## HW2\_psp2133

## February 27, 2018

## 1 Deep Learning for Computer Vision: Assignment 2

1.1 Computer Science: COMS W 4995 004

1.2 Due: February 27, 2018

**Problem** You are given the noisy XOR data generated for you below. Your task is to implement a multi-layer perceptron binary classifier with one hidden layer. For the activiation function of the hidden units use ReLu or leaky ReLu. For the loss function use a softplus on a linear output layer as we did in class.

- a) Implement each layer of the network as a separate function with both forward propagation and backpropagation.
- b) Train the network using stochastic gradient descent with mini-batches.
- c) Show the decision regions of the trained classifier by densely generating points in the plane and color coding these points with the binary labels.
- d) Repeat (b) and (c) varying the number of hidden units: 3, 16, 512. Discuss how the number of hidden units affects the solution.
- e) Try choosing your own loss function (without asking me or the TAs what you should choose), repeating (d).
- f) Now try with three inputs, generating your own training and validation data. (For this XOR the output should be a 1 if and only if exactly one of the inputs is 1. But make the training data noisey as before.) Use softplus loss. Do not try to show the decision regions, instead generate a validation set in the same manner as the training set, classify the samples, and compute the classification accuracy.

If you are struggling to get the network to converge, experiment with different learning rates. Grading: a-d=85%, e=10%, f=5%.

NOTE: Do not to use keras, tensorflow, pytorch, sklearn, etc. to do this. You must build the machine learning components from scratch. Let's start by importing some libraries.

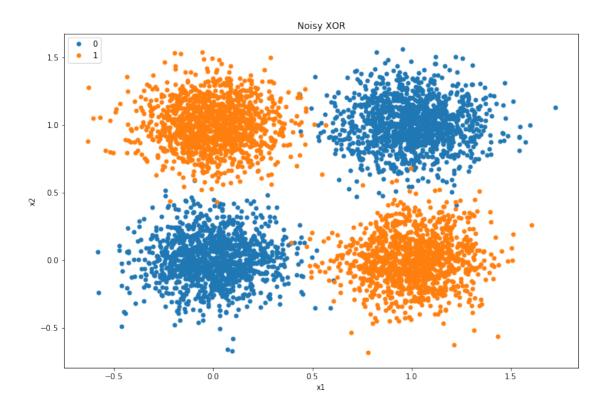
```
In [476]: import numpy as np import random
```

```
import matplotlib.pyplot as plt
          from tqdm import tqdm
  Let's make up some noisy XOR data.
In [501]: data = pd.DataFrame(np.zeros((5000, 3)), columns=['x1', 'x2', 'y'])
          # Let's make up some noisy XOR data to use to build our binary classifier
          for i in range(len(data.index)):
              x1 = 1.0 * random.randint(0,1)
              x2 = 1.0 * random.randint(0,1)
              y = 1.0 * np.logical_xor(x1 == 1 , x2 == 1)
              x1 = x1 + 0.18 * np.random.normal()
              x2 = x2 + 0.18 * np.random.normal()
              data.iloc[i,0] = x1
              data.iloc[i,1] = x2
              data.iloc[i,2] = y
          data.head()
Out [501]:
                   x1
                                   У
          0 -0.225245 0.115329 0.0
          1 0.184413 1.030207
          2 0.914806 -0.179590 1.0
          3 0.081391 0.877957 1.0
          4 0.860010 0.811776 0.0
  Let's message this data into a numpy format.
In [502]: \# set X (training data) and y (target variable)
          cols = data.shape[1]
          X = data.iloc[:,0:cols-1]
          y = data.iloc[:,cols-1:cols]
          \# The cost function is expecting numpy matrices so we need to convert X and y before
          X = np.matrix(X.values)
          y = np.matrix(y.values)
  Let's make a sloppy plotting function for our binary data.
In [503]: # Sloppy function for plotting our data
          def plot_data(X, y_prob):
              fig, ax = plt.subplots(figsize=(12,8))
              ax.margins(0.05) # Optional, just adds 5% padding to the autoscaling
              y_predict = y_prob > 0.5
              indices_0 = [k for k in range(0, X.shape[0])
```

import pandas as pd

Now let's plot it.

In [504]: plot\_data(X, y)



