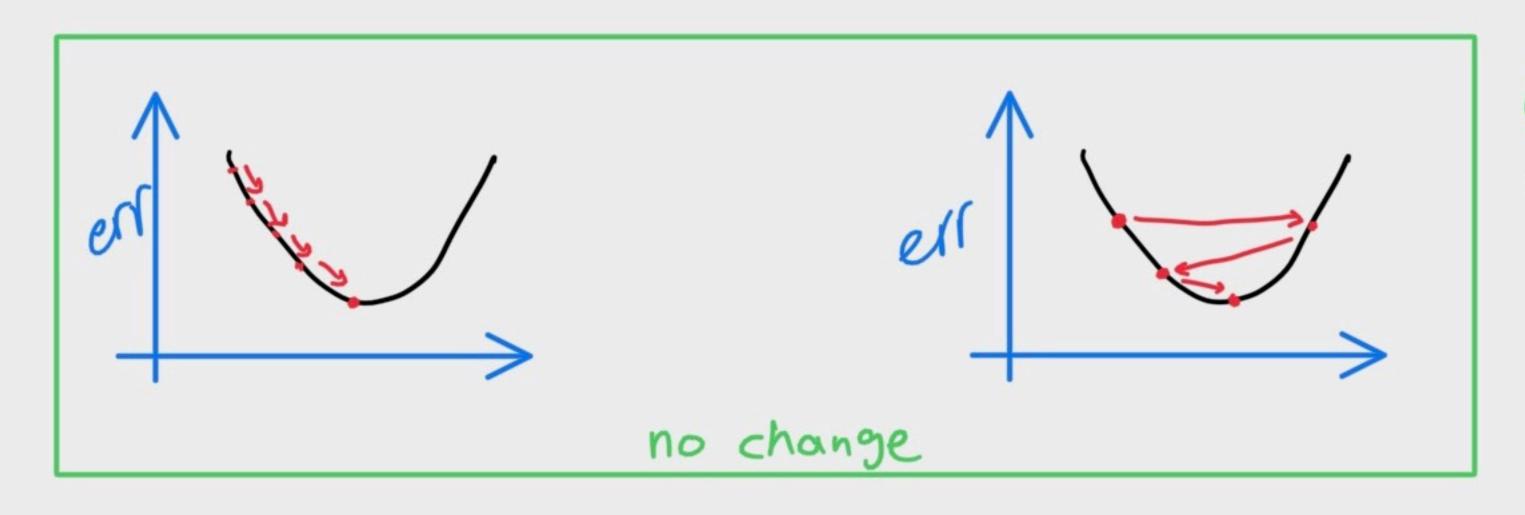
Tuning Deep learning Models

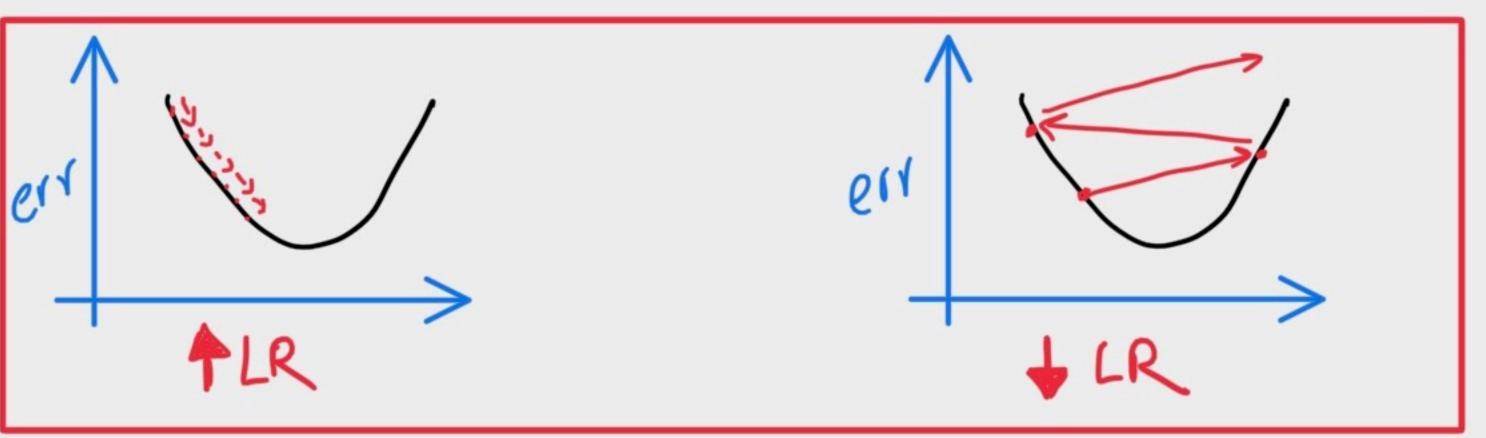
- optimizer Kyerparameters
 learning rate, batch size, epochs
- Model Hyperparameters
 number of layers, hidden units, model-specific

