# Topics in Astronomical Research Computational Astrophysics

PHYS 913

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#### Last time ...

- Simulating observations
- Fitting with regression
- Markov Chain Monte Carlo
- Bayesian Approach to MCMC

#### Today:

- Revisit MCMC: Simulated annealing
- More discussion about Bayesian Inference
- Brief intro to Machine Learning

#### Refresher on MCMC methods

- Markov Chain Monte Carlo is a method for sampling from a probability distribution, P(x). x could be a vector state.
- It yields importance sampling.
- Key steps:
  - Start with a some vector state x<sub>i</sub>.
  - Propose a new vector state x<sub>j</sub>.
  - The probability of accepting the new state = min( $P(x_i)/P(x_i)$ , 100%)
  - If rejected, reuse state i.
- Transitions: Obey detailed balance:

• 
$$\frac{T_{ij}}{T_{ji}} = \frac{P(E_j)}{P(E_i)} = \frac{e^{-E_j/kT}/Z}{e^{-E_i/kT}/Z} = e^{-(E_j - E_i)/kT}$$

#### MCMC: Optimization

- While MCMC is great at sampling the parameter space, as seen last class, It's also a useful tool for minimizing a function.
- Recall: we often are looking for the global minimum.

• Methods like gradient descent (GD) will only find the bottom of the basin you start in.

20 - 15 - 10 - 5 - 0 - 2 - 4 - 2 0 2 4

```
In [87]: x0 = np.arange(-5,5.1,1.)
for x00 in x0:
    x1 = grad_disc(x00,fofx,fprime,h=0.01,c=0.002,tol=1.e-5)
    print(x00,x1,fofx(x1))

-5.0 -4.7653113612906 21.5031533064071
    -4.0 -3.8000651363889144 12.59523155571228
    -3.0 -0.3763473516852742 -2.9038118234513406
    -2.0 -0.376355933983961 -2.903811236048604
    -1.0 -0.3763271539248255 -2.9038132012199287
    0.0 -0.367786929212471 -2.9038141441120957
    1.0 0.4981634324644772 -3.68195701212003
    2.0 1.4549552609428011 -2.5628951007376566
    3.0 2.426942723068116 0.6175994573939354
    4.0 3.39830550316508 5.888852991198876
    5.0 4.35739983480212 13.228583791227603
```

## MCMC: Simulated Annealing (Newman 10.4)

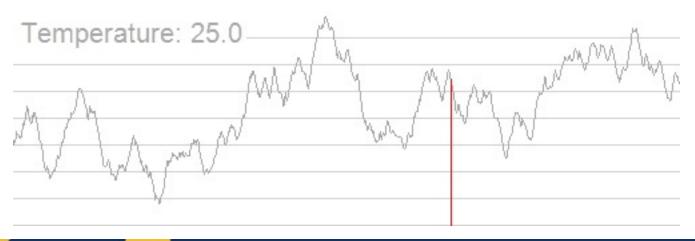
- MCMC on its own will only sample the probability:
  - $P(f(x);T) \sim exp(-f(x)/T)$
- More points will sample minima in f(x), and you could look at your chains to determine the smallest f(x).
- This could inform an initial guess(es) for GD.
- However, let's consider the importance of T.
- What happens for large T?
- What happens as  $T \rightarrow 0$ ?

# MCMC: Simulated Annealing (Newman 10.4)

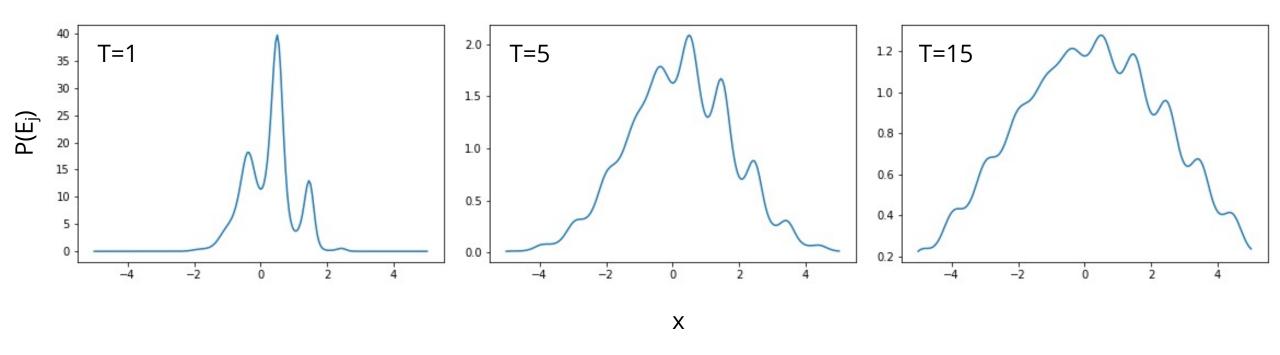
- Simulated annealing is an approach to finding the global minimum (or maximum) of a function by emulating nature.
- Consider a metal or glass that cools very quickly: it will reach some local minimum of energy, but this isn't the global minimum.
  - This can mean it is still brittle, weak.
- Consider a metal of glass that cools slowly: it will find its lowest possible energy state.
  - This will make it the strongest.
  - This is called *annealing*.