Now let's create functions for forward and backward prop through the layers and we are off...

```
In [5]: # Add a dimension for the bias
# X = np.c_[X, np.ones(X.shape[0])]
```

```
In [505]: def relu(a):
              a[a < 0] = 0
              return a
          def leaky_relu(a, eps):
              a[np.where(a < 0)] *= eps
              return a
In [506]: def sigmoid(z):
              return 1.0/(1.0 + np.exp(-z))
In [507]: def softplus(data, labels, a):
              loss = np.multiply(1 - 2*labels, a)
              loss = np.log(1 + np.exp(loss))
              return loss
In [577]: class Network():
              def __init__(self, in_units = 2, hidden_units = 3,
                           out_units = 1, lr = 0.1,
                           batch_size = 100, debug = False):
                  # Network specifications
                  self.in_units = in_units
                  self.hidden_units = hidden_units
                  self.batch_size = batch_size
                  self.out units = out units
                  self.lr = lr
                  self.debug = debug
                  # Initialize network parameters
                  w1 = np.random.rand(self.hidden_units, self.in_units)
                  w2 = np.random.rand(self.out_units, self.hidden_units)
                  b1 = np.zeros((hidden_units, 1))
                  b2 = np.zeros((self.out_units, 1))
                  self.weights = [w1, w2]
                  self.bias = [b1, b2]
                  # Initialize batchwise layer outputs as empty
                  self.linear1 = []
                  self.relu1 = []
                  self.eps = 0.001
                  self.linear2 = []
                  # Initialize batchwise gradients as empty
                  self.allgrad_weight1 = []
                  self.allgrad_weight2 = []
                  self.allgrad_bias1 = []
```

```
self.allgrad_bias2 = []
# Feedforward for entire batch
def forward(self, data, save = True):
    self.linear1 = □
    self.relu1 = []
    self.linear2 = []
    for idx in range(data.shape[0]):
        x = data[idx, ::]
        x = x.reshape(self.in_units, 1)
        self._forward(x, idx, save)
    return np.array(self.linear2)
# Feedforward for a single data point
def _forward(self, x, idx, save = True):
    linear1 = np.dot(self.weights[0], x) + self.bias[0]
    relu1 = leaky_relu(linear1, self.eps)
    linear2 = np.dot(self.weights[1], relu1) + self.bias[1]
    self.linear2.append(linear2)
    self.linear1.append(linear1)
    self.relu1.append(relu1)
    if self.debug and idx == 0:
        print("\n---- PRINT FORWARD DATA ----\n")
        print("x = ", x, x.shape)
        print("weights1 = ", self.weights[0], self.weights[0].shape)
        print("linear1 = ", linear1, linear1.shape)
        print("relu1 = ", relu1, relu1.shape)
        print("weights2 = ", self.weights[1], self.weights[1].shape)
        print("linear2 = ", linear2, linear2.shape)
    return linear2
# Backprop for entire batch
def backward(self, L, data, labels):
    if (data.shape[0] != labels.shape[0]):
        print("Data and labels shapes mismatch")
        return None
    self.allgrad_weight1 = []
    self.allgrad_weight2 = []
    self.allgrad_bias1 = []
    self.allgrad_bias2 = []
    for idx in range(data.shape[0]):
        x = data[idx, ::]
        x = x.reshape(self.in_units, 1)
```

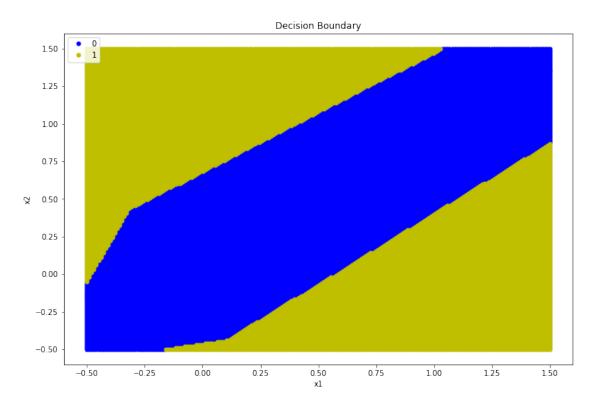
```
v = labels[idx]
        self._backward(L, x, y, idx)
    self.grad_weights = [np.mean(self.allgrad_weight1),
                         np.mean(self.allgrad weight2)]
    self.grad_bias = [np.mean(self.allgrad_bias1),
                      np.mean(self.allgrad bias2)]
# Backprop for a single data point
def _backward(self, L, x, y, idx):
    r = 1.0 - 2*y
    grad_bias2 = sigmoid(r * self.linear2[idx]) * r
    grad_weight2 = np.multiply(grad_bias2, self.relu1[idx])
    grad_relu1 = grad_bias2 * self.weights[1]
    grad_linear1 = grad_relu1.T
    grad_linear1[np.where(self.relu1[idx] <= 0)] *= self.eps</pre>
    grad_weight1 = np.dot(grad_linear1, x.T)
    grad_bias1 = grad_linear1
    self.allgrad_weight1.append(grad_weight1)
    self.allgrad weight2.append(grad weight2)
    self.allgrad_bias1.append(grad_bias1)
    self.allgrad_bias2.append(grad_bias2)
    if (self.debug and idx == 0):
        print("\n---- PRINT BACKWARD DATA ----\n")
        print("linear2 = ", self.linear2[idx])
        print("r:", r, "y:", y)
        print("weight2:", self.weights[1])
        print("grad_bias2:", grad_bias2)
        print("grad_weight2:", grad_weight2)
        print("weight1:", self.weights[0])
        print("grad_relu1:", grad_relu1)
        print("grad linear1:", grad linear1)
        print("grad_weight1:", grad_weight1)
        print("grad_bias1:", grad_bias1)
# Update mini batch weights
def update_weights(self, lr = None):
    if (lr):
        self.lr = lr
    self.weights[0] -= (self.lr * self.grad_weights[0])
    self.weights[1] -= (self.lr * self.grad_weights[1])
    self.bias[0] -= (self.lr * self.grad_bias[0])
    self.bias[1] -= (self.lr * self.grad_bias[1])
# Predict labels
```

```
def predict(self, data):
                  out = self.forward(data, save = False)
                  out[out >= 0] = 1
                  out[out < 0] = 0
                  return out
              # Compute accuracy
              def accuracy(self, data, labels):
                  predicted labels = self.predict(data).reshape(-1, 1)
                  matches = np.where(predicted_labels == labels)
                  return np.sum(labels == predicted_labels) / labels.shape[0] * 100.0
In [509]: # Split indexes for training and testing
          def split_data(data_X, data_y, test_split = 5):
              train_n = data_X.shape[0]
              test_n = batch_size * test_split
              train_n = train_n - test_n
              train_idx = np.arange(train_n)
              test_idx = np.arange(train_n, train_n + test_n)
              print("Split (train/test): (%d/%d)" %(train_n, test_n))
              data, labels = data_X[train_idx, ::], data_y[train_idx, ::]
              test_data, test_labels = data_X[test_idx, ::], data_y[test_idx, ::]
              return data, labels, test_data, test_labels
In [584]: # Train an epoch
          def train(net, epoch, data, labels, batch_size,
                    adaptive_lr = False, debug = False):
              train n = data.shape[0]
              train_idx = np.arange(train_n)
              np.random.shuffle(train_idx)
              train_loss = []
              train_acc = []
              for i in range(0, train_n, batch_size):
                  batch_idx = train_idx[i:i + batch_size]
                  batch_X = data[batch_idx, ::]
                  batch_y = labels[batch_idx, ::]
                  # Feedforward
                  a = net.forward(batch_X)
                  loss = softplus(batch_X, batch_y, a.reshape(batch_size, 1))
                  train_loss.append(loss)
                  acc = net.accuracy(batch_X, batch_y)
                  train_acc.append(acc)
                  net.backward(loss, batch_X, batch_y)
                  if adaptive_lr:
                      lr = 1/(1 + epoch) * 0.1
                  else:
```

