# A literature review on regression with shuffled data

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### Regression with shuffled data

Consider a linear regression problem. Given a set of predictors  $\{X_1, \ldots, X_n\}$  and responses  $\{Y_1, \ldots, Y_n\}$ , we implicitly assume that  $Y_i$  is related to  $X_i$  of the same index through a model

$$Y_i = X_i^T \beta + \epsilon_i.$$

However, suppose the set of predictor is now shuffled and  $Y_i$  is related to  $X_{\pi(i)}$  for some unknown permutation  $\pi$  as

$$Y_i = X_{\pi(i)}^T \beta + \epsilon_i.$$

$Y_1$	$X_1$
$Y_2$	$X_4$
$Y_3$	$X_3$
$Y_4$	$X_2$
$Y_5$	$X_5$

Table: Mismatch example

### Regression with shuffled data

The model can also be expressed using a permutation matrix  $\Pi$ :

$$Y = \Pi X \beta + \epsilon$$
.

Is it possible to i) recover the original ordering of predictors and ii) estimate the regression coefficient  $\beta$  as well? The problem has other names as well:

- regression under mismatch,
- $\triangleright$  permutation recovery (emphasis on recovering  $\Pi$ ),
- $\triangleright$  unlabeled sensing (emphasis on recovering  $\beta$ ),

### But why?

If we ignore the permutation, the least squares estimate is biased:

$$\mathbf{E}\hat{\beta} = \mathbf{E} \left\{ (\Pi X)^T (\Pi X) \right\}^{-1} (\Pi X)^T Y$$
$$= \mathbf{E} (X^T X)^{-1} X^T \Pi Y = (X^T X)^{-1} (X^T \Pi X) \beta.$$

Consider  $Y_i = X_i \beta + \epsilon_i$  with  $\beta = 1, n = 10^4$ , and  $X_i, \epsilon_i \sim N(0, 1)$  i.i.d.

Permutation	$\hat{eta}$
0%	1.0001
1%	0.9901
10%	0.9000
20%	0.8000
50%	0.4997

Table: Estimated coefficient ignoring mismatch from 1000 simulations

### But why? Applications

#### Header-less communication:

- ▶ In large sensor networks, the size of data a sensor records and sends to a main server is sometimes exceeded by or comparable to the size of the sensor ID information.
- ▶ If measurements are linear, transmit data without sensor ID.



### But why? Applications

- ► Post-linkage data analysis:
  - ▶ It is cost-effective to combine data from various sources rather than collection a new data containing all variables of interest.
  - ▶ Due to data quality, the links between the data can be error-prone and modeling mismatch using permutation can help.



### But why? Applications

▶ Unsupervised alignment: Align two sets of text embedding for natural language processing.

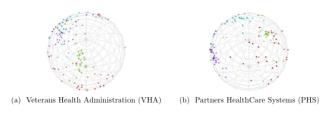


Figure: Examples of word embeddings on a sphere

### Regression with shuffled data

- ▶ At a higher level, there are two different directions of research:
  - ▶ Permutation is random.
  - ▶ Permutation is deterministic.
- ▶ When permutation is assumed to be random, there is a line of research which has the name *record linkage* problem.
- ▶ In this presentation, we will focus more on the recent results in the deterministic case.

#### Deterministic case

One of the first results in the deterministic case was presented by Pananjady et al. (2018) providing sufficient and necessary conditions for a successful recovery. For model

$$Y = \Pi^* X \beta^* + \epsilon,$$

with

- Response:  $Y \in \mathbb{R}^n$ ,
- ▶ Predictor:  $X \in \mathbb{R}^{n \times p}$  s.t.  $X_{ij} \sim N(0,1)$  i.i.d.
- ▶ Random noise:  $\epsilon \in \mathbb{R}^n$  s.t.  $\epsilon_i \sim N(0, \sigma^2)$  i.i.d.

define the maximum likelihood estimator:

$$(\hat{\Pi}, \hat{\beta}) = \underset{\Pi, \beta}{\operatorname{argmin}} \|Y - \Pi X \beta\|_2^2.$$



# Pananjady et al. (2018)

### Theorem 1 (Sufficient condition for successful recovery)

Define signal-to-noise ratio  $SNR = \frac{\|\beta^*\|_2^2}{\sigma^2}$ . For any p < n and  $\xi < \sqrt{n}$ , if

$$\log(SNR) \ge \left(c_1 \frac{n}{n-p} + \xi\right) \log n,$$

then  $\mathbf{P}(\hat{\Pi} \neq \Pi^*) \leq c_2 n^{-2\xi}$  where  $c_1, c_2$  are absolute constants.

