

# A note on observation processes in epidemic models

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July 23, 2019

## Abstract

Epidemic models provide valuable tools for understanding how a disease spreads in a population. Many epidemic models focus on characterizing the underlying transmission mechanism but make naive assumptions about how infections are reported. In this note, we use a simple deterministic Susceptible-Infected-Removed (SIR) model to compare two popular assumptions about disease incidence reports: individuals can report their infection as soon as they become infected or as soon as they recover. We show that making wrong assumptions about the underlying observation processes can result in biased estimates of the basic reproduction number and narrow confidence intervals.

## 1 Introduction

Mechanistic analyses of epidemic time series allow us to infer the underlying transmission mechanism, estimate biologically relevant parameters, and predict the course of an outbreak (Bretó et al., 2009). In order to make a precise and accurate inference, disease modelers try to build more realistic process models. For example, the same London measles time series from the prevaccination era has been analyzed using multiple models – these models account for time-varying transmission rates (Fine and Clarkson, 1982), realistic age structure (Schenzle, 1984), metapopulation structure (Xia et al., 2004), continuous-time infection process (Cauchemez and Ferguson, 2008), and extra-demographic variability (He et al., 2009).

Despite the amount of effort put into developing *better* process models, disease modelers often neglect details of the observation process associated with disease case reports. Most disease models effectively assume that new cases are reported instantaneously when an individual is infected (e.g., Martinez et al. (2016); Kennedy et al. (2018); Pons-Salort and Grassly (2018)) or develops symptom (e.g., Bhadra et al. (2011); King et al. (2015)); a few models (e.g., Bretó et al. (2009); He et al. (2009); Lin et al. (2016)) assume that infec-

tions are counted upon recovery (because diagnosed cases are controlled and are effectively no longer infectious).

Here, we use a simple Susceptible-Infected-Removed (SIR) model to study how assumptions about the underlying observation processes affect parameter estimates of the SIR model. We show that making wrong assumptions about the timing of incidence reports can lead to biases in parameter estimates and narrow confidence intervals.

## 2 Methods

The Susceptible-Infected-Removed (SIR) model describes how a disease spreads in a homogeneous population:

$$\begin{aligned}\frac{dS}{dt} &= -\beta S \frac{I}{N} \\ \frac{dI}{dt} &= \beta S \frac{I}{N} - \gamma I \\ \frac{dR}{dt} &= \gamma I,\end{aligned}\tag{1}$$

where  $\beta$  is the contact rate per unit time,  $\gamma$  is the recovery rate per unit time, and  $N = S + I + R$  is the total population size. We define incidence at time  $t$  as the number of newly infected individuals that are infected between time  $t - \Delta t$  and time  $t$ , where  $\Delta t$  is the reporting time step. We expect infected individuals to report their infection some time after their infection; the number of reported cases defines the *observed* incidence.

For brevity, we consider two extreme cases: individuals instantaneously report their infection when they become infected or when they recover. The observed incidence measured upon infection,  $i_1(t)$ , can be defined by the integral:

$$i_1(t) = \int_{t-\Delta t}^t \beta S \frac{I}{N} dt.\tag{2}$$

Alternatively, we can keep track of cumulative incidence,  $C$ , by adding a new state variable described by  $dC/dt = \beta SI/N$  and taking the difference between the two consecutive reporting periods:  $i_1(t) = C(t) - C(t - \Delta t)$ . Likewise, incidence measured upon recovery,  $i_2(t)$ , can be defined by the integral:

$$i_2(t) = \int_{t-\Delta t}^t \gamma I dt,\tag{3}$$

or by the consecutive difference in the cumulative number of recovered cases:  $i_2(t) = R(t) - R(t - \Delta t)$ . Finally, we model under-reporting using a negative binomial distribution with a mean either  $\rho i_1(t)$  or  $\rho i_2(t)$ , where  $\rho$  is the reporting rate, and an over-dispersion parameter  $\theta$ . For convenience, we will refer to these two negative binomial models as infection model and recovery model hereafter;

likewise, we will refer to epidemic time series generated from these negative binomial models as infection time series and recovery time series.

In this study, we focus on estimating 5 parameters: the basic reproductive number  $\mathcal{R}_0 = \beta/\gamma$ , mean infectious period  $1/\gamma$ , reporting rate  $\rho$ , an over dispersion parameter  $\theta$  and the initial proportion of the infected individuals  $i_0$ . Initial proportion of susceptible individuals is assumed to be  $1 - i_0$ . The total population size  $N$  is assumed to be known.

### 3 Results

First, we compare the dynamics of incidence curves,  $i_1(t)$  and  $i_2(t)$ , (Figure 1). A lag in reporting time delays the observed epidemic peak timing and reduce the size of the peak. However, these differences in the reporting time have small effect to the overall shape of the epidemic curve. In the presence of observation and process error, we would not expect to be able to distinguish between the two reporting processes.

