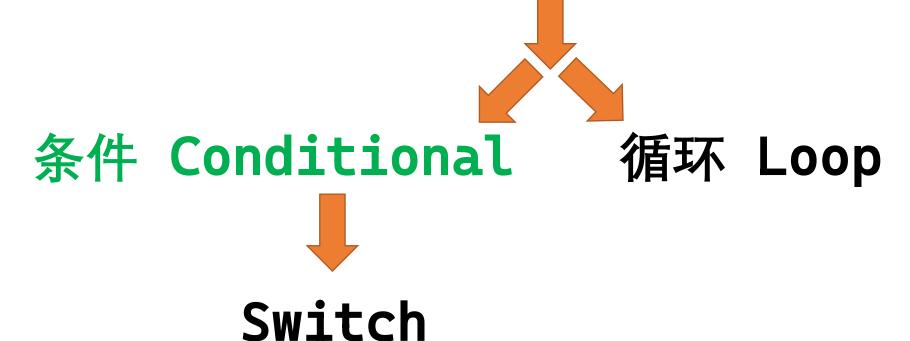
### 控制 Control





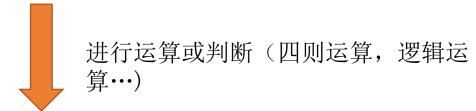
## 控制 Control



#### 常见的条件结构 Conditional Structure

```
void decision(int x) {
    if (x) {
        op1();
    } else {
        op2();
    }
}
```

条件x: 值或表达式



属性(是否为0,大于,小于…)

- 1如何利用这一信息?
- 2 如何存储这一信息?
- 3 如何控制程序进行跳转?

#### 条件码 Condition Code

#### ——如何利用

条件码: 描述最近一次算术或逻辑操作的属性

CF Unsigned 进位或借位标志

**ZF** 最近一次操作结果为0 零标志

SF Signed 最近一次操作为负数 符号标志

$$z = \gamma$$

OF Signed 溢出标志

# 条件码 Condition Code CF/ZF/SF/OF

操作结束后赋值 发生 1 未发生 0

```
addq Src,Dest ↔ t = a+b CF/ZF/SF/0F
cmpq Src2, Src1 CF/ZF/SF/0F
cmpq b,a like computing a-b without setting destination
```

testq Src2, Src1 ZF/SF

-testq b,a like computing a&b without setting destination

#### 条件码的存储与访问

SetX 指令 e.g. sete %al (将%rax最低位设置为此时ZF的值)

SetX	Condition	Description
sete	ZF	Equal / Zero
setne	~ZF	Not Equal / Not Zero
sets	SF	Negative
setns	~SF	Nonnegative
setg	~(SF^OF) &~ZF	Greater (Signed)
setge	~(SF^OF)	Greater or Equal (Signed)
setl	(SF^OF)	Less (Signed)
setle	(SF^OF)   ZF	Less or Equal (Signed)
seta	~CF&~ZF	Above (unsigned)
setb	CF	Below (unsigned)

#### 条件码的存储与访问

setx 指令 e.g. sete %al (将%rax最低位设置为此时ZF的值)

用movzbl指令 对%rax高位清零

```
int gt (long x, long y)
{
  return x > y;
}
```

Register	Use(s)
%rdi	Argument x
%rsi	Argument <b>y</b>
%rax	Return value

```
cmpq %rsi, %rdi # Compare x:y
setg %al # Set when >
movzbl %al, %eax # Zero rest of %rax
ret
```

# 程序跳转 jump jX

jX	Condition	Description
jmp	1	Unconditional
je	ZF	Equal / Zero
jne	~ZF	Not Equal / Not Zero
js	SF	Negative
jns	~SF	Nonnegative
jg	~(SF^OF)&~ZF	Greater (Signed)
jge	~(SF^OF)	Greater or Equal (Signed)
jl	(SF^OF)	Less (Signed)
jle	(SF^OF) ZF	Less or Equal (Signed)
ja	~CF&~ZF	Above (unsigned)
jb	CF	Below (unsigned)

#### 类比 goto 程序

```
if (x > y)
    result = x-y;
else
    result = y-x;
return result;
```

```
long result;
   int ntest = x \le y;
   if (ntest) goto Else;
   result = x-y;
   goto Done;
Else:
   result = y-x;
Done:
   return result;
```

#### 

```
loop:
    .....

if(condition) goto loop;
done:
```

# THANK S!