



# Microprocessor

## 1<sup>st</sup> Week: Introduction

# syllabus.1

1. Professor : Yongjun Park (박영준 교수님)  
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e-mail : [wowow11111@naver.com](mailto:wowow11111@naver.com)
2. 4 absence -> F grade (maybe)
3. 75% Lecture class, 25% Practice class

## syllabus.2

4. Homework every week, (will be submitted via GitLab)  
Homework proves your attendance (Correctness is not graded😊)
5. Slides and Lectures will be uploaded on Blackboard every week  
(portal.hanyang.ac.kr)
6. For this semester, there will be no actual class using demo boards. Videos will be provided.

# microcontroller.microprocessor

- ◆ Small, integrated processors
- ◆ Universal use due to high performance
  - 64-bit high performance microprocessor released
- ◆ Evolution of microprocessors
  - Developed 4-bit microprocessor 4004 (Intel, 1971)
  - 8-bit microprocessor development
    - Intel: 8008 (1972), 8080 (1974), 8085 (1976)
    - Motorola: MC6800 (1947), MC6805 (1976), MC6809 (1977)
    - Zilog: Z80 (1976)
  - 8, 16, 32, 64-bit microprocessor development
    - Intel: 80186, 20286, 80386, 80486, Pentium ...
    - Motorola: 68000, 68020, 68040, 68060 ...

# microcontroller.microcontroller

- ◆ Various components are integrated for intelligence and miniaturization.
  - Micro-processor Core
  - Memory (Size, Type, etc.)
  - Peripheral Devices
  - I / O Ports
- ◆ Evolution of Microcontrollers
  - Developed TI (Texas Instruments) TMS1000 (1975)
  - Intel 8-bit M / C 8048 (MCS-48), Motorola 8-bit MC6801 (1976)
  - Intel 8-bit M / C 8051 (MCS-51) (1980)
  - Intel 16-bit MCS-96 (1982)
  - Intel 32-bit M / C 80960 (1988)

## microcontroller.characteristic

- ◆ Enhanced Input/Output (I/O) capability for peripheral sensing and control
- ◆ Built-in Timer/Counter, communication port
- ◆ Interrupt processing
- ◆ Bit manipulation ability
- ◆ Smaller & lighter
- ◆ Low Cost
  - Reduce parts, production, development cost/time
- ◆ Flexible & Scalable (with SW modification)
- ◆ Enhanced Reliability
  - Simple System
  - Low Failure Rate
  - Easy to Maintain

# microcontroller.application

- ◆ Industry: Motor control, robot control, process control, numerical control, toys, etc.
- ◆ Measurement: Medical instrument, oscilloscope, etc.
- ◆ Appliances: Microwave oven, gas oven, rice cooker, washing machine, etc.
- ◆ Military: missile control, Torpedo control, spacecraft induction control, etc.
- ◆ Communication: Mobile phone, modem, wired / wireless telephone, repeater, etc.
- ◆ Office: Copier, Printer, Plotter, Hard disk drive, etc.
- ◆ Automobile: ignition timing control, fuel injection control, transmission control, etc.
- ◆ Life: Electronic clock, calculator, game machine, cash register, thermostat, etc.

# microcontroller.directionOfImprovement

## ◆ High Performance

- High-performance microcontroller with 32-bit ARM Core

## ◆ Multi-function

- Multi-function microcontroller with various special functions

## ◆ Small Size

- Microcontroller for Micro-Embedded System

## ◆ Low Power

- Ultra-low-power microcontroller that can operate for a long time with a small battery

## ◆ Low Cost

- Low cost microcontrollers under \$1



# avr.characteristic.1

- ◆ RISC (Reduced Instruction Set Code) Architecture
  - Enhanced RISC Architecture
  - Register based Architecture with 32 8-bit General Purpose Registers
  - 1MIPS/MHz
- ◆ Harvard Architecture
- ◆ Very Low Power Consumption & Wide Range of Operating Voltages
  - Operating Voltages: 1.8V to 5.5V
- ◆ Various Operating Mode
- ◆ Internal Memories
  - 256KB Self-programmable instruction Flash Memory
  - 4KB data EEPROM
  - 16KB SRAM

## avr.characteristic.2

- ◆ Various Product Models

- 8 to 100 pins for Many Different Peripheral Devices

(Parallel I/O Port, Internal Clock Generator, 8/16-bit Timer/Counter, Watchdog Timer, UART, SPI, 10-bit ADC, etc.)

