

# **Data Structure:**

## **Binary Search Tree**

# Binary Search Tree

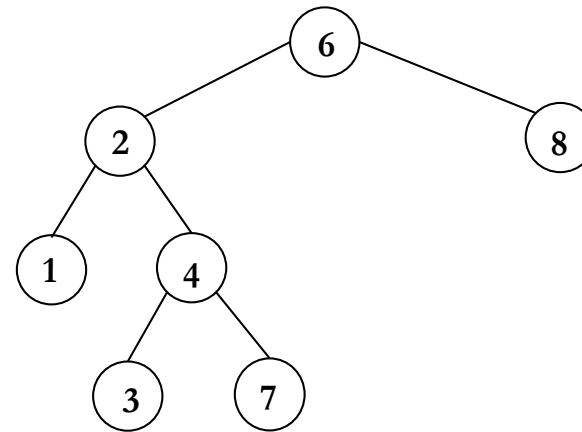
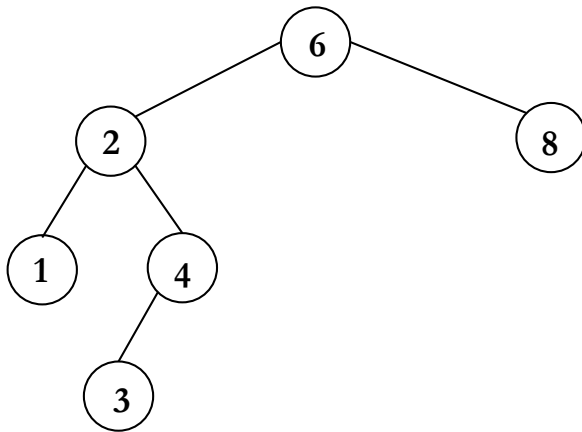
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- one of the most fundamental problems in data structure design
  - there is a set of records  $R_1, R_2, \dots, R_n$ , which are associated with distinct key values  $X_1, X_2, \dots, X_n$ , respectively.
  - given a search key  $x$ , find the record if it occurs in the set.
- for every node  $X$  in the tree,
  - the values of all the keys in its left subtree are smaller than the key value in  $X$
  - the values of all the keys in its right subtree are larger than the key value in  $X$

# Binary Search Tree

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■ which one can be the binary search tree?



# Search in a linear array

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- sequential search
  - simply store the keys in a linear array and search sequentially
  - insertion:  $O(1)$ , searching  $O(n)$
- binary search
  - searching:  $O(\log n)$ , insertion/deletion:  $O(n)$

# Binary Search Tree

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A BST ADT can process the following requests

- `insert(x,T)`:
  - insert  $x$  into  $T$
  - if  $x$  already exists, do appropriate action (e.g., do nothing, return error message, increment reference count.)
- `delete(x,T)`:
  - delete  $x$  from  $T$
  - if  $x$  does not exist, issue an error message
- `find(x,T)`: search  $x$  in  $T$   
return either `True/False` or the pointer to the record

# Binary Search Tree: data structure

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```
struct TreeNode;  
typedef struct TreeNode* SearchTree;  
typedef struct TreeNode* Node;
```

