

CPSC 8420 Advanced Machine Learning

Week 6: Unsupervised Learning

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Learning Outcomes

Our goal for today's lecture is to understand:

- PCA and Projection
- K -means and its variations
- Non-negative Matrix Factorization (NMF) with solutions through Multiplicative Updating Algorithm (MUA)
- NMF with solutions via Alternating Minimization

Non-Negative Matrix Factorization

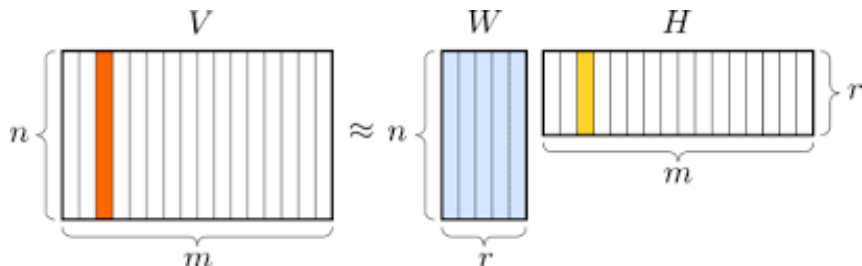
Disadvantage of PCA

Consider Error Construction formulation of PCA:

$\|x_i - U\lambda_i\|^2, s.t. U^T U = I$, that each data point is approximately represented by a linear combination of U_i with coefficients $\lambda_i := U^T x_i$, apparently it can be negative. However, in real-life, some operations are only additive, thus we may add non-negativeness constraint on the factor.

Another example is image processing, that each pixel should be within $[0, 255]$, negative pixel is meaningless. To enhance the interpretability, we introduce Non-negative Matrix Factorization.

Non-Negative Matrix Factorization



Non-Negative Matrix Factorization

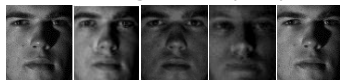
$$\begin{bmatrix} 4.2 & 3.5 & 1 & 1.5 \\ 4 & 3.8 & 1.2 & 1.4 \end{bmatrix} \approx \begin{bmatrix} 4 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 0.9 & 0.8 & 0.1 & 0.2 \\ 0.1 & 0.2 & 0.9 & 0.8 \end{bmatrix} \\
 \approx \begin{bmatrix} 1 & 4 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} 0.1 & 0.2 & 0.9 & 0.8 \\ 0.9 & 0.8 & 0.1 & 0.2 \end{bmatrix}$$

MUA for NMF

Non-negative Matrix Factorization problem:

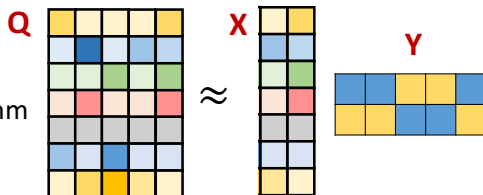
$$\min_{X, Y \geq 0} h(X, Y) = \frac{1}{2} \|Q - XY\|_F^2$$

5 images of 2 people

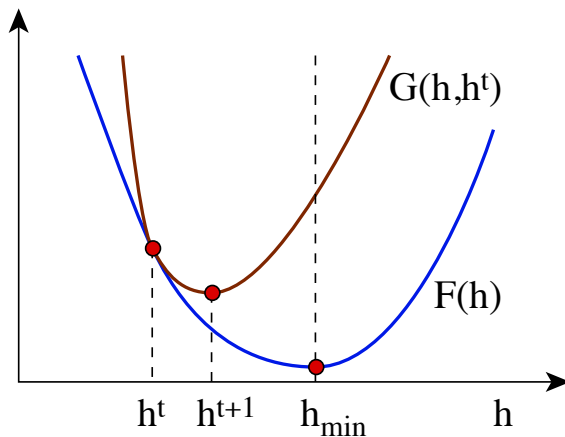


Multiplicative Updating Algorithm
(MUA) (Lee & Seung, 2001):

