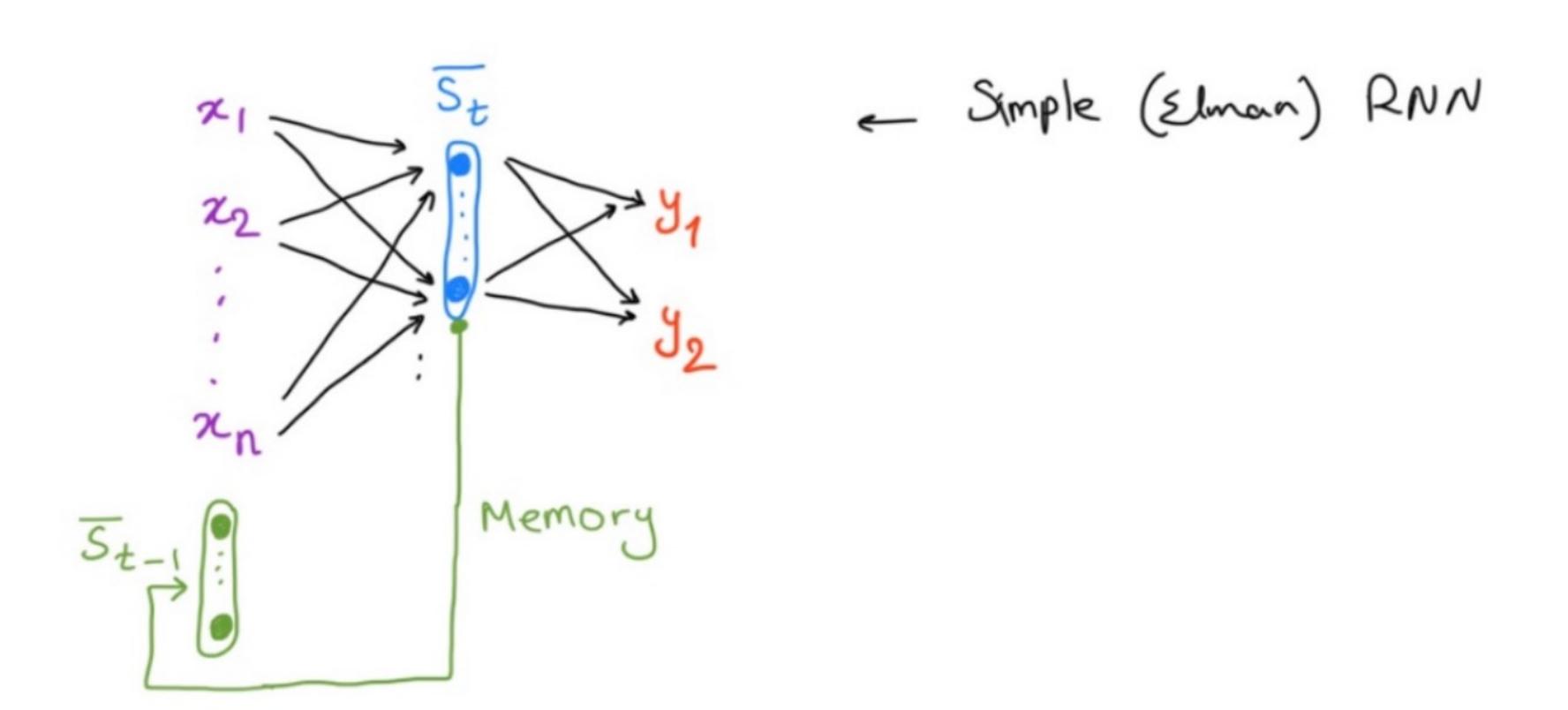