```
struct TreeNode  
{  
    ElementType Element;  
    SearchTree Left;  
    SearchTree Right;  
}
```

# Binary Search Tree: Find

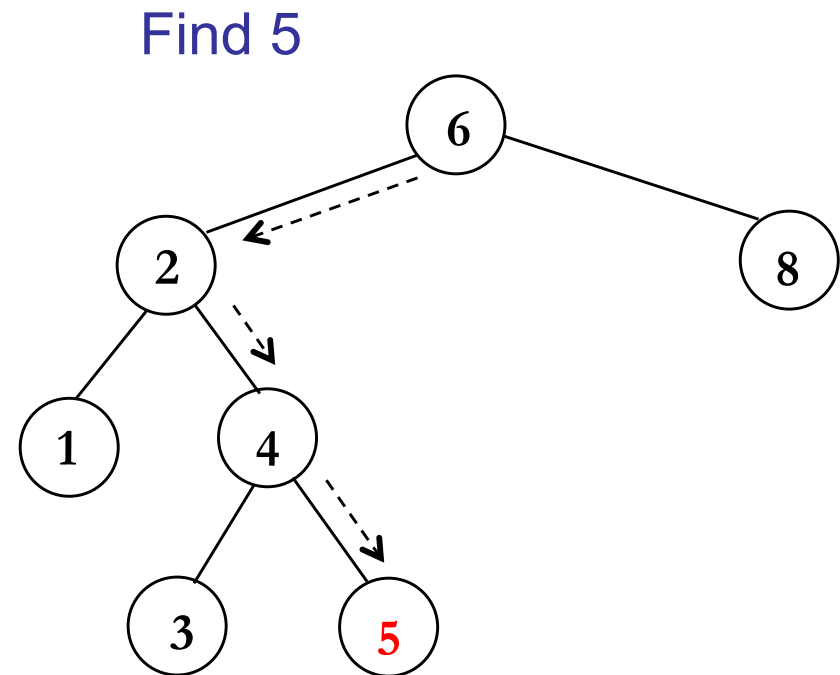
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```
Node Find( ElementType X, SearchTree T )
{
    if ( T == NULL )
        return NULL;

    if ( X < T->Element )
        return Find( X, T->Left );

    else if ( X > T->Element )
        return Find( X, T->Right );

    else /* X == T->Element */
        return T;
}
```



# Binary Search Tree: Find

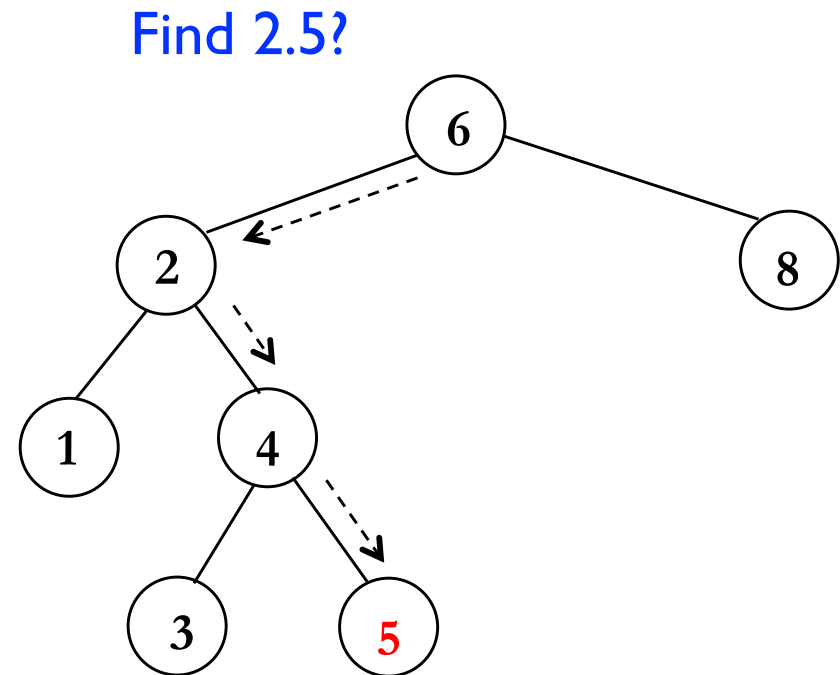
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```
Node Find( ElementType X, SearchTree T )
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    if ( T == NULL )
        return NULL;

    if ( X < T->Element )
        return Find( X, T->Left );

    else if ( X > T->Element )
        return Find( X, T->Right );