Note that incidence is different from prevalence,  $I(t)$ , which is defined as the number of *currently* infected individuals; the dynamics of observed incidence depend on the reporting time step (because the sum of true incidence is equal to the final size of an epidemic), whereas those of prevalence do not. We expect the dynamics of incidence and prevalence to be similar only when the reporting time step is equal to the disease generation time. While it is uncommon, some models do not make a clear distinction between the two (e.g., Hooker et al. (2010)).

In order to understand how assumptions about the timing of case reporting affect parameter estimates of the SIR model, we simulate observed epidemic curves (i.e., infection time series and recovery time series), measured upon both infection and recovery, 100 times and fit both models (i.e., infection model and recovery model) to each time series. We compare the estimates of the basic reproductive number  $\mathcal{R}_0$ , and its coverage probability, defined as the proportion of confidence intervals that contain the true value (95% confidence interval is expected to contain the true value 95% of the time by definition). We summarize the results in Figure 2.

When we try to estimate all 5 parameters, fitting the recovery model to infection time series underestimates the basic reproduction number and gives a slightly low coverage (Figure 2A). Fitting the infection model to recovery time series slightly overestimates the basic reproduction number but gives good coverage. Fitting the correct models to their corresponding time series gives unbiased estimates and good coverage.

Disease modelers often assume that the mean infectious period of a disease is known and focus on estimating the basic reproduction number (e.g., Hooker et al. (2010); Lin et al. (2016); Pons-Salort and Grassly (2018)). When we assume that the mean infectious period is known and try to estimate the remaining 4 parameters of the SIR model, fitting the wrong model results in a clearer bias and a much lower coverage (Figure 2B); however, bias from fitting

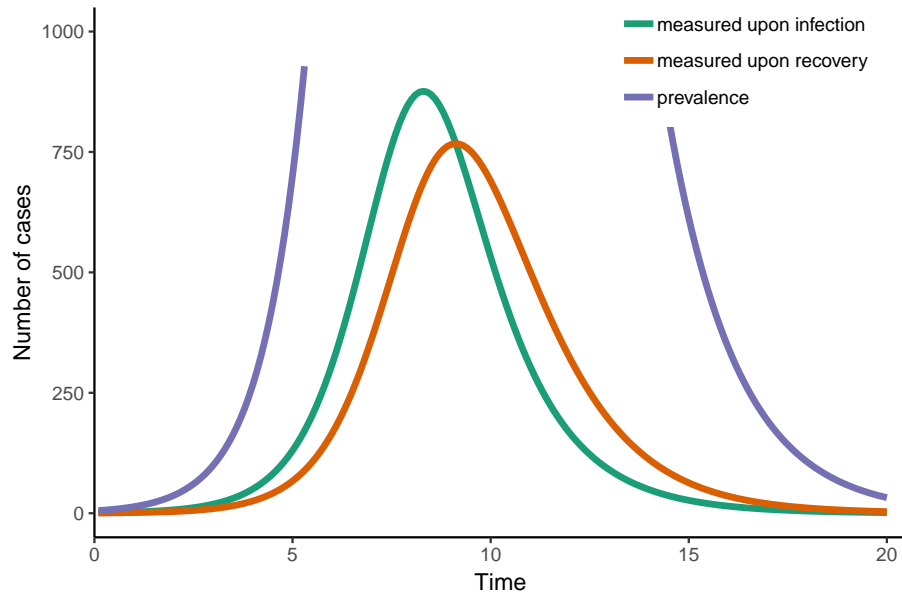


Figure 1: **A comparison of incidence measured at two different time points in infection.** A deterministic SIR model is simulated using the following parameters:  $\mathcal{R}_0 = 2$ ,  $1/\gamma = 1$  time units,  $N = 1 \times 10^5$ ,  $i_0 = 1 \times 10^{-4}$ , and  $\Delta t = 0.1$  time units.

