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# **Computer Graphics**

## **1 - Lab: Environment Setting for Lectures - Introduction to NumPy**

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# Topics Covered

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- Why Python in this Computer Graphics class?
- Python 2 & Python 3
- Installing Python Interpreter & Additional Modules
- Running Python Interpreter
- Introduction to NumPy

# Why Python?

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- Productivity
  - Easy to learn.
  - You can write code much faster.
  - You can focus on "logic", not language-specific issues.
- Powerful modules
  - A wide range of reliable modules are available.
  - NumPy for scientific computing, matplotlib for data visualization, ...
- **Python allows you to implement key computer graphics concepts**

# Why Python?

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- Popular in the research communities
  - Most ML / DL frameworks provide Python APIs.
    - TensorFlow, PyTorch, Keras, Theano, ...
  - Most game engines and physics engines also provide Python APIs.
- **Python allows you to**

# Install Python Interpreter

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- Python 3.5 or later
  - <https://www.python.org/downloads/>
- Note that all submissions for assignments should work in Python 3.5.
- You can use any OS that runs Python3

# Python 2 & Python 3

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- Python 2 is still in active use.
- Python 3 is rapidly gaining popularity especially in the research communities.
  - A lot of very useful features & fixes for well-known problems
  - To do this, **Python 3 breaks backward compatibility**.
- If you're familiar with Python 2, you only need to know the differences between Python 2 and 3.
  - The following link would be helpful:
  - [http://sebastianraschka.com/Articles/2014\\_python\\_2\\_3\\_key\\_diff.html](http://sebastianraschka.com/Articles/2014_python_2_3_key_diff.html)  
[http://sebastianraschka.com/Articles/2014\\_python\\_2\\_3\\_key\\_diff.html](http://sebastianraschka.com/Articles/2014_python_2_3_key_diff.html)

# Install Additional Modules

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- We'll use a few python modules in this class
  - NumPy, PyOpenGL, glfw
- My recommendation for installing python modules is using **pip** (Python Package Index)

- NumPy

- Windows
- Ubuntu

```
> python3 -m pip install numpy
```

```
# if you don't have pip, install it first.  
$ sudo apt-get install python3-pip  
  
$ python3 -m pip install numpy
```

# Install Additional Modules

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- PyOpenGL
  - Windows
    - Download proper *PyOpenGL-3.1.2-cp3x-cp3xm\_xxx.whl* for your system from <https://www.lfd.uci.edu/~gohlke/pythonlibs/#pyopengl>

```
> py -3 -m pip install PyOpenGL<version in your file>.whl
```

–

```
$ python3 -m pip install PyOpenGL
```



# Install Additional Modules

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- GLFW
  - Windows

```
> py -3 -m pip install glfw
```

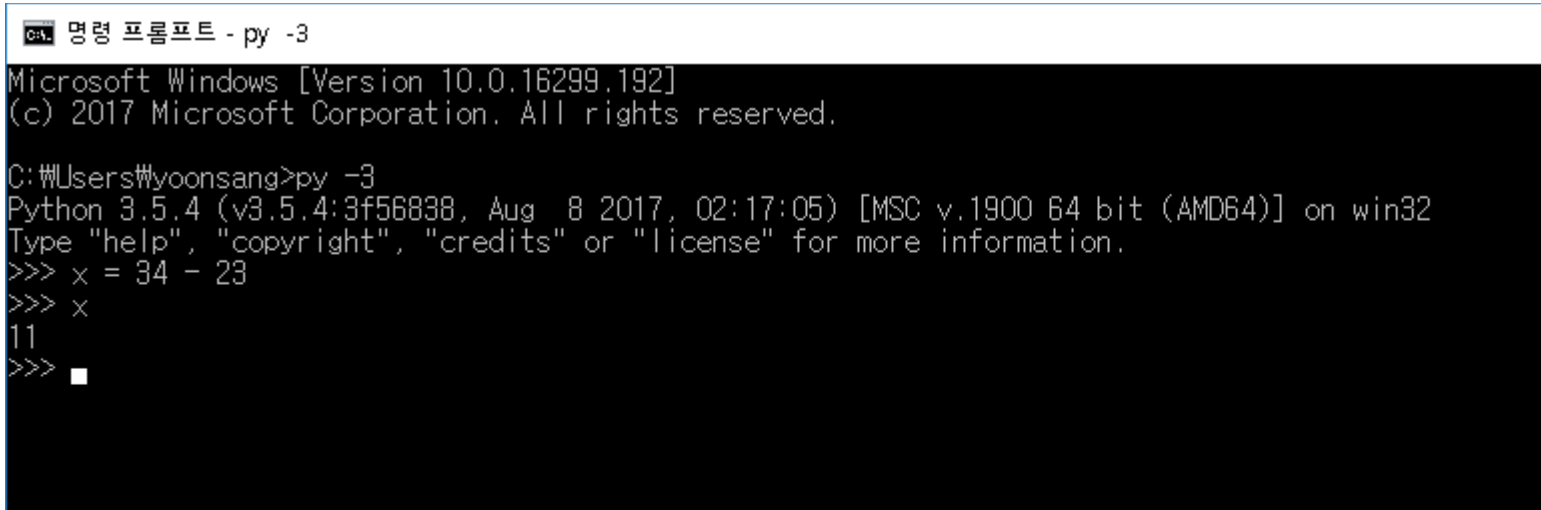
- Ubuntu

```
$ sudo apt-get install libglfw3  
$ python3 -m pip install glfw
```