    else /* X == T->Element */
        return T;
}
```

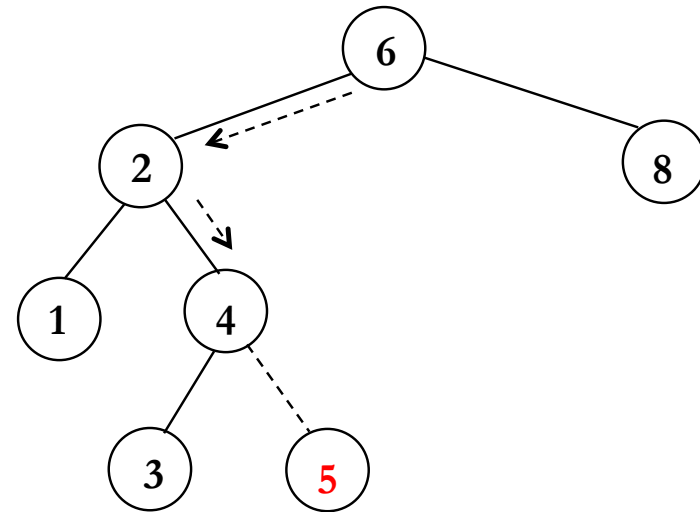
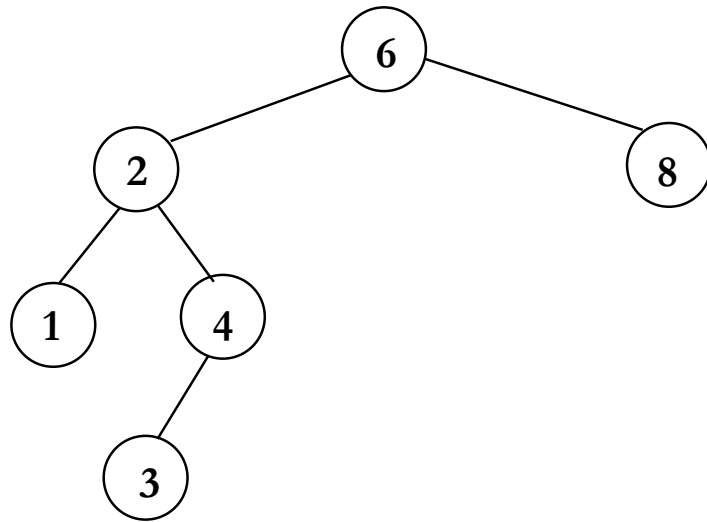




# Binary Search Tree: Insert

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insertion of 5



# Binary Search Tree: Insert

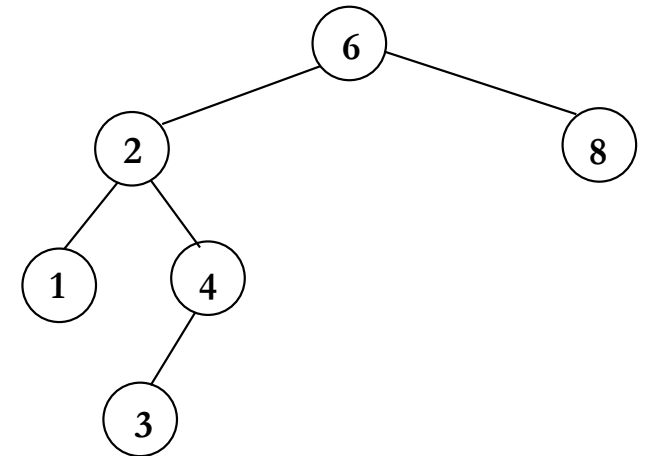
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```
SearchTree Insert ( ElementType X, SearchTree T )
{
    if( T == NULL ) {

        T = malloc( sizeof( struct TreeNode ) );
        if( T == NULL )
            FatalError( "Out of space!!!" );
        else
        {
            T->Element = X;
            T->Left = T->Right = NULL;
        }
    } else if( X < T->Element ) {
        T->Left = Insert( X, T->Left );
    } else if( X > T->Element )
        T->Right = Insert( X, T->Right );

    /* Else X is in the tree already; we'll do nothing */

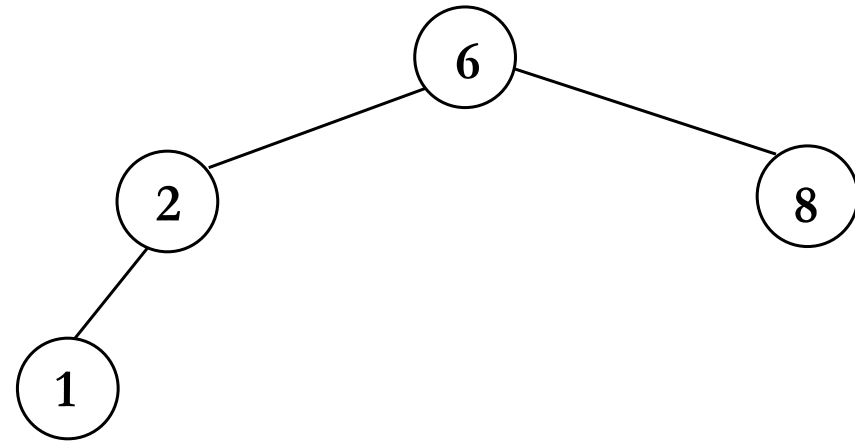
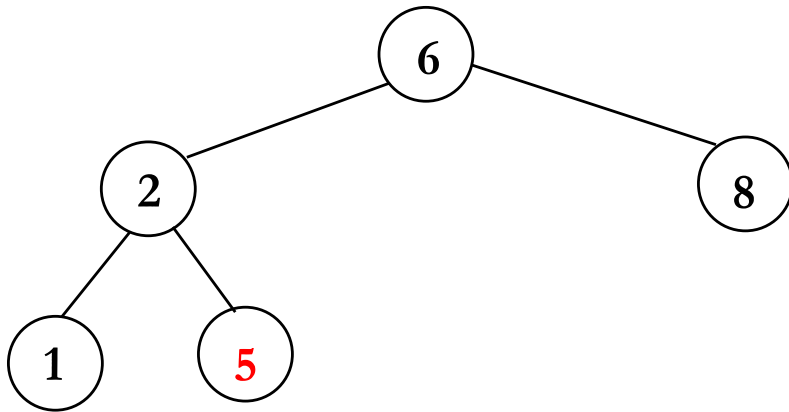
    return T; /* Do not forget this line! */
}
```