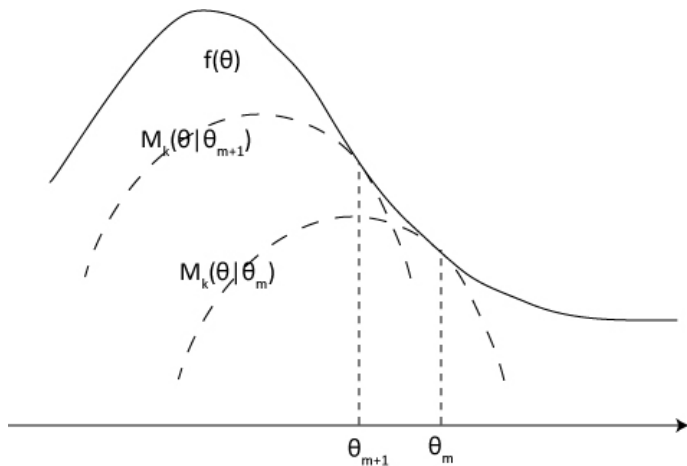
$$Y_{ij} \leftarrow Y_{ij} \frac{(X^T Q)_{ij}}{(X^T X Y)_{ij}}, \quad X_{ij} \leftarrow X_{ij} \frac{(Q Y^T)_{ij}}{(X Y Y^T)_{ij}}$$



Convergence and Majorize-Minimization



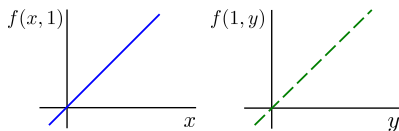
Minorize-Maximization



Alternating-Minimization

$$\min_{X, Y \geq 0} h(X, Y) = \frac{1}{2} \|Q - XY\|_F^2$$

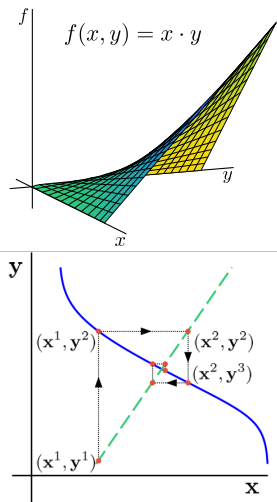
1. The NMF objective is **Nonconvex**.
2. **Convex** w.r.t. each component (X, Y)



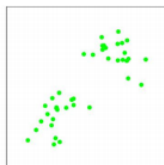
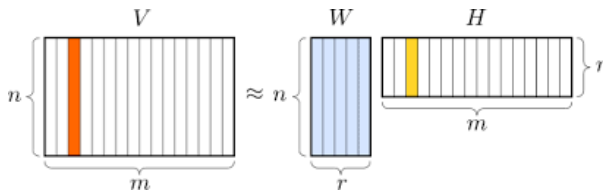
— $f(x, 1) : \mathbb{R} \rightarrow \mathbb{R}$

- - $f(1, y) : \mathbb{R} \rightarrow \mathbb{R}$

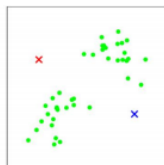
MARGINALLY CONVEX FUNCTION



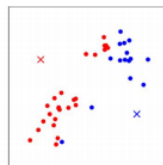
K-means v.s. NMF



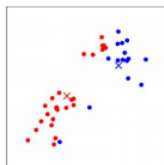
(a)



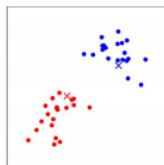
(b)



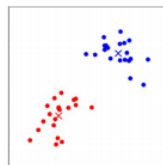
(c)



(d)



(e)



(f)