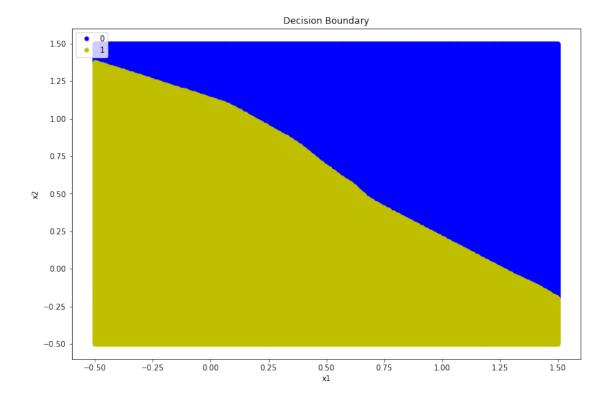
```
lr = None
                  net.update_weights(lr)
              if debug:
                  print("Epoch %d, Train loss: %.4f" %(epoch, np.mean(train_loss)))
                  print("Epoch %d, Train Accuracy: %.4f" %(epoch, np.mean(train_acc)))
In [590]: # Test validation data
          def test(net, test_data, test_labels, batch_size, debug = True):
              test n = test data.shape[0]
              test_idx = np.arange(test_n)
              test loss = []
              test_acc = []
              for i in range(0, test_n, batch_size):
                  batch_idx = test_idx[i:i + batch_size]
                  batch_X = test_data[batch_idx, :]
                  batch_y = test_labels[batch_idx, ::]
                  a = net.forward(batch_X)
                  loss = softplus(batch_X, batch_y, a.reshape(batch_size, 1))
                  test_loss.append(loss)
                  acc = net.accuracy(batch_X, batch_y)
                  test_acc.append(acc)
                  if debug:
                      print("Batch %d: %d/%d Accuracy: %f" %(i/batch_size, i, test_n, acc))
              if debug:
                  print("Test loss:", np.mean(test loss))
                  print("Accuracy:", np.mean(test_acc))
In [591]: # Define decision boundary
          def plot_boundary(X, y_prob):
              fig, ax = plt.subplots(figsize=(12,8))
              ax.margins(0.05) # Optional, just adds 5% padding to the autoscaling
                indices_0 = np.where(y_prob \le 0.5)
                indices_1 = np.where(y_prob > 0.5)
                print(y_prob.shape)
              indices_0 = [k for k in range(0, X.shape[0])
                           if y_prob[k, ::] <= 0.5]</pre>
              indices_1 = [k for k in range(0, X.shape[0])
                           if y_prob[k, ::] > 0.5]
              ax.plot(X[indices_0, 0], X[indices_0,1],
                      'b', marker='o', linestyle='', ms=5, label='0')
              ax.plot(X[indices_1, 0], X[indices_1,1],
                      'y', marker='o', linestyle='', ms=5, label='1')
```

```
ax.legend()
              ax.legend(loc=2)
              ax.set_xlabel('x1')
              ax.set_ylabel('x2')
              ax.set_title('Decision Boundary')
              plt.show()
In [592]: # Random initialization that works for network with 3 hidden units
          seed = int(np.random.rand(1) * 10000)
          seed = 6524
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch_size = 50
          num_epochs = 10
          hidden_units = 3
          # Initialize network
          net3 = Network(in_units = 2, hidden_units = hidden_units, lr = 0.1,
                        batch_size = batch_size, debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(X, y)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train(net3, epoch, data, labels, batch_size,
                    adaptive_lr = False, debug = False)
          test(net3, test_data, test_labels, batch_size, debug = True)
Random seed: 6524
Split (train/test): (4750/250)
Batch 0: 0/250 Accuracy: 94.000000
Batch 1: 50/250 Accuracy: 90.000000
Batch 2: 100/250 Accuracy: 92.000000
Batch 3: 150/250 Accuracy: 98.000000
Batch 4: 200/250 Accuracy: 94.000000
Test loss: 0.5732782175474475
Accuracy: 93.6
In [594]: n = 200
          idx = np.linspace(-0.5, 1.5, n)
          x1, x2 = np.meshgrid(idx, idx)
          new_X = np.zeros((n*n, 2))
          new_X[:, 0] = x1.flatten()
```

```
new_X[:, 1] = x2.flatten()
new_y = net3.predict(new_X)
plot_boundary(new_X, new_y)
```



```
data, labels, test_data, test_labels = split_data(X, y)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train(net16, epoch, data, labels, batch_size, debug = False)
          test(net16, test_data, test_labels, batch_size, debug = True)
Random seed: 6524
Split (train/test): (4750/250)
Batch 0: 0/250 Accuracy: 62.000000
Batch 1: 50/250 Accuracy: 48.000000
Batch 2: 100/250 Accuracy: 70.000000
Batch 3: 150/250 Accuracy: 70.000000
Batch 4: 200/250 Accuracy: 60.000000
Test loss: 0.6531193933053229
Accuracy: 62.0
In [598]: n = 500
          idx = np.linspace(-0.5, 1.5, n)
          x1, x2 = np.meshgrid(idx, idx)
          new_X = np.zeros((n*n, 2))
          new_X[:, 0] = x1.flatten()
          new_X[:, 1] = x2.flatten()
          new_y = net16.predict(new_X)
          new_labels = net16.predict(test_data)
          plot_boundary(new_X, new_y)
```



```
In [607]: # Random initialization that works for network with 3 hidden units
          seed = int(np.random.rand(1) * 10000)
          seed = 3997
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch_size = 50
          num_epochs = 4
          hidden_units = 512
          # Initialize network
          net512 = Network(hidden_units = hidden_units, lr = 0.10,
                        batch_size = batch_size, debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(X, y)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train(net512, epoch, data, labels, batch_size,
                    adaptive_lr = True, debug = True)
              test(net512, test_data, test_labels, batch_size, debug = True)
```