# Binary Search Tree: Delete

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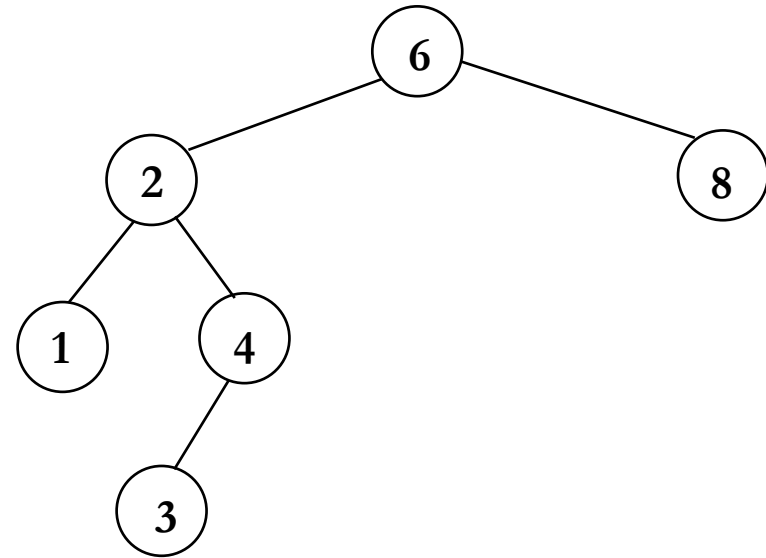
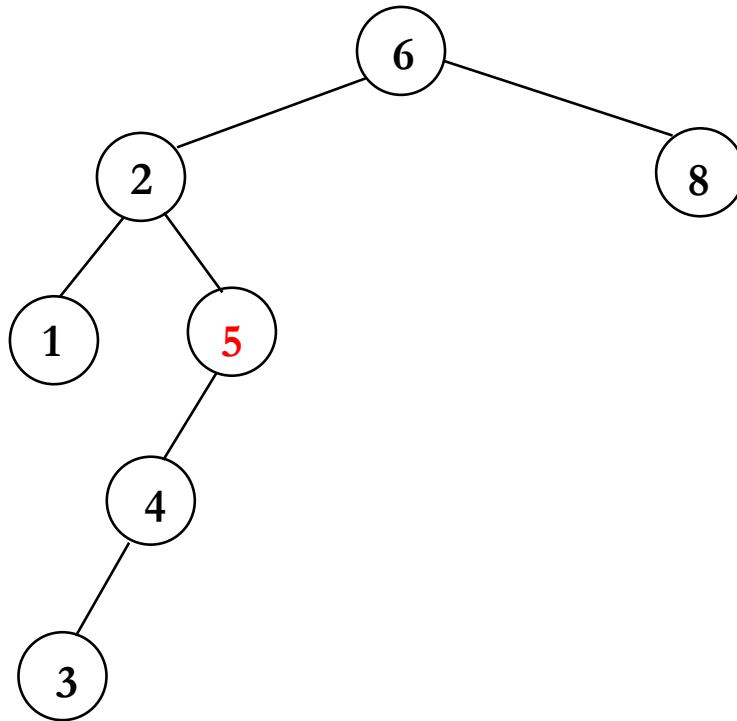
If the node to be deleted is **a leaf**, just delete it!



