this location is in the basic input/output system (BIOS), which is stored in flash memory on the motherboard. The central processing unit (CPU) in an embedded system invokes the reset vector to start a program at a known address in flash/ROM. In either case, the result is the same. Because PCs offer so much flexibility, the BIOS must determine which devices are candidates for boot. We'll look at this in more detail later.

When a boot device is found, the first-stage boot loader is loaded into RAM and executed. This boot loader is less than 512 bytes in length (a single sector), and its job is to load the second-stage boot

loader.

When the second-stage boot loader is in RAM and executing, a splash screen is commonly displayed, and Linux and an optional initial RAM disk (temporary root file system) are loaded into memory. When the images are loaded, the second-stage boot loader passes control to the kernel image and the kernel is decompressed and initialized. At this stage, the second-stage boot loader checks the system hardware, enumerates the attached hardware devices, mounts the root device, and then loads the necessary kernel modules. When complete, the first user-space program (`init`) starts, and high-level system initialization is performed.

That's Linux boot in a nutshell. Now let's dig in a little further and explore some of the details of the Linux boot process.

System startup

The system startup stage depends on the hardware that Linux is being booted on. On an embedded platform, a bootstrap environment is used when the system is powered on, or reset. Examples include U-Boot, RedBoot, and MicroMonitor from Lucent. Embedded platforms are commonly shipped with a boot monitor. These programs reside in special region of flash memory on the target hardware and provide the means to download a Linux kernel image into flash memory and subsequently execute it. In addition to having the ability to store and boot a Linux image, these boot monitors perform some level of system test and hardware initialization. In an embedded target, these boot monitors commonly cover both the first- and second-stage boot loaders.

In a PC, booting Linux begins in the BIOS at address `0xFFFF0`. The first step of the BIOS is the power-on self test (POST). The job of the POST is to perform a check of the hardware. The second step of the BIOS is local device enumeration and initialization.

Given the different uses of BIOS functions, the BIOS is made up of two parts: the POST code and runtime services. After the POST is complete, it is flushed from memory, but the BIOS runtime services remain and are available to the target operating system.

To boot an operating system, the BIOS runtime searches for devices that are both active and bootable in the order of preference defined by the complementary metal oxide semiconductor (CMOS) settings. A boot device can be a floppy disk, a CD-ROM, a partition on a hard disk, a device on the network, or even a USB flash memory stick.

Commonly, Linux is booted from a hard disk, where the Master Boot Record (MBR) contains the primary boot loader. The MBR is a 512-byte sector, located in the first sector on the disk (sector 1 of cylinder 0, head 0). After the MBR is loaded into RAM, the BIOS yields control to it.

Stage 1 boot loader

The primary boot loader that resides in the MBR is a 512-byte image containing both program code and a small partition table (see Figure 2). The first 446 bytes are the primary boot loader, which contains both executable code and error message text. The next sixty-four bytes are the partition table, which contains a record for each of four partitions (sixteen bytes each). The MBR ends with two bytes that are defined as the magic number (`0xAA55`). The magic number serves as a validation check of the MBR.

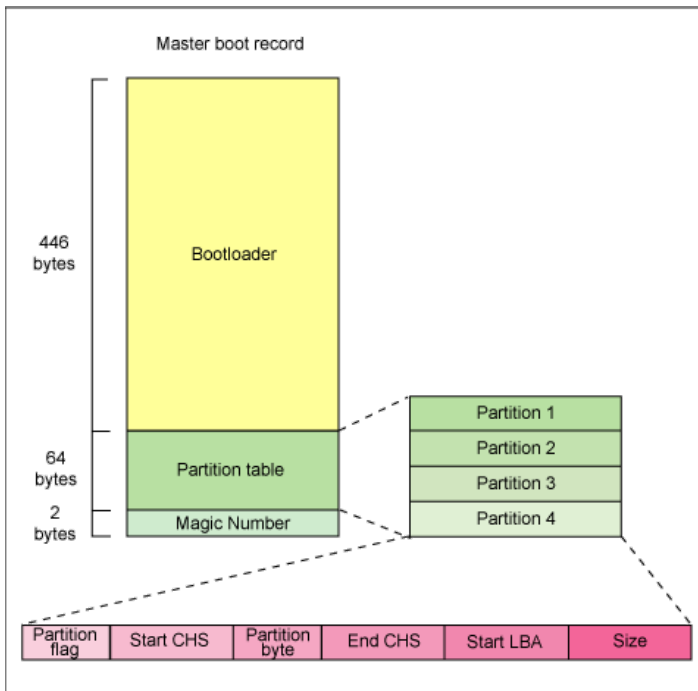
Figure 2. Anatomy of the MBR

Extracting the MBR

To see the contents of your MBR, use this command:

```
# dd if=/dev/hda of=mbr.bin bs=512 count=1
# od -xa mbr.bin
```

The `dd` command, which needs to be run from root, reads the first 512 bytes from `/dev/hda` (the first Integrated Drive Electronics, or IDE drive) and writes them to the `mbr.bin` file. The `od` command prints the binary file in hex and ASCII formats.