## test(net512, test\_data, test\_labels, batch\_size, debug = True)

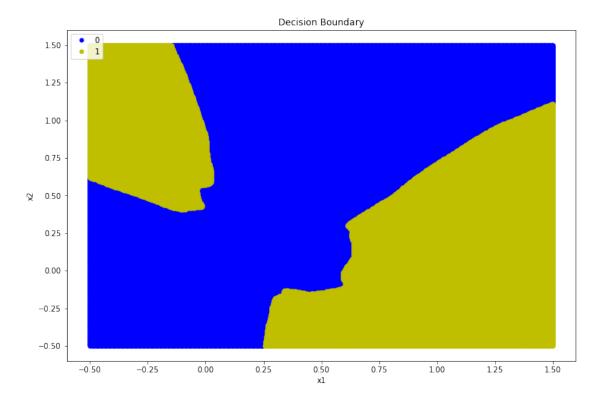
Random seed: 3997 Split (train/test): (4750/250) Epoch 0, Train loss: 7.4746 Epoch 0, Train Accuracy: 60.2947 Batch 0: 0/250 Accuracy: 66.000000 Batch 1: 50/250 Accuracy: 54.000000 Batch 2: 100/250 Accuracy: 56.000000 Batch 3: 150/250 Accuracy: 68.000000 Batch 4: 200/250 Accuracy: 60.000000 Test loss: 0.6487984018715431 Accuracy: 60.8 Epoch 1, Train loss: 0.6384 Epoch 1, Train Accuracy: 67.6421 Batch 0: 0/250 Accuracy: 82.000000 Batch 1: 50/250 Accuracy: 62.000000 Batch 2: 100/250 Accuracy: 68.000000 Batch 3: 150/250 Accuracy: 76.000000 Batch 4: 200/250 Accuracy: 74.000000 Test loss: 0.6372125502330925 Accuracy: 72.4 Epoch 2, Train loss: 0.6284 Epoch 2, Train Accuracy: 75.4526 Batch 0: 0/250 Accuracy: 82.000000 Batch 1: 50/250 Accuracy: 58.000000 Batch 2: 100/250 Accuracy: 62.000000 Batch 3: 150/250 Accuracy: 80.000000 Batch 4: 200/250 Accuracy: 72.000000 Test loss: 0.6405757812452638 Accuracy: 70.8 Epoch 3, Train loss: 0.6263 Epoch 3, Train Accuracy: 78.3158 Batch 0: 0/250 Accuracy: 86.000000 Batch 1: 50/250 Accuracy: 76.000000 Batch 2: 100/250 Accuracy: 82.000000 Batch 3: 150/250 Accuracy: 84.000000 Batch 4: 200/250 Accuracy: 80.000000 Test loss: 0.6305097199985602 Accuracy: 81.6 Batch 0: 0/250 Accuracy: 86.000000 Batch 1: 50/250 Accuracy: 76.000000 Batch 2: 100/250 Accuracy: 82.000000 Batch 3: 150/250 Accuracy: 84.000000 Batch 4: 200/250 Accuracy: 80.000000 Test loss: 0.6305097199985602