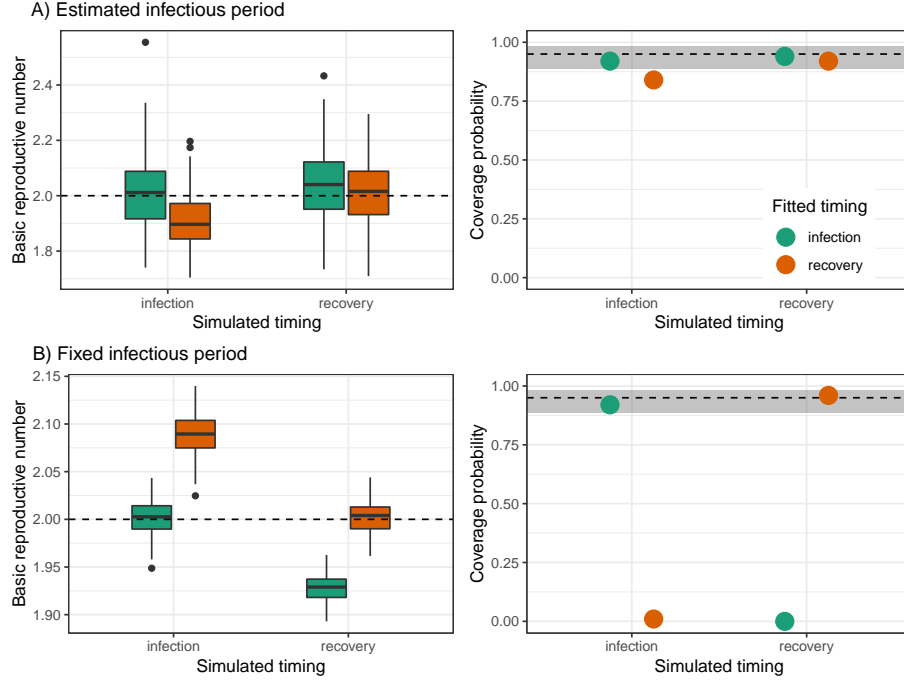


Figure 2: **A comparison of incidence measured at two different time points in infection.** We simulate infection time series and recovery time series 100 times using the following parameters:  $\mathcal{R}_0 = 2$ ,  $1/\gamma = 1$  time units,  $N = 1 \times 10^5$ ,  $i_0 = 1 \times 10^{-4}$ ,  $\rho = 0.5$ ,  $\theta = 10$ , and  $\Delta t = 0.1$  time units. For each simulation, we fit the infection model and the recovery model by (A) allowing for the mean infectious period to be estimated and (B) assuming that the mean infectious period is known. Coverage probabilities represent the proportion of confidence intervals that contain the true value of the basic reproductive number ( $\mathcal{R}_0$ ).

the wrong model changes direction (e.g., fitting the infection model to recovery model overestimates the reproduction number instead).

Differences in the direction of the bias can be explained by the estimates of the exponential growth rate ( $r = \beta - \gamma$ ) and the mean infectious period ( $1/\gamma$ ). When we fit the recovery model to an infection time series, the model overestimates the initial growth rate in order to match the higher epidemic peak of the infection time series. When the mean infectious period is fixed, higher growth rate translates to higher basic reproduction number as we see in Figure 2B. When we allow the mean infectious period to vary, the model also underestimates the mean infectious period (high  $\gamma$ ), which decreases the overall estimate of the basic reproduction number. Likewise, fitting the infection model to a recovery time series overestimates the mean infectious period (low  $\gamma$ ), increasing the estimate of the basic reproduction number; when the mean infectious period is fixed, low growth rate estimates (to match the lower epidemic peak of the recovery time series) decrease the overall estimate of the basic reproduction number.

## 4 Discussion

Mathematical modeling of infectious disease outbreaks helps us understand how disease spreads in a population; however, many epidemic models make naive assumptions about how cases are reported. Here, we used a deterministic SIR model to show that making wrong assumptions about observational processes in epidemic models can give biased estimates of the basic reproduction number and narrow confidence intervals.

We assumed that newly infected cases are reported instantaneously when individuals become infected or when they recover. Although neither of these assumptions is realistic, they are broadly consistent with the assumptions of other state-of-art epidemic models (see Introduction). More realistic models may distinguish reported and unreported (identified and unidentified) cases by adding new state variables (Browne et al., 2015; Webb et al., 2015) or by modeling an explicit delay kernel in reporting time (Harris, 1990; Ferguson et al., 2001; Ster et al., 2009; Birrell et al., 2011; Funk et al., 2018).

While we have only considered observation processes associated with incidence reporting in this study, it is equally as important to consider observation processes in mortality reporting. In particular, many disease modelers have tried to infer underlying transmission mechanisms from historical mortality data but assumed that individual deaths are recorded as soon as individuals die (He et al., 2013; Didelot et al., 2017; Dean et al., 2018). This assumption does not account for the possibility that a delay in reporting of deaths can change the shape of an epidemic curve: longer delays are expected to decrease the size of an epidemic peak and delay the timing of the peak (Figure 1). Ignoring potential delays in reporting may affect their conclusions about the underlying transmission mechanisms.

Our study shows that seemingly irrelevant changes in the assumptions of

an epidemic model affects the inference of infectious disease transmission. We caution disease modelers to be more mindful about their decisions in developing epidemic models and the implications of their model assumptions.

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