## Multivariate Linear Regression

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#### Single Feature (Recap)

In the previous version of linear regression,

Size (feet <sup>2</sup> )	Price (\$1000)
$\mathcal{X}$	у
2104	460
1416	232
1534	315
852	178
• • •	• • •

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

#### Multiple Features (Variables)

$\boldsymbol{x}_1$	$x_2$	$x_3$	$\mathcal{X}_4$	$\mathcal{Y}$
Size (feet <sup>2</sup> )	Number of bedrooms	Number of floors	Age of home (years)	Price (\$1000)
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178
• • •	• • •	• • •	• • •	•••

#### Notation:

- *n* : number of features
- $x^{(i)}$ : input (features) of  $i^{th}$  training example
- $x^{(i)}_j$ : value of feature j in i<sup>th</sup> training example

#### Multiple Features (Variables)

$x_1$	$x_2$	$x_3$	$\mathcal{X}_4$	y
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#### Notation:

- *n* : number of features
- $x^{(i)}$ : input (features) of  $i^{th}$  training example
- $x^{(i)}_j$ : value of feature j in i<sup>th</sup> training example

$$n = 4 x^{(2)} = \begin{bmatrix} 1416 \\ 3 \\ 2 \\ 40 \end{bmatrix} x_3^{(2)} = 2$$

#### Question

Size (feet <sup>2</sup> )	Number of	Number of	Age of home	Price (\$1000)
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178
•••	• • •	•••	• • •	• • •

- In the training set above, what is  $x_1^{(4)}$ ?
  - (i) The size (in feet<sup>2</sup>) of the 1<sup>st</sup> home in the training set
  - (ii) The age (in years) of the 1st home in the training set
  - (iii) The size (in feet<sup>2</sup>) of the 4<sup>th</sup> home in the training set
  - (iv) The age (in years) of the 4th home in the training set

#### Hypothesis Function

Previously,

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

#### Hypothesis (Reviewed)

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$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

In our example,

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 + \theta_4 x_4$$

E.g. 
$$h_{\theta}(x) = 80 + 0.1x_1 + 0.01x_2 + 3x_3 - 2x_4$$

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$$

For convenience of notation, define  $x_0 = 1$ 

$$\iff x_0^{(i)} = 1$$

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$$

For convenience of notation, define  $x_0 = 1$ 

$$\iff x_0^{(i)} = 1$$

$$\iff x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix} \in \mathbb{R}^{n+1}$$

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$$

Then, we have 
$$\mathbf{x} = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix} \in \mathbb{R}^{n+1}$$
 and  $\mathbf{\theta} = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \vdots \\ \theta_n \end{bmatrix} \in \mathbb{R}^{n+1}$ 

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$$

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te as: 
$$\begin{bmatrix} \theta_0 & \theta_1 & \dots & \theta_n \end{bmatrix} \times \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$$

$$= \begin{bmatrix} \theta_0 & \theta_1 & \dots & \theta_n \end{bmatrix} \times \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$= \boldsymbol{\theta}^T \boldsymbol{x}$$

'Multivariate Linear Regression'

# Gradient Descent for Multiple Features

#### Things we have

Hypothesis: 
$$h_{\theta}(x) = \boldsymbol{\theta}^T \boldsymbol{x} = \theta_0 x_0 + \theta_1 x_1 + \dots \theta_n x_n$$

Parameters:  $\theta_0, \theta_1, ..., \theta_n$ 

Cost Function: 
$$J(\theta_0, \theta_1, ..., \theta_n) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

#### Let's vectorize them

Hypothesis: 
$$h_{\theta}(x) = \boldsymbol{\theta}^T \boldsymbol{x} = \theta_0 x_0 + \theta_1 x_1 + \dots + \theta_n x_n$$

Parameters: 
$$\theta_0, \theta_1, \dots, \theta_n$$
  $\theta \in \mathbb{R}^{n+1}$ 

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$$J(\theta)$$

#### Question

When there are *n* features, we define the cost function as

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

For linear regression, which of the following are also equivalent and correct definitions of  $J(\theta)$ ?

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)})^2$$

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} ((\sum_{j=0}^{n} \theta_j x_j^{(i)}) - y^{(i)})^2$$

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$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} ((\sum_{j=1}^{n} \theta_j x_j^{(i)}) - (\sum_{j=0}^{n} y_j^{(i)}))^2$$

#### Vectorizing Gradient Descent

#### **Gradient Descent:**

Repeat { 
$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, ..., \theta_n)$$
 } (simultaneously update for every  $j = 0, ..., n$ )

#### Vectorizing Gradient Descent

#### **Gradient Descent:**

Repeat { 
$$J(\theta)$$
 
$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, ..., \theta_n)$$
 { simultaneously update for every  $j = 0, ..., n$ )

#### Single Feature (Recap)

```
Single feature (n = 1):  
Repeat { \theta_0 := \theta_0 - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})}_{\frac{\partial}{\partial \theta_0} J(\theta)}  \theta_1 := \theta_1 - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x^{(i)}}_{\text{(simultaneously update } \theta_0, \, \theta_1)}
```

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Single feature (n = 1): Repeat { \theta_0 := \theta_0 - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})}_{\frac{\partial}{\partial \theta_0} J(\theta)} \theta_1 := \theta_1 - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})}_{x_1^{(i)}}_{x_1^{(i)}} { (simultaneously update \theta_0, \theta_1)
```

#### Single vs. Multiple Features

```
Single feature (n = 1):

Repeat {
\theta_0 := \theta_0 - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})}_{\frac{\partial}{\partial \theta_0} J(\theta)}
\theta_1 := \theta_1 - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_1^{(i)}}_{1}
} (simultaneously update \theta_0, \theta_1)
```

#### Single vs. Multiple Features

#### Single feature (n = 1):

Repeat {

$$\theta_0 := \theta_0 - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})}_{\frac{\partial}{\partial \theta_0} J(\theta)} \qquad \text{Repeat } \{$$

$$\theta_j := \theta_j - \alpha \frac{1}{m} \underbrace{\sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})}_{j} x_j^{(i)}$$

$$\theta_{1} := \theta_{1} - \alpha \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x_{1}^{(i)}$$

(simultaneously update  $\theta_0, \theta_1$ )

#### Multiple features $(n \ge 1)$ :

Repeat {

$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

(simultaneously update  $\theta_j$  for j = 0, ..., n)

#### Single vs. Multiple Features

#### Multiple features $(n \ge 1)$ :

Repeat {

$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

(simultaneously update  $\theta_j$  for j = 0, ..., n)

$$\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_0^{(i)}$$

$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_1^{(i)}$$

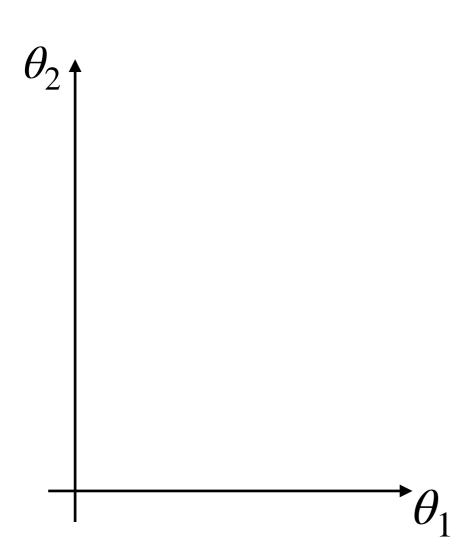
$$\theta_2 := \theta_2 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_2^{(i)}$$

## Gradient Descent in Practice I - Feature Scaling

Idea: Make sure that features are on a similar scale

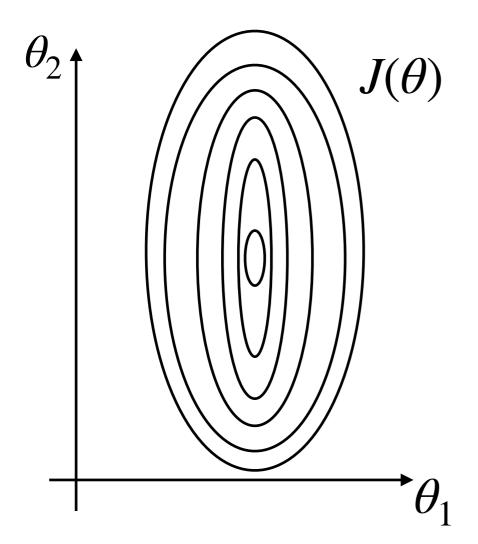
```
e.g. x_1 = \text{size } (0 - 2000 \text{ feet}^2)