Accuracy: 81.6

```
In [608]: n = 500
    idx = np.linspace(-0.5, 1.5, n)
    x1, x2 = np.meshgrid(idx, idx)
    new_X = np.zeros((n*n, 2))
    new_X[:, 0] = x1.flatten()
    new_X[:, 1] = x2.flatten()

    new_y = net512.predict(new_X)

    plot_boundary(new_X, new_y)
```



```
self.lr = lr
    self.debug = debug
    # Initialize network parameters
    w1 = np.random.rand(hidden_units, self.in_units) - 0.5
    w2 = np.random.rand(self.out_units, hidden_units) - 0.5
    b1 = np.zeros((hidden units, 1))
    b2 = np.zeros((self.out_units, 1))
    self.weights = [w1, w2]
    self.bias = [b1, b2]
    # Initialize batchwise layer outputs as empty
    self.linear1 = []
    self.relu1 = []
    self.eps = 0.00
    self.linear2 = []
    # Initialize batchwise gradients as empty
    self.allgrad_weight1 = []
    self.allgrad_weight2 = []
    self.allgrad bias1 = []
    self.allgrad_bias2 = []
# Feedforward for entire batch
def forward(self, data, save = True):
    self.linear1 = []
    self.relu1 = []
    self.linear2 = []
    for idx in range(data.shape[0]):
        x = data[idx, ::]
        x = x.reshape(self.in_units, 1)
        self._forward(x, idx, save)
    return np.array(self.linear2)
# Feedforward for a single data point
def _forward(self, x, idx, save = True):
    linear1 = np.dot(self.weights[0], x) + self.bias[0]
    relu1 = leaky_relu(linear1, self.eps)
    linear2 = np.dot(self.weights[1], relu1) + self.bias[1]
    self.linear2.append(linear2)
    self.linear1.append(linear1)
    self.relu1.append(relu1)
    if self.debug and idx == 0:
        print("\n---- PRINT FORWARD DATA ----\n")
```

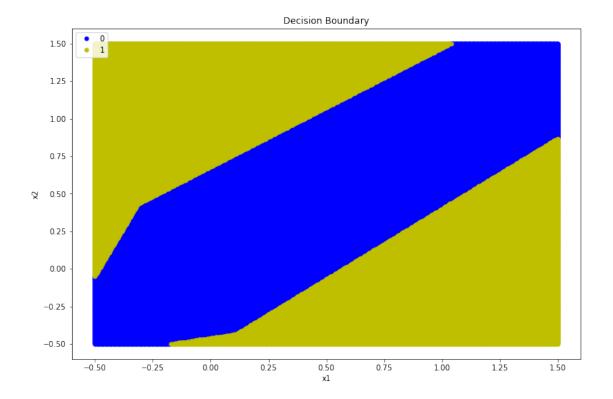
```
print("x = ", x, x.shape)
        print("weights1 = ", self.weights[0], self.weights[0].shape)
        print("linear1 = ", linear1, linear1.shape)
        print("relu1 = ", relu1, relu1.shape)
        print("weights2 = ", self.weights[1], self.weights[1].shape)
        print("linear2 = ", linear2, linear2.shape)
    return linear2
# Backprop for entire batch
def backward(self, L, data, labels):
    if (data.shape[0] != labels.shape[0]):
        print("Data and labels shapes mismatch")
        return None
    self.allgrad_weight1 = []
    self.allgrad_weight2 = []
    self.allgrad_bias1 = []
    self.allgrad_bias2 = []
    for idx in range(data.shape[0]):
        x = data[idx, ::]
        x = x.reshape(self.in units, 1)
        y = labels[idx]
        self._backward(L, x, y, idx)
    self.grad_weights = [np.mean(self.allgrad_weight1),
                         np.mean(self.allgrad_weight2)]
    self.grad_bias = [np.mean(self.allgrad_bias1),
                      np.mean(self.allgrad_bias2)]
# Backprop for a single data point
def _backward(self, L, x, y, idx):
    eps = 0.01
    grad_bias2 = sigmoid(self.linear2[idx]) - y
      qrad\ bias2 = 2*(y - self.linear2[idx])
    grad_weight2 = np.multiply(grad_bias2, self.relu1[idx])
    grad_relu1 = grad_bias2 * self.weights[1]
    grad_linear1 = grad_relu1.T
    grad_linear1[np.where(self.relu1[idx] <= 0)] *= self.eps</pre>
    grad_weight1 = np.dot(grad_linear1, x.T)
    grad_bias1 = grad_linear1
    self.allgrad_weight1.append(grad_weight1)
    self.allgrad_weight2.append(grad_weight2)
    self.allgrad_bias1.append(grad_bias1)
    self.allgrad_bias2.append(grad_bias2)
    if (self.debug and idx == 0):
```

```
print("linear2 = ", self.linear2[idx])
                      print("r:", r, "y:", y)
                      print("weight2:", self.weights[1])
                      print("grad bias2:", grad bias2)
                      print("grad_weight2:", grad_weight2)
                      print("weight1:", self.weights[0])
                      print("grad_relu1:", grad_relu1)
                      print("grad_linear1:", grad_linear1)
                      print("grad_weight1:", grad_weight1)
                      print("grad_bias1:", grad_bias1)
              # Update mini batch weights
              def update_weights(self, lr = None):
                  if lr is not None:
                      self.lr = lr
                  self.weights[0] -= (self.lr * self.grad_weights[0])
                  self.weights[1] -= (self.lr * self.grad_weights[1])
                  self.bias[0] -= (self.lr * self.grad_bias[0])
                  self.bias[1] -= (self.lr * self.grad_bias[1])
              # Predict labels
              def predict(self, data):
                  out = self.forward(data, save = False)
                  out[out >= 0] = 1
                  out[out < 0] = 0
                  return out
              # Compute accuracy
              def accuracy(self, data, labels):
                  predicted_labels = self.predict(data).reshape(-1, 1)
                  matches = np.where(predicted_labels == labels)
                  return np.sum(labels == predicted_labels) / labels.shape[0] * 100.0
In [610]: def categorical_cross_entropy(data, labels, out):
              n = data.shape[0]
              eps = 0.01
              L = - np.multiply(labels, np.log(sigmoid(out)))
              L = L - np.multiply(1.0 - labels, np.log(1.0 - sigmoid(out)))
              L = np.sum(L)/n
              return L
In [614]: # Train an epoch
          def train_cce(net, epoch, data, labels, batch_size,
                        adaptive_lr = False, debug = False):
              train_n = data.shape[0]
              train_idx = np.arange(train_n)
              np.random.shuffle(train_idx)
```