# Binary Search Tree: Delete

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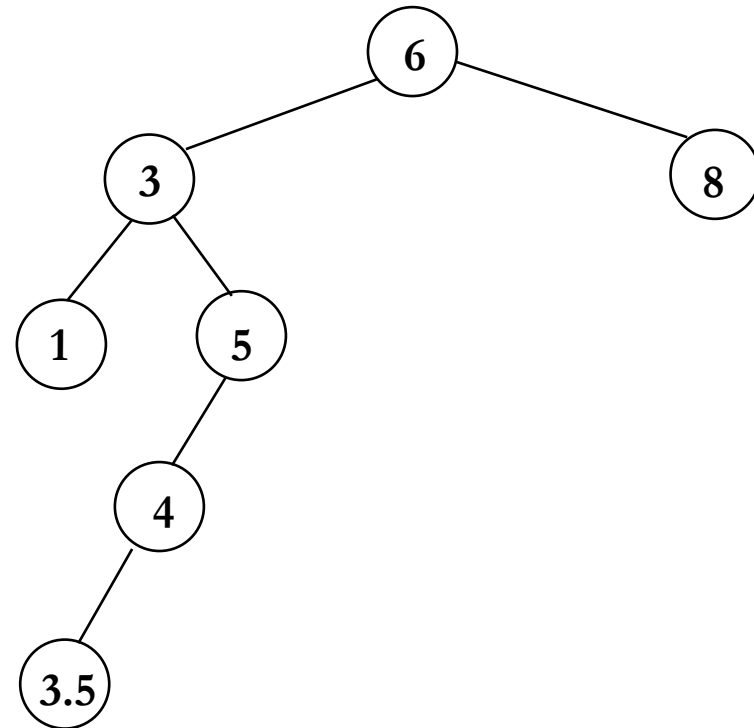
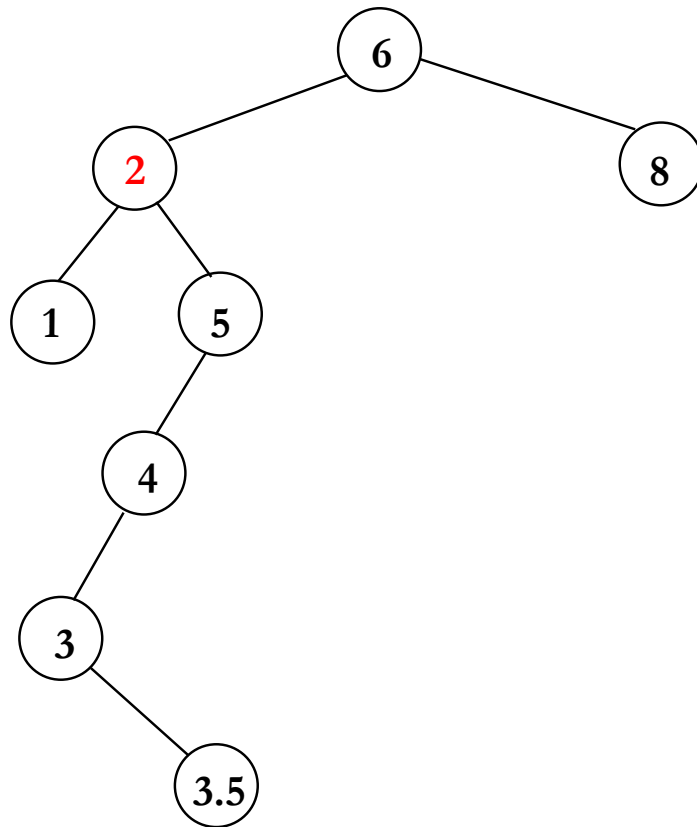
If the node to be deleted has **one child**,  
the child of the node is connected to the parent of the node



