Choosing Initial Weights

inside the init function of the module;

for m in self. modules();

if isinstance (m, nn.linear):

nn.init. Constant - (m. weight, Const.w)

nn.init. Constant - (m. bias, 0)

Comparison: model-zero vs. model-one

loss of all ones } all zeros } both have low accuracy of both

e.g., np. random. uniform (-3, 3, [1000])

values between Lagenerate

3, -3

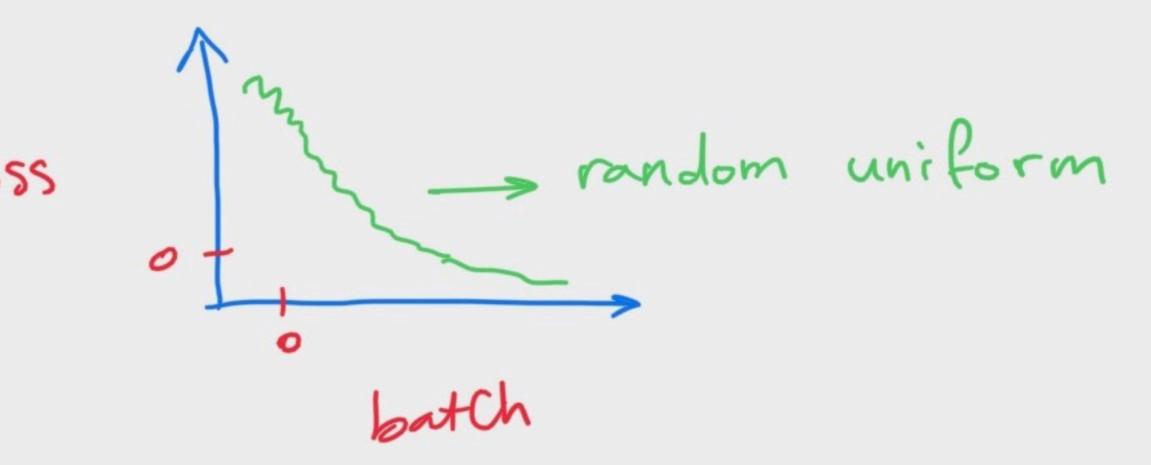
1000 numbers

Writing an initialization function: def weight_init_uniform (m): class name = m. _dass___.__nam_ for every linear = if dass name. find ('Linear') != 1:

layer in a model...

*m. weight. data. uniform = (0.0, 1.0) she best m. bias. data. fill_(A) -> set bias to zero uniform distribution for weights

> model = Net() model apply (weight_init_uniform)



Relationship between #inputs and uniform range more input; smaller range Rule of thumb;

> choose uniform random weights from the range [-y,+y]. $y=\frac{1}{\sqrt{2}}$ In # inputs of the

loss

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Normal Distribution mean mean rear zero

e.g., np. random. normal (0,1, [1000])

stolder

stolder

typically, mean = 0 and staded = 1/n.
in weight init function, we do the following,

def weight_init_ normal(m):

class name = m. _ class _ _ . _ _ nam _

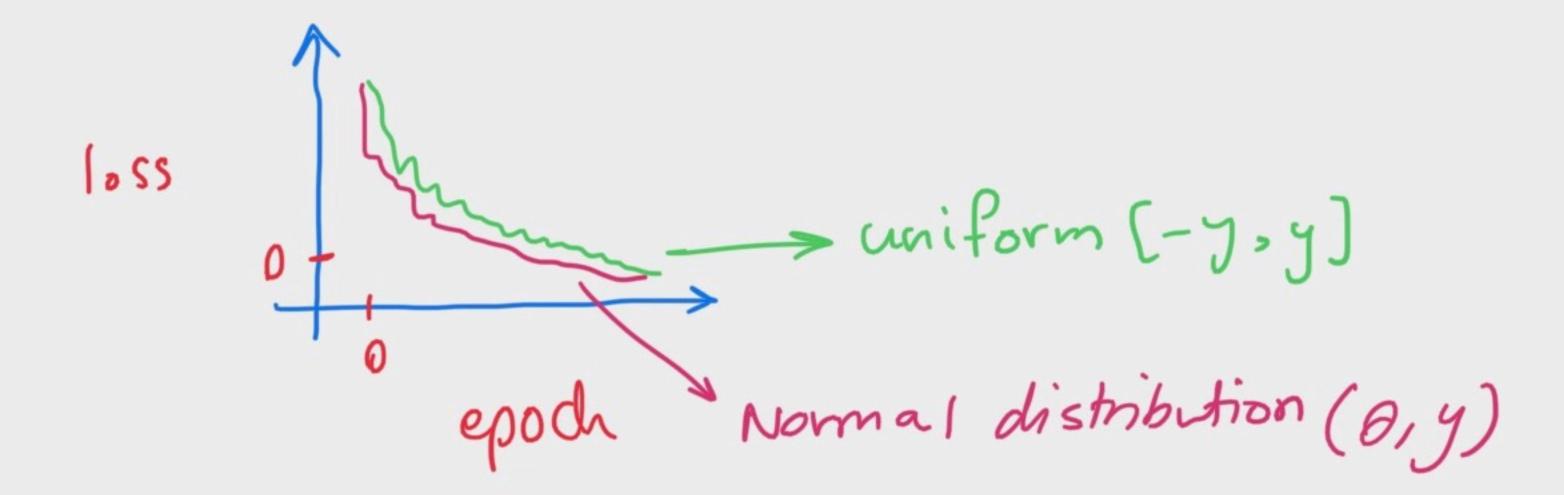
if class name . find('Linear') != 1:

n=m:in-features

y= 1.0/np. sqrt(n)

* m. weight. data.normal _ (0, y)

m. bias. data. fill_(0)



* In PyTorch, the default behavior for initialization of weights is Cool! Actually, it is usually the "uniform" distribution. However, there are Cased where "normal" distribution will be better.