### Theorem 2 (Necessary condition for successful recovery)

For any  $\delta \in (0,2)$ , if

$$2 + \log(1 + SNR) \le (2 - \delta) \log n,$$

then  $\mathbf{P}(\tilde{\Pi} \neq \Pi^*) \geq 1 - c_3 e^{-c_4 n \delta}$  for any estimator  $\tilde{\Pi}$  where  $c_3, c_4$  are absolute constants.

# Pananjady et al. (2018)

- ➤ Sufficient and necessary conditions of successful recovery is characterized by a threshold on the signal-to-noise ratio.
- ► A few downsides:
  - ► (Computation) Solving

$$(\hat{\Pi}, \hat{\beta}) = \underset{\Pi, \beta}{\operatorname{argmin}} \|Y - \Pi X \beta\|_2^2$$

is generally intractable for  $\dim(\beta) > 1$  (quadratic assignment problem).

- Sufficient condition requires SNR =  $\frac{\|\beta^*\|_2^2}{\sigma^2}$  to be stronger than  $n^c$  ( $\approx n^5$ ). Stronger SNR is needed as we acquire more data.
- ▶ Why? The search space is growing exponentially. (n! permutations)

#### More realistic cases

Do we always need to search the entire set of permutations?

- ► Mismatch may occur only rarely (sparsity).
- ▶ Permutations may only occur within groups (hierarchy in the observations).

If mismatch only occurs rarely (sparse), then there are other methods available as well. Nguyen and Tran (2012) provides a method to consistently estimate the regression parameters under a regression model with grossly corrupted observations (errors-in-variables model):

$$Y = X\beta^* + \sqrt{n}e^* + \epsilon$$

#### where

- ightharpoonup Response:  $Y \in \mathbb{R}^n$ ,
- ▶ Design matrix:  $X \in \mathbb{R}^{n \times p}$ ,
- Gross-error:  $e \in \mathbb{R}^n$  (fixed),
- Random noise:  $\epsilon \sim N(0, \sigma^2 I)$ .

$$Y = X\beta^* + \sqrt{n}e^* + \epsilon$$

▶ Looking at the model more closely, we have

1. 
$$\pi(i) = i, Y_i = x_i^T \beta^* + \sqrt{n} e_i^* + \epsilon_i = x_i^T \beta^* + 0 + \epsilon_i,$$

2. 
$$\pi(i) \neq i, Y_i = x_i^T \beta^* + \sqrt{n} e_i^* + \epsilon_i = x_i^T \beta^* + (x_{\pi(i)} - x_i)^T \beta^* + \epsilon_i,$$

or, 
$$e_i \neq 0 \iff \pi(i) \neq i$$
.

▶ Furthermore, assume that  $\beta^*$  and  $e^*$  are sparse:

$$\|\beta^*\|_0 = \sum_i I(\beta_i \neq 0) = k,$$

$$\|e^*\|_0 = s.$$

Let  $(\hat{\beta}, \hat{e})$  be the solution to

$$\min_{\beta,e} \frac{1}{2n} \|Y - X\beta - \sqrt{n}e\|_2^2 + \lambda_{n,\beta} \|\beta\|_1 + \lambda_{n,e} \|e\|_1.$$

#### Theorem 3

Under some regularity conditions,

$$\|\hat{\beta} - \beta^*\|_2 + \|\hat{e} - e^*\|_2 \le C\left(\frac{1}{\mu}\sqrt{\frac{\sigma^2 k \log p}{n}} + \sqrt{\frac{\sigma^2 s \log n}{n}}\right)$$

 $with \ high \ \underline{probability} \ if \ regulariza\underline{tion} \ \underline{parameters} \ are \ chosen \ as$ 

$$\lambda_{n,\beta} = \frac{4}{\mu} \sqrt{\frac{\sigma^2 \log p}{n}} \text{ and } \lambda_{n,e} = 4\sqrt{\frac{\sigma^2 \log n}{n}} \text{ for some } \mu \in \left[\frac{1}{\sqrt{\log n}}, 1\right].$$

$$\|\hat{\beta} - \beta^*\|_2 + \|\hat{e} - e^*\|_2 \le C\left(\frac{1}{\mu}\sqrt{\frac{\sigma^2 k \log p}{n}} + \sqrt{\frac{\sigma^2 s \log n}{n}}\right)$$

Therefore, if

- ▶ the number of mismatch  $s = o\left(\frac{n}{\log n}\right)$ ,
- or the ratio of mismatch  $\frac{s}{n} = o\left(\frac{1}{\log n}\right)$ ,

then we can consistently estimate  $\beta^*$  and also the indexes of observations where  $\pi(i) \neq i$  in regression with suffled data.

