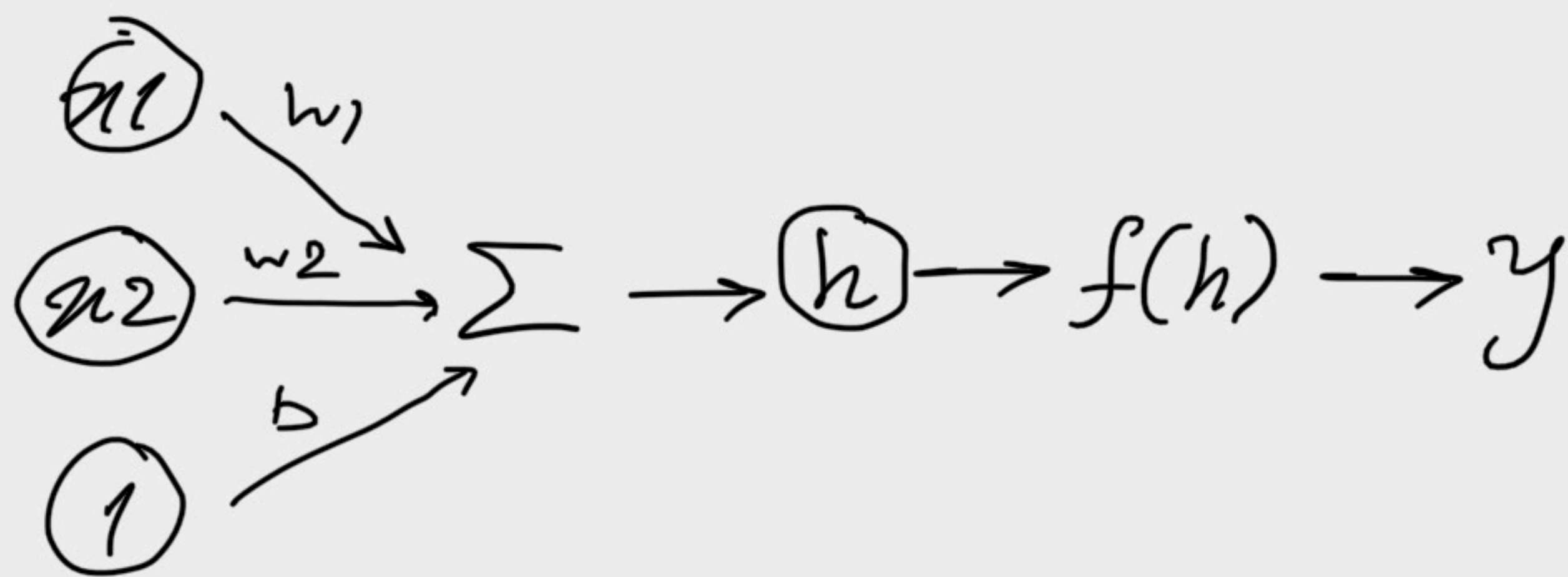


# Tensors



$$y = f(w_1 x_1 + w_2 x_2 + b)$$

$$h = [x_1 \dots x_n] \cdot \begin{bmatrix} w_1 \\ \vdots \\ w_n \end{bmatrix}$$

`def sigmoid(x): return 1/(1+torch.exp(-x))`

`torch.manual_seed(7)`

`features = torch.randn((1,5))` ← five random normal vars

`weights = torch.randn_like(features)` ← a vector with the shape of features, random.

`bias = torch.randn((1,1))` ← a 1x1 bias term

elem-by-elem mult

`y = sigmoid(torch.sum(features * weights) + bias)` ← output of a single layer

`torch.mm` and `torch.matmul` → mat multiplication



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for changing the shape of tensors:

1. `weights.reshape(a,b)` → returns new tensor

2. `weights.resize_(a,b)` → in place operation

3. `weights.view(a,b)` → return new data with same data

a/f →  $y = \text{sigmoid}(\text{torch.mm}(\text{features}, \text{weights.view}(5,1)) + \text{bias})$

Stacking up units:

$$\vec{h} = [h_1, h_2] = [x_1, \dots, x_n] \cdot \begin{matrix} \text{input units} \downarrow & \xrightarrow{\text{hidden units}} \\ \begin{bmatrix} w_{11} & w_{12} \\ \vdots & \vdots \\ w_{n1} & w_{n2} \end{bmatrix} \end{matrix}$$

$$h = \text{sigmoid}(\text{torch.mm}(\text{features}, w_1) + B_1)$$

$$y = \text{output} = \text{sigmoid}(\text{torch.mm}(h, w_2) + B_2)$$

Going between Torch and Numpy.

memory is shared between them {  $a = \text{np.random.rand}(4,3)$   
 $b = \text{torch.from\_numpy}(a)$   
 $b.numpy()$