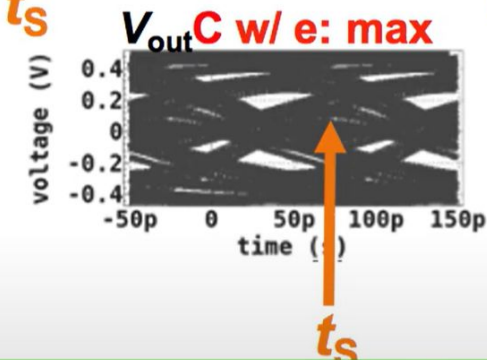
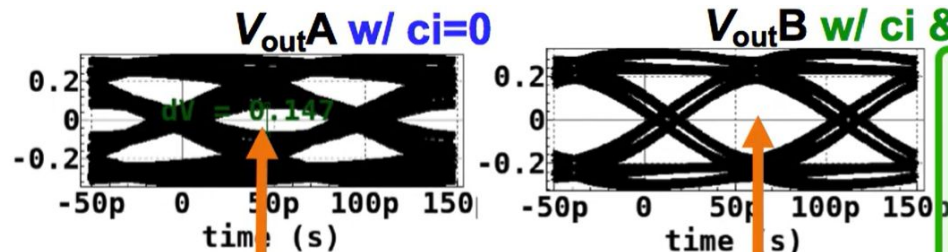
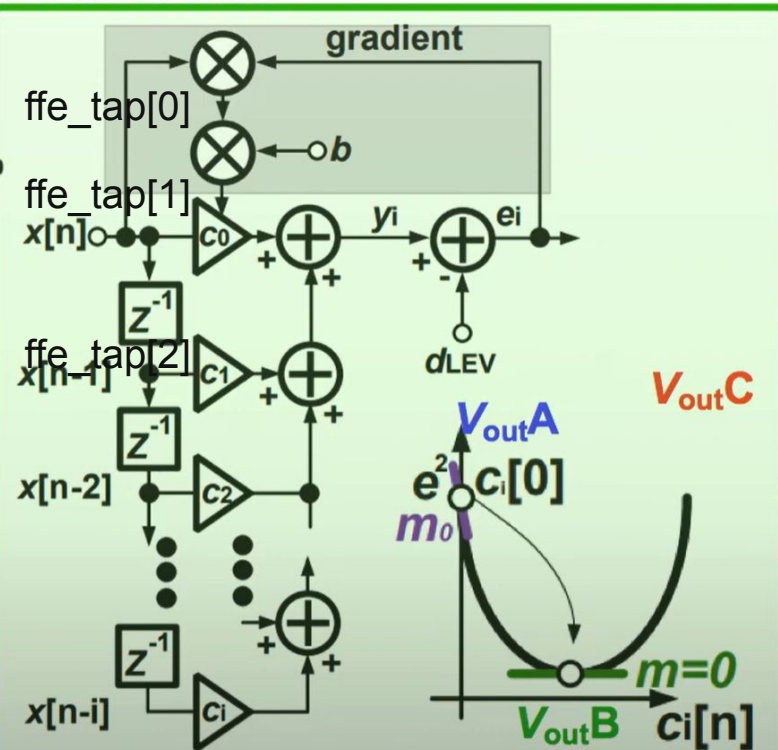


FFE with LMS

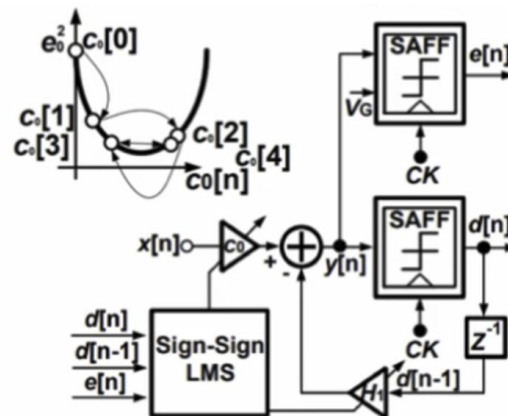
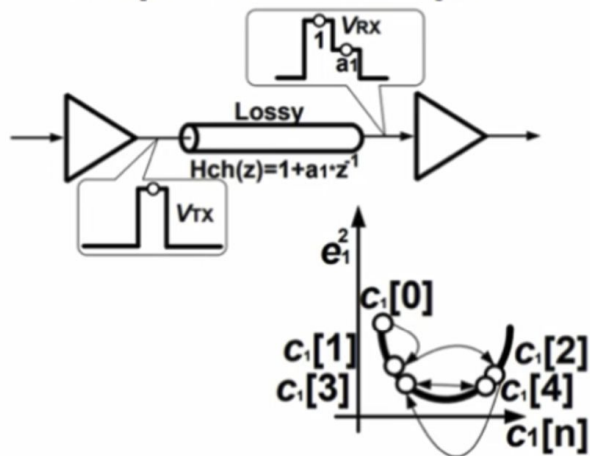