The job of the primary boot loader is to find and load the secondary boot loader (stage 2). It does this by looking through the partition table for an active partition. When it finds an active partition, it scans the remaining partitions in the table to ensure that they're all inactive. When this is verified, the active partition's boot record is read from the device into RAM and executed.

Stage 2 boot loader

The secondary, or second-stage, boot loader could be more aptly called the kernel loader. The task at this stage is to load the Linux kernel and optional initial RAM disk.

The first- and second-stage boot loaders combined are called Linux Loader (LILO) or GRand Unified Bootloader (GRUB) in the x86 PC environment. Because LILO has some disadvantages that were corrected in GRUB, let's look into GRUB. (See many additional resources on GRUB, LILO, and related topics in the [Resources](#) section later in this article.)

GRUB stage boot loaders

The `/boot/grub` directory contains the `stage1`, `stage1.5`, and `stage2` boot loaders, as well as a number of alternate loaders (for example, CR-ROMs use the `iso9660_stage1_5`).

The great thing about GRUB is that it includes knowledge of Linux file systems. Instead of using raw sectors on the disk, as LILO does, GRUB can load a Linux kernel from an ext2 or ext3 file system. It does this by making the two-stage boot loader into a three-stage boot loader. Stage 1 (MBR) boots a stage 1.5 boot loader that understands the particular file system containing the Linux kernel image. Examples include `reiserfs_stage1_5` (to load from a Reiser journaling file system) or `e2fs_stage1_5` (to load from an ext2 or ext3 file system). When the stage 1.5 boot loader is loaded and running, the stage 2 boot loader can be loaded.

With stage 2 loaded, GRUB can, upon request, display a list of available kernels (defined in `/etc/grub.conf`, with soft links from `/etc/grub/menu.lst` and `/etc/grub.conf`). You can select a kernel and even amend it with additional kernel parameters. Optionally, you can use a command-line shell for greater manual control over the boot process.

With the second-stage boot loader in memory, the file system is consulted, and the default kernel image and `initrd` image are loaded into memory. With the images ready, the stage 2 boot loader invokes the kernel image.

Kernel

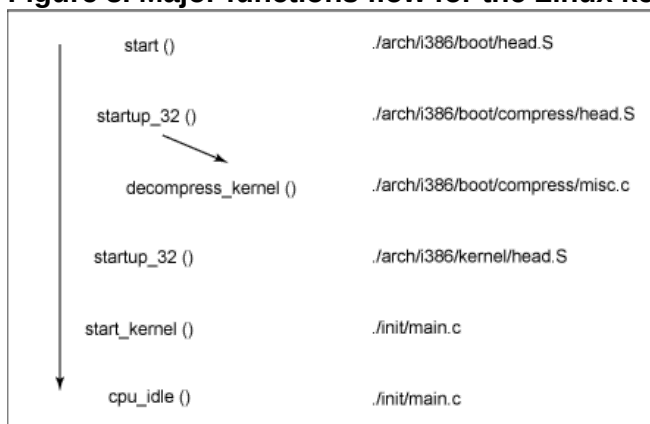
With the kernel image in memory and control given from the stage 2 boot loader, the kernel stage begins. The kernel image isn't so much an executable kernel, but a compressed kernel image.

Typically this is a `zImage` (compressed image, less than 512KB) or a `bzImage` (big compressed image, greater than 512KB), that has been previously compressed with `zlib`. At the head of this kernel image is a routine that does some minimal amount of hardware setup and then decompresses the kernel contained within the kernel image and places it into high memory. If an initial RAM disk image is present, this routine moves it into memory and notes it for later use. The routine then calls the kernel and the kernel boot begins.

When the `bzImage` (for an i386 image) is invoked, you begin at `./arch/i386/boot/head.S` in the `start` assembly routine (see Figure 3 for the major flow). This routine does some basic hardware setup and invokes the `startup_32` routine in `./arch/i386/boot/compressed/head.S`. This routine sets up a basic environment (stack, etc.) and clears the Block Started by Symbol (BSS). The kernel is then decompressed through a call to a C function called `decompress_kernel` (located in `./arch/i386/boot/compressed/misc.c`). When the kernel is decompressed into memory, it is called. This is yet another `startup_32` function, but this function is in `./arch/i386/kernel/head.S`.

In the new `startup_32` function (also called the swapper or process 0), the page tables are initialized and memory paging is enabled. The type of CPU is detected along with any optional floating-point unit (FPU) and stored away for later use. The `start_kernel` function is then invoked (`init/main.c`), which takes you to the non-architecture specific Linux kernel. This is, in essence, the `main` function for the Linux kernel.

Figure 3. Major functions flow for the Linux kernel i386 boot



With the call to `start_kernel`, a long list of initialization functions are called to set up interrupts, perform further memory configuration, and load the initial RAM disk. In the end, a call is made to `kernel_thread` (in `arch/i386/kernel/process.c`) to start the `init` function, which is the first user-space process. Finally, the idle task is started and the scheduler can now take control (after the call to `cpu_idle`). With interrupts enabled, the pre-emptive scheduler periodically takes control to provide multitasking.