- ◆ Extension of Data Memory or I/O Devices

- By using The External System Bus

- ◆ Many Types of Interrupts & Processing Capability

- ◆ Free/Low Cost S/W Development Kits

- AVR Studio

- ◆ Internal ISP (In System Program) Function

## avr.types

### ◆ Tiny Series

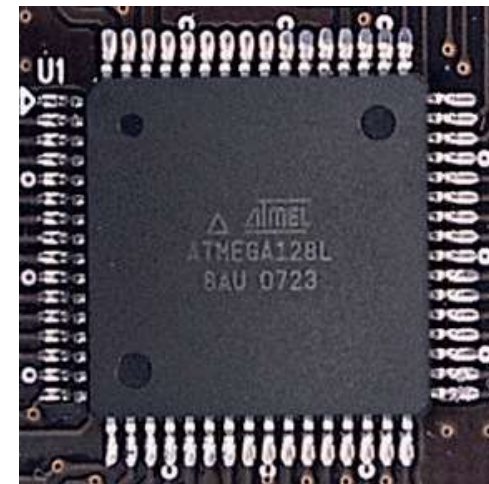
- 6~32 Pins Package
- 0.5~16KB Program Memory
- Limited Peripheral Set
- Low Speed/Performance/Cost

### ◆ Mega Series

- 28~100 Pins Package
- 4~256KB Program Memory
- Extended Instruction Set
- Extensive Peripheral Set
- High Speed/Performance/Cost

# atmega128.details

- Atmel 8-bit Microcontroller
- ◆ 32 8-bit General Purpose Registers & Peripheral Control Registers
- ◆ 6-type Sleep Modes
- ◆ 8-channel 10-bit ADC Interface
- ◆ RISC Pipeline
  - 1 Instruction per Clock Period
- ◆ Separated Bus
  - Program Memory Bus & Data Memory Bus
- ◆ Enhanced RISC Architecture (16MIPS @ 16Mhz)
  - 133 Instruction Set (in 1 Cycle)
- ◆ Programmable 128KB ISP Flash Memory
- ◆ 4KB EEPROM & 4KB SRAM
- ◆ JTAG SUPPORT