### Multivariate case

Going back to the specific case of shuffled data, Zhang et al. (2021) expands the results of Pananjady et al. (2018) to multivariate linear regression

$$Y = \Pi^* X B^* + E$$

or

$$Y_j = \Pi^* X \beta_j^* + \epsilon_j \text{ for } j = 1, \dots, m$$

where

- ▶ Response:  $Y = [Y_1, ..., Y_m] \in \mathbb{R}^{n \times m}$ ,
- ▶ Predictor:  $X \in \mathbb{R}^{n \times p}$ ,  $X_{ij} \sim N(0,1)$  i.i.d.,
- ▶ Regression coefficient:  $B^* = [\beta_1^*, \dots, \beta_m^*] \in \mathbb{R}^{p \times m}$ ,
- ▶ Random noise:  $E = [\epsilon_1, \dots, \epsilon_m] \in \mathbb{R}^{n \times m}, E_{ij} \sim N(0, 1)$  i.i.d.

Again, define the maximum likelihood estimator

$$(\hat{\Pi}, \hat{B}) = \underset{\Pi, B}{\operatorname{argmin}} \|Y - \Pi XB\|_2^2.$$

#### Theorem 4 (Inachievability results)

Let  $\mathcal{H}$  be any subset of  $\mathcal{P}_n$ , the set of all  $n \times n$  permutation matrices. Assuming  $B^*$  is known, we have

$$\inf_{\tilde{\Pi}} \sup_{\Pi^* \in \mathcal{H}} \mathbf{P}(\tilde{\Pi} \neq \Pi^*) \geq \frac{1}{2} \quad \textit{if} \quad \log \det \left(I + \frac{B^{*T}B^*}{\sigma^2}\right) < \frac{\log(|\mathcal{H}|) - 2}{n}$$

where the expectation is taken w.r.t X and E, and the infimum is over all estimators  $\tilde{\Pi}$ .

The necessary condition for sufficient recovery

$$\log \det \left(I + \frac{B^{*T}B^*}{\sigma^2}\right) \geq \frac{\log(|\mathcal{H}|) - 2}{n}$$

▶ If m = 1,  $\mathcal{H} = \mathcal{P}_n$ ,  $|\mathcal{H}| = n!$  and  $\frac{\log(|\mathcal{H}| - 2)}{n} \approx \frac{n \log n}{n} = \log n$  holds showing us a similar bound found in Pananjady et al. (2018)

$$2 + \log\left(1 + \frac{\|\beta^*\|_2^2}{\sigma^2}\right) \le (2 - \delta)\log n$$

▶ If our search space is smaller than the entire set of permutation matrices (e.g.  $|\mathcal{H}|$  is a fixed nonnegative integer), the necessary condition becomes less restrictive.

▶ Let  $\lambda_i$ 's be the singular values of  $B^*$ . Then

$$\log \det \left(I + \frac{B^{*T}B^*}{\sigma^2}\right) = \sum_i \log \left(1 + \frac{\lambda_i^2}{\sigma^2}\right)$$

Suppose the signal energy  $||B^*||_F^2 = \sum_i \lambda_i^2$  is fixed. In order to maximize  $\log \det \left(I + \frac{B^{*T}B^*}{\sigma^2}\right)$ , it is favorable to have  $\lambda_i$ 's with more or less similar magnitude.

This leads to the notion of *stable rank*:

$$\rho(B^*) := \frac{\|B^*\|_F^2}{\|B^*\|_2^2} = \frac{\sum_i \lambda_i^2}{\max_i \lambda_i^2} \quad \text{for} \quad B^* \neq 0.$$

▶ (Worst case)  $B^*$  is rank 1:

$$\rho(B^*) = \frac{\sum_i \lambda_i^2}{\max_i \lambda_i^2} = \frac{\lambda_1^2}{\lambda_1^2} = 1.$$

▶ (Best case)  $B^*$  is full rank (rank m) with constant singular values:

$$\rho(B^*) = \frac{\sum_i \lambda_i^2}{\max_i \lambda_i^2} = \frac{\sum_{i=1}^m \lambda^2}{\lambda^2} = m.$$

### Theorem 5 (Achievability results)

Define Hamming distance  $d_H(\Pi_1, \Pi_2) = \sum_{i=1}^n I(\pi_1(i) \neq \pi_2(i))$ . Suppose

- 1.  $d_H(I, \Pi^*) \le h_{max} \text{ with } h_{max} \times rank(B^*) \le \frac{n}{8}$ ,
- 2.  $SNR = \frac{\|B^*\|_F^2}{m\sigma^2} > c_0,$
- 3.  $\rho(B^*) \ge c_1 \log n,$
- 4.  $\log(SNR) \ge \frac{c_2 \log n}{\rho(B^*)} + c_3$ ,

then ML estimator  $\hat{\Pi}$  equals  $\Pi^*$  with probability going to 1, where  $c_0, \ldots, c_3$  are some positive constants.