# Simulated Annealing

- Recall the transition probability: Probability of accepting state j from state i:
- $P(x_i, x_j; T) = e^{-(f(x_j) f(x_i))/kT}$
- Large T  $\rightarrow$  even if  $f(x_j) > f(x_i)$  there is a high probability of accepting the new state.
- Low T  $\rightarrow$  only accept state if  $f(x_i) < f(x_i)$ .



# Example: Probability of $x \sim \exp(-f(x)/T)$



# Simulated Annealing

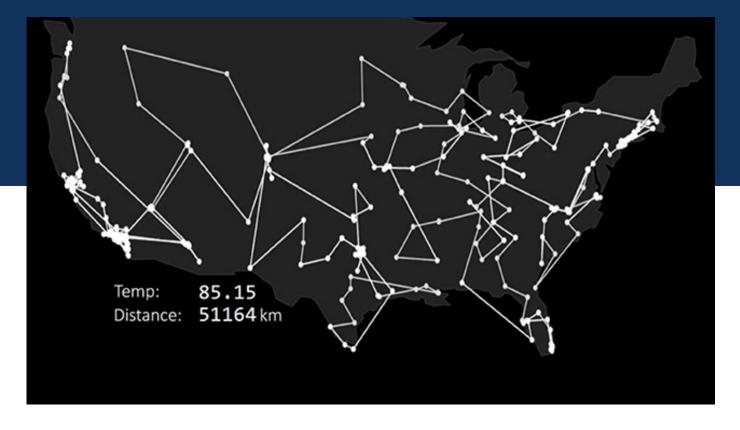
- General approach:
- Start with a large  $T=T_0$ , typically  $>> \Delta f$
- Slowly decrease  $T \rightarrow T = T_0 e^{-t/\tau}$
- Finding good values of  $T_0$  and  $\tau$  requires trial and error. Generally, better solutions are found for large  $T_0$  and  $\tau$  but will require longer to converge.
- For choosing a new state:
  - Discrete states: swap indices.
  - Continuous: choose a state nearby (use a normal distribution, with any constraints added).

# Simulated Annealing: Traveling Salesperson

- Imagine a list of cities (with [x,y] positions on a map).
- You want to travel to all of the cities in the shortest amount of time (minimizes distance of root).
- Also typically want to return where you started.
- Typically very hard. Simulated Annealing was actually created to solve it.
- Brute force: try combination. e.g., 5 cities: (n-1)! ways