x_2 = \text{number of bedrooms } (1 - 5)
```



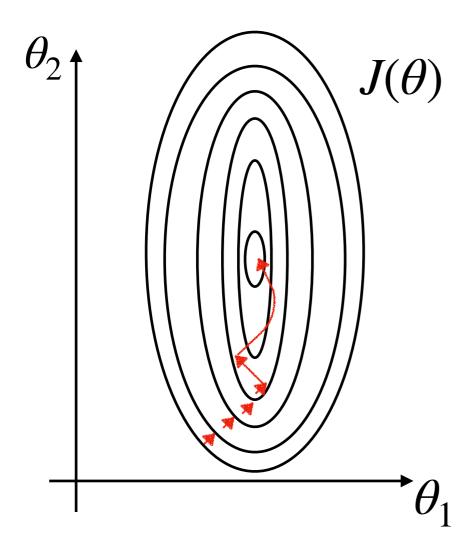
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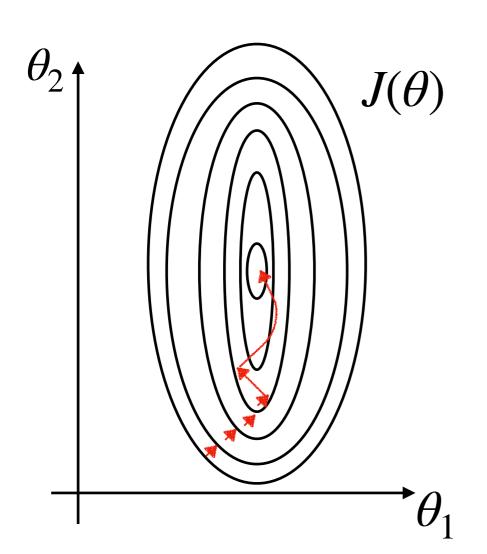
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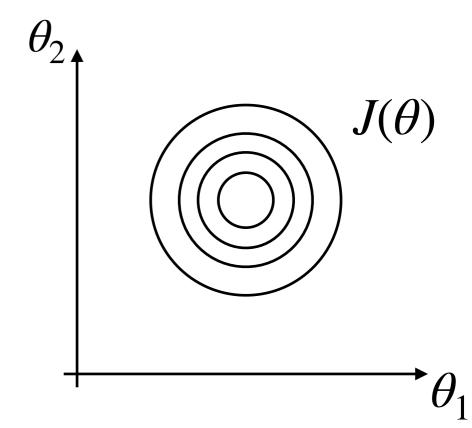
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e.g. 
$$x_1 = \text{size } (0 - 2000 \text{ feet}^2)$$
  
 $x_2 = \text{number of bedrooms } (1 - 5)$ 



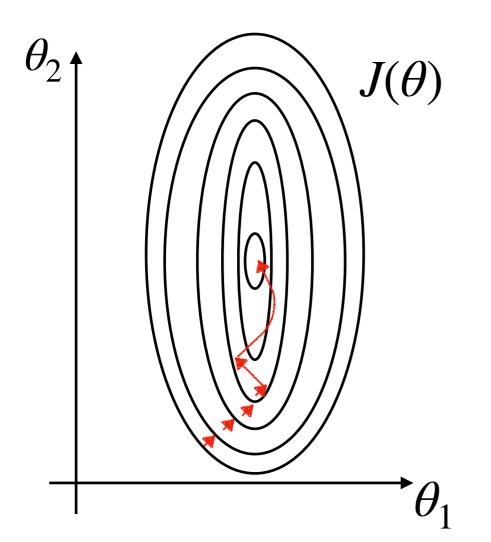
$$x_1 = \text{size (feet}^2) / 2000$$

$$x_2 = \#bedrooms / 5$$



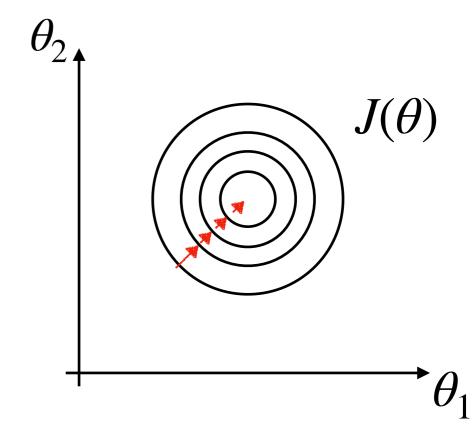
Idea: Make sure that features are on a similar scale

e.g.  $x_1 = \text{size } (0 - 2000 \text{ feet}^2)$  $x_2 = \text{number of bedrooms } (1 - 5)$ 



 $0 \le x_1 \le 1$   $x_1 = \text{size (feet}^2) / 2000$  $0 \le x_2 \le 1$ 

 $x_2 = \#bedrooms / 5$ 



#### Feature Scaling (in Practice)

- Get every feature into approximately a  $-1 \le x_i \le 1$  range
- In fact, the range [-1, 1] is not so necessary *e.g.*

$$0 \le x_1 \le 3$$
 (fine)  
 $-2 \le x_2 \le 0.5$  (fine)  
 $-100 \le x_3 \le 100$  (too big)  
 $-0.0001 \le x_4 \le 0.0001$  (too small)

#### Feature Scaling (in Practice)

#### **Mean Normalization**

 $(S_i := \max - \min)$  or the standard deviation.

Redefine  $x_i$  as  $(x_i - \mu_i)/S_i$  to make features have approximately zero mean (do not apply to  $x_0 = 1$ )

e.g. 
$$x_1 = (size - 1000) / 2000$$
 (given that  $\mu_1 = 1000$ )  $x_2 = (\#bedrooms - 2) / 4$  (given that  $\mu_2 = 2$ )

#### Question

- Suppose you are using a learning algorithm to estimate the price of houses in a city. You want one of your features  $x_i$  to capture the age of the house. In your training set, all of your houses have an age between 30 and 50 years, with an average age of 38 years. Which of the following would you use as features, assuming you use feature scaling and mean normalization?
  - (i)  $x_i$  = age of house
  - (ii)  $x_i = age of house / 50$
  - (iii)  $x_i$  = (age of house 38) / 50
  - (iv)  $x_i = (age of house 38) / 20$

## Gradient Descent in Practice II - Learning Rate

#### Gradient Descent (Recap)

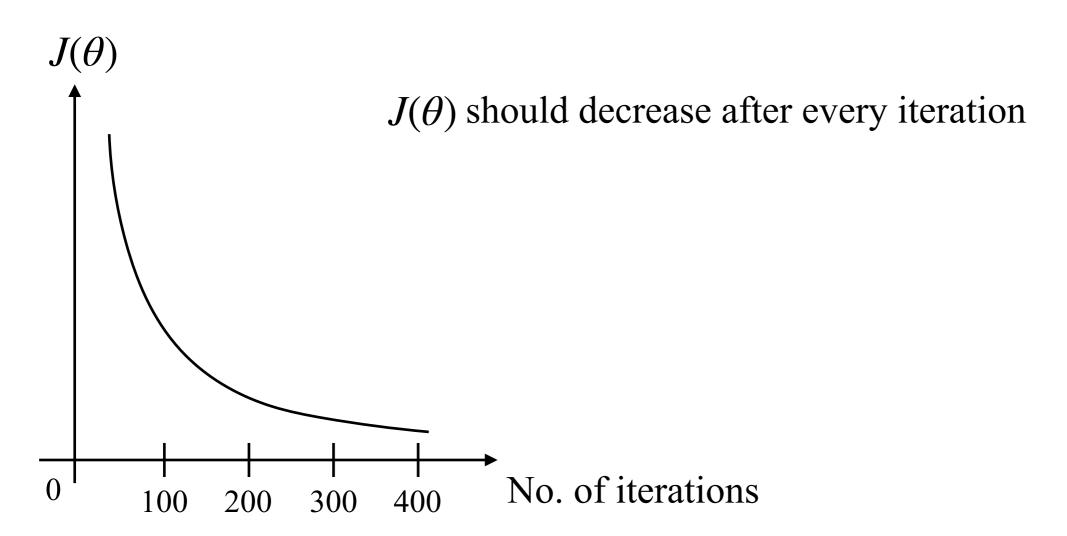
#### **Gradient Descent Update Rule**

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta)$$

- 'Debugging': How to make sure gradient descent is working correctly.
- How to choose learning rate

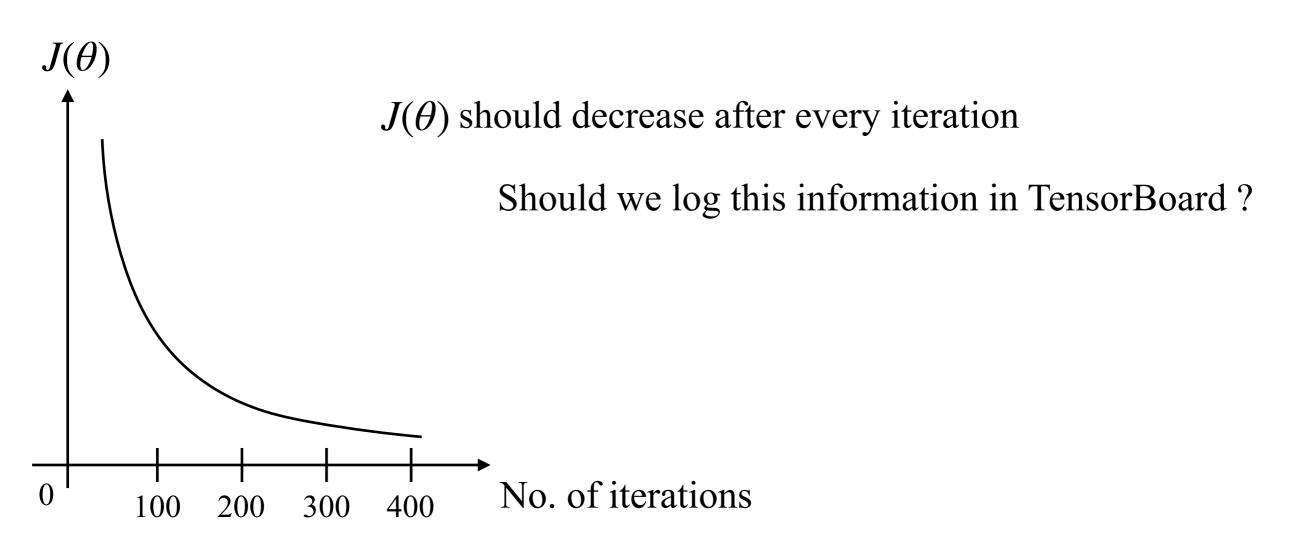
## Is descent working correctly?

Some tips to make sure that gradient descent is working correctly.



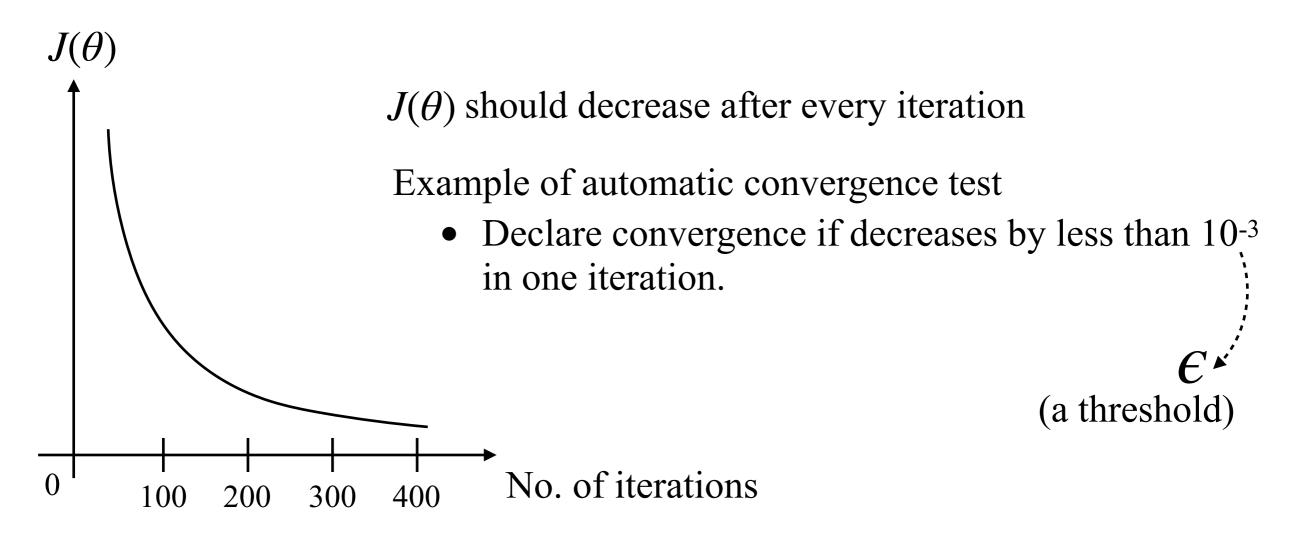