# Running Python Interpreter 1

- **Interactive mode**

- Windows: Start, type “cmd”, `> py -3`
- Ubuntu: Start, type “terminal”, `$ python3`
- Suitable for simple tests
- To exit the interpreter, type `exit()` and press enter key.



```
명령 프롬프트 - py -3
Microsoft Windows [Version 10.0.16299.192]
(c) 2017 Microsoft Corporation. All rights reserved.

C:\Users\Wyoonsang>py -3
Python 3.5.4 (v3.5.4:3f56838, Aug  8 2017, 02:17:05) [MSC v.1900 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license" for more information.
>>> x = 34 - 23
>>> x
11
>>> ■
```

# Running Python Interpreter 2

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- Non-interactive mode (runs a source file)
  - Windows `> py -3 test.py`
  - Ubuntu `$ python3 test.py`
  - In most cases, you will use this mode.
- You can write a Python source file using your favorite editor.
  - Vim, Notepad++, Sublime Text, Atom, IDLE ...
  - I'm personally using vim & gvim

# Python References

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- <https://docs.python.org/ko/3/tutorial/index.html>
- <https://docs.python.org/3/tutorial/index.html>
- <https://www.tutorialspoint.com/python3/>

# Introduction to NumPy

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- What is NumPy?
  - How to use NumPy
  - Handling vectors & matrices using NumPy

# What is NumPy?

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- NumPy is a Python module for scientific computing.
  - Written in C
  - Fast vector & matrix operations
- NumPy is **de-facto standard** for numerical computing in Python.
- Very useful for computer graphics applications, which are made of vectors & matrices.

# NumPy usage

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- Now, let's launch python3 interpreter in the interactive mode and import numpy like this:
- The following NumPy slides are from:
  - <https://github.com/enthought/Numpy-Tutorial-SciPyConf-2017/blob/master/slides.pdf>

```
>>> import numpy as np
```

: use 'np' as the local name for the module numpy

# Introducing NumPy Arrays

## SIMPLE ARRAY CREATION

```
>>> a = np.array([0, 1, 2, 3])  
>>> a  
array([0, 1, 2, 3])
```

## CHECKING THE TYPE

```
>>> type(a)  
numpy.ndarray
```

## NUMERIC "TYPE" OF ELEMENTS

```
>>> a.dtype  
dtype('int32')
```

## NUMBER OF DIMENSIONS

```
>>> a.ndim  
1
```



# Array Operations

## SIMPLE ARRAY MATH

```
>>> a = np.array([1, 2, 3, 4])
>>> b = np.array([2, 3, 4, 5])
>>> a + b
array([3, 5, 7, 9])

>>> a * b
array([ 2,  6, 12, 20])

>>> a ** b
array([ 1,  8, 81, 1024])
```



NumPy defines these constants:  
 $\pi = 3.14159265359$   
 $e = 2.71828182846$

```
# multiply entire array by
# scalar value
```

```
>>> 0.1 * a
array([0.1, 0.2, 0.3, 0.4])
```

```
# in-place operations
```

```
>>> a *= 2
>>> a
array([2, 4, 6,
      8])
```