$$c_i[n+1] = c_i[n] - b * e * x[n-i]$$



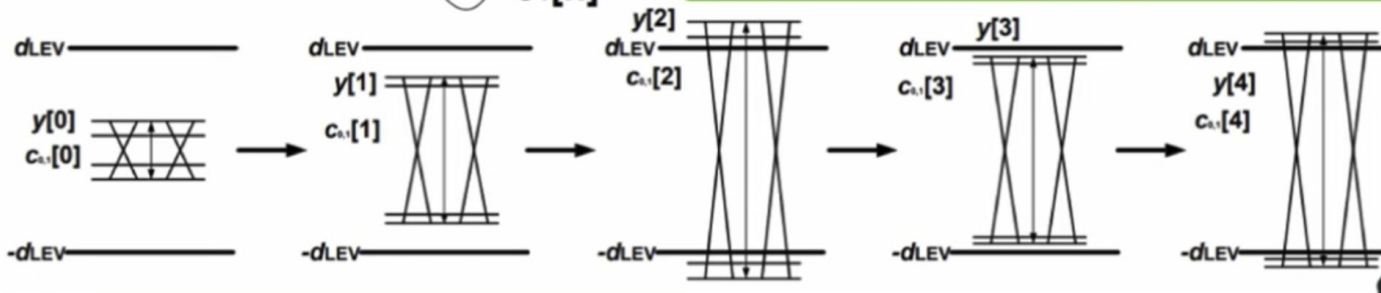
Sign-sign LMS DFE with dLev Adaptation (1)

- Simple channel response:

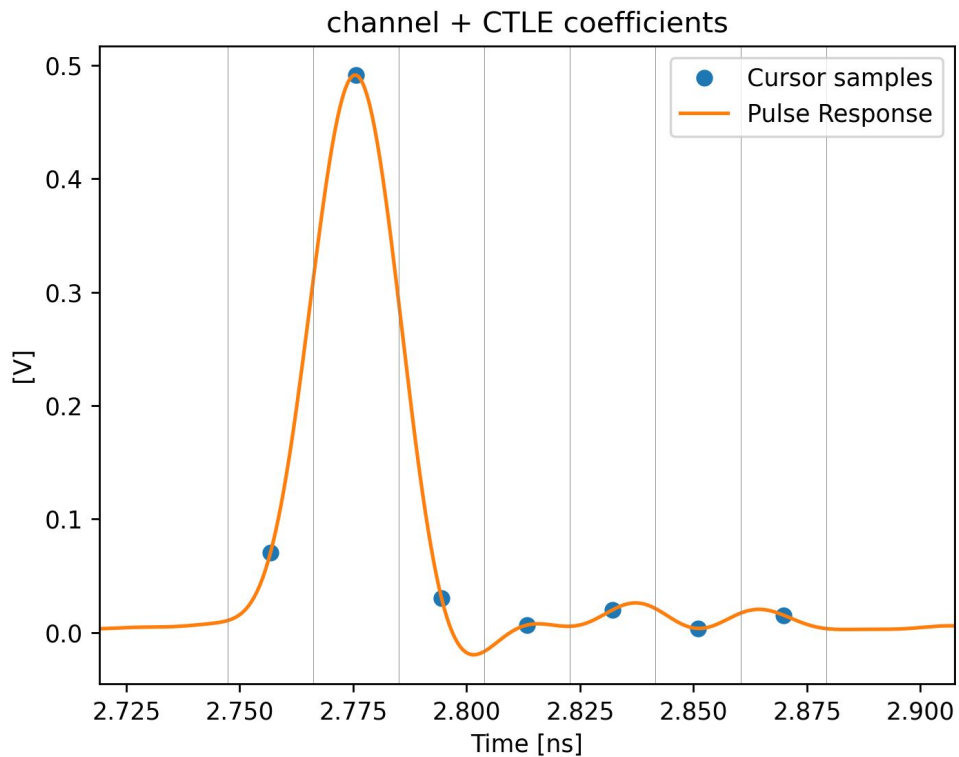


$$C_0[n+1] = C_0[n] - \mu * \text{sign}(e[n])\text{sign}(d[n])$$

$$C_1[n+1] = C_1[n] + \mu * \text{sign}(e[n])\text{sign}(d[n-1])$$

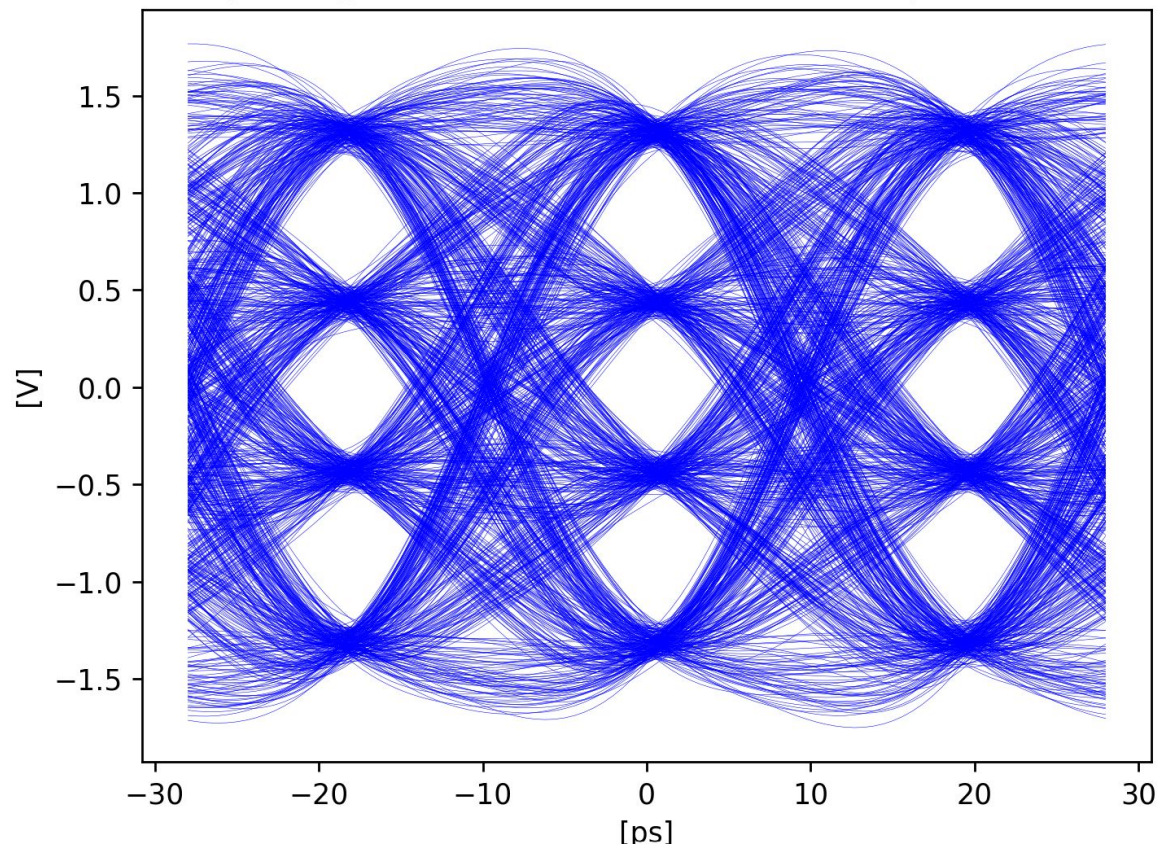


Impulse Response