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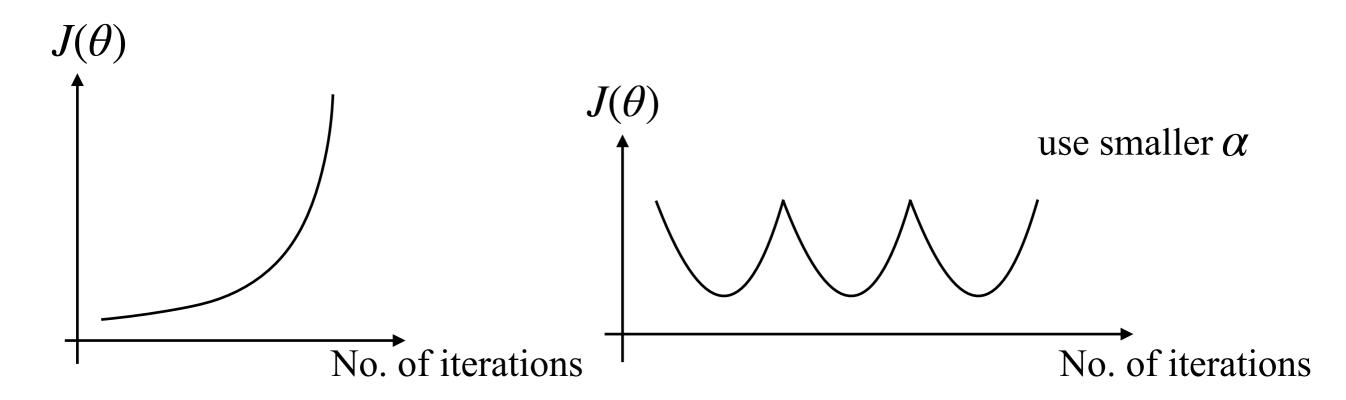


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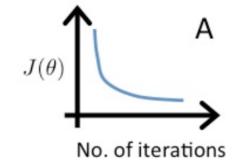
## Is descent working correctly?

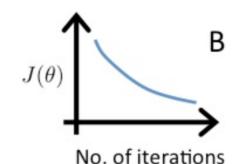


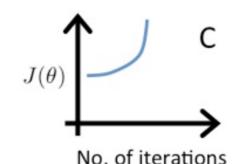
- For sufficiently small  $\alpha$ ,  $J(\theta)$  should decrease on every iteration.
- But if  $\alpha$  is too small, gradient descent can be slow to converge.

#### Question

- Suppose a friend ran gradient descent three times, with  $\alpha = 0.01$ ,  $\alpha = 0.1$ , and  $\alpha = 1$ , and got the following three plots (labeled A, B, and C). Which plots corresponds to which values of  $\alpha$ ?
  - (i) A is  $\alpha = 0.01$ , B is  $\alpha = 0.1$ , C is  $\alpha = 1$
  - (ii) A is  $\alpha = 0.1$ , B is  $\alpha = 0.01$ , C is  $\alpha = 1$
  - (iii) A is  $\alpha = 1$ , B is  $\alpha = 0.01$ , C is  $\alpha = 0.1$
  - (iv) A is  $\alpha = 1$ , B is  $\alpha = 0.1$ , C is  $\alpha = 0.01$





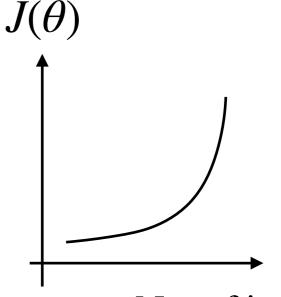


#### Summary

- If  $\alpha$  is too small, then convergence is slow.
- If  $\alpha$  is too large, then  $J(\theta)$  may not decrease on every iteration; may not converge.
- To choose  $\alpha$ , try

...,0.001, ,0.01, ,0.1, ,1,...

 $\dots, 0.001, 0.003, 0.01, 0.03, 0.1, 0.3, 1, \dots$ 



No. of iterations

# Features and Polynomial Regression

### Selecting Features (Intuitively)

#### Housing prices prediction

$$h_{\theta}(x) = \theta_0 + \theta_1 \times \text{frontage} + \theta_2 \times \text{depth}$$



## Selecting Features (Intuitively)

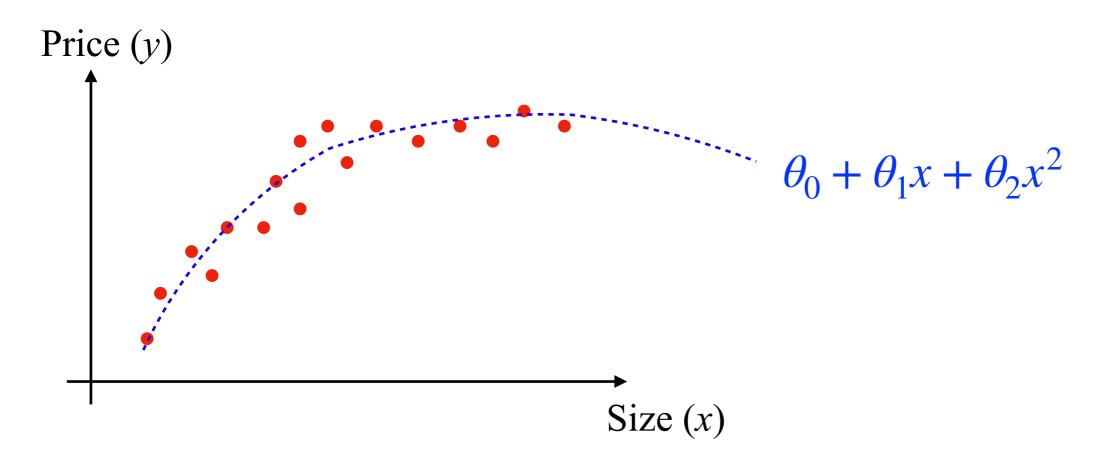
#### Housing prices prediction

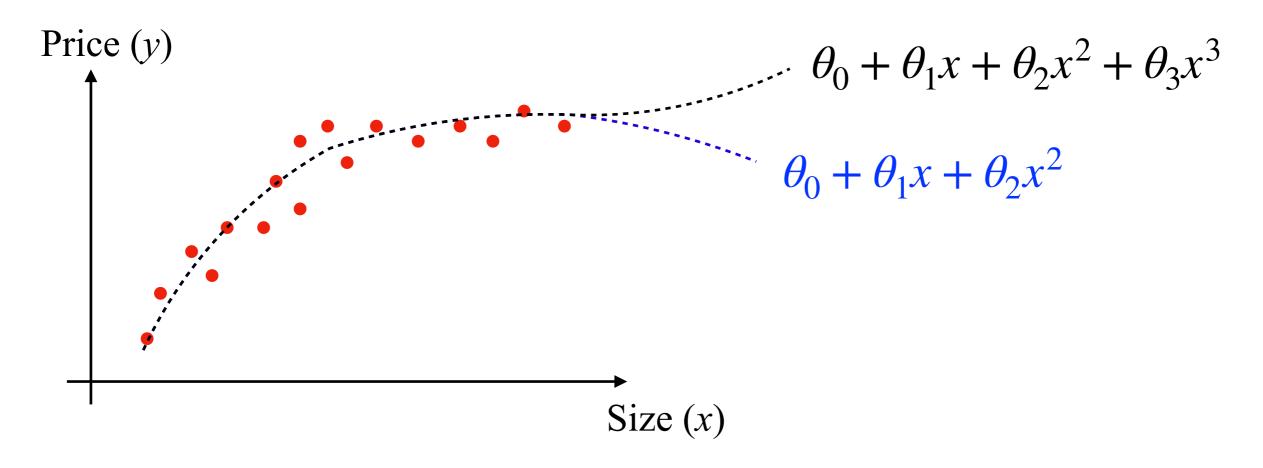
$$h_{\theta}(x) = \theta_0 + \theta_1 \times \text{frontage} + \theta_2 \times \text{depth}$$

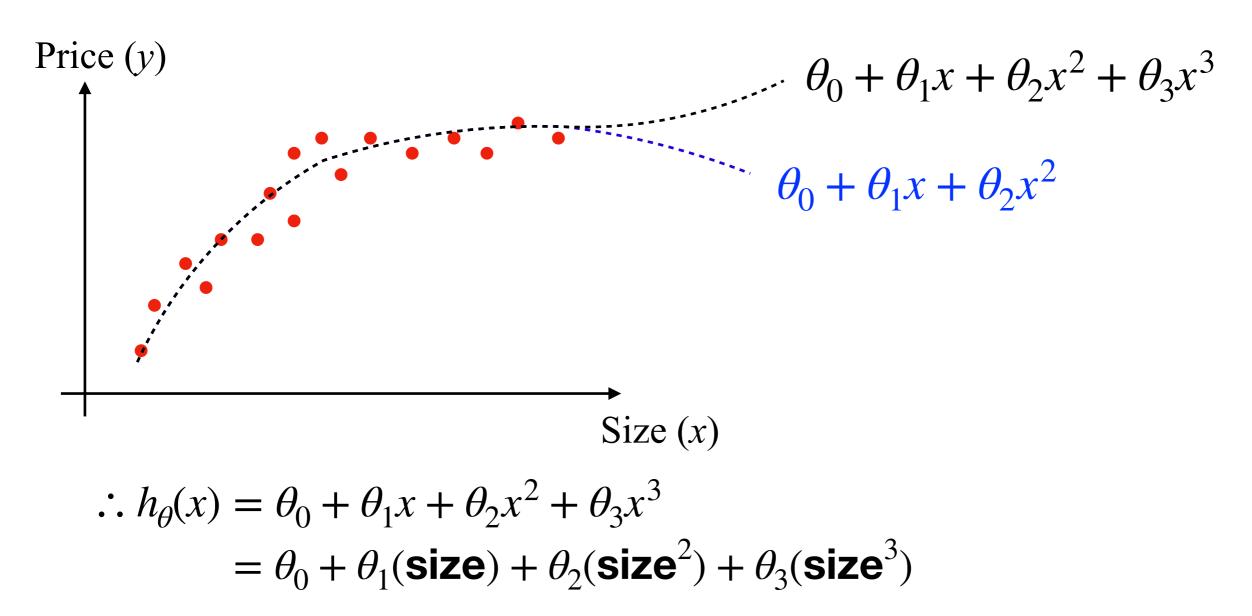
$$\underbrace{x_1} \qquad \underbrace{x_2}$$

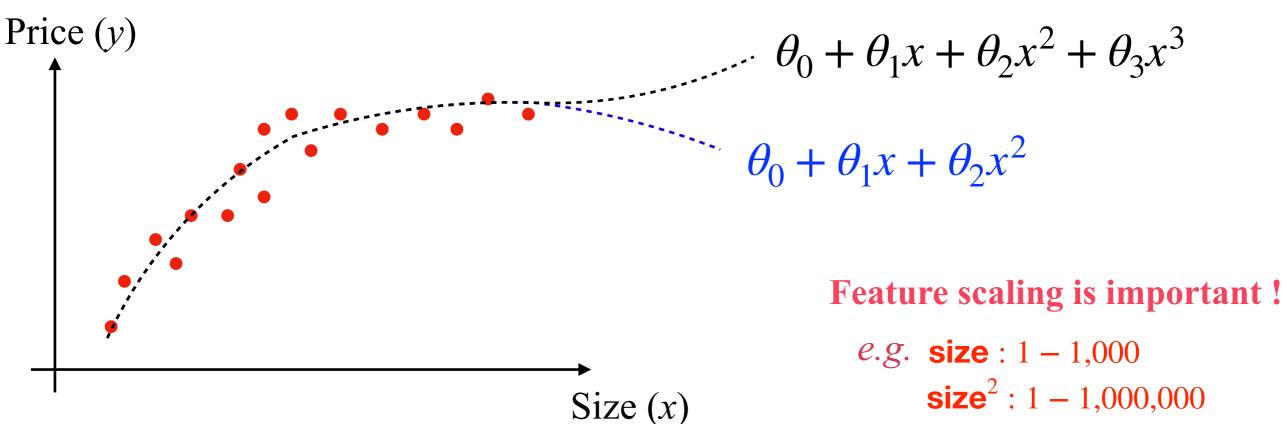


- $\therefore$  area(x) = frontage  $\times$  depth
- $\therefore h_{\theta}(x) = \theta_0 + \theta_1 x$









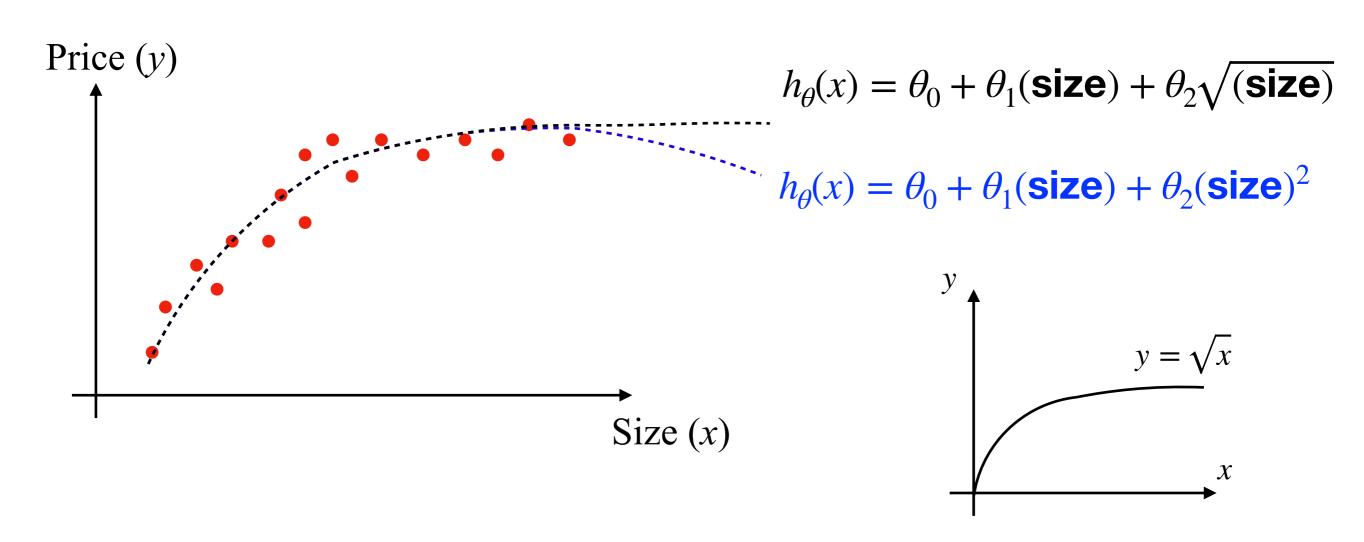
$$\therefore h_{\theta}(x) = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3$$

$$= \theta_0 + \theta_1(\text{size}) + \theta_2(\text{size}^2) + \theta_3(\text{size}^3)$$

 $size^2 : 1 - 1,000,000$ 

 $size^3 : 1 - 1,000,000,000$ 

#### Other Hypothesis Functions



#### Question

• Suppose you want to predict a house's price as a function of its size. Your model is:  $h_{\theta}(x) = \theta_0 + \theta_1(\text{size}) + \theta_2\sqrt{(\text{size})}$ . Suppose size ranges from 1 to 1000 (feet<sup>2</sup>). You will implement this by fitting a model  $h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2$ . Finally, suppose you want to use feature scaling (without mean normalization). Which of the following choices for  $x_1$  and  $x_2$  should you use ? (Note:  $\sqrt{1000} \approx 32$ )