During the boot of the kernel, the initial-RAM disk (`initrd`) that was loaded into memory by the stage 2 boot loader is copied into RAM and mounted. This `initrd` serves as a temporary root file system in RAM

Manual boot in GRUB

From the GRUB command-line, you can boot a specific kernel with a named `initrd` image as follows:

```

grub> kernel /bzImage-2.6.14.2
        [Linux-bzImage, setup=0x1400,
        size=0x29672e]

grub> initrd /initrd-2.6.14.2.img
        [Linux-initrd @ 0x5f13000, 0xcc199 bytes]

grub> boot
  
```

Uncompressing Linux... Ok, booting the kernel.

If you don't know the name of the kernel to boot, just type a forward slash (/) and press the Tab key. GRUB will display the list of kernels and `initrd` images.

and allows the kernel to fully boot without having to mount any physical disks. Since the necessary modules needed to interface with peripherals can be part of the `initrd`, the kernel can be very small, but still support a large number of possible hardware configurations. After the kernel is booted, the root file system is pivoted (via `pivot_root`) where the `initrd` root file system is unmounted and the real root file system is mounted.

The `initrd` function allows you to create a small Linux kernel with drivers compiled as loadable modules. These loadable modules give the kernel the means to access disks and the file systems on those disks, as well as drivers for other hardware assets. Because the root file system is a *file system* on a disk, the `initrd` function provides a means of bootstrapping to gain access to the disk and mount the real root file system. In an embedded target without a hard disk, the `initrd` can be the final root file system, or the final root file system can be mounted via the Network File System (NFS).

decompress_kernel output

The `decompress_kernel` function is where you see the usual decompression messages emitted to the display:

```
Uncompressing Linux... Ok, booting the
kernel.
```

Init

After the kernel is booted and initialized, the kernel starts the first user-space application. This is the first program invoked that is compiled with the standard C library. Prior to this point in the process, no standard C applications have been executed.

In a desktop Linux system, the first application started is commonly `/sbin/init`. But it need not be. Rarely do embedded systems require the extensive initialization provided by `init` (as configured through `/etc/inittab`). In many cases, you can invoke a simple shell script that starts the necessary embedded applications.

Summary

Much like Linux itself, the Linux boot process is highly flexible, supporting a huge number of processors and hardware platforms. In the beginning, the `loadlin` boot loader provided a simple way to boot Linux without any frills. The `LILO` boot loader expanded the boot capabilities, but lacked any file system awareness. The latest generation of boot loaders, such as `GRUB`, permits Linux to boot from a range of file systems (from `Minix` to `Reiser`).

Resources

Learn

[Boot Records Revealed](#) is a great resource on MBRs and the various boot loaders. This resource not only disassembles MBRs, but also discusses `GRUB`, `LILO`, and the various Windows® boot loaders.

Check out the [Disk Geometry](#) page to understand disks and their geometries. You'll find an interesting summary of disk attributes.

A [live CD](#) is an operating system that's bootable from a CD or DVD without needing a hard drive.

"[Boot loader showdown: Getting to know LILO and GRUB](#)" (developerWorks, August 2005) gives you a detailed look at the `LILO` and `GRUB` boot loaders.

In the [Linux Professional Institute \(LPI\) exam prep](#) series of developerWorks tutorials, get a comprehensive introduction to booting a Linux system and many other fundamental Linux tasks while you prepare for system administrator certification.

[LILO](#) was the precursor to `GRUB`, but you can still find it booting Linux.

Dig deeper into Linux on developerWorks

[Overview](#)

[New to Linux](#)

[Technical library \(tutorials and more\)](#)

[Forums](#)

[Open source projects](#)

[Events](#)



Bluemix Developers Community

Get samples, articles, product docs, and community resources to help build, deploy, and manage your cloud apps.



developerWorks Labs

Experiment with new directions in software development.

DevOps Services

Software development in the

The [mkintrd](#) command is used to create an initial RAM disk image. This command is useful for building an initial root file system for boot configuration that allows preloading of block devices needed to access the real root file system.

At the [Debian Linux Kernel Project](#), find more information on the Linux kernel, boot, and embedded development.

In the [developerWorks Linux zone](#), find more resources for Linux developers.

Stay current with [developerWorks technical events and Webcasts](#).



cloud. Register today to create a project.



IBM evaluation software

Evaluate IBM software and solutions, and transform challenges into opportunities.

Get products and technologies

The [MicroMonitor](#) provides a boot environment for a variety of small target devices. You can use this monitor to boot Linux in an embedded environment. It has ports for ARM, XScale, MIPS, PowerPC, Coldfire, and Hitachi's Super-H.

[GNU GRUB](#) is a boot shell filled with options and flexibility.

[LinuxBIOS](#) is a BIOS replacement. Not only does it boot Linux, LinuxBIOS, itself, is a compressed Linux kernel.

[OpenBIOS](#) is another portable BIOS project that operates on a variety of architectures such as x86, Alpha, and AMD64.

At [kernel.org](#), grab the latest kernel tree.

With [IBM trial software](#), available for download directly from developerWorks, build your next development project on Linux.

Discuss

Check out [developerWorks blogs](#) and get involved in the [developerWorks community](#).