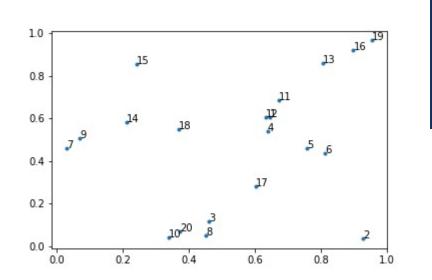
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(1,3,2,4,5,1)
                                (1,4,2,3,5,1) (1,5,2,3,4,1)
• (1,2,3,4,5,1)
• (1,2,3,5,4,1)
                  (1,3,2,5,4,1)
                                (1,4,2,5,3,1)
                                                (1,5,2,4,3,1)
• (1,2,4,3,5,1)
                  (1,3,4,2,5,1)
                                (1,4,3,2,5,1)
                                                 (1,5,3,2,4,1)
                                 (1,4,3,5,2,1)
                                                 (1,5,3,4,2,1)
• (1,2,4,5,3,1)
                  (1,3,4,5,2,1)
• (1,2,5,3,4,1)
              (1,3,5,2,4,1)
                                (1,4,5,2,3,1)
                                                (1,5,4,2,4,1)
• (1,2,5,4,3,1)
                  (1,3,5,4,2,1)
                                (1,4,5,3,2,1)
                                                 (1,5,4,3,2,1)
```

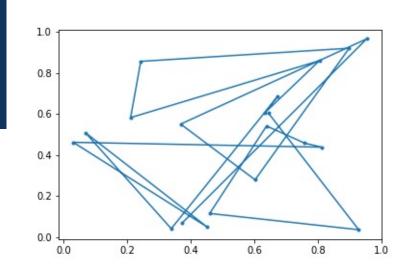
#### Example cont.



- Can be a huge parameter space.
- Minimizing the total distance function:
  - $d = \sum_{i=1}^{N} \sqrt{(x_{i+1} x_i)^2 + (y_{i+1} y_i)^2}$ , with the N+1 point = first point to close the loop.
  - Here *i* refers to city in the i<sup>th</sup> place in the list.

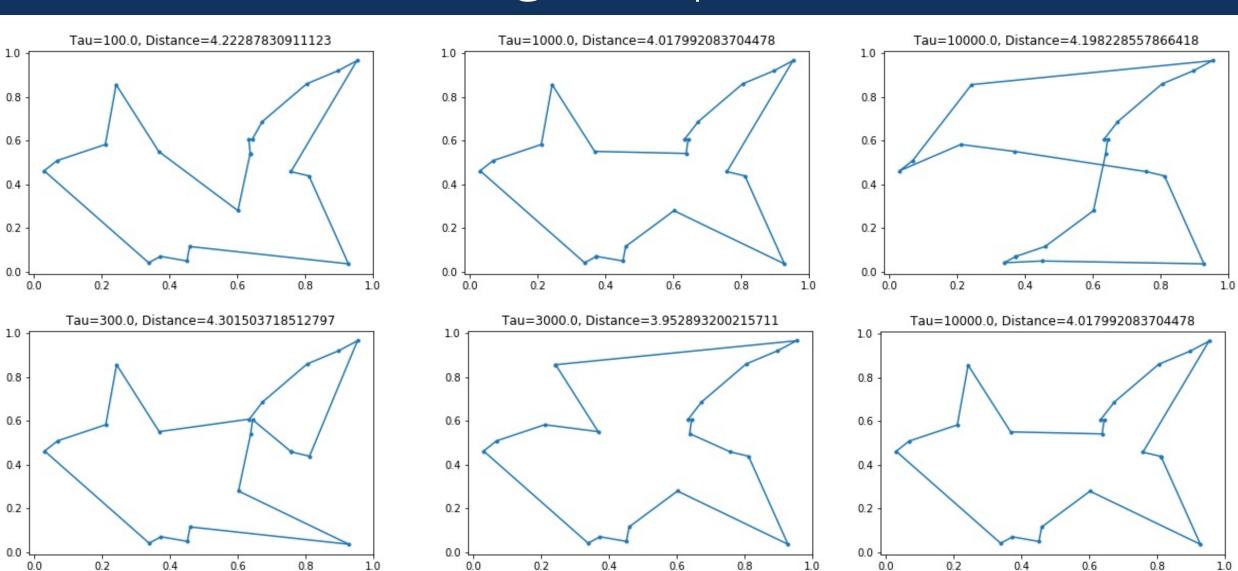
#### Example





- I took  $T_0$  to be N\*sqrt(2)\*2  $\rightarrow$  twice as long as going back and forth between the diagonals N times ... this is much larger than the worst case scenario.
- τ took trial and error. I ended up using 10,000 which took ~20 seconds.
- Found a minimum of  $\sim$ 4:  $\sim$  tracing the outside of the domain.

# Traveling salesperson

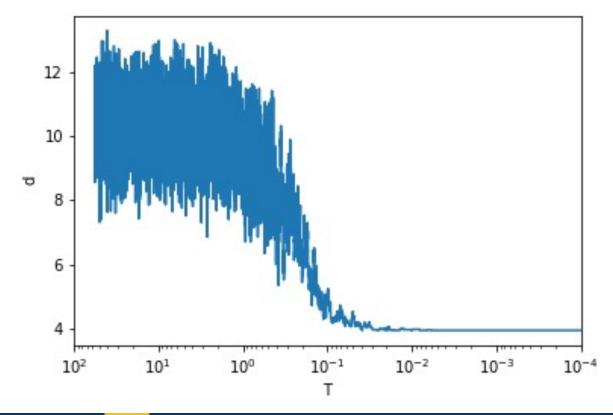


# Simulated Annealing

- \*\*NB: Simulated annealing is a better approach to finding the global minimum, but it is not guaranteed to do so.
- Some extra tips:
- Restarting: Restart the annealing process from previous minimum value, possibly with a different temperature etc.
- Run several chains: Method may still get stuck in local minima: It finds a good solution, not necessarily the best.
- Some adaption for initial T: Generate an initial state, try N moves, if >= 80% rejected, increase T.

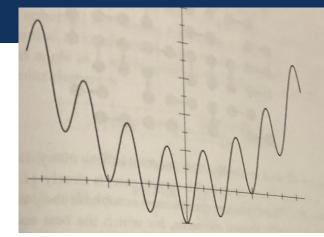
# Simulated Annealing

 You can monitor your function value during the process: How well does our cooling function work?



