

Parsa Yazdankhah

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EDUCATION

University of Tehran Bachelor of Science in Mechanical Engineering <ul style="list-style-type: none">GPA: 3.86/4.0 (18.29/20)	2019 – Expected 2024 Tehran, Iran
University of Tehran Minor in Business Management <ul style="list-style-type: none">GPA: 4.0/4.0 (18.62/20)	2020 – Expected 2024 Tehran, Iran

RESEARCH INTERESTS

- Robotics / Soft Robotics
- Mechatronics
- System Design
- Biomechanics
- Machine Learning
- Optimization

EXPERIENCES

Research Assistant Center of Advanced Systems & Technologies (CAST), University of Tehran <ul style="list-style-type: none">Collaborated as a Dynamics and Control team member of <i>SURENA</i> humanoid robotExecuted a feasibility study and recommended an energy-efficient automated system for thermal inspectionContributed in modal analysis through hammer impact testing, along with MATLAB script development for data processing	Feb 2022 – Present Tehran, Iran
Artificial Intelligence Intern Cheetah Autonomous Vehicles Center, Sharif University of Technology <ul style="list-style-type: none">Developed extensive python scripts within <i>CARLA</i> simulator (an open-source tool for autonomous driving research), executing algorithm deployment and evaluating performance against ground truth data	Jul 2023 – Sep 2023 Tehran, Iran
Teaching Assistant School of Mechanical Engineering College of Engineering, University of Tehran <ul style="list-style-type: none">Mechatronics <i>Dr. Moosa Ayati</i> Spring 2023Numerical Computations <i>Dr. Ali Fahim</i> Spring 2022 & Fall 2022Computer Programming <i>Group of Professors</i> Fall 2021 & Spring 2022Calculus 1 <i>Dr. Hossein Rahami</i> Fall 2020	Feb 2021 – Jun 2023 Tehran, Iran
Technical Manufacturing Intern Behran Asanbar Industrial Group <ul style="list-style-type: none">Accumulated hands-on experience while collaborating with a diverse set of equipment, including lathe machines, milling machines, drilling machines, CNC systems, and CAD tools	Jul 2021 – Oct 2021 Tehran, Iran

PUBLICATIONS

- M. Mehdikhani, **P. Yazdankhah**, R. Nasiri, "*Lower Limb Joint Angle Estimation From Ground Reaction Force Using Physics-Informed Neural Networks*", In Preparation
- A.H. Vedadi, **P. Yazdankhah**, A. Yousefi-Koma, M. Shariat-Panahi, "*Real-time localization and configuration identification of a humanoid robot using machine vision*", In Preparation

TECHNICAL SKILLS

Programming: Python C/C++ MATLAB
Design & Analysis: SolidWorks CATIA ANSYS ABAQUS MSC Adams Maple OpenSim Proteus
Simulators: Simulink Choreonoid PyBullet Gazebo CarLa
Miscellaneous: ROS Git Linux Arduino MS Office L ^A T _E X

SELECTED PROJECTS

SURENA Humanoid Robot (5th Generation) | *Python, C++, ROS, Git, Choreonoid simulator*

- Developed an online trajectory planner utilizing the Divergent Component of Motion (DCM) method
- Enhanced the robot's Center of Mass (CoM) positioning through the redesign of upper-body components and the creation of a novel casing
- Conducted simulations using *Choreonoid* simulator to validate algorithm performance prior to robot deployment

Lower Limb Joint Angle Estimation from Vertical Ground Reaction Force | *Python, TensorFlow, Git*

- Implemented a novel neural networks architecture utilizing physics-informed networks to anticipate ankle, knee and hip joint angles from ground reaction forces of both soles
- Facilitated real-time gait analysis of subjects with minimal data

Solar Tracker System | *Arduino, SolidWorks*

- Designed and constructed a functional prototype of a 2 DoF solar tracker system, including the successful integration of the control algorithm
- Optimized for rapid alignment with the light source in under 2 seconds and maintains light source tracking with an angular velocity of 2 rad/s

Identification and Control of a Serial Industrial Manipulator | *MATLAB, Simulink, Simscape, Maple*

- Analyzed the dynamics of the *Motoman SK16* robotic arm, and implemented several classic controllers (CTC, Impedance, PID) to evaluate and contrast their respective performances
- Coupled two of these serial manipulators together to form a parallel robot, assessing its operational efficiency in comparison to the original serial robot

Study of Human Gait Metabolic Energy Consumption | *OpenSim, MATLAB*

- Investigated the metabolic energy consumption of walking, employing both active and passive assistive devices
- Proposed an optimal assistive device that effectively minimized muscle fatigue, mechanical workload and average metabolism

SELECTED COURSES

Academic Courses

- | | |
|---------------------------------|-------------------------------------------------|
| • Automatic Control (4/4) | • Mechanical Vibrations (4/4) |
| • Rehabilitation Robotics (4/4) | • Measurement Systems and Instrumentation (4/4) |
| • Mechatronics (4/4) | • Optimization of Mechanical Systems (4/4) |

Extracurricular Courses

- Machine Learning Specialization | *Coursera*
 - Supervised Machine Learning: Regression and Classification
 - Advanced Learning Algorithms
 - Unsupervised Learning, Recommenders, Reinforcement Learning
- IoT Hardware Practical Course | *Iran Internet of Things Center*

University of Tehran

LANGUAGE SKILLS

English: Professional working proficiency

IELTS Band Score: **7.5** (L: 8.5, R: 8.5, W: 6.5, S: 7.0)

Farsi/Persian: Native proficiency

Azerbaijani: Native proficiency

HONORS & AWARDS

- Ranked among the top 15% of class 2023 in School of Mechanical Engineering, University of Tehran
- Ranked among the top 0.3% of participants (164000 candidates) in the National University Entrance Exam, Been granted full tuition fee waiver for the course of study at University of Tehran

REFERENCES

Dr. Aghil Yousefi-Koma	Professor, School of Mechanical Engineering, University of Tehran. Supervisor of CAST Research Center	aykoma@ut.ac.ir
Dr. Ehsan Hosseinian	Assistant Professor, School of Mechanical Engineering, University of Tehran	ehosseinian@ut.ac.ir
Dr. Ali Fahim	Assistant Professor, Faculty of Engineering Sciences, University of Tehran	a.fahim@ut.ac.ir