Verification and Validation Report: Park'd

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1 Revision History

Date	Version	Notes
Mar 2, 2023	1.0	Revision 0

2 Symbols, Abbreviations and Acronyms

symbol	description
T	Test
BE	Business Event
SRS	Software Requirements Specification
NFR	Non-Functional Requirement
FR	Functional Requirement
M	Modules
HTTP Request	A message sent by a client to initiate an action on the server through Hypertext Transfer Protocol
$DEFAULT_DELAY$	Time until parking directions to the default recommended parking space is shown (e.g. 10)

Contents

1	Revision History	i
2	Symbols, Abbreviations and Acronyms	ii
3	Functional Requirements Evaluation	2
4	Nonfunctional Requirements Evaluation 4.1 Look and Feel	8 8 9 10 12
5	Comparison to Existing Implementation	18
6	Unit Testing	19
7	Changes Due to Testing	19
8	Automated Testing	20
9	Trace to Requirements	21
10	Trace to Modules	21
11	Code Coverage Metrics	25
${f L}$	ist of Tables	
	1 Traceability Matrix for Test Cases and Modules - Part 1 2 Traceability Matrix for Test Cases and Modules - Part 2	
	3 Traceability Matrix for Test Cases and Modules - Part 3	

List of Figures

Since this report is heavily based on validating the test cases we had derived in the Verification and Validation Plan, which was done well in advance of the implementation, we found that it would be inappropriate to test our system against these test cases if certain features were not yet implemented. Instead of failing a test case because the feature is not yet implemented, we have opted to mention Not Tested. These features will be ready in either Revision 1 or another revision, and can be tested then. However, if a feature was implemented and it satisfies the test case conditions, it will be denoted with PASS and FAIL otherwise.

3 Functional Requirements Evaluation

Test	Driver	Expected Value	Actual Value	Result
Id	Action			
BE1-	Driver	System prompts driver	No prompt is given	Not Tested
FR1-	launches	to allow location access		
T1	the appli- cation			
BE1-	Driver	System displays a map	System displays a map,	Not Tested
FR2-	launches	of the driver's sur-	but centred on a de-	
T1	the appli-	roundings	fault point	
	cation			
BE2-	N/A	System uses parking	System uses parking	PASS
FR3-		lot camera footage to	lot camera footage to	
T1		survey status	survey status	
BE2-	N/A	System recognizes and	System does not dis-	Not Tested
FR4-		displays special park-	play special parking	
T1		ing spots	spots	
BE2-	N/A	System must allow	System allows admins	PASS
FR5-		parking spot locations	to determine parking	
T1		to be determined	spot locations	

BE2- FR6- T1	N/A	System prompts the driver for the lot they wish to navigate to	System displays available spaces arranged by lot	PASS
BE2- FR7- T1	Driver views a lot	System displays all available spaces in the lot	System displays all available spaces in the lot	PASS
BE3- FR8- T1	Driver filters by normal, accessible, and reserved spaces	System displays or hides the relevant spaces	System does not distinguish such spaces	Not Tested
BE3- FR9- T1	N/A	System must display only normal spaces by default	System displays only spaces marked by the admin	PASS
BE3- FR10- T1	Driver selects a parking space	System recognizes the selection	System recognizes the selection	PASS

BE4- FR11- T1	Driver selects an available parking space	Driver must be shown directions from their location to the desired parking space	Driver is shown directions from their location to the desired parking space	PASS
BE4- FR12- T1	Driver selects the default parking space recommen- dation	Driver must be given directions to reach the recommended parking space	Driver is neither provided a recommendation nor provided directions to the parking space	Not Tested
BE4- FR13- T1	N/A	The system must display directions to the default recommended parking space after DEFAULT_DELAY seconds	The system does not display navigation di- rections to the recom- mended space	Not Tested
BE5- FR14- T1	Driver selects an unavailable parking space	System must inform the driver that they cannot park in a spot that is already occu- pied by another vehicle	System does not notify the driver of a spot's occupancy	Not Tested
BE5- FR15- T1	Driver selects a reserved or accessibility parking space	System must inform the driver that they have tried to select a parking space that does not meet their needs	When the driver does not require reserved or accessibility park- ing, the system does not inform the driver when they select such a space	Not Tested