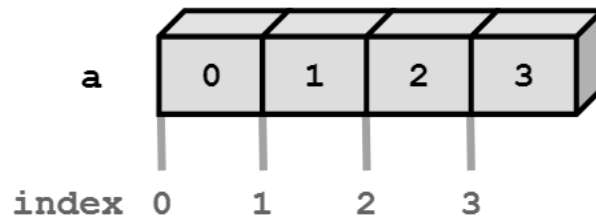
```
# apply functions to array
```

```
>>> x = 0.1*a
>>> x
array([0.2, 0.4, 0.6, 0.8])
>>> y = np.sin(x)
>>> y
array([0.19866933, 0.38941834,
      0.56464247, 0.71735609])
```

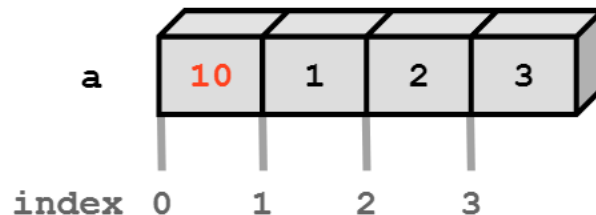
# Setting Array Elements

## ARRAY INDEXING

```
>>> a[0]
0
```



```
>>> a[0] = 10
>>> a
array([10, 1, 2, 3])
```



## BEWARE OF TYPE COERCION

```
>>> a.dtype
dtype('int32')
```

```
# assigning a float into
# an int32 array truncates
# the decimal part
```

```
>>> a[0] = 10.6
>>> a
array([10, 1, 2, 3])
```

**Numpy array: All elements have the same type and the size.**



**Python list: Elements can have various sizes and types.**

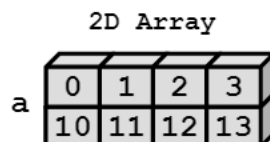
# Multi-Dimensional Arrays

## MULTI-DIMENSIONAL ARRAYS

```
>>> a = np.array([[ 0, 1, 2, 3],
...               [10,11,12,13]])
```

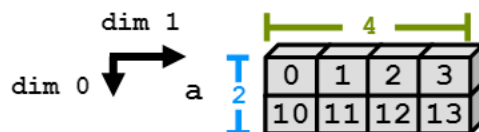
```
>>> a
```

```
array([[ 0,  1,  2,  3],
       [10, 11, 12, 13]])
```



## SHAPE = (ROWS, COLUMNS)

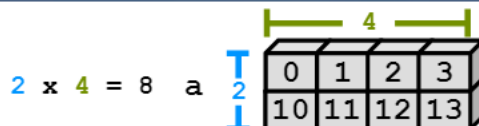
```
>>> a.shape
(2, 4)
```



# Shape returns a tuple  
# listing the length of the  
# array along each dimension.

## ELEMENT COUNT

```
>>> a.size
8
```



## NUMBER OF DIMENSIONS

```
>>> a.ndim
2
```



## GET / SET ELEMENTS

```
>>> a[1, 3]
```

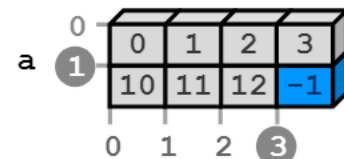
```
13
```



```
>>> a[1, 3] = -1
```

```
>>> a
```

```
array([[ 0,  1,  2,  3],
       [10, 11, 12, -1]])
```



`var[lower:upper:step]`

Extracts a portion of a sequence by specifying a lower and upper bound.  
The lower-bound element is included, but the upper-bound element is **not** included.  
Mathematically:  $[lower, upper)$ . The step value specifies the stride between elements.

## SLICING ARRAYS

```
#           -5 -4 -3 -2 -1
# indices:   0  1  2  3  4
>>> a = np.array([10,11,12,13,14])
```

```
# [10, 11, 12, 13, 14]
>>> a[1:3]
array([11, 12])
```

```
# negative indices work also
>>> a[1:-2]
array([11, 12])
>>> a[-4:3]
array([11, 12])
```

## OMITTING INDICIES

```
# omitted boundaries are
# assumed to be the beginning
# (or end) of the list
```

```
# grab first three elements
>>> a[:3]
array([10, 11, 12])
```

```
# grab last two elements
>>> a[-2:]
array([13, 14])
```

```
# every other element
>>> a[::2]
array([10, 12, 14])
```

