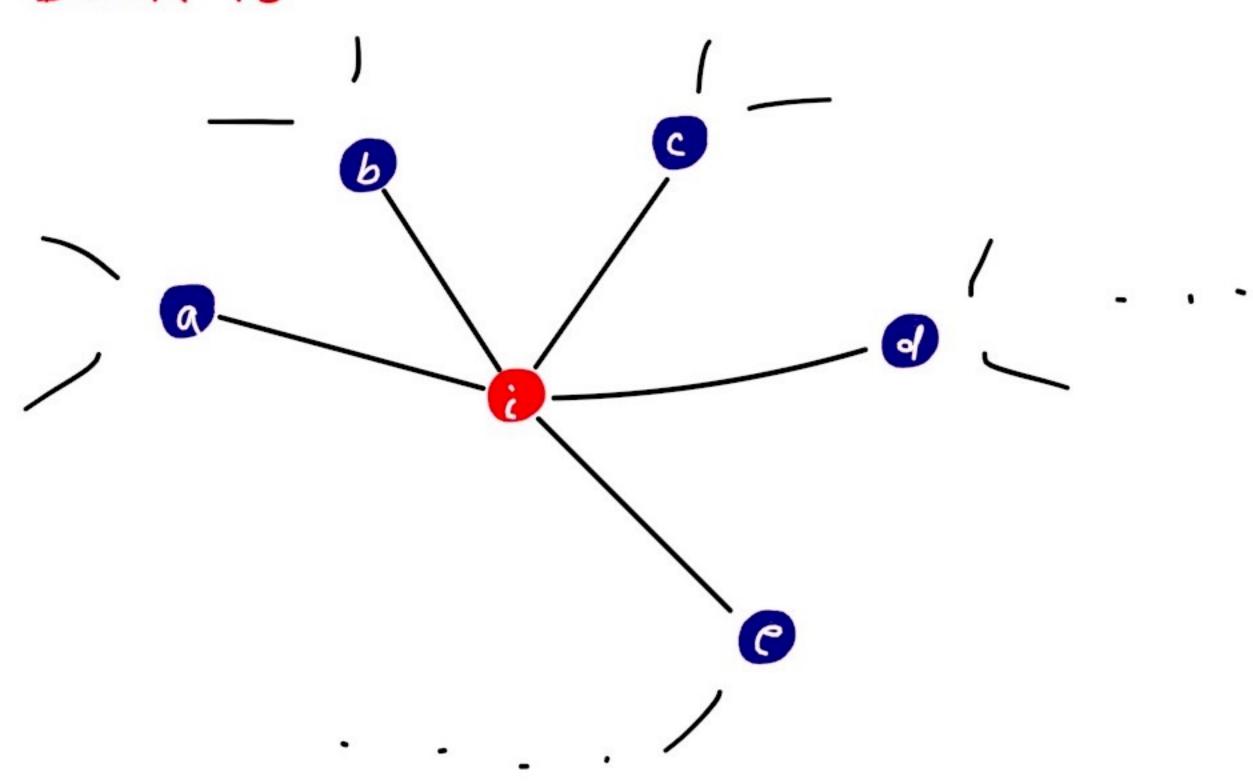
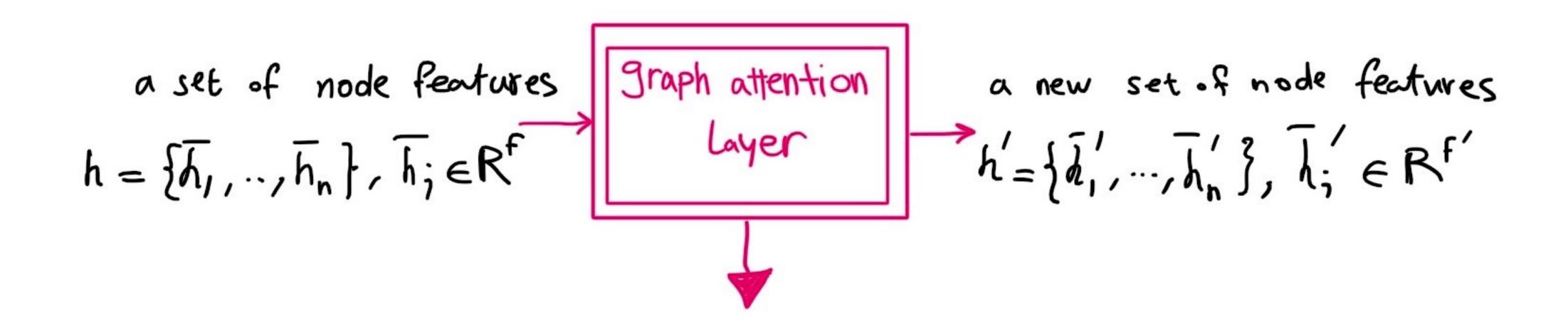
Graph Attention Networks (GAN) in PGG ICLR'18



* How much the features of a-e are important to node i? - we'd like to learn this



- opply a parameterized linear transformation to each node $W.h_i$, $W \in \mathbb{R}^{F' \times F}$
- 2 do self attention $a: R^F \times R^F \rightarrow R$ importance of $\leftarrow e_{ij} = a(W.\overline{h}_i, W.\overline{h}_j)$ node j's features to node i.