learning Rate

Seemingly most important hyperparameter. Good initial value = 0.01



Good Cases
Validation Emor
decreases



Bad Cases

Validation Error Increases or obses not decrease fast enough en

Bad Case

Validation Error Stops decreasing and somehow oscillates.

Solutions Learning rate decay

- · LR hinearly (divide by half every k epochs)
- · LR exponentially (mult by 0.5 every k epochs)
- · Adaptive Learning 1/4 as needed

Batch Size

Affects both resource requirements and training.
A good initial value ~ 32,64

Botch size requires more memory.

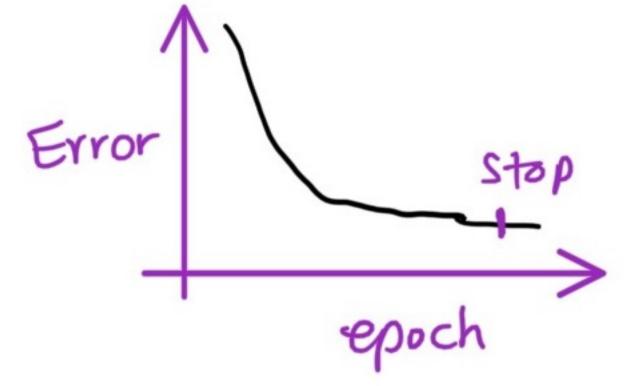
Batch size has more noise which helps the GD not to get stuck in local minima.

training too slow (1,2,...,16) ~32 hatch size

Computationally taxing poorer performance

epochs

- · We must monitor validation loss when it stops decreasing, we should stop.
 - · carly stopping technique: stop training if



stop training if

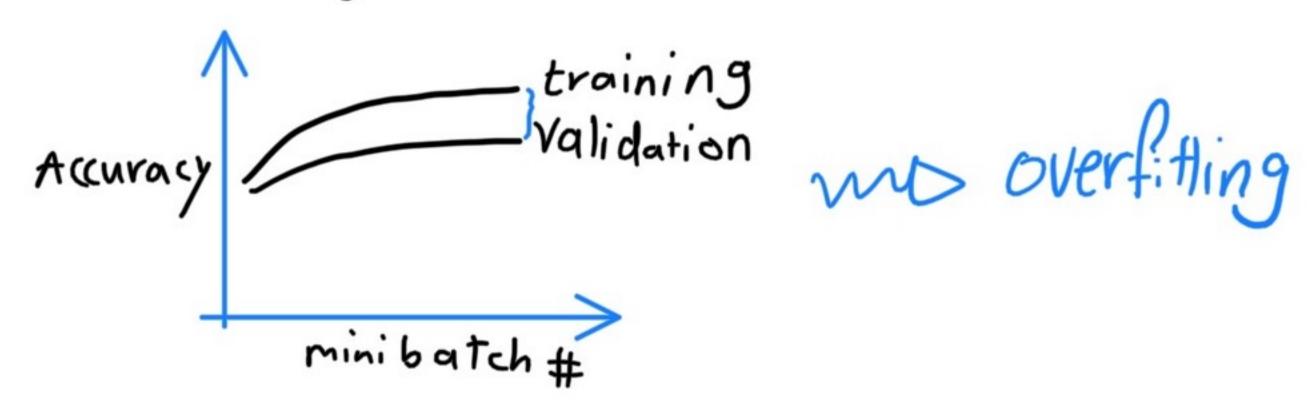
the validation loss

has not decreased in

k epochs.