(i) 
$$x_1 = \text{size}, x_2 = 32\sqrt{(\text{size})}$$

(ii) 
$$x_1 = 32(\text{size}), x_2 = \sqrt{(\text{size})}$$

(iii) 
$$x_1 = \frac{\text{size}}{1000}$$
 ,  $x_2 = \frac{\sqrt{\text{(size)}}}{32}$ 

(iv) 
$$x_1 = \frac{\text{size}}{32}$$
,  $x_2 = \sqrt{(\text{size})}$ 

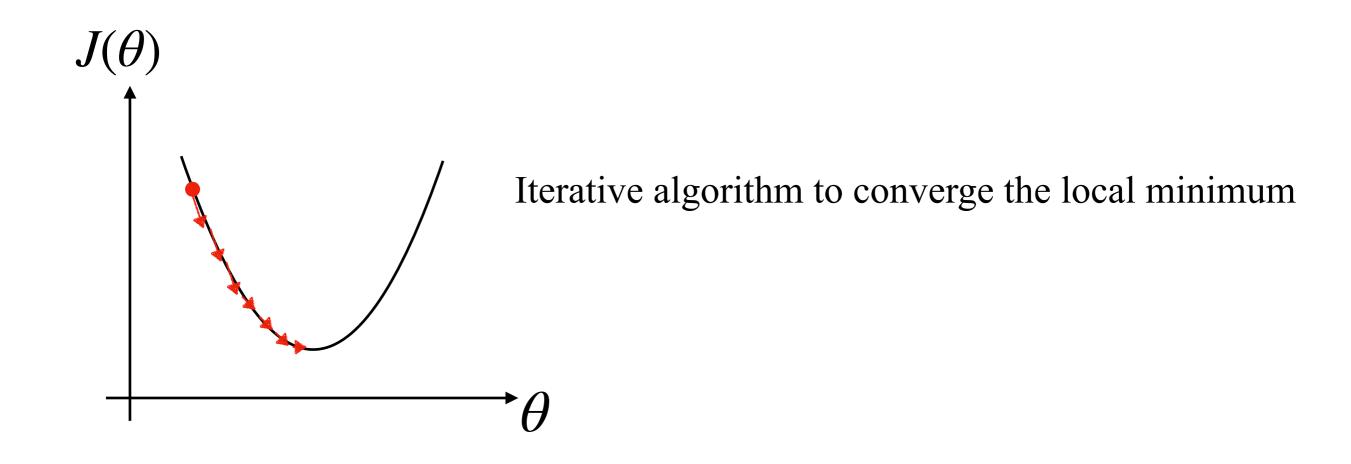
#### Question

• Suppose m = 4 students have taken some class, and the class had a midterm exam and a final exam. You have collected a data set of their scores on the two exams, which is as follows:

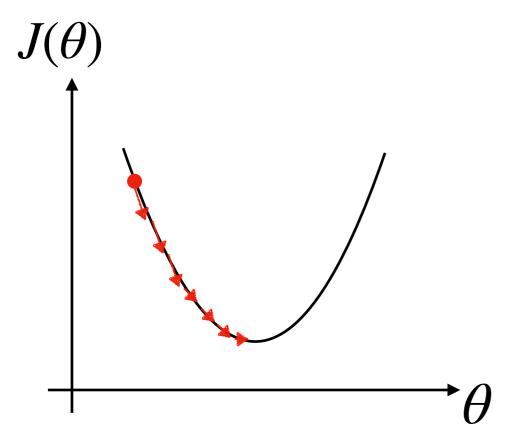
midterm exam	(midterm exam) <sup>2</sup>	final exam
89	7921	96
72	5184	74
94	8836	87
69	4761	78

You'd like to use polynomial regression to predict a student's final exam score from their midterm exam score. Concretely, suppose you want to fit a model of the form:  $h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2$ , where  $x_1$  is the midterm score and  $x_2$  is (midterm score)<sup>2</sup>. Further, you plan to use both feature scaling and mean normalization. What is the normalized feature  $x_2^{(4)}$ ?

## Gradient Descent (Recap)



## Gradient Descent vs. Normal Equation



Iterative algorithm to converge the local minimum

#### Normal equation:

Method to solve for heta analytically

*i.e.* we can solve for the local minimum within just one step

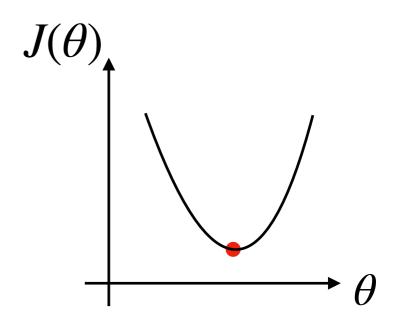
### Normal Equation (Intuitively)

#### Intuition : $(\theta \in \mathbb{R})$

Let 
$$J(\theta) = a\theta^2 + b\theta + c$$

To solve for the optimum, we take the derivative, set to 0 and solve for  $\theta$ 

*i.e.* 
$$\frac{\partial}{\partial \theta} J(\theta) = 2a\theta + b = 0$$



### Normal Equation (Intuitively)

To solve for the optimum, we take the derivative, set to 0 and solve for  $\theta$ 

*i.e.* 
$$\frac{\partial}{\partial \theta} J(\theta) = 2a\theta + b = 0$$

 $\theta \in \mathbb{R}^{n+1} \Longrightarrow J(\theta_0, \theta_1, \dots, \theta_m) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^i) - y^{(i)})^2$  $\frac{\partial}{\partial \theta_j} J(\theta) = \dots = 0 \quad \text{(for every } j\text{)}$ 

Solving for  $\theta_0, \theta_1, ..., \theta_n$  yields  $\theta_0, \theta_1, ..., \theta_n$  that minimizes  $J(\theta_0, ..., \theta_m)$ 

Notice that feature scaling is not necessary for normal equation!

Since we have to take the derivatives and set them to 0 *i.e.* 