# Binary Search Tree: Delete

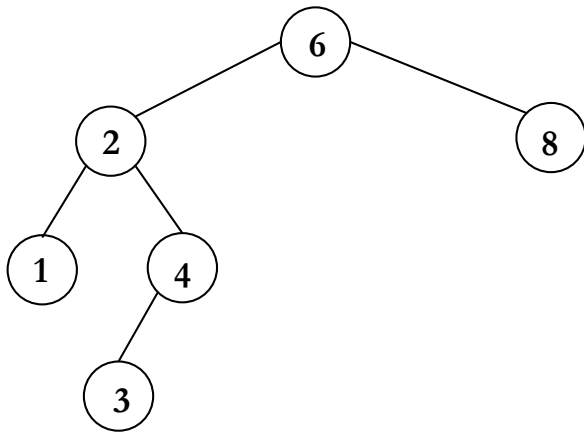
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If the node to be deleted has **both children**,  
it is replaced with the smallest node in the right subtree.



# Binary Search Tree: FindMin

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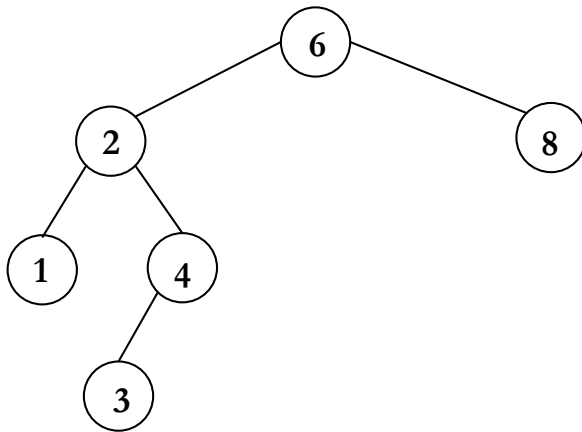
recursive implementation

```
Node FindMin( SearchTree T )  
{  
    if( T == NULL )  
        return NULL;  
  
    else if ( T->Left == NULL )  
        return T;  
  
    else /* T->Left != NULL */  
        return FindMin( T->Left );  
}
```

# Binary Search Tree: FindMax

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nonrecursive implementation



```
Node FindMax( SearchTree T )
{
    if (T == NULL)
        return NULL;

    else
        while( T->Right != NULL )
            T = T->Right;

        return T;
}
```

# Binary Search Tree: delete

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```
SearchTree Delete( ElementType X, SearchTree T )
{
    Node TmpCell;


    if ( T == NULL )
        Error( "Element not found" );

    else if ( X < T->Element )      /* Go Left */
        T->Left = Delete( X, T->Left );

    else if ( X > T->Element )      /* Go Right */
        T->Right = Delete( X, T->Right );

    else if ( T->Left && T->Right ) { /* found the node to be deleted */

        TmpCell = FindMin( T->Right );
        T->Element = TmpCell->Element;
        T->Right = Delete( T->Element, T->Right );