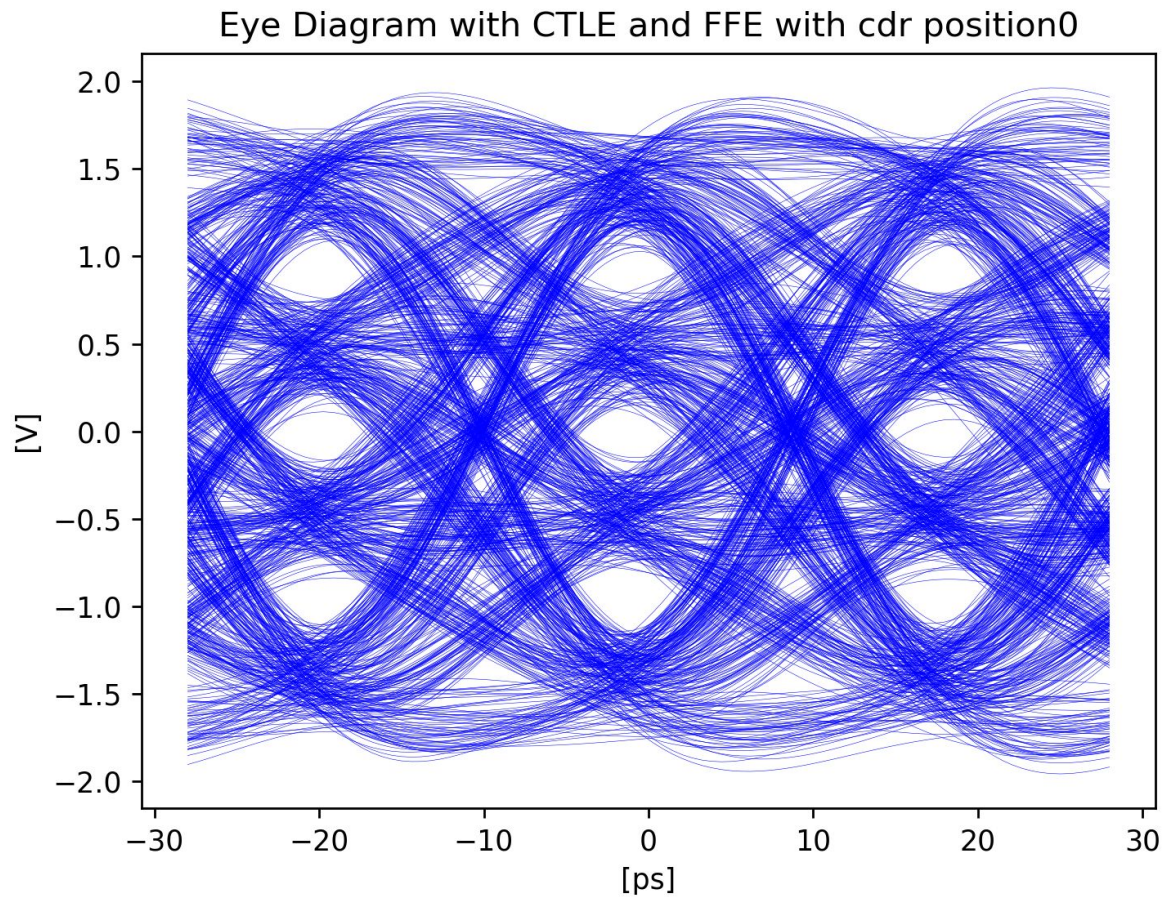


FFE+CDR

Eye Diagram with CTLE and FFE with cdr position28

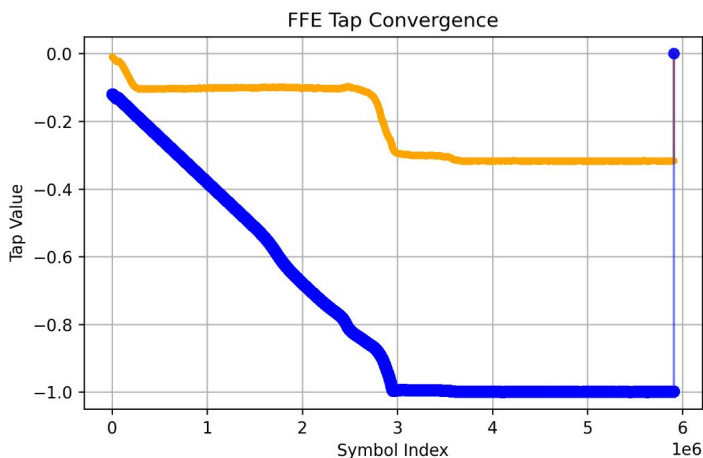
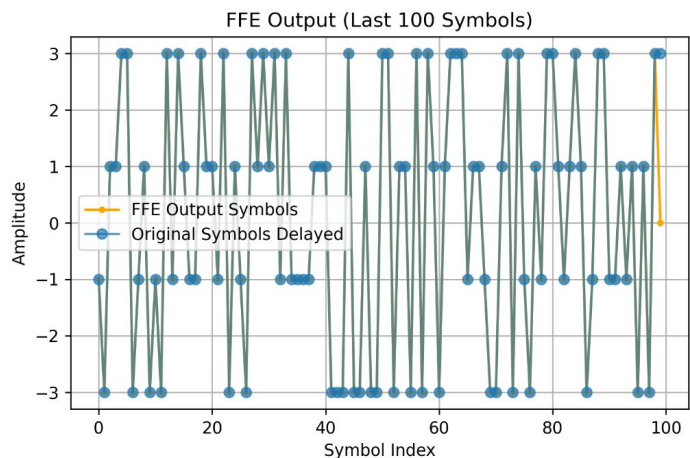
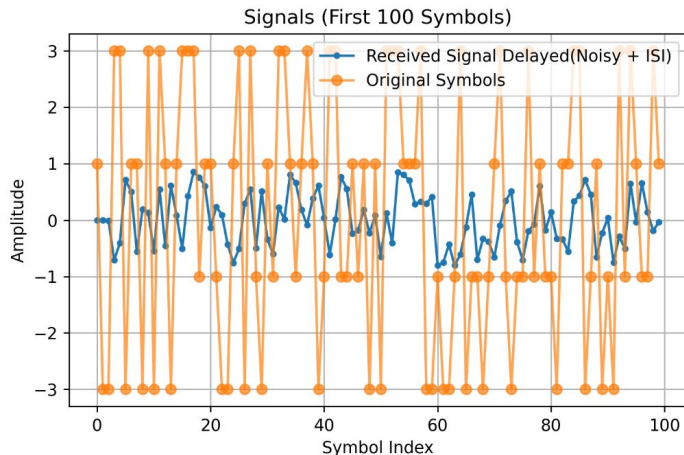
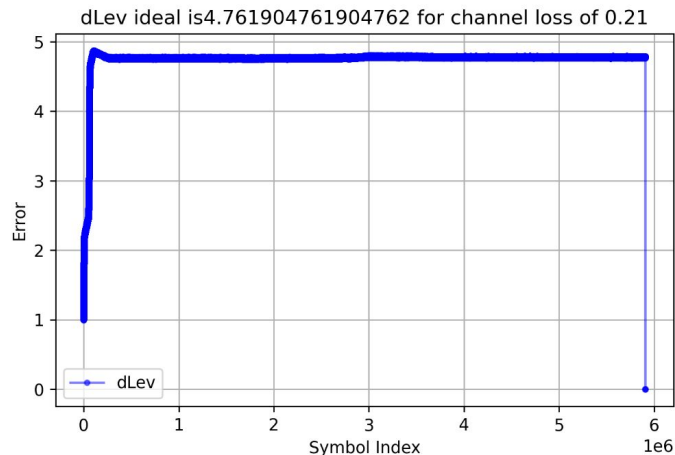