# Simulated Annealing for a function

- This is Q3 from Assignment 3 (Newman 10.10).
- Differences:
  - Choice of  $T_0$  and  $\tau$
  - Finding x<sub>i</sub> from x<sub>i</sub>:
    - chose a random number,  $\delta$ , on Norm(x=0, $\sigma$ ).
    - Let  $x_i = x_i + \delta$
  - Function is given rather than dependent on the state.
  - Not guaranteed to get global minimum.
- Questions?



## Back to Bayesian Inference

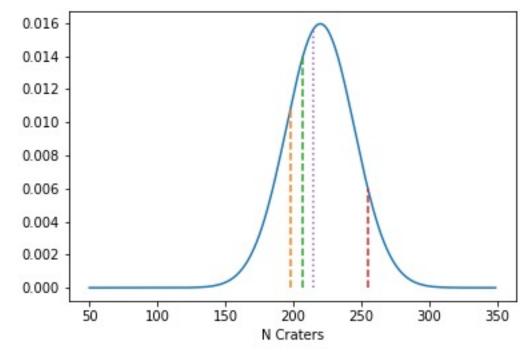
- As seen previously: Bayes theorem is:
- Posterior =  $\frac{\text{Likelihood} * \text{Prior}}{\text{Marginal Likelihood}} \rightarrow P(\boldsymbol{\theta}|D)d\boldsymbol{\theta} = \frac{P(D|\boldsymbol{\theta})P(\boldsymbol{\theta})d\boldsymbol{\theta}}{\int P(D|\boldsymbol{\theta})P(\boldsymbol{\theta})d\boldsymbol{\theta}}$
- MCMC allows you to sample the distributions with importance sampling.
- Essentially this allows you to approximately integrate complex probability functions in high-dimensional parameter space.

## Bayesian Inference quick example

- You're estimating the age of a region of Mars. You do this by crater counting (more craters means geologically older).
- A computer algorithm can look at a picture very quickly and count the number of craters, but it's fairly in accurate.
   Correct within 20%, 95% of the time.
- Humans are usually more accurate (say correct within 5%, 95% of the time), so you verify the number by having three students count by hand.
- Computer: There are 215 craters.
- Humans: There are {198, 207, 255} craters.

#### Example

- Without Bayes' and ignoring the computer:
  - $\langle N \rangle = 1/3(198 + 207 + 255) = 220.$
  - $\sigma(N) = (1/3 [(198-220)^2 + (207-220)^2 + (255-220)^2])^{1/2} = 25.$
  - So Expect 220 +- 25.
  - Gives P(N<sub>crater</sub> | Human Data)
- Can we do better?



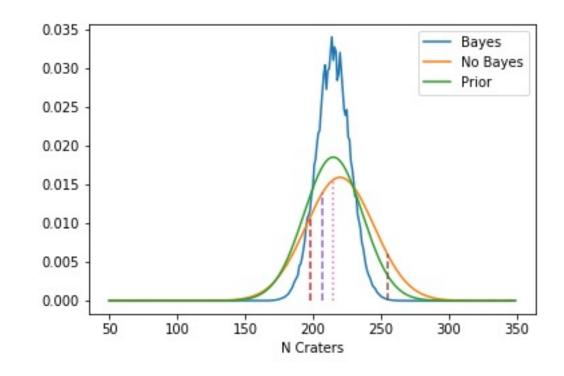
## Example

• Prior:  $P(\theta)$ = Computer has 215 +- 22.

•  $P(D|\theta) = P(D_1|\theta) * P(D_2|\theta) * P(D_3|\theta)$ 

•  $P(x | \theta) = normal(\theta, \sigma, x)$ 

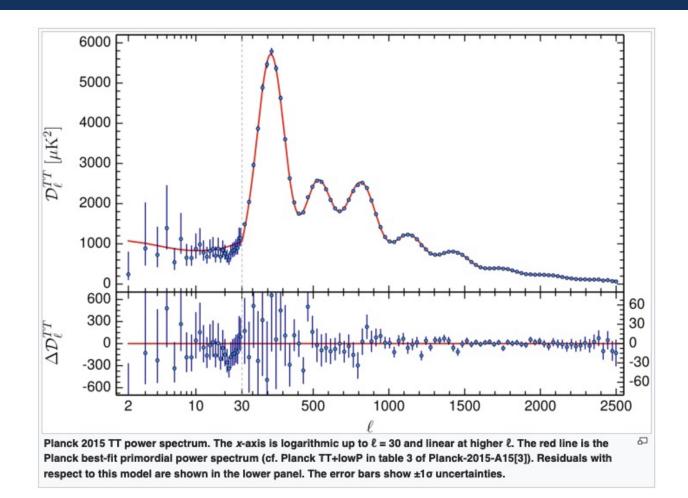
• P(D) = normalization

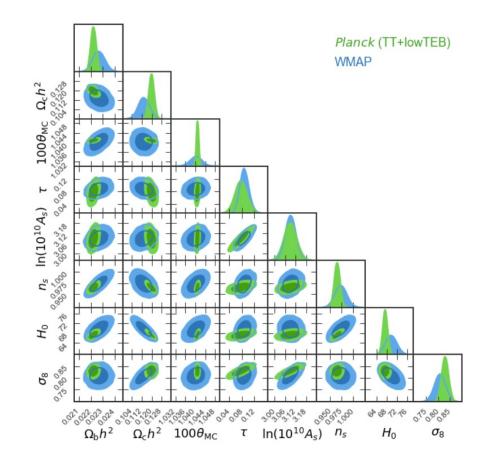


#### Another Example

- Example: A galaxy's star formation rate and metallicity can be determined by looking at specific nebular emission lines.
  - What are the:
    - Data, D?
    - Parameters, **θ**?
    - Priors?
    - Likelihood?
    - Nuisance parameters?