print("\n---- PRINT BACKWARD DATA ----\n")

```
train_loss = []
              train_acc = []
              for i in range(0, train_n, batch_size):
                  batch_idx = train_idx[i:i + batch_size]
                  batch_X = data[batch_idx, ::]
                  batch_y = labels[batch_idx, ::]
                  # Feedforward
                  a = net.forward(batch_X)
                  loss = categorical_cross_entropy(batch_X, batch_y, a.reshape(batch_size, 1))
                    loss = quadratic(batch_X, batch_y, a.reshape(batch_size, 1))
                  train_loss.append(loss)
                  acc = net.accuracy(batch_X, batch_y)
                  train_acc.append(acc)
                  net.backward(loss, batch_X, batch_y)
                  if adaptive_lr:
                      lr = np.exp(-epoch * 0.1)
                  else:
                      lr = None
                  net.update_weights(lr)
              if debug:
                  print("Epoch %d, Train loss: %.4f" %(epoch, np.mean(train_loss)))
                  print("Epoch %d, Train Accuracy: %.4f" %(epoch, np.mean(train_acc)))
In [613]: # Test validation data
          def test_cce(net, test_data, test_labels, batch_size, debug = True):
              test_n = test_data.shape[0]
              test_idx = np.arange(test_n)
              test_loss = []
              test_acc = []
              for i in range(0, test_n, batch_size):
                  batch_idx = test_idx[i:i + batch_size]
                  batch_X = test_data[batch_idx, :]
                  batch_y = test_labels[batch_idx, ::]
                  a = net.forward(batch_X)
                  loss = categorical_cross_entropy(batch_X, batch_y, a.reshape(batch_size, 1))
                  test_loss.append(loss)
                  acc = net.accuracy(batch_X, batch_y)
                  test_acc.append(acc)
                  if debug:
                      print("Batch %d: %d/%d Accuracy: %f" %(i/batch_size, i, test_n, acc))
              if debug:
                  print("Test loss:", np.mean(test_loss))
                  print("Accuracy:", np.mean(test_acc))
In [615]: # Random initialization that works for network with 3 hidden units
```

```
seed = int(np.random.rand(1) * 10000)
          seed = 6524
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch size = 50
          num_epochs = 10
          hidden_units = 3
          # Initialize network
          net3_cce = Network_cce(hidden_units = hidden_units, lr = 0.1,
                                 out_units = 1, batch_size = batch_size,
                                 debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(X, y)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train_cce(net3_cce, epoch, data, labels, batch_size, debug = False)
          test_cce(net3_cce, test_data, test_labels, batch_size, debug = True)
Random seed: 6524
Split (train/test): (4750/250)
Batch 0: 0/250 Accuracy: 94.000000
Batch 1: 50/250 Accuracy: 90.000000
Batch 2: 100/250 Accuracy: 94.000000
Batch 3: 150/250 Accuracy: 98.000000
Batch 4: 200/250 Accuracy: 94.000000
Test loss: 0.5813633907518609
Accuracy: 94.0
In [616]: n = 500
          idx = np.linspace(-0.5, 1.5, n)
          x1, x2 = np.meshgrid(idx, idx)
          new_X = np.zeros((n*n, 2))
          new_X[:, 0] = x1.flatten()
          new_X[:, 1] = x2.flatten()
          new_y = net3_cce.predict(new_X)
          plot_boundary(new_X, new_y)
```



```
In [617]: # Random initialization that works for network with 3 hidden units
          seed = int(np.random.rand(1) * 10000)
          # seed = 6524
          # seed = 5792
          # seed = 6257
          # seed = 2013
          # seed = 9928
          seed = 3581
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch_size = 100
          num_epochs = 10
          hidden_units = 16
          # Initialize network
          net16_cce = Network_cce(hidden_units = hidden_units, lr = 0.2,
                        out_units = 1, batch_size = batch_size, debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(X, y)
```

Split (train/test): (4500/500)