Model Size

- · number of hidden units. Intuitily, it controls the models capacity to learn a function.
- · Having too much apacity overfit



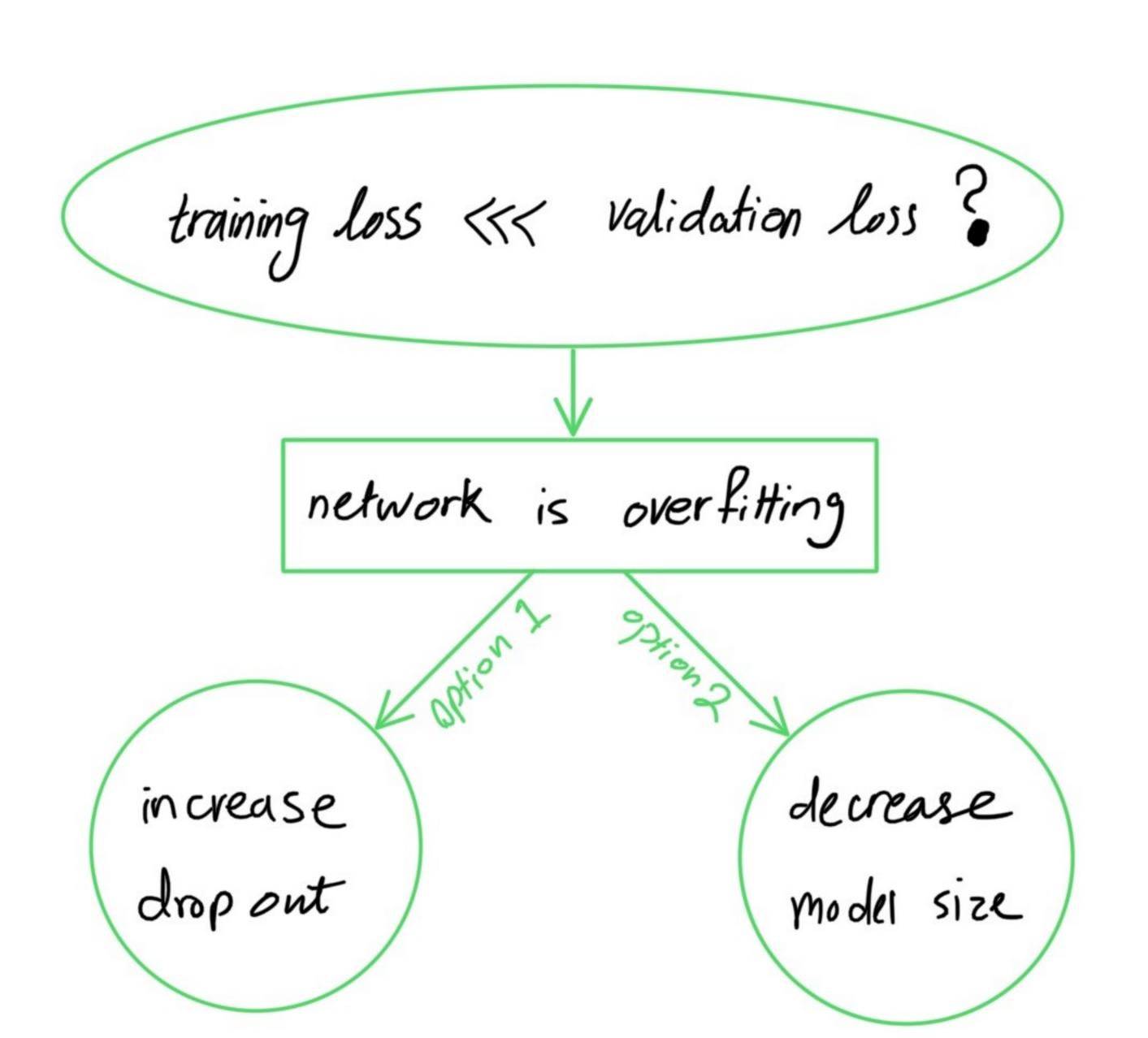
- e but the general rule is "More is Better"
- Number of layers. As a rule of thumb, 3 layers is better than 2. But more than that does not usually help. (exception: CNN)