# E.g., Planck Data





# Machine Learning

- Broadly speaking:
  - An automatic system to learn, improve, optimize, and/or characterize data without being explicitly programmed to do so in a particular way.
- Common examples/uses:
  - Image classification: Hand writing, facial recognition, crater counting, Animal recognition etc.
  - SNe and other transient identification (visual, audio, etc.)
  - Diagnosis
- Given how quick humans are for some classification, it's surprising how hard it is to program such a process.

# Machine Learning

 In the 60s, Marvin Minsky assigned a couple of undergrads to spend the summer programming a computer to use a camera to identify objects in a scene. He figured they'd have the problem solved by the end of the summer. Half a century later, we're still working on it.



IN CS, IT CAN BE HARD TO EXPLAIN THE DIFFERENCE BETWEEN THE EASY AND THE VIRTUALLY IMPOSSIBLE.

xkcd

# Machine Learning: Unsupervised vs Supervised

- Supervised: You have training data that is already characterized, and you use this data train your machine learning program to characterize input data.
- Supervised: Typically done with Neural Networks. We will mostly look at these.
- Examples: Classification (Dog or Cat? Chihuahua or Muffin), Regression (result of a bunch of data; e.g., stock market or stellar mass, etc.)

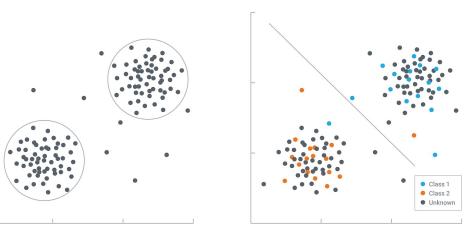
Chihuahua or Muffin?

# Machine Learning: Unsupervised vs Supervised

- Unsupervised: Finds features, clusters, or associations in a dataset. Typically exploring high-dimensional dataspace where visually characterizing the data is difficult for humans.
- Here there is no clear answer (at least not one known in advance)

• Unsupervised: Commonly principal component analysis & cluster

analysis.



# Other machine learning

- Reinforcement learning: Determine a transition process (e.g., in a Markov Chain) to maximize a reward measure.
- Genetic Algorithms: Sometimes paired with e.g., reinforcement learning, using the ideas of genetic offspring to let successful models procreate and create new ones e.g., <a href="https://rednuht.org/genetic\_cars\_2/">https://rednuht.org/genetic\_cars\_2/</a>
- Semi-supervised: Mix of supervised (known answers) and unsupervised.

#### QSSETs

- Expires April 4
- Sorry that it's early.
- Please do fill it in!

#### Next time:

- More Machine Learning
- Conclusion of the course
- Logistics for the presentations