Batch 0: 0/500 Accuracy: 87.000000

Batch 1: 100/500 Accuracy: 93.000000

Batch 2: 200/500 Accuracy: 89.000000

Batch 3: 300/500 Accuracy: 84.000000

Batch 4: 400/500 Accuracy: 90.000000

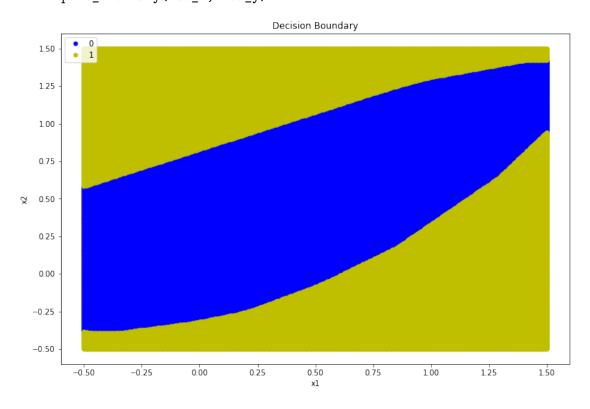
Test loss: 0.5537342012391172

Accuracy: 88.6

In [618]: n = 500
 idx = np.linspace(-0.5, 1.5, n)
 x1, x2 = np.meshgrid(idx, idx)
 new\_X = np.zeros((n\*n, 2))
 new\_X[:, 0] = x1.flatten()
 new\_X[:, 1] = x2.flatten()

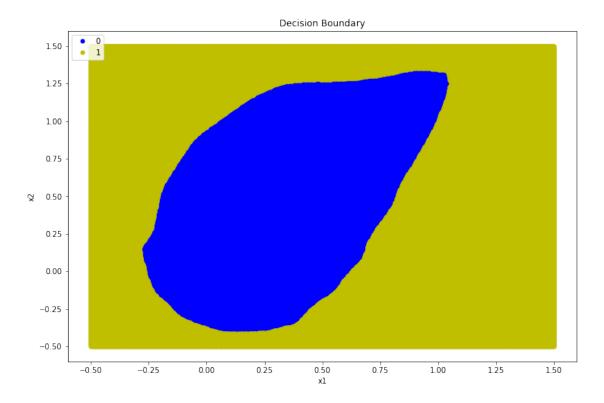
 new\_y = net16\_cce.predict(new\_X)