K -means v.s. NMF

NMF	a	b	c	d
C1	0.9	0.15	0.8	0.25
C2	0.2	0.8	0.1	0.8

K -means	a	b	c	d
C1	1	0	1	0
C2	0	1	0	1

Convergence of Gradient Descent

Strongly Convex Strongly Smooth Function

We say a continuously differentiable function $f : \mathbb{R}^p \rightarrow \mathbb{R}$ is α -strongly convex (SC) and β -strongly smooth (SS) if for every $x, x^+ \in \mathbb{R}^p$, we have:

$$\frac{\alpha}{2} \|x^+ - x\|_2^2 \leq f(x^+) - f(x) - \langle \nabla f(x), x^+ - x \rangle \leq \frac{\beta}{2} \|x^+ - x\|_2^2, \quad (1)$$

based on which we will have:

$$\begin{aligned} f(x^+) &\leq f(x) - \frac{1}{2\beta} \|\nabla f(x)\|^2 \\ f(x^+) &\geq f(x) - \frac{1}{2\alpha} \|\nabla f(x)\|^2. \end{aligned} \quad (2)$$

Replacing x^+ with x^* , then we will have:

$$\frac{1}{2\beta} \|\nabla f(x)\|^2 \leq f(x) - f(x^*) \leq \frac{1}{2\alpha} \|\nabla f(x)\|^2 \quad (3)$$

Linear Convergence Rate

$$\begin{aligned}f(x^+) - f(x^*) &\leq f(x) - f(x^*) - \frac{1}{2\beta} \|\nabla f(x)\|^2 \\&\leq f(x) - f(x^*) - \frac{\alpha}{\beta} (f(x) - f(x^*)) \\&= (1 - \frac{\alpha}{\beta})(f(x) - f(x^*))\end{aligned}\tag{4}$$

which implies $\frac{f(x^+) - f(x^*)}{f(x) - f(x^*)} = 1 - \frac{\alpha}{\beta}$, is the definition of linear convergence. Then to obtain ϵ -suboptimal result, we need $\mathcal{O}(\log \frac{1}{\epsilon})$ iterations, which is way faster than sub-linear rate $\mathcal{O}(\frac{1}{\epsilon})$.

Non Strongly Convex

$$\begin{aligned} f(x^+) - f(x^*) &\leq f(x) - f(x^*) - \frac{1}{2\beta} \|\nabla f(x)\|^2 \\ &\leq \langle \nabla f(x), x - x^* \rangle - \frac{1}{2\beta} \|\nabla f(x)\|^2 \end{aligned} \quad (5)$$

on the other hand we have:

$$\begin{aligned} \|x^+ - x^*\|^2 &= \|x - \eta \nabla f(x) - x^*\|^2 \\ &= \|x - x^*\|^2 - 2\eta \langle \nabla f(x), x - x^* \rangle + \eta^2 \|\nabla f(x)\|^2 \\ &= \|x - x^*\|^2 - 2\eta (\langle \nabla f(x), x - x^* \rangle - \frac{\eta}{2} \|\nabla f(x)\|^2), \end{aligned} \quad (6)$$

then we have

$\langle \nabla f(x), x - x^* \rangle - \frac{\eta}{2} \|\nabla f(x)\|^2 = \frac{1}{2\eta} (\|x - x^*\|^2 - \|x^+ - x^*\|^2)$, and
therefore $f(x^+) - f(x^*) \leq \frac{1}{2\eta} (\|x - x^*\|^2 - \|x^+ - x^*\|^2)$

Non Strongly Convex

Summation the equation above from $k = 0$ to $k = T - 1$, we have:

$$\sum_{k=0}^{T-1} f(x_{k+1}) - f(x^*) \leq \frac{\|x_0 - x^*\|^2 - \|x_T - x^*\|^2}{2\eta} \leq \frac{\|x_0 - x^*\|^2}{2\eta}, \text{ then}$$

$f(x_T) - f(x^*) \leq \frac{1}{T} \sum_{k=0}^{T-1} f(x_{k+1}) - f(x^*) \leq \frac{\|x_0 - x^*\|^2}{2T\eta}$, which is sub-linear convergence rate. Then to obtain ϵ -suboptimal result, we need $T = \mathcal{O}(\frac{1}{\epsilon})$ iterations.