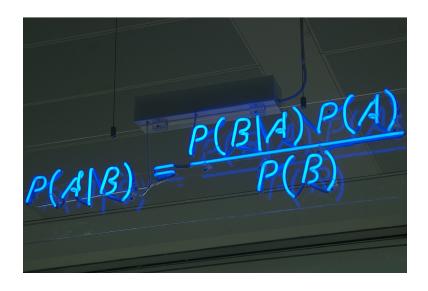
CPSC 8420 Advanced Machine Learning Week 10: Bayesian Decision Theory

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When event X, Y are independant, then:

$$P(X,Y) = P(X)P(Y). (1)$$

Now let's take a look at the definition of Conditional Probability:

$$P(Y|X) = P(X,Y)/P(X),$$

$$P(X|Y) = P(X,Y)/P(Y).$$
(2)

Based on which we have

$$P(X, Y) = P(Y|X) * P(X) = P(X|Y) * P(Y)$$
, which implies:

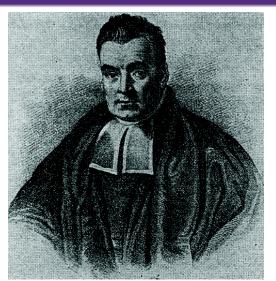
$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)} \tag{3}$$

$$P(X) = \sum_{k} P(X|Y = Y_k)P(Y_k), \quad s.t. \ \sum_{k} P(Y_k) = 1$$
 (4)

therefore, we have:

$$P(Y_k|X) = \frac{P(X|Y_k)P(Y_k)}{\sum_{k} P(X|Y = Y_k)P(Y_k)}$$
 (5)

Who is Bayes



Thomas Bayes (1701? – 1761), he was elected as a Fellow of the Royal Society in 1742. His work was popularised by Laplace.

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Frequentist vs. Bayesian



(a) Karl Pearson (27 March 1857 – 27 April 1936)



(b) Sir Ronald Aylmer Fisher (17 February 1890 – 29 July 1962)

$$P(Y_k|X) = \frac{P(X|Y_k)P(Y_k)}{\sum\limits_k P(X|Y=Y_k)P(Y_k)}$$

We have two colored (red and blue) boxes, the red one has 2 apples and 6 oranges while the blue box contains one orange and 3 apples. Assume the probability to take from the red box is 0.4:

- What is the overall probability that the selection procedure will pick an apple?
- Given that we have chosen an orange, what is the probability that the box we chose was the red one?

Bayesian Model

we are given data:

$$(x_1^{(1)}, x_2^{(1)}, ... x_n^{(1)}, y_1), (x_1^{(2)}, x_2^{(2)}, ... x_n^{(2)}, y_2), ... (x_1^{(m)}, x_2^{(m)}, ... x_n^{(m)}, y_m),$$
 that is we have m samples with n features, also assume there are K classes defined as $C_1, C_2, ..., C_k$.

From the training samples we can get $P(Y = C_k)(k = 1, 2, ...K)$, if we know conditional probability distribution

 $P(X = x | Y = C_k) = P(X_1 = x_1, X_2 = x_2, ... X_n = x_n | Y = C_k)$, then we will know joint probability distribution P(X, Y):

$$P(X, Y = C_k) = P(Y = C_k)P(X = x | Y = C_k)$$

$$= P(Y = C_k)P(X_1 = x_1, X_2 = x_2, ... X_n = x_n | Y = C_k)$$
(6)

To compute $P(X_1 = x_1, X_2 = x_2, ... X_n = x_n | Y = C_k)$ is difficult, as it is of dimension n density distribution. Bayes theorem make an assumption that each feature is independent to each other, in addtion, the order doesn't matter. Therefore:

$$P(X_1 = x_1, X_2 = x_2, ...X_n = x_n | Y = C_k)$$

$$= P(X_1 = x_1 | Y = C_k) P(X_2 = x_2 | Y = C_k) ... P(X_n = x_n | Y = C_k)$$
(7)

Though the (Naive) presumption doesn't have to be 100% true, but it is not that wrong. Moreover, it makes the model very concise and computationally friendly. That's the reason we call it as **Naive Bayes**.

How to Classify New Data?