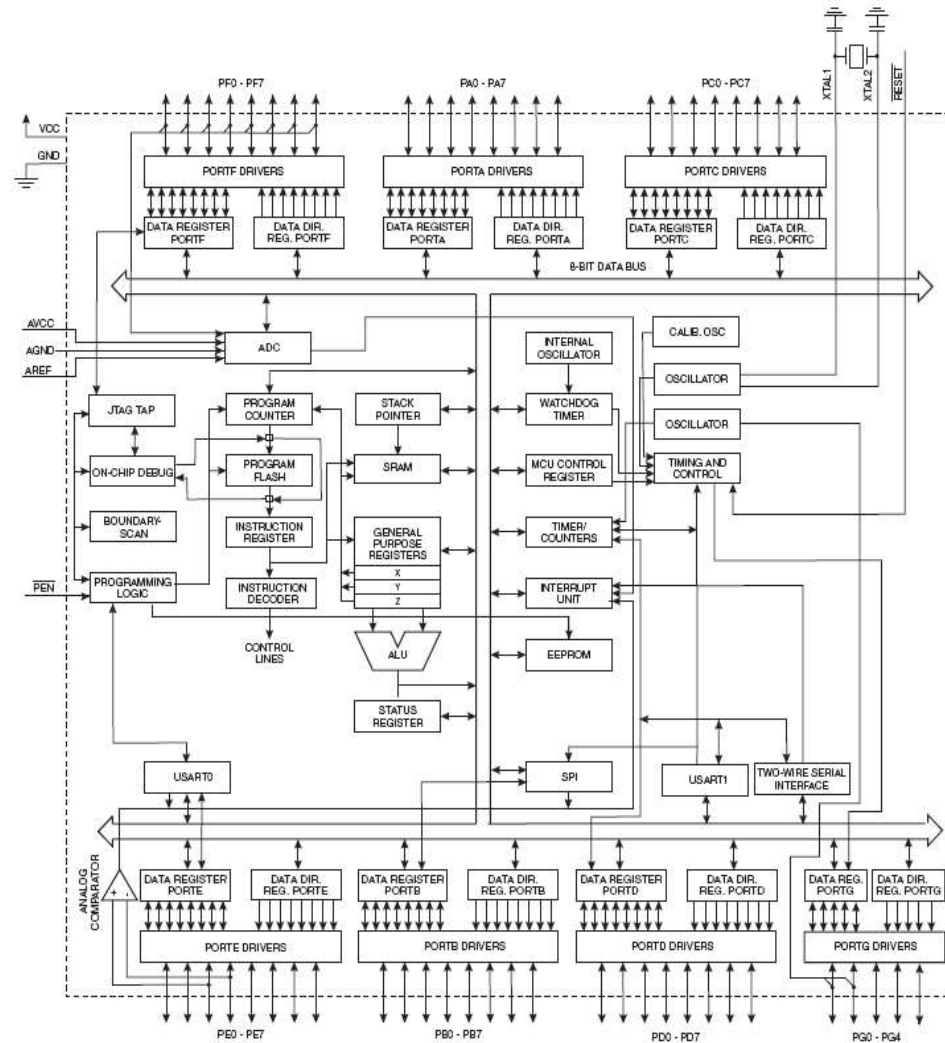
# atmega128.peripherals

- ◆ 2 8-bit Timer/Counter, 2 16-bit Timer/Counter
- ◆ 2 8-bit PWM Channels
- ◆ 6 2~16-bit Programmable PWM Channels
- ◆ 2 Extend 16-bit Timers/Counters
- ◆ Real Time Count
- ◆ Output Compare Modulator
- ◆ 8 channel, 10-bit ADC
- ◆ Two-wire Serial Interface
- ◆ 2 UARTs
- ◆ Master/Slave SPI
- ◆ Programmable Watchdog Timer
- ◆ Analog Comparator