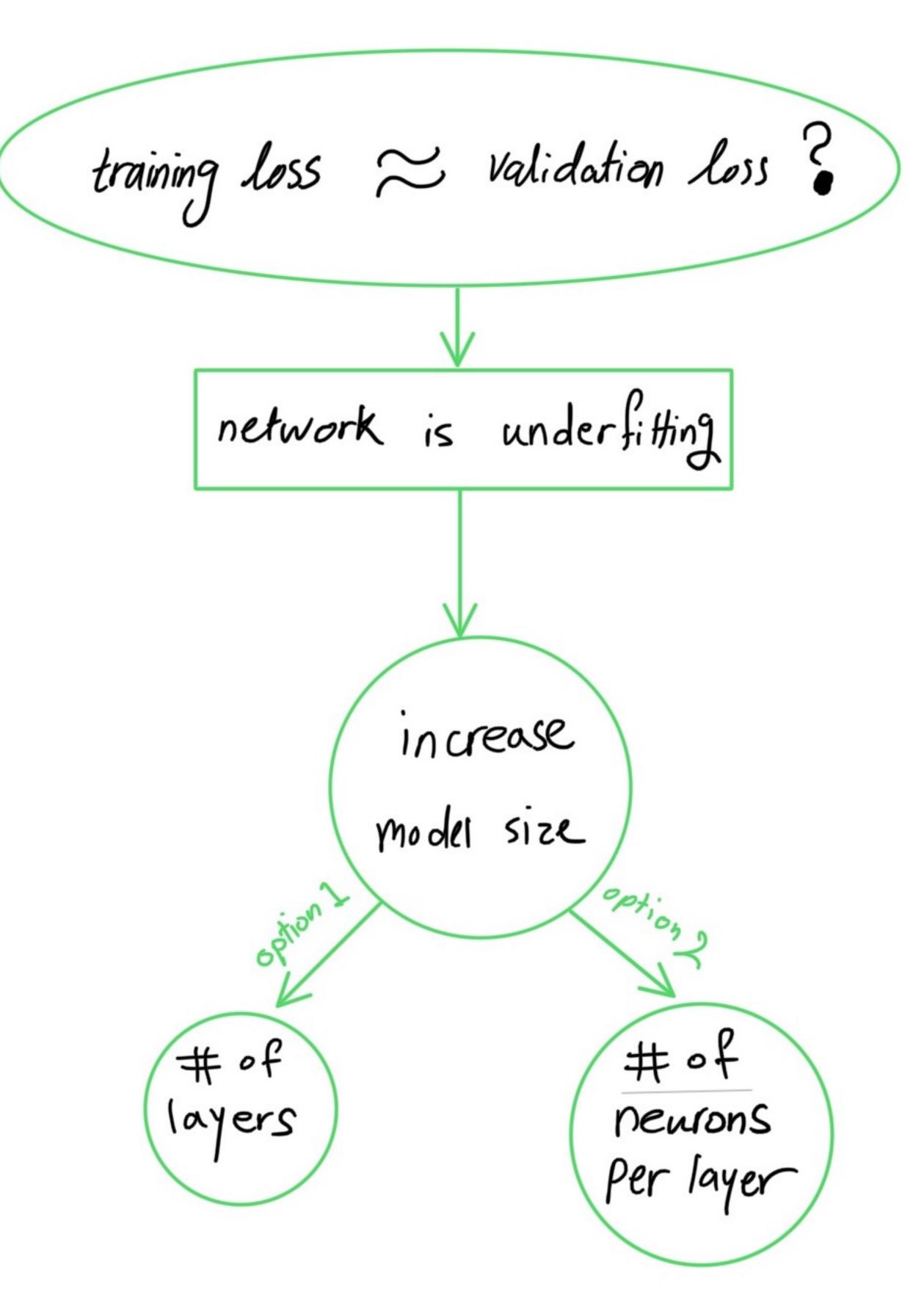
Cell Type

- In an RNN, we can choose LSTM, GRU, or just the vanilla RNN. The first 2 are usually better.
- · Chousing LSTM or GRU is task-dependent.



Selecting Reasonable Hyperparameters





• the number of model parameters should be about same magnitude as the size of dataset.

100 MB dataset (~ 100 million chars)

number of model params << size of dataset?

the model underfits