BE6- FR16- T1	Driver's geographi- cal location	As the driver commutes, the directions must be updated such that the parking space remains stationary and the driver's location is dynamic	Directions are not updated because geographical data collection from the driver's device is not yet implemented	Not Tested
BE6- FR17- T1	N/A	If the initial parking space selected by the driver is no longer available, the system must show another recommendation to the driver	Driver is not shown another parking recommendation if their initial choice becomes unavailable	Not Tested
BE6- FR18- T1	N/A	Once the initial parking space is no longer available, the system must allow the driver pick another space from those that are available	Driver is able to select another parking space, but this is not due to the unavailability of the previous space	Not Tested
BE7- FR19- T1	Driver's geographi- cal location	The system must inform the driver when they have reached their parking spot	Since the system is not yet configured to know when the driver has reached their location, no notification will be sent to the user	Not Tested
BE7- FR20- T1	Driver's geographi- cal location	The parking space must change from available to unavail- able	Parking space does change from available to unavailable, but this is due to constant machine learning surveillance, and not geographical information	Not Tested

BE7- FR21- T1	Driver reaches their destination	A survey for user feedback and dissat- isfaction is presented	No survey is presented	Not Tested
BE8- FR22- T1	Driver changes settings	The system changes accordingly to match the new settings	No changes occur	Not Tested
BE8- FR23- T1	Driver opens the settings page	System settings such as volume and sound adjustment, unit identification, vehicle details, and notification preferences are shown	Only unit identification is shown	FAIL
BE9- FR24- T1	Driver cancels their current route	The parking spot selection and path are removed	The system removes the path and returns to the spot selection page	PASS
BE9- FR25- T1	Driver cancels their current route	The system returns to the spot selection page	The system removes the path and returns to the spot selection page	PASS
BE10- FR26- T1	Admin logs in to the system	The system requests user credentials	The systems asks for a username and pass- word	PASS

BE10- FR27- T1	Admin enters the wrong credentials	The system does not accept the credentials	The systems specifies the given credentials does not match any ad- min user	PASS
BE10- FR28- T1	Admin accesses occupancy map	A map over the parking lot showing which spots are occupied or not	A map showing the oc- cupancy and controls for changing the layout	PASS
BE10- FR29- T1	Admin accesses parking lot analytics	Analytics shows trends in the parking lot over a period of time	Analytics shows trends in a predefined period	FAIL
BE11- FR30- T1	Admin changes the parking layout	Layout changes are saved	Layout changes are not saved	FAIL
BE11- FR31- T1	Admin changes a parking spot	Parking spot changes are saved	Parking spot changes are not saved	FAIL

4 Nonfunctional Requirements Evaluation

4.1 Look and Feel

Test	User Action	Expected	Actual Value	Result
Id		Value		
NFR-	Development team sweeps	All interface	All interface	PASS
LF1-	through app by accessing	elements are	elements are	
T1	all features they possibly	deemed neces-	deemed neces-	
	can through buttons and	sary	sary	
	other interfaces			
NFR-	Users surveyed on vi-	At least 80% of	N/A	Not Tested
LF1-	sual similarity to existing	testers indicate		
T2	navigation apps after given	that the app		
	EXPLORATION_TIME	is visually sim-		
	to navigate and use the	ilar to existing		
	app	apps		

4.2 Usability

Test	User Action	Expected	Actual Value	Result
Id		Value		
NFR-	Users test all functions	All functions	All functions	PASS
UH1-	considered atomic and	take less than	take less than	
T1	check that none take more	MAX_TAPS	MAX_TAPS	
	than MAX_TAPS	taps		
NFR-	Users surveyed on the	At least 80%	N/A	Not Tested
UH2-	interface's similarity	of testers in-		
T1	to existing naviga-	dicate that		
	tion apps after given	the interface		
	EXPLORATION_TIME	is similar to		
	to navigate and use the	existing apps		
	app			

NFR-	Users given	At least 80% of	N/A	Not Tested
UH3-	$EXPLORATION_TIME$	testers success-		
T1	to find and navigate to an	fully find and		
	available spot	navigate to an		
		available spot		
NFR-	Developers go through all	All assets	All assets	PASS
UH4-	graphical assets used in the	conform to	conform to	
T1	application and verify that	the Ontario	the Ontario	
	each conform to any regu-	Ministry of	Ministry of	
	lations set out by the On-	Transportation	Transportation	
	tario Ministry of Trans-	regulations	regulations	
	portation			

