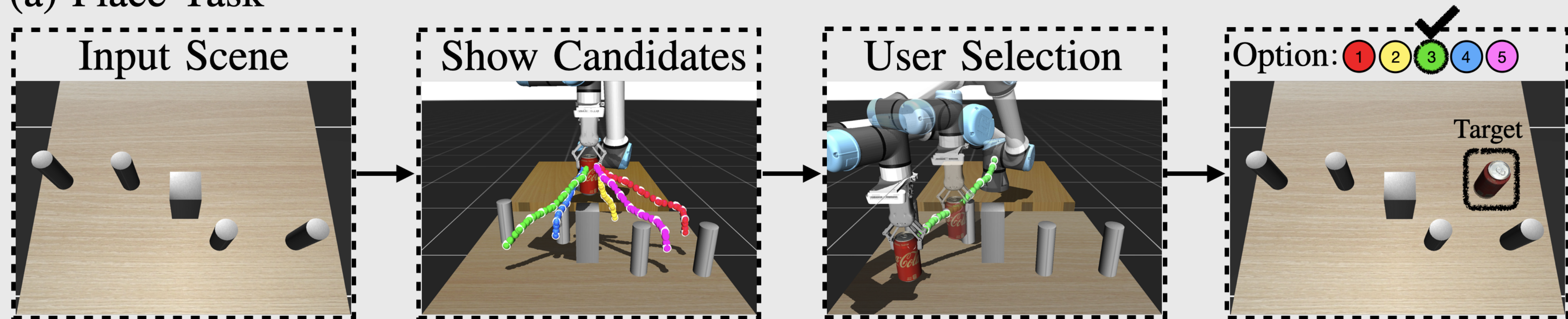


QD-based Semi-Autonomous Teleoperation

(a) Place Task



(b) Sweep Task