$$\frac{\partial J}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)}) = 0$$

$$\frac{\partial J}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)}) x_1^{(i)} = 0$$

$$\vdots$$

$$\frac{\partial J}{\partial \theta_n} = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)}) x_n^{(i)} = 0$$

Since we have to take the derivatives and set them to 0 *i.e.* 

$$\begin{split} &\frac{1}{m} \Sigma_{i=1}^m (h_{\theta}(\boldsymbol{x}^{(i)}) - y^{(i)}) = 0 \Longleftrightarrow \Sigma_{i=1}^m (\theta_0 + \theta_1 x_1^{(i)} + \dots + \theta_n x_n^{(i)} - y^{(i)}) = 0 \\ &\frac{1}{m} \Sigma_{i=1}^m (h_{\theta}(\boldsymbol{x}^{(i)}) - y^{(i)}) x_1^{(i)} = 0 \Longleftrightarrow \Sigma_{i=1}^m (\theta_0 x_1^{(i)} + \theta_1 x_1^{(i)} x_1^{(i)} + \dots + \theta_n x_n^{(i)} x_1^{(i)} - y^{(i)} x_1^{(i)}) = 0 \end{split}$$

$$\frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(\boldsymbol{x}^{(i)}) - y^{(i)}) x_n^{(i)} = 0 \iff \sum_{i=1}^{m} (\theta_0 x_n^{(i)} + \theta_1 x_1^{(i)} x_n^{(i)} + \dots + \theta_n x_n^{(i)} x_n^{(i)} - y^{(i)} x_n^{(i)}) = 0$$

With a bit more manipulation, we get the normal equations i.e.

$$\begin{split} \Sigma_{i=1}^m(\theta_0 + \theta_1 x_1^{(i)} + \ldots + \theta_n x_n^{(i)} - y^{(i)}) &= 0 \\ &\iff \theta_0 m + \theta_1 \Sigma_{i=1}^m x_1^{(i)} + \ldots + \theta_n \Sigma_{i=1}^m x_n^{(i)} = \Sigma_{i=1}^m y^{(i)} \\ \Sigma_{i=1}^m(\theta_0 x_1^{(i)} + \theta_1 x_1^{(i)} x_1^{(i)} + \ldots + \theta_n x_n^{(i)} x_1^{(i)} - y^{(i)} x_1^{(i)}) &= 0 \\ &\iff \theta_0 \Sigma_{i=1}^m x_1^{(i)} + \theta_1 \Sigma_{i=1}^m x_1^{(i)} x_1^{(i)} + \ldots + \theta_n \Sigma_{i=1}^m x_n^{(i)} x_1^{(i)} = \Sigma_{i=1}^m y^{(i)} x_1^{(i)} \\ \vdots \\ \Sigma_{i=1}^m(\theta_0 x_n^{(i)} + \theta_1 x_1^{(i)} x_n^{(i)} + \ldots + \theta_n x_n^{(i)} x_n^{(i)} - y^{(i)} x_n^{(i)}) &= 0 \end{split}$$

 $\iff \theta_0 \sum_{i=1}^m x_n^{(i)} + \theta_1 \sum_{i=1}^m x_1^{(i)} x_n^{(i)} + \dots + \theta_n \sum_{i=1}^m x_n^{(i)} x_n^{(i)} = \sum_{i=1}^m y^{(i)} x_n^{(i)}$ 

Remember that  $x_j^{(i)}$  and  $y^{(i)}$  are all constant (they are the training datasets).

$$\Sigma_{i=1}^{m}(\theta_0 + \theta_1 x_1^{(i)} + \dots + \theta_n x_n^{(i)} - y^{(i)}) = 0$$

$$\iff \theta_0 m + \theta_1 \Sigma_{i=1}^{m} x_1^{(i)} + \dots + \theta_n \Sigma_{i=1}^{m} x_n^{(i)} = \Sigma_{i=1}^{m} y^{(i)}$$

$$\begin{split} \Sigma_{i=1}^{m}(\theta_{0}x_{1}^{(i)} + \theta_{1}x_{1}^{(i)}x_{1}^{(i)} + \dots + \theta_{n}x_{n}^{(i)}x_{1}^{(i)} - y^{(i)}x_{1}^{(i)}) &= 0 \\ \iff \theta_{0}\Sigma_{i=1}^{m}x_{1}^{(i)} + \theta_{1}\Sigma_{i=1}^{m}x_{1}^{(i)}x_{1}^{(i)} + \dots + \theta_{n}\Sigma_{i=1}^{m}x_{n}^{(i)}x_{1}^{(i)} &= \Sigma_{i=1}^{m}y^{(i)}x_{1}^{(i)} \end{split}$$