3 normalize.
$$d_{ij} = softman_{ij} \cdot (e_{ij}) = \frac{exp(e_{ij})}{\sum_{k \in N(i)} exp(e_{i,k})}$$

Sum of neighbors of i

The single-byer fill.

Which if

Leaky RelV = max (0.2m, n)

Complete Formula:

$$\alpha_{ij} = \frac{\exp(\text{Leaky RelV}(\bar{a}^{T}[Wh_{i}; Wh_{i}]))}{\sum_{\substack{k \in N(i)}} \exp(\text{LeakyRelU}(\bar{a}^{T}[Wh_{i}; Wh_{k}]))}}$$

5 apply.
$$h_i' = 5 \left(\sum_{j \in N(i)} \alpha_{ij} W h_j \right)$$

(6) multi-head attention

$$h_{i}' = \|_{k=1}^{k} \sigma \left(\sum_{j \in N(i)} \alpha_{ij}^{K} w^{K} h_{j} \right)$$

 $h'_{i} = \overline{b} \left(\frac{1}{K} \sum_{K=1}^{K} \sum_{j \in N(i)} \overset{K}{\forall i j} W h_{j} \right)$ average on the last layer of the network

Message Passing

Seature repr of node i at the k-th layer of node i. Sum, meall,...

$$\begin{pmatrix}
(k) \\
(k-1) \\
(k) \\
(k-1) \\
($$

* PyTorch Geometric provides MessagePassing class. aggregate (): aggr msgs from neighbors message (): Construct msg from node j to i (P) propagate (): propagate nessages update (): update node embeddings (Y) Simple Message laising Usage class GCN Conv (Message Passing): def __init__ (self, in_channels, out-channels): super (GCN Conv, seif). —init— (aggr = 'add') det forward (seif, n, edge_inden): return seif, propagate George_indea, n=n, norm=norm)

det message (self, ..) Compute the message return...

GCN

$$\varkappa_{i}^{(k)} = \frac{1}{\sqrt{\deg(i)} \cdot \sqrt{\deg(j)}} \cdot \left(\Theta \cdot \chi_{j}^{(k-1)} \right)$$

$$j \in \mathcal{N}(i) \cup \{i\}$$

steps to implement

- 1 add self-loops
- 2 a linear transformation to node feature matrix
- 3 Compute normalization Coefficient
- 4 normalize node features
- 5 sum up reighboring node features

class GCN Conv (Message Passing):

Nx in-channels 2xt def forward (self, 21, edge_idx):

- 1 edge-idx, _ = add_self-bops (edge_idx, num_nodes = x.size(0))
- 2 x= self. lin (x)

GAN

Simplified GAN Layer:

class GAT Layer (nn. Module):

def __init __ (self, in_feats, out_feats, dropout, alpha,

true for all but last byer - Concat = True):

super(GATLayer, self). __init __()

get all input args ...

self. W = NN. Parameter (torch. zeros ((in-feats, out-feats))