# Array Slicing

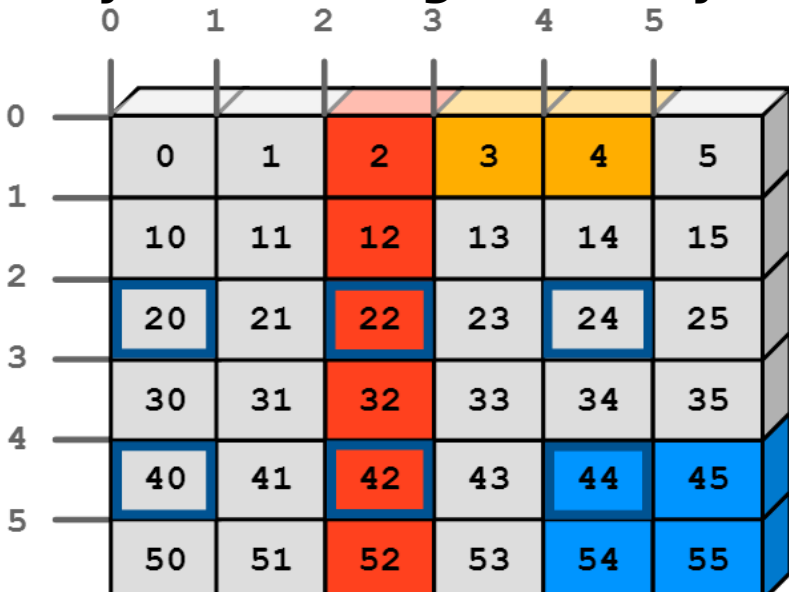
## SLICING WORKS MUCH LIKE STANDARD PYTHON SLICING

```
>>> a[0, 3:5]
array([3, 4])
```

```
>>> a[4:, 4:]
array([[44, 45],
       [54, 55]])
```

```
>>> a[:, 2]
array([2, 12, 22, 32, 42, 52])
```

```
a = np.array([[i+10*j for i in range(6)] for j in range(6)])
```



	0	1	2	3	4	5
0	0	1	2	3	4	5
1	10	11	12	13	14	15
2	20	21	22	23	24	25
3	30	31	32	33	34	35
4	40	41	42	43	44	45
5	50	51	52	53	54	55

## STRIDED ARE ALSO POSSIBLE

```
>>> a[2::2, ::2]
array([[20, 22, 24],
       [40, 42, 44]])
```

# Array Constructor Examples

## FLOATING POINT ARRAYS

```
# Default to double precision
>>> a = np.array([0, 1.0, 2, 3])
>>> a.dtype
dtype('float64')
>>> a.nbytes
32
```

## REDUCING PRECISION

```
>>> a = np.array([0, 1., 2, 3],
...               dtype='float32')
>>> a.dtype
dtype('float32')
>>> a.nbytes
16
```

# Array Creation Functions

## IDENTITY

$n \times n$  square matrix with ones on the main diagonal and zeros elsewhere.

```
# Generate an n by n identity
# array. The default dtype is
# float64.
```

```
>>> a = np.identity(4)
>>> a
array([[ 1.,  0.,  0.,  0.],
       [ 0.,  1.,  0.,  0.],
       [ 0.,  0.,  1.,  0.],
       [ 0.,  0.,  0.,  1.]])
```

```
>>> a.dtype
dtype('float64')
>>> np.identity(4, dtype=int)
array([[ 1,  0,  0,  0],
       [ 0,  1,  0,  0],
       [ 0,  0,  1,  0],
       [ 0,  0,  0,  1]])
```

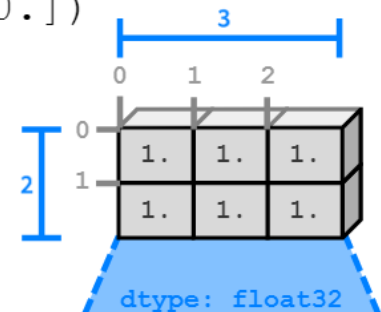
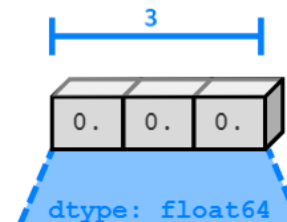
## ONES, ZEROS

```
ones(shape, dtype='float64')
zeros(shape, dtype='float64')
```