•

$$\begin{split} \Sigma_{i=1}^m(\theta_0x_n^{(i)} + \theta_1x_1^{(i)}x_n^{(i)} + \dots + \theta_nx_n^{(i)}x_n^{(i)} - y^{(i)}x_n^{(i)}) &= 0 \\ \iff \theta_0\Sigma_{i=1}^mx_n^{(i)} + \theta_1\Sigma_{i=1}^mx_1^{(i)}x_n^{(i)} + \dots + \theta_n\Sigma_{i=1}^mx_n^{(i)}x_n^{(i)} &= \Sigma_{i=1}^my^{(i)}x_n^{(i)} \end{split}$$

Let's try to write our equations in matrix and vector forms as follows:

(Design Matrix) 
$$X = \begin{bmatrix} 1 & x_1^{(1)} & \dots & x_n^{(1)} \\ 1 & x_1^{(2)} & \dots & x_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^{(m)} & \dots & x_n^{(m)} \end{bmatrix}$$
 and 
$$y = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix}$$

You should be able to verify that our system of linear equations become:

$$X^T X \theta = X^T y$$

Assuming that  $X^TX$  is invertible, then:  $\theta = (X^TX)^{-1}X^Ty$ 

#### Question

• Suppose you have the training in the table below:

age $(x_1)$	height in cm $(x_2)$	weight in kg (y)
4	89	16
9	124	28
5	103	20

You would like to predict a child's weight as a function of his age and height with the model: **weight** =  $\theta_0 + \theta_1$ **age** +  $\theta_2$ **height** What are *X* and *y*?

Assuming that  $X^TX$  is invertible, then:  $\theta = (X^TX)^{-1}X^Ty$ 

Question: when a matrix is non-invertible (aka. singular/degenerate)?

Assuming that  $X^TX$  is invertible, then:  $\theta = (X^TX)^{-1}X^Ty$ 

Question: when  $X^TX$  is non-invertible (aka. singular/degenerate)?

This case happens when we have:

- redundant features (i.e. some columns are linearly dependent) e.g.
  - $x_1$  = size in feet<sup>2</sup>
  - $x_2$  = size in m<sup>2</sup>

1 m 
$$\approx 3.28$$
 feet  $x_1 = (3.28)^2 x_2$ 

- too many features  $(m \le n)$ 
  - delete some features, or
  - use regularization (we'll talk about this later)

## Gradient Descent vs. Normal Equation

#### m training examples, n features

#### **Gradient Descent**

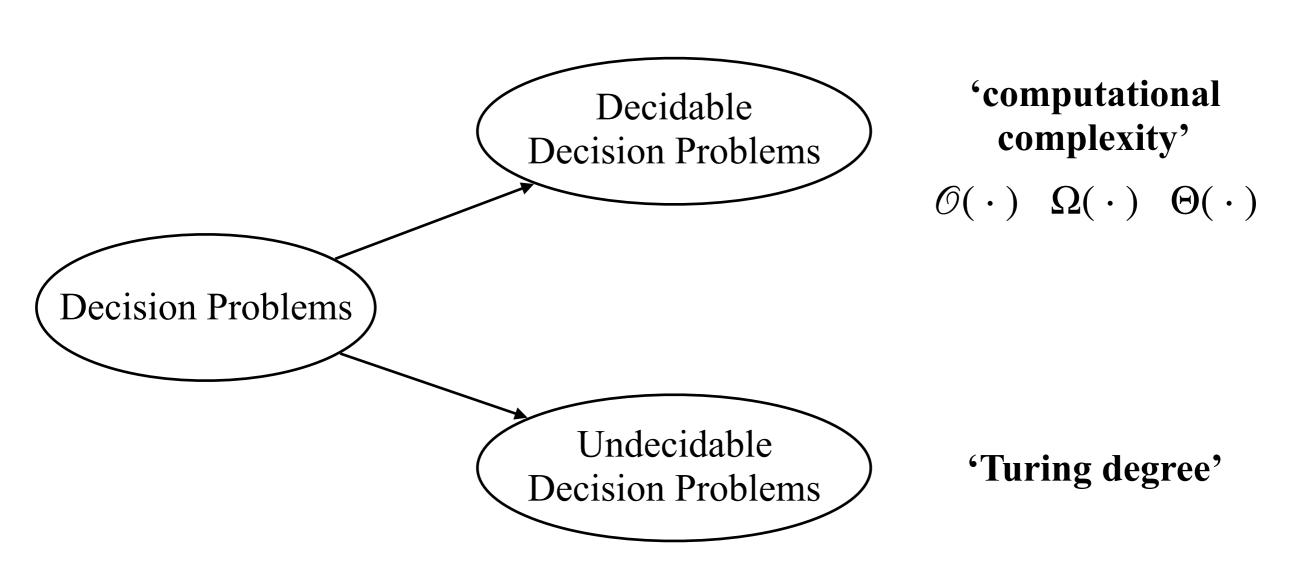
- Need to choose  $\alpha$
- Needs many iterations
- Works well even when n is large  $\mathcal{O}(kn^2)$

#### **Normal Equation**

- No need to choose  $\alpha$
- Don't need to iterate
- Need to compute  $(X^TX)^{-1}$
- Slow if *n* is very large  $\mathcal{O}(n^3)$

(Large if  $n \ge 10^4$ )

## Computational Complexity (Review for non-CS students)



#### Question

- Suppose you have a dataset with m = 1,000,0000 examples and n = 200,000 features for each example. You want to use multivariate linear regression to fit the parameters  $\theta$  to our data. Should you prefer gradient descent or the normal equation?