FFE+CDR



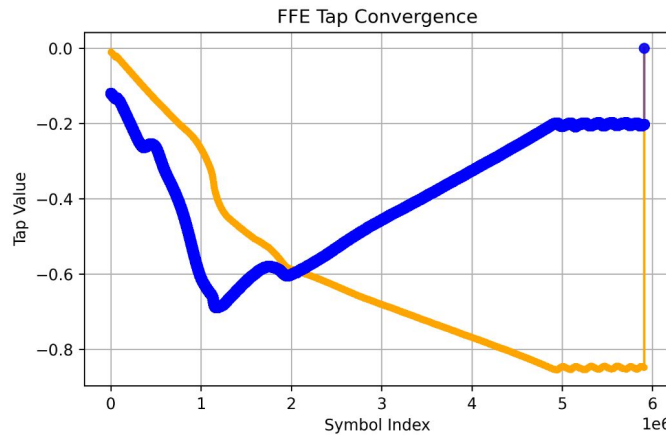
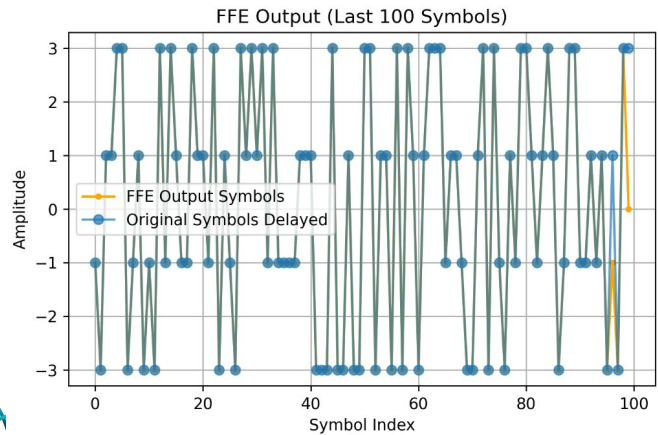
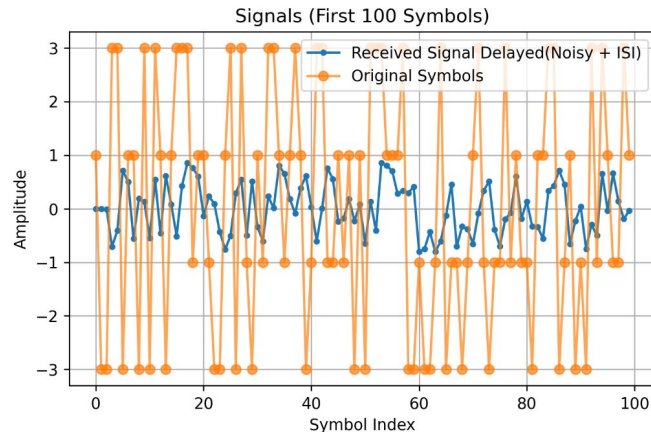
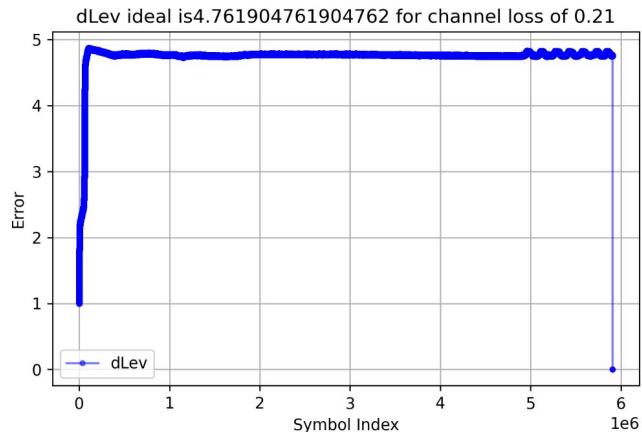
Sign-sign LMS FFE with dLev Adaptation (3)