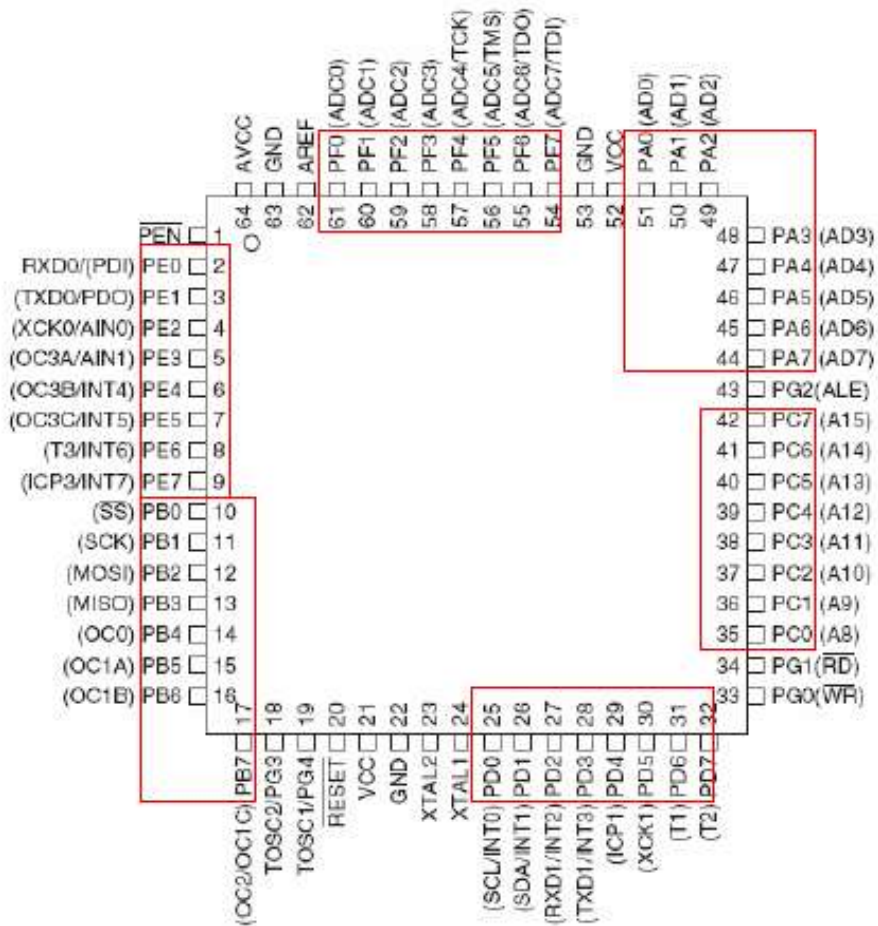
## atmega128.core

- ◆ Power-on Reset
- ◆ Programmable Brown-out Detection
- ◆ Internal Calibrated RC Oscillator
- ◆ Internal/External Interrupt Sources
- ◆ 6 Sleep Modes
- ◆ Software Selectable Clock Frequency
- ◆ Global Pull-up Disable
- ◆ 53 Programmable I/O Lines
- ◆ 64-lead TQFP and 64-pad QFN/MLF
- ◆ Operating Voltages: 2.7V ~ 5.5V
- ◆ Speeding Grades: 0 ~ 8/16Mhz

# atmega128.architecture



# atmega128.pin



## ◆ ATmega128 Packages

- 64 Pins
- TQFP or MLF
- 6 General Purpose I/O Ports



## atmega128.pin.controlSignals

- ◆ Reset (Pin 20)
- ◆ XTAL1, XTAL2 (Pin 24, Pin 23)
- ◆ Vcc (Pin 21, 51)
- ◆ GND (Pin 22, 53, 63)
- ◆ AVCC (Pin 64)
- ◆ AREF (Pin 62)
- ◆ PEN (Pin 1)