How can we classify a new data $(x_1^{(test)}, x_2^{(test)}, ... x_n^{(test)})$?

It is equivalent to maximize $P(Y = C_k | X = X^{(test)})$, which we can make use of Bayes Theorem:

$$C_{result} = \underbrace{argmax}_{C_k} P(Y = C_k | X = X^{(test)})$$

$$= \underbrace{argmax}_{C_k} P(X = X^{(test)} | Y = C_k) P(Y = C_k) / P(X = X^{(test)})$$
(9)

How to Classify?

For all classes to compute $P(Y = C_k | X = X^{(test)})$, the denominator is all the same, thus we can simplify the above equation as:

$$C_{result} = \underbrace{argmax}_{C_k} P(X = X^{(test)} | Y = C_k) P(Y = C_k)$$

$$= \underbrace{argmax}_{C_k} P(Y = C_k) \prod_{j=1}^{n} P(X_j = X_j^{(test)} | Y = C_k)$$
(10)

where $P(Y = C_k) = \frac{|D_k|}{|D|}$. The only problem remains how to compute $P(X_j = X_j^{(test)}|Y = C_k)$.

Computing Conditional Probability Distribution

We discuss two cases for $P(X_j = X_j^{(test)} | Y = C_k)$:

- If the data is discrete, then $P(X_j = X_j^{(test)} | Y = C_k) = \frac{|D_{k,j}|}{|D_k|}$
- If the data is continous and assume it is Normal Distribution with μ_k, σ_k^2 being the expecation and variance respectively. Then

$$P(X_j = X_j^{(test)} | Y = C_k) = \frac{1}{\sqrt{2\pi\sigma_k^2}} exp\left(-\frac{(X_j^{(test)} - \mu_k)^2}{2\sigma_k^2}\right).$$

Example

Given 5 comments with positive/negative labels:

- P: extremely impressive
- N: extremely boring
- P: boring but impressive
- N: impressive but boring
- P: impressive and amazing

please determine the sentiment of a new testing comment: "amazing and impressive but somewhat boring" by making use of *Naive Bayes* rule.

Laplacian Smoothing

Sometimes, some features may not appear in training samples, which may lead $P(X_j = X_j^{(test)}|Y = C_k) = 0$, to avoid that, Laplacian Smoothing is introduced:

$$P(X_j = X_j^{(test)} | Y = C_k) = \frac{m_{kj^{test}} + \lambda}{m_k + O_j \lambda}$$
(11)

where $\lambda > 0$, and usually taken as 1. O_j is the number of value for X_j .

Example

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Bayes Decision Boundary

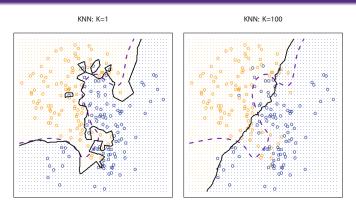


FIGURE 2.16. A comparison of the KNN decision boundaries (solid black curves) obtained using K=1 and K=100 on the data from Figure 2.13. With K=1, the decision boundary is overly flexible, while with K=100 it is not sufficiently flexible. The Bayes decision boundary is shown as a purple dashed line.

How can we determine Bayes Decision Boundary?

Bayes Decision Boundary

$$\frac{P(C_1 \mid X)}{P(C_2 \mid X)} = \frac{P(X \mid C_1)}{P(X \mid C_2)} \frac{P(C_1)}{P(C_2)}$$
(12)

- First, compute μ_k, σ_k^2 for training data points.
- Then, compute prior probabilty $P(Y = C_k) = m_k/m$.

•
$$P(X_j = x_j | Y = C_k) = \frac{1}{\sqrt{2\pi\sigma_k^2}} exp\left(-\frac{(x_j - \mu_k)^2}{2\sigma_k^2}\right)$$

Semi-naive Bayes Classifiers

Naive Bayes assumes that each feature is independent, however, this is somewhat unrealistic. For example: word 'I' and 'am' are closely related. So the independent property can be relaxed such as:

One-Dependent Estimator (ODE), which assumes each attribute is dependent with at most another parent attribute, that is:

$$P(c|x) \propto P(c) \prod_{j=1}^{d} P(x_j|c, pa_j)$$
 (13)