  - (i) The normal equation, since gradient descent might be unable to find the optimal  $\theta$
  - (ii) Gradient descent, since  $(X^TX)^{-1}$  will be very slow to compute in the normal equation
  - (iii) The normal equation, since it provides an efficient way to directly find the solution.
  - (iv)Gradient descent, since it will always converge to the optimal heta

Why least square? Why not some other cost function?

The least square method comes naturally from a probabilistic interpretation of the problem.

Let's suppose that  $(x^{(i)}, y^{(i)})$  were generated according to:

$$y^{(i)} = \boldsymbol{\theta}^T \boldsymbol{x}^{(i)} + \boldsymbol{\epsilon}^{(i)},$$

where  $\epsilon^{(i)}$  is an error term representing noise and whatever effects our linear model doesn't capture.

We might assume that the noise term  $e^{(i)}$  were sampled independently and identically distributed from some distribution  $p(e^{(i)})$ .

Is independently and identically distributed a reasonable assumption?

In many applications, a natural choice of  $p(\epsilon^{(i)})$  is a Gaussian (aka. normal distribution), which we write:

$$\epsilon^{(i)} \sim \mathcal{N}(0, \sigma^2)$$

The univariate zero-mean Gaussian distribution is written:

$$p(\epsilon^{(i)}) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{\left(-\frac{(\epsilon^{(i)})^2}{2\sigma^2}\right)}$$

Now, we would like to know  $p(y^{(i)}|\mathbf{x}^{(i)};\boldsymbol{\theta})$ .

Suppose  $y^{(i)} \sim \mathcal{N}(\theta^T \mathbf{x}^{(i)}, \sigma^2)$ , then:

$$p(y^{(i)}|\mathbf{x}^{(i)};\boldsymbol{\theta}) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{(-\frac{(y^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)})^2}{2\sigma^2})}$$

Now, consider the distribution of the vector of targets y given the design matrix X. We write this:

$$p(y|X;\theta)$$

Since the elements of y are independent, we can write:

$$p(\mathbf{y} | \mathbf{X}; \boldsymbol{\theta}) = \prod_{i=1}^{m} p(\mathbf{y}^{(i)} | \mathbf{x}^{(i)}; \boldsymbol{\theta})$$

The Gaussians are centered at our predictions of the  $y^{(i)}$ 's, so the conditional probability  $p(y|X;\theta) = \prod_{i=1}^m p(y^{(i)}|x^{(i)};\theta)$  will be maximized when our predictions of the  $y^{(i)}$ 's are perfect.

This means choosing  $\theta$  to maximize  $p(y|X;\theta)$  would be good!

Now, we would like to choose  $\theta$  that maximize  $p(y | X; \theta)$ .

First, let's write this distribution as a function of the parameter vector  $\theta$ :