- ► If
  - $\rho(B^*) = \operatorname{rank}(B^*) \ge O(\log n),$
  - ▶ the number of maximum mismatch  $h_{\max} = O\left(\frac{n}{\log n}\right)$ ,

then ML estimator consistently estimates  $\Pi^*$  without having a stringent condition on the order of signal-to-noise ratio.

- ▶ This result is better than Nguyen and Tran (2012) as they require the number of mismatch to be  $o\left(\frac{n}{\log n}\right)$ .
- ▶ The authors hypothesize that they can further remove the constraint on  $h_{\text{max}}$  using more advanced proof techniques.

### Testing for the presence of mismatch

While there are numerous results on the estimation problem, there are not as many results on the inference part. Slawski et al. (2019) suggests a method to test the presence of mismatch in the linear regression model.

- 1. define  $P_X$  be the orthogonal projection onto range(X),
- 2. do SVD on  $P_X^{\perp} = I P_X := UU^T$ .

Under the assumption of a linear model with i.i.d. normal error,

$$\xi := U^T Y = U^T (\Pi^* X \beta^* + \epsilon) \stackrel{H_0}{=} U^T I X \beta + U^T \epsilon \stackrel{d}{=} \epsilon \sim N(0, \sigma^2 I)$$

Test whether the elements of  $\xi$  follow i.i.d. normal by applying Kolmogorov-Smirnov test or Cramer-von-Mises test.

#### Pseudo-likelihood based inference

Slawski et al. (2019) also derives an asymptotic distribution under a restricted model setting:

- 1. True permutation in the data is chosen uniformly from  $\mathcal{P}_n(k) = \{\pi \in \mathcal{P}_n : \sum_{i=1}^n I(\pi(i) \neq i) = k\}$ , the set of permutations with only k mismatch.
- 2. Conditional on  $\pi^*$ , the pairs  $\{x_{\pi^*(i),y_i}\}_{i=1}^n$  are i.i.d. zero-mean random variables drawn from a joint density  $f_{x,y}(x,y)$  s.t.

$$f_{x,y}(x,y) = f_{y|x}(y|x) \times f_x(x)$$
$$f_{y|x} \sim N(x^T \beta^*, \sigma_*^2)$$
$$f_x \sim N(0, I)$$

### Pseudo-likelihood based inference

Define indicator  $z_i = I(\pi^*(i) \neq i)$ . Then from previous assumptions

$$y_i | \{x_i, z_i = 0\} \sim N(x_i^T \beta^*, \sigma_*^2)$$
  
 $y_i | \{x_i, z_i = 1\} \sim f_y$ 

where  $f_y \sim N(0, \|\beta^*\|_2^2 + \sigma_*^2)$ . Then  $y_i|x_i$  can be expressed as a mixture model with mixing parameter  $\mathbf{P}(Z_i \neq 1) = \alpha_* = \frac{k}{n}$ .

$$f_{y_i|x_i} \sim (1 - \alpha_*)N(x_i^T \beta^*, \sigma_*^2) + \alpha_* N(0, \|\beta^*\|_2^2 + \sigma_*^2)$$

### Pseudo-likelihood based inference

Formulate a pseudo-likelihood function of  $\theta = (\beta, \sigma^2, \alpha)$ 

$$L(\theta) = \sum_{i=1}^{n} \log f_{y_i|x_i}(y_i|x_i;\theta).$$

It is a pseudo-likelihood because  $\{y_i|x_i\}_{i=1}^n$ 's are not independent. Nevertheless, the maximizer  $\hat{\theta}$  of  $L(\theta)$  enjoys several attractive properties.

#### Theorem 6

Under the regularity conditions for the theory of pseudo-likelihood,

$$\sqrt{n}(\hat{\theta}_n - \theta^*) \stackrel{d}{\rightarrow} N(0, H_*^{-1} G^* H_*^{-1})$$

where

$$H_* = \mathbf{E}[-\nabla_{\theta}^2 \log f(y|x; \theta^*)]$$

$$G^* = \mathbf{E}[\nabla_q \log f(y|x; \theta^*) \nabla_q \log f(y|x; \theta^*)^T]$$

#### Reference

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