plot\_boundary(new\_X, new\_y)



```
In [625]: # Random initialization that works for network with 3 hidden units
          seed = int(np.random.rand(1) * 10000)
          # seed = 8128
          # seed = 7900
          # seed = 2247
          # seed = 9928
          # seed = 3581
          # seed = 1386
          seed = 6118
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch_size = 50
          num_epochs = 10
          hidden_units = 512
          # Initialize network
          net512_cce = Network_cce(hidden_units = hidden_units, lr = 0.1,
                        out_units = 1, batch_size = batch_size, debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(X, y)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train(net512_cce, epoch, data, labels, batch_size,
                    adaptive_lr = True, debug = False)
                test (net512 cce, test_data, test_labels, batch_size, debug = True)
          test(net512_cce, test_data, test_labels, batch_size, debug = True)
Random seed: 6118
Split (train/test): (4750/250)
Batch 0: 0/250 Accuracy: 74.000000
Batch 1: 50/250 Accuracy: 62.000000
Batch 2: 100/250 Accuracy: 70.000000
Batch 3: 150/250 Accuracy: 78.000000
Batch 4: 200/250 Accuracy: 74.000000
Test loss: 0.5836245096929604
Accuracy: 71.6
In [627]: n = 500
          idx = np.linspace(-0.5, 1.5, n)
```

```
x1, x2 = np.meshgrid(idx, idx)
new_X = np.zeros((n*n, 2))
new_X[:, 0] = x1.flatten()
new_X[:, 1] = x2.flatten()
new_y = net512_cce.predict(new_X)
plot_boundary(new_X, new_y)
```



```
data.iloc[i,3] = xor
          data.head()
          # set X (training data) and y (target variable)
          cols = data.shape[1]
          Xf = data.iloc[:, 0:cols - 1]
          yf = data.iloc[:, cols - 1:cols]
          # The cost function is expecting numpy matrices so we need to convert X and y before
          Xf = np.matrix(Xf.values)
          yf = np.matrix(yf.values)
In [632]: # Random initialization that works for network with 3 hidden units
          seed = int(np.random.rand(1) * 1000)
          # seed = 6524
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch size = 20
          num_epochs = 10
          hidden_units = 3
          # Initialize network
          net3_f = Network(in_units = Xf.shape[1], hidden_units = hidden_units,
                               out_units = yf.shape[1], lr = 0.1,
                               batch_size = batch_size, debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(Xf, yf, test_split = 20)
          print(data.shape, test_data.shape)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train(net3_f, epoch, data, labels, batch_size,
                    adaptive_lr = False, debug = False)
          test(net3_f, test_data, test_labels, batch_size, debug = True)
Random seed: 306
Split (train/test): (5600/400)
(5600, 3) (400, 3)
Batch 0: 0/400 Accuracy: 45.000000
Batch 1: 20/400 Accuracy: 55.000000
Batch 2: 40/400 Accuracy: 45.000000
Batch 3: 60/400 Accuracy: 35.000000
Batch 4: 80/400 Accuracy: 50.000000
```

```
Batch 5: 100/400 Accuracy: 45.000000
Batch 6: 120/400 Accuracy: 40.000000
Batch 7: 140/400 Accuracy: 60.000000
Batch 8: 160/400 Accuracy: 45.000000
Batch 9: 180/400 Accuracy: 40.000000
Batch 10: 200/400 Accuracy: 35.000000
Batch 11: 220/400 Accuracy: 55.000000
Batch 12: 240/400 Accuracy: 70.000000
Batch 13: 260/400 Accuracy: 45.000000
Batch 14: 280/400 Accuracy: 50.000000
Batch 15: 300/400 Accuracy: 60.000000
Batch 16: 320/400 Accuracy: 45.000000
Batch 17: 340/400 Accuracy: 55.000000
Batch 18: 360/400 Accuracy: 15.000000
Batch 19: 380/400 Accuracy: 50.000000
Test loss: 0.6982227977229182
Accuracy: 47.0
In [630]: # Random initialization that works for network with 3 hidden units
          seed = int(np.random.rand(1) * 1000)
          # seed = 6524
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch_size = 50
          num_epochs = 10
          hidden_units = 16
          # Initialize network
          net16_f = Network(in_units = Xf.shape[1], hidden_units = hidden_units,
                               out_units = yf.shape[1], lr = 0.5,
                               batch_size = batch_size, debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(Xf, yf, test_split = 20)
          print(data.shape, test_data.shape)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train(net16_f, epoch, data, labels, batch_size,
                    adaptive_lr = True, debug = False)
                test(net16_f, test_data, test_labels, batch_size, debug = True)
          test(net16_f, test_data, test_labels, batch_size, debug = True)
Random seed: 42
Split (train/test): (5000/1000)
```

```
(5000, 3) (1000, 3)
Batch 0: 0/1000 Accuracy: 54.000000
Batch 1: 50/1000 Accuracy: 54.000000
Batch 2: 100/1000 Accuracy: 52.000000
Batch 3: 150/1000 Accuracy: 56.000000
Batch 4: 200/1000 Accuracy: 58.000000
Batch 5: 250/1000 Accuracy: 58.000000
Batch 6: 300/1000 Accuracy: 48.000000
Batch 7: 350/1000 Accuracy: 58.000000
Batch 8: 400/1000 Accuracy: 48.000000
Batch 9: 450/1000 Accuracy: 40.000000
Batch 10: 500/1000 Accuracy: 58.000000
Batch 11: 550/1000 Accuracy: 40.000000
Batch 12: 600/1000 Accuracy: 44.000000
Batch 13: 650/1000 Accuracy: 50.000000
Batch 14: 700/1000 Accuracy: 42.000000
Batch 15: 750/1000 Accuracy: 46.000000
Batch 16: 800/1000 Accuracy: 56.000000
Batch 17: 850/1000 Accuracy: 54.000000
Batch 18: 900/1000 Accuracy: 52.000000
Batch 19: 950/1000 Accuracy: 54.000000
Test loss: 0.7010135698934545
Accuracy: 51.1
In [631]: # Random initialization that works for network with 3 hidden units
          seed = int(np.random.rand(1) * 10000)
          # seed = 6524
          print("Random seed:", seed)
          np.random.seed(seed)
          # Network parameters
          batch_size = 50
          num_epochs = 10
          hidden_units = 512
          # Initialize network
          net512_f = Network(in_units = Xf.shape[1], hidden_units = hidden_units,
                               out_units = yf.shape[1], lr = 0.1,
                               batch_size = batch_size, debug = False)
          # Split Data into training and test sets
          data, labels, test_data, test_labels = split_data(Xf, yf, test_split = 20)
          print(data.shape, test_data.shape)
          # Train the network for 'num_epochs'
          for epoch in range(num_epochs):
              train(net512_f, epoch, data, labels, batch_size,
```

```
adaptive_lr = False, debug = False)
                print(net512_f.weights)
                test(net512_f, test_data, test_labels, batch_size, debug = True)
          test(net512 f, test data, test labels, batch size, debug = True)
Random seed: 5298
Split (train/test): (5000/1000)
(5000, 3) (1000, 3)
Batch 0: 0/1000 Accuracy: 56.000000
Batch 1: 50/1000 Accuracy: 54.000000
Batch 2: 100/1000 Accuracy: 58.000000
Batch 3: 150/1000 Accuracy: 44.000000
Batch 4: 200/1000 Accuracy: 38.000000
Batch 5: 250/1000 Accuracy: 36.000000
Batch 6: 300/1000 Accuracy: 52.000000
Batch 7: 350/1000 Accuracy: 48.000000
Batch 8: 400/1000 Accuracy: 46.000000
Batch 9: 450/1000 Accuracy: 50.000000
Batch 10: 500/1000 Accuracy: 56.000000
Batch 11: 550/1000 Accuracy: 64.000000
Batch 12: 600/1000 Accuracy: 50.000000
Batch 13: 650/1000 Accuracy: 54.000000
Batch 14: 700/1000 Accuracy: 52.000000
Batch 15: 750/1000 Accuracy: 50.000000
Batch 16: 800/1000 Accuracy: 54.000000
Batch 17: 850/1000 Accuracy: 52.000000
Batch 18: 900/1000 Accuracy: 46.000000
Batch 19: 950/1000 Accuracy: 56.000000
Test loss: 0.7332692589848414
Accuracy: 50.8
```