$$L(\boldsymbol{\theta}) = L(\boldsymbol{\theta}; \boldsymbol{X}, \boldsymbol{y}) = p(\boldsymbol{y} | \boldsymbol{X}; \boldsymbol{\theta})$$

 $L(\boldsymbol{\theta})$  is called the <u>likelihood</u> function.

The maximum likelihood principle states that we should choose the  $\theta$  that makes the likelihood  $L(\theta)$  as large as possible:

$$\boldsymbol{\theta}^* = \max_{\boldsymbol{\theta}} L(\boldsymbol{\theta})$$

OK! Let's try to maximize  $L(\theta)$ .

$$\therefore L(\boldsymbol{\theta}) = \prod_{i=1}^{m} p(y^{(i)} | \boldsymbol{x}^{(i)}; \boldsymbol{\theta})$$

$$= \prod_{i=1}^{m} \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{(y^{(i)} - \boldsymbol{\theta}^T \boldsymbol{x}^{(i)})^2}{2\sigma^2})$$

This looks so difficult to maximize directly (try to evaluate  $\frac{\partial L}{\partial \theta}$ )!

However, we can equivalently maximize any function that is strictly increasing in  $L(\theta)$ .

It will be more convenient to maximize the log likelihood  $l(\theta)$ :

$$l(\theta) = \log L(\theta)$$

$$= \log \prod_{i=1}^{m} p(y^{(i)} | \mathbf{x}^{(i)}; \theta)$$

$$= \sum_{i=1}^{m} \log \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{(y^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)})^2}{2\sigma^2})$$

$$= m \log \frac{1}{\sqrt{2\pi\sigma^2}} - \frac{1}{2\sigma^2} \sum_{i=1}^{m} (y^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)})^2$$

Clearly, any  $\theta$  maximizing

$$m \log \frac{1}{\sqrt{2\pi\sigma^2}} - \frac{1}{2\sigma^2} \sum_{i=1}^{m} (y^{(i)} - \boldsymbol{\theta}^T \boldsymbol{x}^{(i)})^2$$

will also maximize

$$-\frac{1}{2m}\sum_{i=1}^{m}(y^{(i)}-\boldsymbol{\theta}^{T}\boldsymbol{x}^{(i)})^{2}$$

Amazingly, maximizing  $L(\theta)$  or  $l(\theta)$  gives us the same  $\theta$  we get by minimizing

$$J(\boldsymbol{\theta}) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\boldsymbol{\theta}}(\boldsymbol{x}^{(i)}) - y^{(i)})^2$$

We now see that, for linear regression, least squares and maximum likelihood are equivalent.

The equivalence comes from the assumption of independently and identically distributed Gaussian errors in our samples  $y^{(i)}$ .

For other problems, we may not be able to formulate a least squares cost function, but we will be able to use the more general principle of maximum likelihood.

#### Summary

Now, we have two choices for minimizing  $J(\theta)$  as follows:

- 1. Solve the normal equations
- 2. Use the iterative methods:
  - a) Batch gradient descent
  - b) Stochastic gradient descent
  - c) Mini-batch gradient descent (compromise between GD and SGD)

Now, you are ready for Assignment 2!