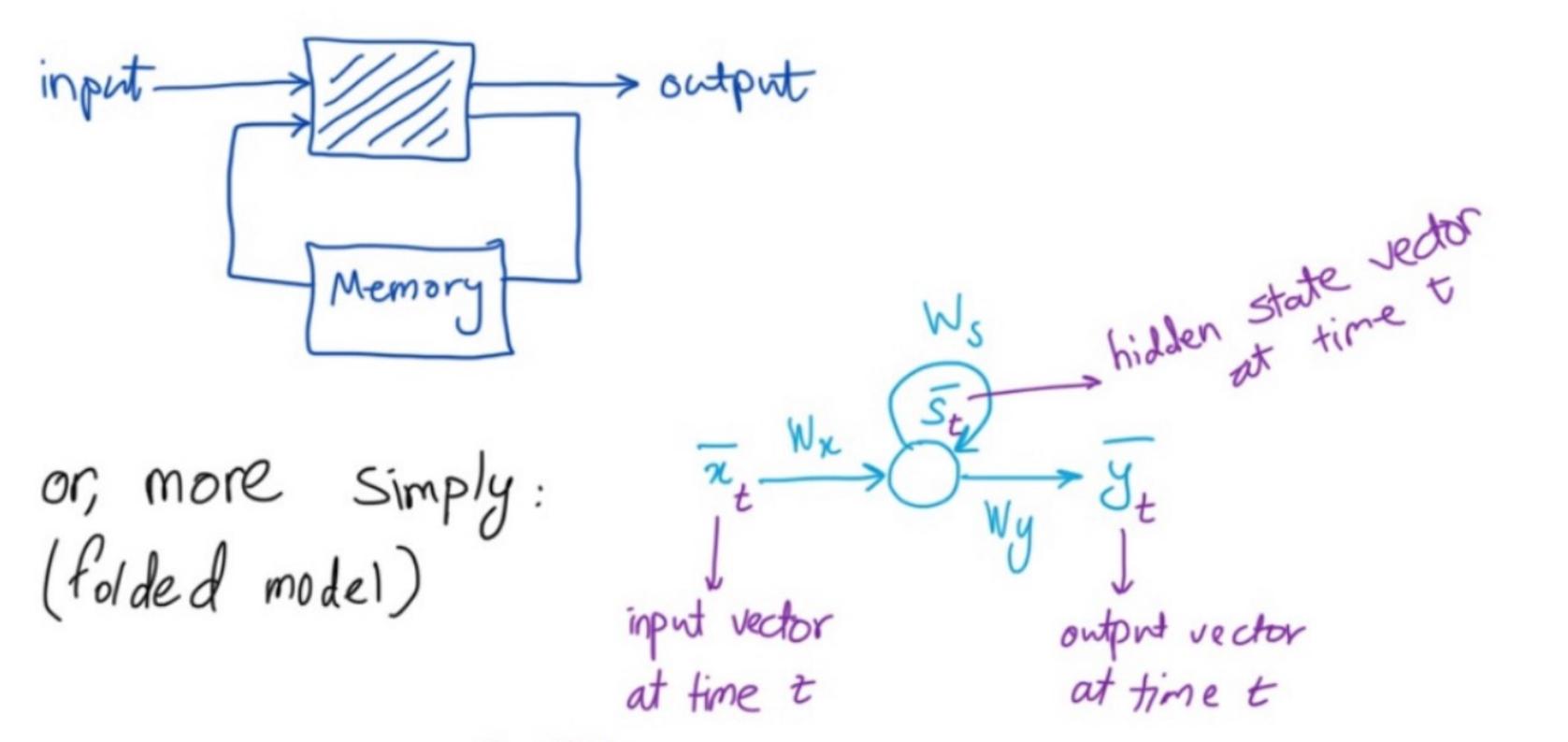