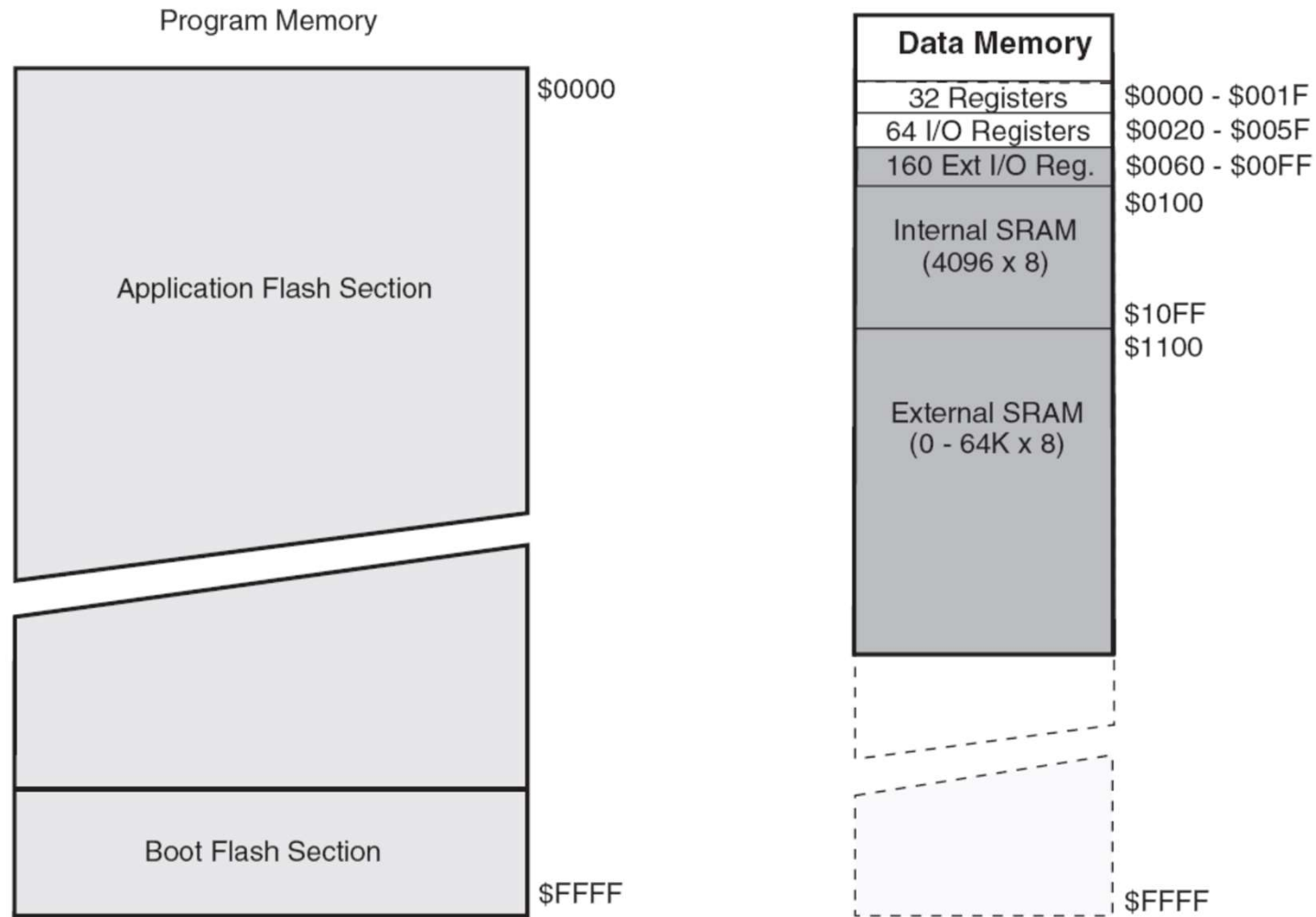
# atmega128.pin.gpioSignals

- GPIO: General Purpose I/O
- ◆ PortA (PA7 ~ PA0: Pin 44 ~ 51)
  - External Memory Address Bus (A7-A0) and Data Bus (D7-D0)
- ◆ PortB (PB7 ~ PB0: Pin 10 ~ 17)
  - SPI Port or PWM Port
- ◆ PortC (PC7 ~ PC0: Pin 35 ~ 42)
  - External Memory Address Bus (A15-A8)
- ◆ PortD (PD7 ~ PD0: Pin 25 ~ 31)
  - Timer or External Interrupt Port
- ◆ PortE (PE7 ~ PE0: Pin 2~ 9)
  - Timer, External Interrupt, Analog Analyzer, USART Port
- ◆ PortF (PF7 ~ PF0: Pin 54 ~ 61)
  - AD Converter or JTAG IF Port
- ◆ PortG (PG7 ~ PG0: Pin 19, 18, 43, 34, 33)
  - External Memory Strobe Signal, Real Time Counter Timer Oscillator

# atmega128.memoryArchitecture.1

- ◆ Harvard Architectre
- ◆ Program Memory
- ◆ Data Memory
  - RAM
    - Registers
    - SRAM: 4KB
  - ROM
    - EEPROM: 4KB
  - External Data Memory

## atmega128.memoryArchitecture.2



# atmega128.memoryArchitecture.3

- ◆ ATmega128 Program Memory
  - Internal 128KB Flash Memory
  - 16-bit Address
  - Boot Flash Section & Application Flash Section
- ◆ ATmega128 Data Memory (Register)
  - General Purpose Register
  - Special Function Register
    - I/O Registers
    - Extend I/O Registers

	7	0	Addr.	
General Purpose Working Registers	R0		\$00	
	R1		\$01	
	R2		\$02	
	...			
	R13		\$0D	
	R14		\$0E	
	R15		\$0F	
	R16		\$10	
	R17		\$11	
	...			
	R26		\$1A	X-register Low Byte
	R27		\$1B	X-register High Byte
	R28		\$1C	Y-register Low Byte
	R29		\$1D	Y-register High Byte
	R30		\$1E	Z-register Low Byte
	R31		\$1F	Z-register High Byte

## atmega128.clocks

- ◆ CPU Clock
- ◆ I/O Clock
- ◆ Flash Clock
- ◆ Asynchronous Timer Clock
- ◆ ADC Clock

# atmega128.sleepModes

- ◆ Idle Mode
- ◆ ADC Noise Reduction Mode
- ◆ Power-down Mode
- ◆ Power-save Mode
- ◆ Standby Mode
- ◆ Extended Standby Mode