*shape* is a number or sequence specifying the dimensions of the array. If **dtype** is not specified, it defaults to **float64**.

```
>>> np.ones((2, 3),
...          dtype='float32')
array([[ 1.,  1.,  1.],
       [ 1.,  1.,  1.]])
dtype=float32)
```

```
>>> np.zeros(3)
array([ 0.,  0.,  0.]])
```



`zeros(3)` is equivalent to `zeros((3, ))`

# Array Creation Functions (cont'd)

## Linspace

```
# Generate N evenly spaced
# elements between (and including)
# start and stop values.
>>> np.linspace(0, 1, 5)
array([0., 0.25., 0.5, 0.75, 1.0])
```

## Arange

```
arange([start,] stop[, step],
       dtype=None)
```

- Nearly identical to Python's range()
- Creates an array of the interval including *start* but **excluding stop**
- When using a **non-integer step**, the results will **often not be consistent due to finite machine precision**. It is **better to use linspace()** for this case.

```
>>> np.arange(4)
array([0, 1, 2, 3])
```

```
>>> np.arange(1.5, 2.1, 0.3)
array([ 1.5, 1.8, 2.1])
```



# Transpose

## TRANSPOSE

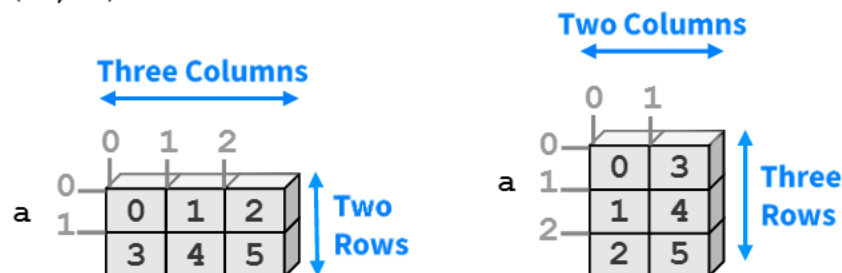
```
>>> a = np.array([[0,1,2],  
...               [3,4,5]])
```

```
>>> a.shape  
(2,3)
```

# Transpose swaps the order  
# of axes.

```
>>> a.T  
array([[0, 3],  
       [1, 4],  
       [2, 5]])
```

```
>>> a.T.shape  
(3,2)
```



# Reshaping Arrays

## RESHAPE

```
>>> a = np.array([[0,1,2],  
...               [3,4,5]])
```

# Return a new array with a  
# different shape (a view  
# where possible)

```
>>> a.reshape(3,2)  
array([[0, 1],  
       [2, 3],  
       [4, 5]])
```

# Reshape cannot change the  
# number of elements in an  
# array

```
>>> a.reshape(4,2)
```

ValueError: total size of new  
array must be unchanged

# Vector & Matrix with NumPy

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- Vectors are just 1d arrays:

```
>>> v = np.arange(3)
>>> v
array([0, 1, 2])
```

- Matrices are just 2d arrays:

```
>>> M = np.arange(9).reshape(3,3)
>>> M
array([[0, 1, 2],
       [3, 4, 5],
       [6, 7, 8]])
```

# Matrix & Vector Multiplication

---

- `*` is an element-wise multiplication operator.

```
>>> v * v
array([0, 1, 4])
>>> M * M
array([[ 0,  1,  4],
       [ 9, 16, 25],
       [36, 49, 64]])
```

- Not so much used in computer graphics.

# Matrix & Vector Multiplication

- *@* is a *matrix multiplication operator*.

```
>>> v @ v
5
>>> M @ M
array([[ 15, 18, 21],
       [ 42, 54, 66],
       [ 69, 90, 111]])
>>> M @ v
array([ 5, 14, 23])
```

- Very often used in computer graphics!

# Matrix & Vector Multiplication

- Matrix multiplication requires "dot product" (inner product in Euclidian space)

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \times \begin{bmatrix} 7 & 8 \\ 9 & 10 \\ 11 & 12 \end{bmatrix} = \begin{bmatrix} 58 \\ \end{bmatrix}$$

The "Dot Product" is where we **multiply matching members**, then sum up:

$$(1, 2, 3) \cdot (7, 9, 11) = 1 \times 7 + 2 \times 9 + 3 \times 11 \\ = 58$$