RNN illustrated differently:



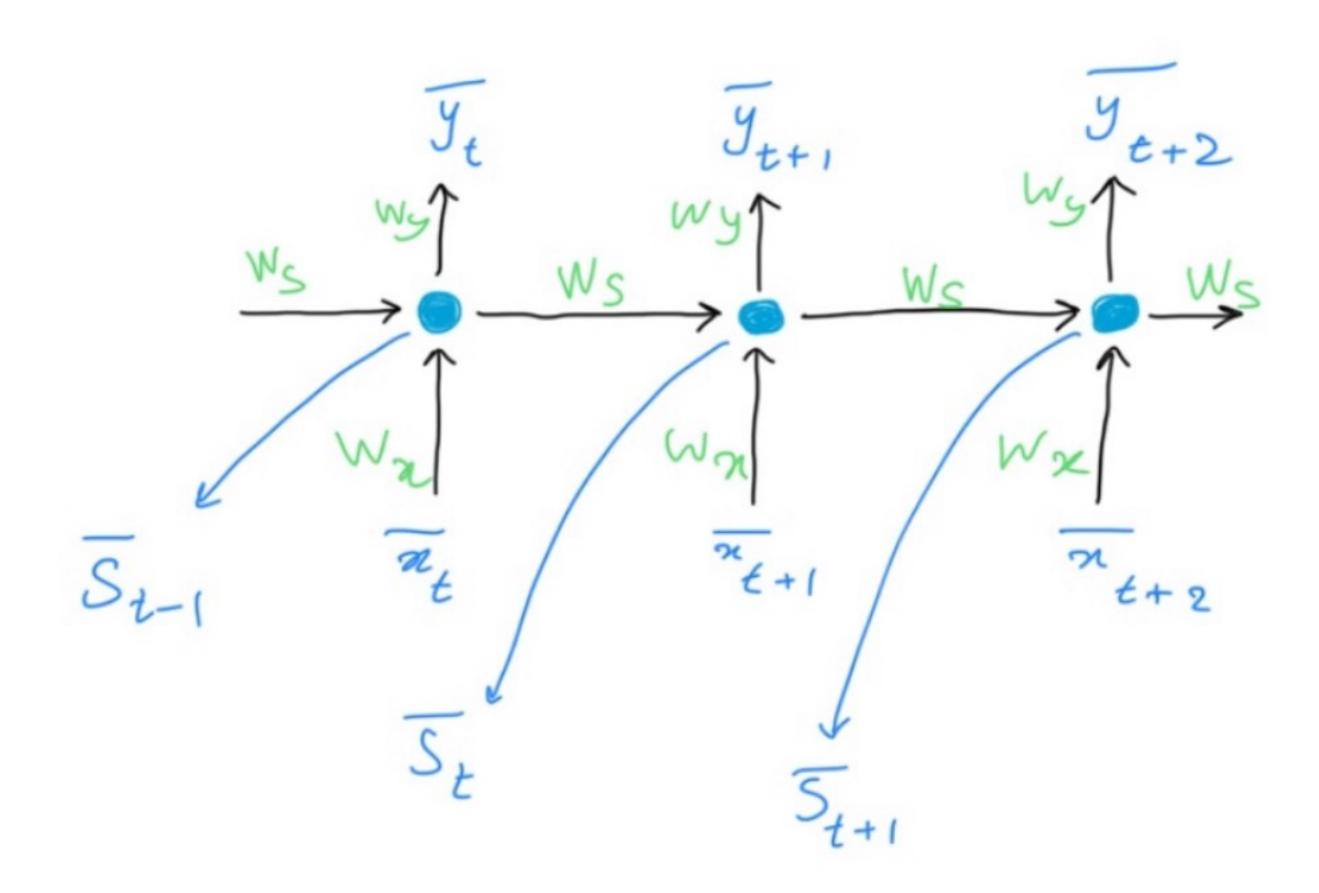
RNN as State Machine



$$\overline{S_t} = \phi(\overline{z_t} \cdot W_{x} + \overline{S_{t-1}} \cdot W_{s})$$

$$\frac{\overline{y}_{t}}{s_{t}} = \overline{s}_{t} \cdot W_{y}$$

Unfolded representation in obtainer and easier to understand.



* RNNs can handle varying lengths of inputs.