4.3 Performance

Test	User Ac-	Expected Value	Actual Value	Result
Id	tion			
NFR-	Monitor	The system main-	The system main-	PASS
PE1-	the sys-	tains a minimum of	tains a minimum of	
T1	tem's FPS	$MIN_FRAMERATE$	$MIN_FRAMERATE$	
	on different	at all times	at all times	
	platforms			
	during			
	the app's			
	normal			
	operation			
	by users			
NFR-	User nav-	System should never	System does not navi-	PASS
PE2-	igates to	navigate the user off	gate users off the road	
T1	available	the road		
	parking			
	spot			

NFR- PE3- T1	User navigates to available parking spot	System should never navi- gate the user to park at a restricted or reserved area or spot	System does not navigate the user to park at a restricted or reserved area or spot	PASS
NFR- PE4- T1	User finds and navigates to an available parking spot while the back-end service is disabled	The system displays the most recent recommended available parking spot	System displays incorrect parking spot status	FAIL
NFR- PE5- T1	10 users request different parking lot information at the same time	Parking lot information requested by 10 different users shall be processed and sent to the users devices	Correct parking lot information that is requested is provided to each individual user	PASS
NFR- PE6- T1	User is able to see at least 2 parking lot layouts in 6 months from the launch of the application and is launched in a vehicle	At least 2 parking lot layout in 6 months and is launched in a vehicle	N/A	Not Tested

4.4 Operational and Environment

Test Id	User Ac- tion	Expected Value	Actual Value	Result
NFR- OE1- T1	User inputs an address, selects a parking space, and follows the directions given by the parking space	Accurate directions to the designated address is given to the user and the user is able to suc- cessfully drive and lo- cate the parking space	N/A	Not Tested
NFR- OE2- T1	N/A	New update is given every month	N/A	Not Tested
NFR- MA1- T1	Developer takes the camera offline	The application prompts the User that the camera is offline and that the application is still functional	N/A	Not Tested
NFR- MA2- T1	Users are given the instructions on the help section of the application and fills a survey indicating the satisfaction with the information given	80% of the results should be satisfied with the instructs and contacts given	N/A	Not Tested

4.5 Security

Test Id	User Ac- tion	Expected Value	Actual Value	Result
NFR- SR1- T1	Admin logins with a valid username and pass- word for the parking lot they own/manage	Redirection to the admin console with proper parking lot data of their parking lot and administrative controls	Redirected to the admin console with proper parking lot data of their parking lot and administrative controls	PASS
NFR- SR1- T2	Admin attempts to login with an invalid username and password for the parking lot they own/manage	Prompt indicating that the login was unsuccessful	Prompt indicating that the login was unsuccessful	PASS
NFR- SR1- T3	Driver selects a parking lot on the application	No analytics and parking lot data is shown	No analytics and parking lot data is shown	PASS

Test Id	User Ac- tion	Expected Value	Actual Value	Result
NFR- SR2- T1	Admin logins with a valid username and password for the parking lot they own/manage	Edit function is enabled allowing the Administrator to edit their parking lot	Edit function is enabled allowing the Administrator to edit their parking lot	PASS
NFR- SR2- T2	Driver selects a parking lot on the application	Edit function is not shown	Edit function is not shown	PASS
NFR- SR3- T1	Admin logs in to the admin con- sole and searches for a park- ing lot that they do not own	Edit functionality disabled and analytics are not displayed.	N/A	Not Tested

Test Id	User Ac-	Expected Value	Actual Value	Result
NFR- SR4- T1	Developers log into the database on the server and changes the status of an empty parking lot entry in the database to full and refresh the databse	The database reverts the status of the parking lot entry to the correct one, indiciating it is empty	N/A	Not Tested
NFR- SR5- T1	Admin logs in to the admin console, edits and saves the parking lot layout, and disconnects the system from the internet	Parking lot layout layout is cached as a JSON file and a prompt is indicating that the unsaved layout is cached and the location.	N/A	Not Tested

Test Id	User Ac- tion	Expected Value	Actual Value	Result
NFR- SR6- T1	User edit parking lot layout informa- tion and do not submit changes until the timer ex- ceeds AT- TEMPT UPLOAD TIME	Layout information should be saved and a prompt window should show up indicate the action is completed successfully	The layout information is not saved	Fail
NFR- SR7- T1	Check the backup log file and see if it is updated daily	The log file should contains the record for each daily updates	No changes occur	Fail
NFR- SR8- T1	User creates multiple different parking lot layout and ex- amine the returned JSON	The data format should be the same for each parking lots	The JSON format is consistent with each parking lots	PASS
NFR- SR9- T1	User logs in and check the availability of certain parking lots	Each spot should have at max 1 special prop- erty	No properties are shown	Not Tested