flip_next_data



Sign-sign LMS FFE with dLev Adaptation (4)

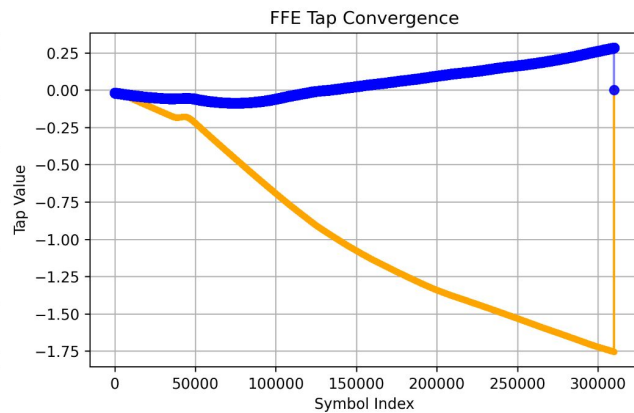
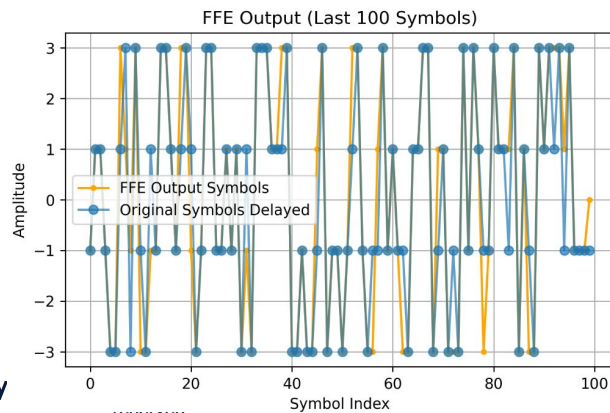
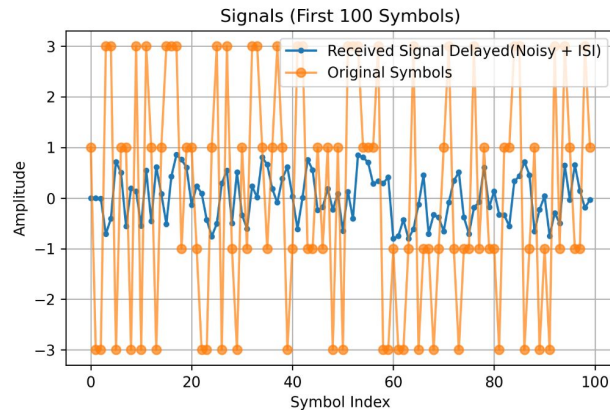
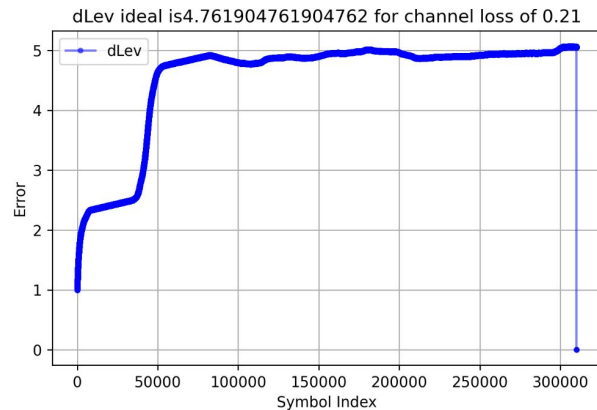
next_data