## atmega128.resetModes

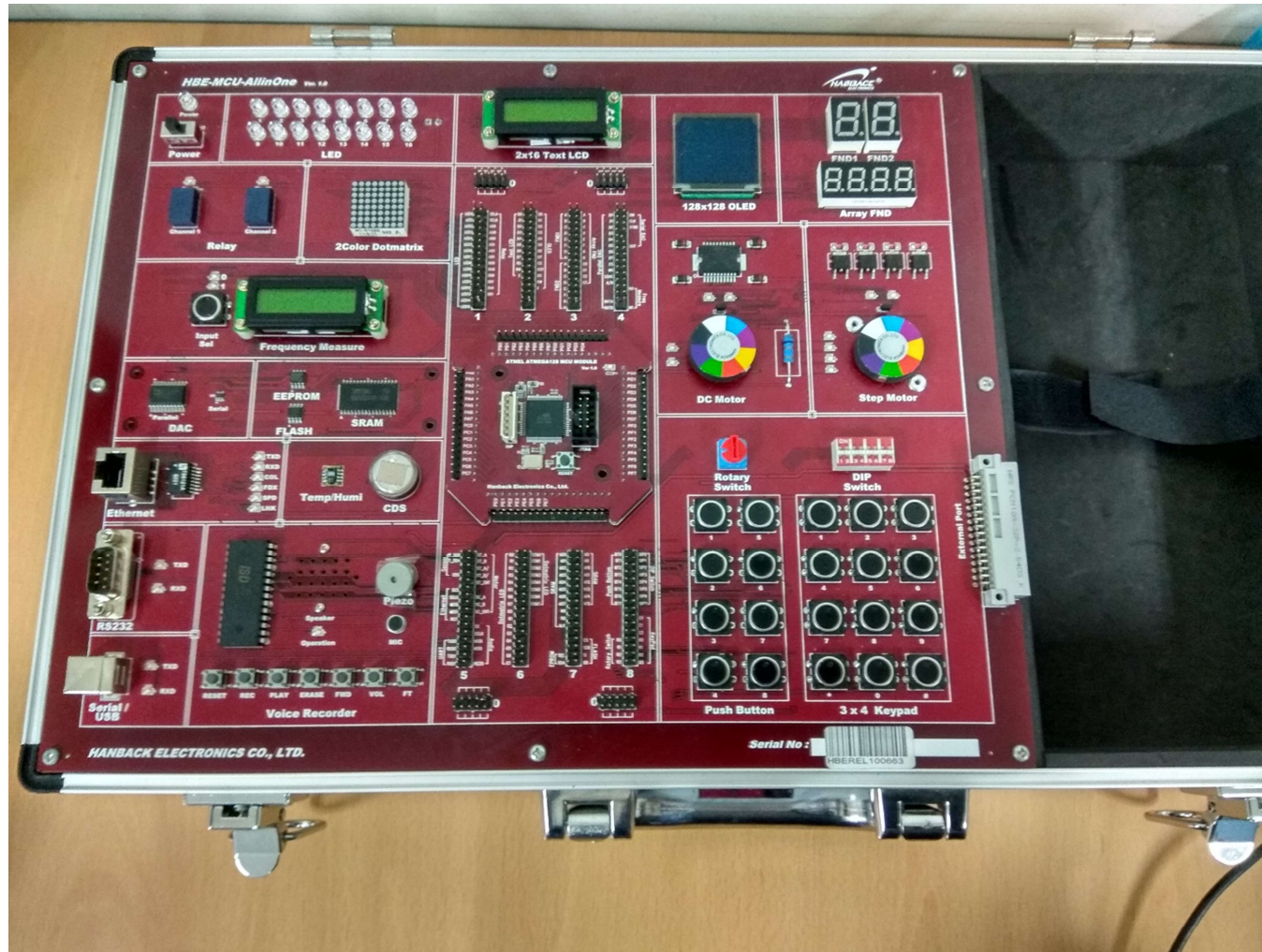
- ◆ Power-on Reset
- ◆ External Reset
- ◆ Watchdog Reset
- ◆ Brown-out Reset
- ◆ JTAG AVR Reset



# atmega128.dataSheet

<http://www.atmel.com/images/doc2467.pdf>

# atmega128



# Thank you