NFR- SR10- T1	User attempt to add a parking spot to the database when it reaches maximum capacity	A window should be prompted indicates the action is illegal	No prompt are shown	Not Tested
NFR- SR11- T1	User attempt to add parking lot and save the layout to database	A window should be prompted indicates the action succeed	No prompt are shown	FAIL
NFR- SR12- T1	User request navigation from current location to destination	The correct navigation path should be shown	Paths are shown on the main page	PASS
NFR- SR13- T1	User request navigation for a destination that is impossible to reach with vehicles	A window should be prompted indicates the action is not permitted	The navigation failed with a prompt message indicates the reason	PASS

NFR-	User re-	A window should be	Window is not shown	Not Tested
SR14-	quest	prompted asked for ac-		
T1	navigation	cess for location data		
	for a desti-			
	nation			

4.6 Legal

Test	User Ac-	Expected Value	Actual Value	Result
Id	tion			
NFR-	The user is	notification window	Window pops out	PASS
LR1-	in naviga-	should pop out, in-		
T1	tion mode	forming the driver to		
	and while	follow the regulations		
	moving,			
	the user			
	attempt			
	to interact			
	with the			
	website			

5 Comparison to Existing Implementation

In our SRS, we had discussed two applications, namely ParKam App and Spot Sensor, that are already on the market and perform similar features to our implementation.

ParKam is closed source, therefore a white box comparison is impossible to perform. In addition, it is infeasible to perform a direct feature comparison between our solution and ParKam, because their solution is not offered in the North American market. Attempting to use their product would entail a lengthy application process that may or may not succeed. According to their website (https://parkam.com) and in some of their YouTube videos, their product seems to be much more polished, robust and feature-packed compared to our current implementation. For example, in addition to navigation and availability, which our solution supports, they also detect illegal parking. They also perform a variety of edge case testing, such as not double counting parking spaces when the outline of a parking lot is drawn twice on top of the same space.

The other application, Spot Sensor, uses ultrasonic signal sending hard-ware to detect parking spaces. Since this implementation is widely used among various parking spaces in Toronto, we can compare how well the sensor detects the parking's availability compared to our machine learning model, which on the other hand, is a pure software solution. Needless to say, Spot Sensor, does not provide any other functionality, such as navigation, therefore, this solution can only be used to evaluate our parking detection algorithm.

6 Unit Testing

Tested Mod- ule	User Action	Expected Value	Actual Value	Result
Gaussian model bird view	Input values of video frames	The module should output result object with timestamp and boolean array in their field indicating the availability of parking lots (3 free and 4 occupied)	The time stamp and boolean array values matches the availability shown in each video frame: result: {'timestamp': 16278900565, 'availability': [True, True, False, False, True]}	PASS
Gaussian model side view	Input values of video frames	The module should output result object with timestamp and boolean array in their field indicating the availability of parking lots (3 free and 6 occupied)	The time stamp and boolean array values matches the availability shown in each video frame: {'timestamp': 16278900723, 'availability': [True, True, False, False, True, False, False]}	PASS
Data mapper	Querying parking lot layout info with parking lot id	Return the JSON value of saved parking lots	JSON values are correctly parsed and returned	PASS

7 Changes Due to Testing

1. BE8-FR23-T1

Add more preference options for volume adjustment, vehicle details, and notification preferences.

2. BE10-FR29-T1

Add dropdown menu beside Analytics to allow Admins to see trends over a specified period of time.

3. BE10-FR30-T1

Add back-end service to allow the front-end to modify coordinates of boxes that define the parking lot layout.

4. BE10-FR31-T1

Add back-end service to allow the front-end to modify the status of spots in the parking lot.

5. NFR-PE4-T1

Add temporary storage for front-end to modify and pull status of parking spot status in the case that it loses connection with the back-end services.

6. NFR-SR6-T1

Add back-end service to allow the front-end to modify coordinates of boxes that define the parking lot layout.

7. NFR-SR7-T1

Add back-end service to regularly back up the parking lot layout data daily.

8. NFR-SR11-T1

Add pop up modal or message to indicate to the user that the action was successful.