reserved

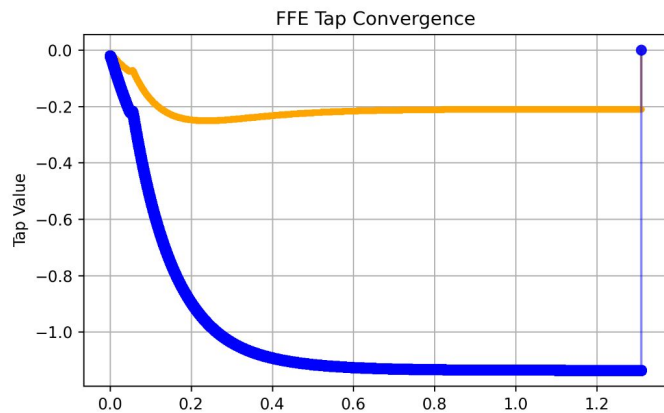
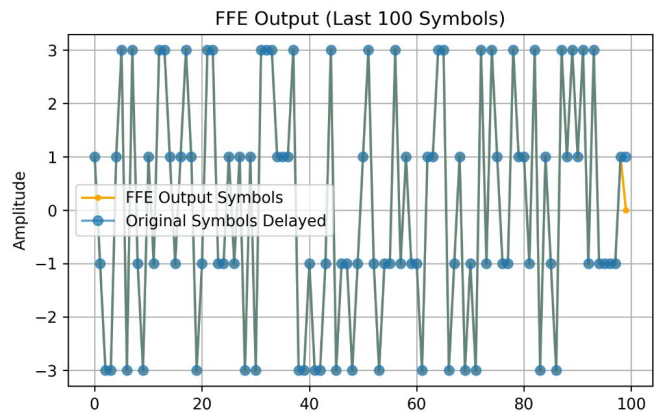
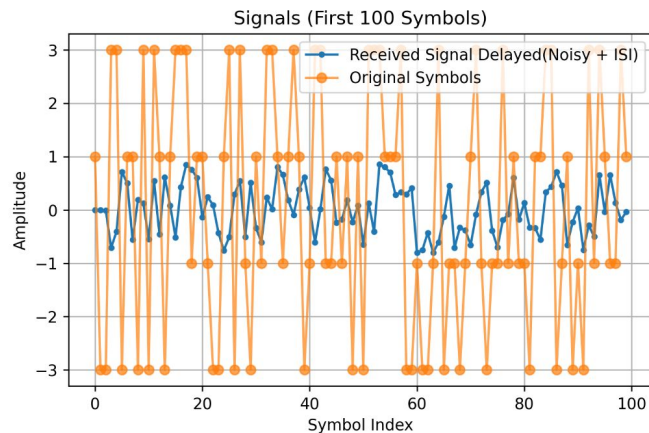
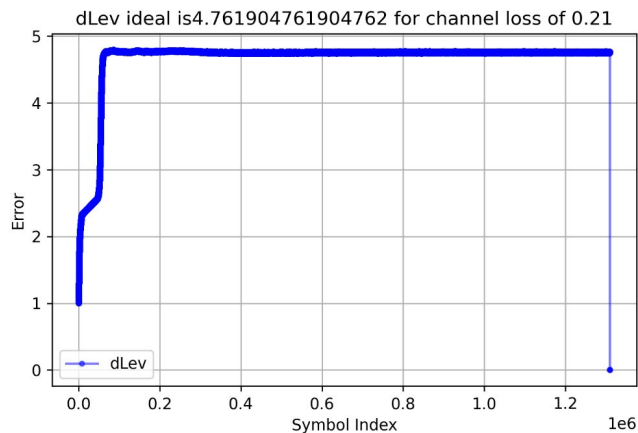
split_error

next_data



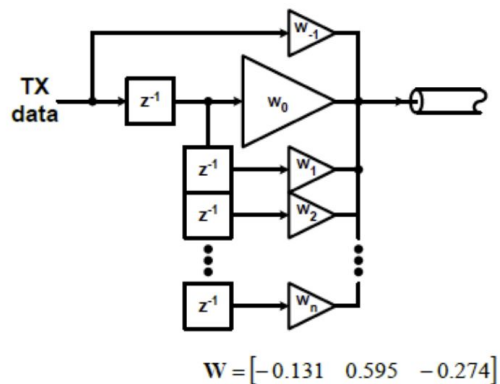
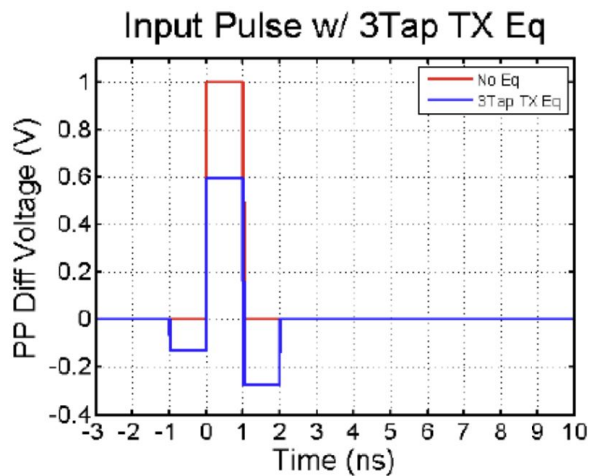
Split_error