slope of

Leaky ReLU

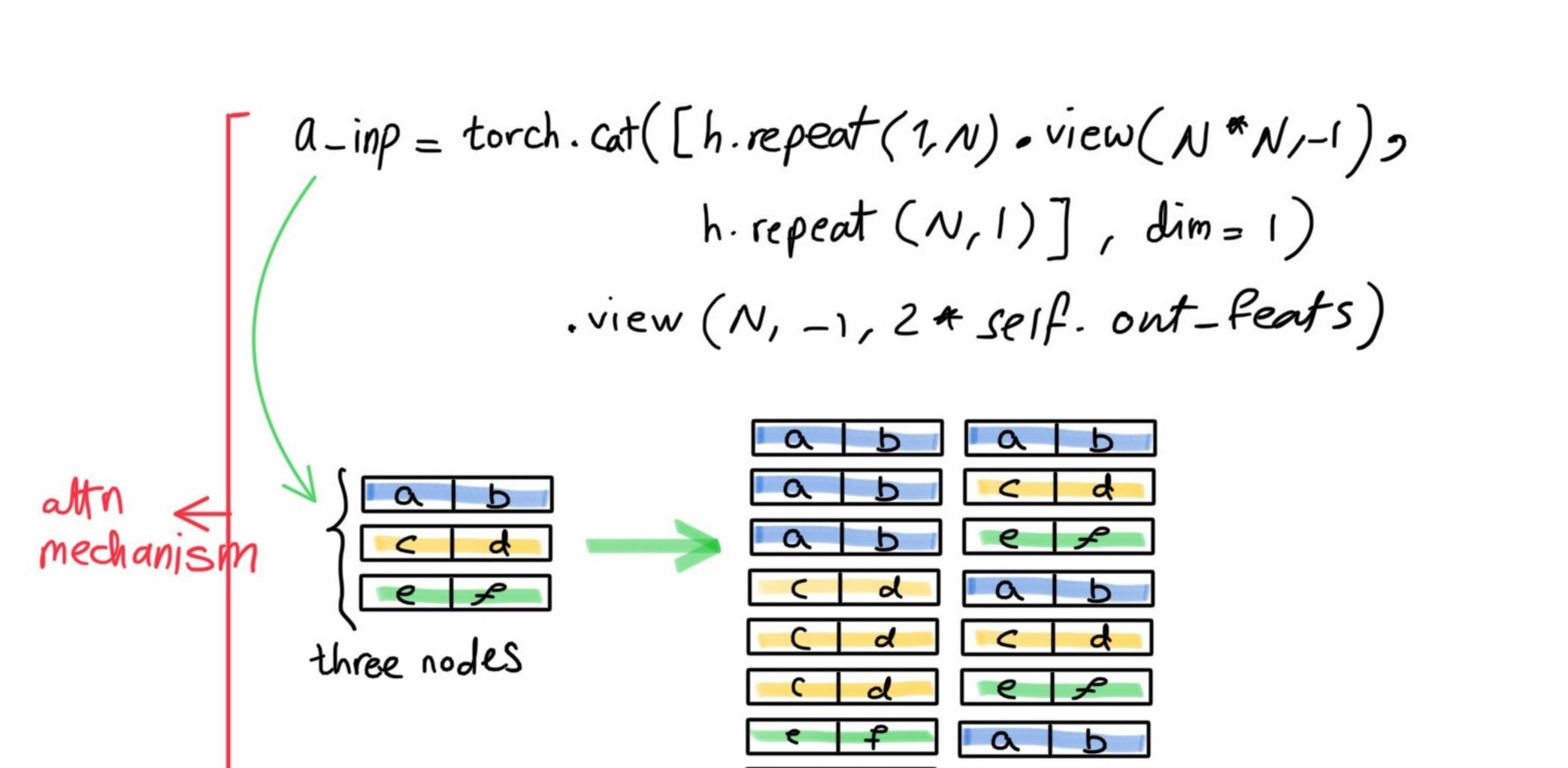
nn. init. xavier_uniform _ (self. W. data, gain = 1.514)

Self. a = nn. Parameter (torch. zeros (2* out_feats, 1)))

nn. init. xavier_uniform _ (self. a. data, gain = 1.414)

Self. leakyrehr = nn. LeakyReLU (self. alpha)

def forward (self, input, adj): $h = torch. mm (input, self. W) \rightarrow linear transformation$



e=Seif. leaky relu (torch. matmul (a_inp, Seif. a). squeeze (2)

masked $\int zero_vec = -9e15 * torch·ones_like(e)$ attn $= torch·where(adj>0, e, zero_vec)$

attn = F. softmax (attn, dim=1)

attn = F. dropout (attn, self. dropout, training = self. training)

h_prime = torch. matmul (attn, h)

if self. Concat: return F.elu (h-prime) else: return h-prime Fortunately, we don't need to implement GAN layers.

from torch_geometric.data import Data

From torch_geometric.nn import GAT Conv

From torch-geometric.datasets import Planetoid

dataset = Planefoid (100+= 'Imp/', name='Gra')

class GAT (torch. nn. Module):

def __init __ (GAT, self).__init__ ()

self. hid = 8

self. in-head = 8

self. out-head = 1

Self. Conv1 = GATConv (dotaset. num - features, self. hid,

heads = Self. in-head, dropout = .6)

Self. Conv2 = GATConv (self. hid * Self. in-head,

dataset. num - classes,

Concat = False, heads = Self. out-head,

dropout = .6)

def forward (self, data): x, edge_idx = data.x, data.edge_index

x = f. dropout (x, p = .6, training = self. training) x = f. Conv1 (x, edge - idx) x = F. elu(x) x = f. dropout (x, p = .6, training = self. training) x = f. Conv2 (x, edge - idx)

return F. log - softmax (24 dim = 1)

model = GAT().to (device)

data = dataset [0].to (device)

opt = torch.optim.Adam(model.parameters(), Ir=.005,

weight_decay = 5e-4)

for epoch in range (epochs): model.train() opt. zero _ grad() out=model (data) loss = F. n//_loss (out [data . train _ mask], data.y [data.train_mask]) loss. backward() opt. Step ()