SHALLOW WATER WAVES 11.3 10/16/2009 Start from our Shallow Water Equations ( = 0) = 10" [x mm]  $u_t + uu_x = -g\eta x$ \*

[wass]  $v_{t+1} = v_{t+1} = v_{t+$ Consider small perturbations away from a state of rest => allows us to linearize consider mais , scale [M] = E, assume E << H [ Me + Hux + Mux + Axu + Mx4 = 0] E HU EU (2) >> (3) n (4) so dray (3 + (4) V leaves [mail] Mt + Hux = 0 \ linear!

Wait! Previously we assumed "advective scaling" = = = 1 L
which would mean (1) was also nightly!

But ... many important wave flows (Tides, Kelin Waves, ede,) have and and T ( wave privat) (wavelength) even as U -> 0 => for waves + may be >> 1/2 ! we retain term ( means we require = >> ?) Next, ansider x mm = - g Mx Lut + uux U ma + > 4 = drap (2) (J) 868 (I) lea ve 2 equations in u, y x mm / Ut = -9 1/x man 1 + + Hux = 0

Take 
$$\frac{\partial}{\partial t} [max] = \int M_{tt} + H_{Uxt} = 0$$

$$\frac{\partial}{\partial x} [xmm] = \int Uxt = -gMxt$$

$$= \int M_{tt} - gHMxx = 0$$

$$= \int M_{tt}$$

M= 
$$f(G)$$
 when  $G = x \pm ct$ 

So  $\frac{\partial \eta}{\partial t} = \frac{\partial f}{\partial t$ 

L St VgH