flip_next_data



Transmitter FFE

Have access to data before ISI



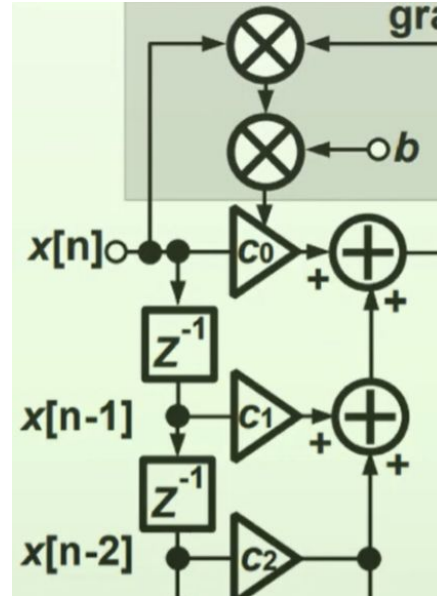
Receiver FFE

Received data already have ISI

$$y_0 = h_0 * c_0 + 0 + 0$$

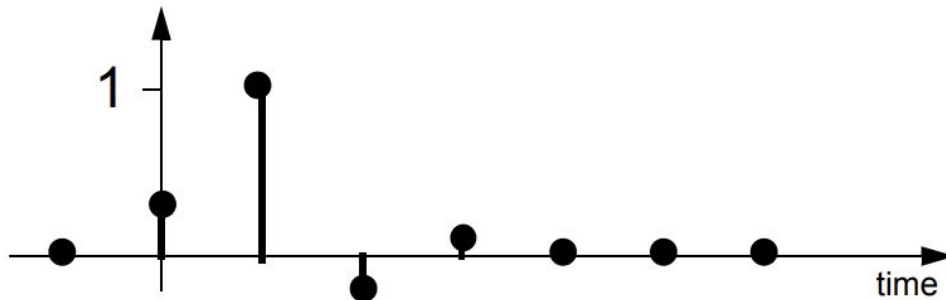
$$y_1 = h_{-1} * c_0 + h_{-2} * c_1 + 0$$

$$y_2 = h_0 * c_0 + h_{-1} * c_1 + h_{-2} * c_2$$



Receiver FFE

- Suppose channel, $H_{tc}(z)$, has impulse response 0.3, 1.0, -0.2, 0.1, 0.0, 0.0



- If FFE is a 3-tap FIR filter with

$$y(n) = p_1 u(n) + p_2 u(n-1) + p_3 u(n-2)$$

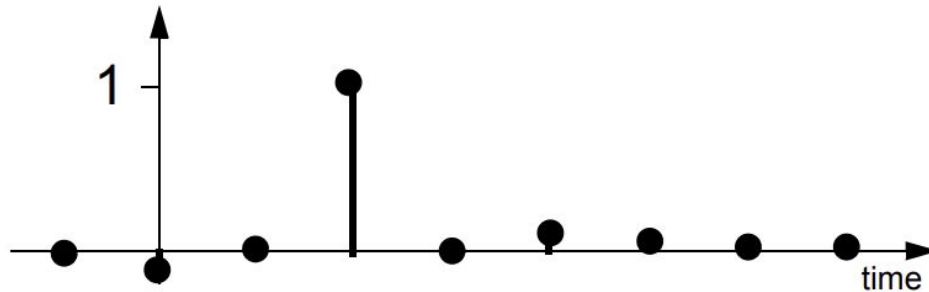
Receiver FFE

$$y(1) = 0 = 1.0p_1 + 0.3p_2 + 0.0p_3$$

$$y(2) = 1 = -0.2p_1 + 1.0p_2 + 0.3p_3$$

$$y(3) = 0 = 0.1p_1 + (-0.2)p_2 + 1.0p_3 \quad (3)$$

- Solving results in $p_1 = -0.266$, $p_2 = 0.886$, $p_3 = 0.204$
- Now the impulse response through both channel and equalizer is: 0.0, -0.08, 0.0, 1.0, 0.0, 0.05, 0.02, ...



Receiver FFE