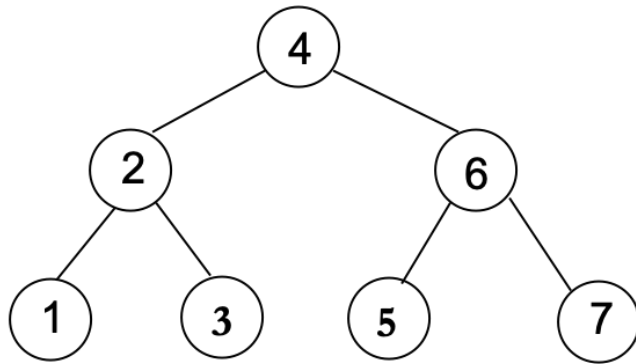
    } else {  /* 1 or 0 child */
        TmpCell = T;
        if( T->Left == NULL )
            T = T->Right;
        else if( T->Right == NULL )
            T = T->Left;
        free(TmpCell);
    }
    return T;
}
```



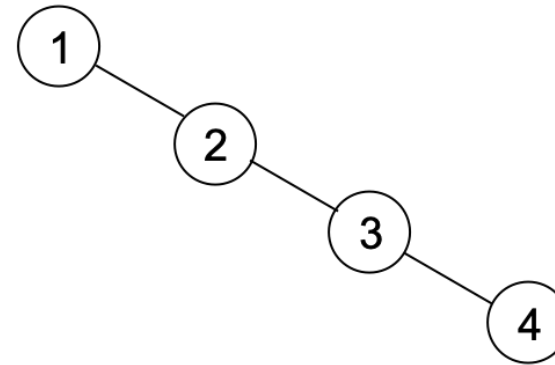
# Analysis of binary search tree

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- The runtime of `find()`, `insert()`, and `delete()` is proportional to the height of the tree.
- What is the height of the tree with  $N$  nodes?
  - Worst case: Linear tree  $O(n)$
  - Best case: Complete binary tree  $O(\log n)$



Best Case: Insert 4, 2, 6, 1, 3, 5, 7



Worst Case: insert 1, 2, 3, 4 ...

- Average case depends on the distribution of insertion/deletion
  - Assumption: insertions only
  - The order in which the keys are inserted is completely random.  
=> will average all possible  $n!$  insertion orders.

# Binary Search Tree: average-case analysis

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■ **Internal Path Length**  $D(N)$  is the sum of depths of all nodes in a binary search tree  $T$  with  $N$  nodes, which is  $O(N \log N)$

- An  $N$ -node tree consists of a root, an  $i$ -node left subtree and an  $(N - i - 1)$ -node right subtree for  $0 \leq i < N$
- let  $D(i)$  and  $D(N - i - 1)$  are internal path lengths of the left and right subtree w.r.t. their roots, respectively.

$$D(0) = D(1) = 0$$

$$D(N) = D(i) + D(N - i - 1) + N - 1$$

for the edge from the root to the root of the left and right subtree

The average value of  $D(i)$  (or  $D(N - i - 1)$ ) is  $\frac{1}{N} \sum_{j=0}^{N-1} D(j)$ :

$$D(N) = \frac{2}{N} \sum_{j=0}^{N-1} D(j) + N - 1$$

# Binary Search Tree: average-case analysis

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- **Prove**  $D(n) \leq 4n \log n, n \geq 1$ 
  - Base:  $D(1) = 0$
  - Induction: Assume that the theorem is true for  $1 \leq n \leq k-1$

$$\begin{aligned} D(k) &= \frac{2}{k} \left[ \sum_{j=1}^{k-1} D(j) \right] + k - 1 \\ &\leq \frac{2}{k} \left[ \sum_{j=1}^{k-1} 4j \log j \right] + k - 1 \\ &= \frac{8}{k} \left[ \sum_{j=1}^{k-1} j \log j \right] + k - 1 \\ &\leq \frac{8}{k} \left[ \sum_{j=1}^{\lceil k/2 \rceil - 1} j \log \left( \frac{k}{2} \right) + \sum_{j=\lceil k/2 \rceil}^{k-1} j \log k \right] + k - 1 \\ &\leq \frac{8}{k} \left[ \frac{k^2}{2} \log k - \frac{k^2}{8} \right] + k - 1 \\ &= 4k \log k - 1 \leq 4k \log k \end{aligned}$$

# Binary Search Tree: balanced binary tree

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- non-random insertion to BST can produce unbalanced trees
- can we rebalance the tree so that the tree always has  $O(\log n)$  height?
- We need *balance* information for each node.