8 Automated Testing

Automated API testing is used for python back-end server and test suits were built on postman. Using the automated testing features in Postman, each APIs were tested as following.

Test	Input	Expected Value	Actual Value	Result
Id				
API-	{'park_id': 0 }	response:	{'timestamp':	PASS
T1-		{'timestamp':	16278900565, 'avail-	
avail		16278900565, 'avail-	ability': [True, True,	
		ability': [True, True,	False, False, True]}	
		False, False, True]}		
API-	{'park_id': 0 }	response:	{'timestamp':	PASS
T1-		{'timestamp':	16278900565, 'Res':	
save		16278900565, 'Res':	True}	
		True}		
API-	{'park_id': 0}	response:	{'timestamp':	PASS
T1-		{'timestamp':	16278900565,	
snap		16278900565, 'Res':	'Res':snap_shot_0.jpg}	
		$snap_shot_0.jpg$		

9 Trace to Requirements

The traceability of test cases to requirements can be referred to in the VNV Plan Document.

10 Trace to Modules

Table 1: Traceability Matrix for Test Cases and Modules - Part 1 $\,$

		Modules												
		M1	M2	М3	M4	M5	M6	M7	M8	M9	M10	M11	M12	M13
	BE1-FR1-T1								X	X				
	BE1-FR2-T1								X	X				
	BE2-FR3-T1		X									X		
	BE2-FR4-T1			X	X	X	X	X	X			X		
	BE2-FR5-T1			X	X	X	X	X	X					
	BE2-FR6-T1										X			X
Test Cases	BE2-FR7-T1			X										
	BE3-FR8-T1						X	X						X
	BE3-FR9-T1					X								
	BE4-FR10-T1						X	X						X
	BE4-FR11-T1									X				
	BE4-FR12-T1					X								X
	BE4-FR13-T1									X				

Table 2: Traceability Matrix for Test Cases and Modules - Part 2

		Modules												
		M1	M2	М3	M4	M5	M6	M7	M8	M9	M10	M11	M12	M13
	BE5-FR14-T1							X						X
	BE5-FR15-T1							X						X
	BE6-FR16-T1									X				
	BE6-FR17-T1					X		X				X		
	BE6-FR18-T1													X
	BE7-FR19-T1									X				
Test Cases	BE7-FR20-T1							X				X		
	BE7-FR21-T1													X
	BE8-FR22-T1													X
	BE8-FR23-T1													X
	BE9-FR24-T1									X				X
	BE9-FR25-T1									X				

Table 3: Traceability Matrix for Test Cases and Modules - Part 3

		Modules												
		M1	M2	М3	M4	M5	M6	M7	M8	M9	M10	M11	M12	M13
Test Cases	BE10-FR26-T1			X					X					
	BE10-FR27-T1			X					X					
	BE10-FR28-T1				X				X					
	BE10-FR29-T1								X		X			
	BE11-FR30-T1				X				X					
	BE11-FR31-T1				X				X					

11 Code Coverage Metrics

From the VnV plan, we targeted at least 80% code coverage on Python code with Coverage.py and on UI code with Istanbul. We reached 100% and 90% respectively.

Appendix — Reflection

The information in this section will be used to evaluate the team members on the graduate attribute of Reflection. Please answer the following question:

1. In what ways was the Verification and Validation (VnV) Plan different from the activities that were actually conducted for VnV? If there were differences, what changes required the modification in the plan? Why did these changes occur? Would you be able to anticipate these changes in future projects? If there weren't any differences, how was your team able to clearly predict a feasible amount of effort and the right tasks needed to build the evidence that demonstrates the required quality? (It is expected that most teams will have had to deviate from their original VnV Plan.)

The main differences are as follows:

1. Some functional requirements from the first version of the VnV Plan were not tested because the functionality they encompassed was dropped from the Revision 0 Demo, due to time constraints.

Changes like these can be anticipated to an extent in future projects because group members can often approximately predict the time needed to implement a given feature or function. However, given the large number of requirements, and the possibility of unexpected issues such as code incompatibility, this is not always the case. Ultimately, designers can only guess at what will be feasible to implement by the next deadline.

Therefore, there should always be some leeway in which requirements are tested and which ones are left for later. By highlighting which requirements are of high priority, and by only using such a classification sparingly, we can ensure the most important functionality of an application is always verified and validated. A hierarchy of requirements always exists, but writing it down can help designers prioritize and delegate tasks appropriately.