

Price Directed Distributed Optimization and Primal Recovery

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Outline

Price directed distributed optimization

Primal recovery

Numerical results

Appendix

Our focus

our setting

- ▶ substantial computational cost per agent
- ▶ small number of iterations is desirable
- ▶ care about feasibility, some suboptimality is tolerable

we propose (postprocessing) method that

- ▶ uses low-precision optimal dual variable
- ▶ recovers close to feasible primal point
- ▶ uses only parallel calls to agents; avoids sequential calls

Distributed optimization

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{subject to} & Ax \leq b\end{array}$$

- ▶ $x = (x_1, \dots, x_M) \in \mathbf{R}^n$ is variable, $x_i \in \mathbf{R}^{n_i}$
- ▶ $f(x) = \sum_{i=1}^M f_i(x_i)$ is block separable
- ▶ $f_i : \mathbf{R}^{n_i} \rightarrow \mathbf{R} \cup \{\infty\}$ convex, closed and proper
- ▶ infinite values of f encode constraints
- ▶ $A = (A_1, \dots, A_M) \in \mathbf{R}^{m \times n}$ and $b \in \mathbf{R}^m$ are given

Conjugate subgradient oracle

- ▶ for $y \in \mathbf{R}^m$ ($\text{dom } f^* = \mathbf{R}^m$), oracle returns $x(y) \in \partial f^*(y)$

$$-f^*(y) = \inf_{x \in \text{dom } f} (f(x) - y^T x)$$

- ▶ no access to function values $f(x)$ or subgradient in $\partial f(x)$
- ▶ neutral cutting plane for dual variable

$$\left\{ \tilde{\lambda} \in \mathbf{R}^m \mid (-Ax(y) + b)^T (\tilde{\lambda} - \lambda) \leq 0, \ y = -A^T \lambda \right\}$$

Dual problem

solve the dual problem

- ▶ subgradient methods (Shor, 1962)
- ▶ localization methods
 - ▶ analytic center cutting-plane method (ACCPM)
 - ▶ maximum volume ellipsoid cutting-plane method
 - ▶ Chebyshev center cutting-plane method
- ▶ we've settled on proximal point ACCPM

Optimality conditions

► KKT conditions

$$x \in \partial f^*(y), \quad y = -A^T \lambda \quad (1)$$

$$Ax \leq b \quad (2)$$

$$\lambda_j (Ax - b)_j = 0, \quad j = 1, \dots, m \quad (3)$$

$$\lambda \geq 0 \quad (4)$$

► primal and complementary slackness residuals for a pair $(x, \lambda) \in \mathbf{R}^n \times \mathbf{R}_+^m$

$$r_p = \mathbf{1}^T (Ax - b)_+, \quad r_c = \lambda^T |Ax - b|$$

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Primal recovery

given current prices $y^k = -A^T \lambda^k = (y_1^k, \dots, y_M^k)$

1. agent i returns multiple offers $z_i^{(1)}, \dots, z_i^{(N)}$ wrt $y_i^k = -A_i^T \lambda^k$

▶ $-f_i^*(y_i^k) \leq f_i(z_i) - y_i^{kT} z_i \approx -f_i^*(y_i^k)$

▶ computed in parallel (clock time equivalent to single response)

2. central node constructs a convex combination of offers \bar{x} minimizing the residuals

$$\begin{aligned} & \text{minimize} && r_p + r_c \\ & \text{subject to} && \bar{x}_i = Z_i u_i, \quad i = 1, \dots, M \\ & && \mathbf{1}^T u_i = 1, \quad u_i \geq 0, \quad i = 1, \dots, M \\ & && \bar{x} = (\bar{x}_1, \dots, \bar{x}_M) \end{aligned}$$

don't need to run primal recovery at every step k (periodic runs sufficient)

Approximate conjugate subgradient oracle

- ▶ for any y , an ϵ_v -value suboptimal primal variable $x^v(y)$

$$-f^*(y) \leq f(x^v(y)) - y^T x^v(y) \leq -f^*(y) + \epsilon_v |f^*(y)|$$

- ▶ any convex combination \bar{x} : $f(\bar{x}) - y^T \bar{x} \leq -f^*(y) + \epsilon_v |f^*(y)|$

- ▶ for any y , primal variable $x^p(y)$ with ϵ_p -perturbed prices

$$f(x^p(y)) - (y + \delta)^T x^p(y) = -f^*(y + \delta), \quad \delta \in [-\epsilon_p |y|, \epsilon_p |y|]$$

- ▶ for L -Lipschitz f^* , for any convex combination \bar{x} : $f(\bar{x}) - y^T \bar{x} \leq -f^*(y) + \epsilon_p L \|y\|$

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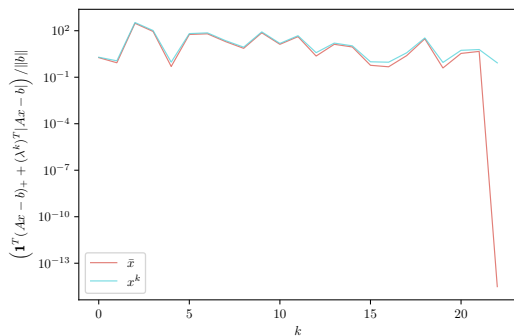
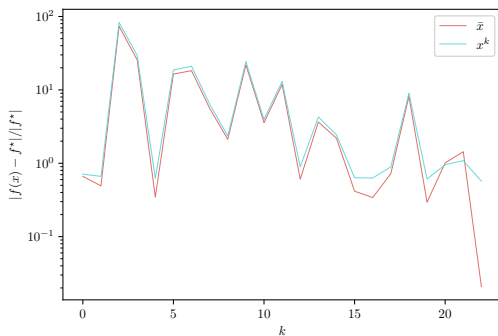
Appendix

Setting

- ▶ run localization method for solving the dual, compute λ^k
- ▶ price directed interface gives $x^k \in \partial f^*(-A^T \lambda^k)$
- ▶ \bar{x} returned by primal recovery method
- ▶ $N = 10$ suboptimal offers with $\epsilon = 10\%$ -suboptimality
- ▶ primal recovery effective when $m \ll n$

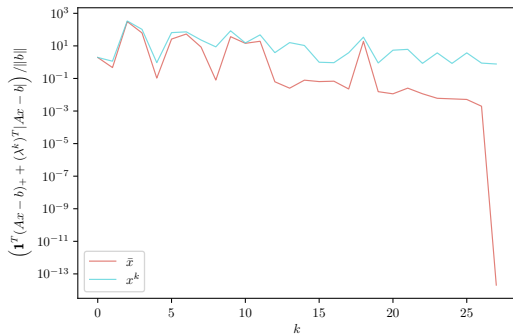
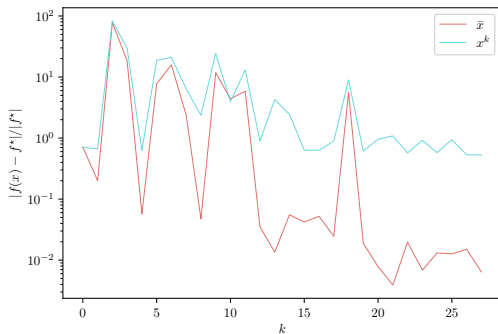
Resource allocation

- ▶ $M = 100$ agents, $m = 8$ resources, $n = 800$
- ▶ $\epsilon_v = 10\%$ -value suboptimality



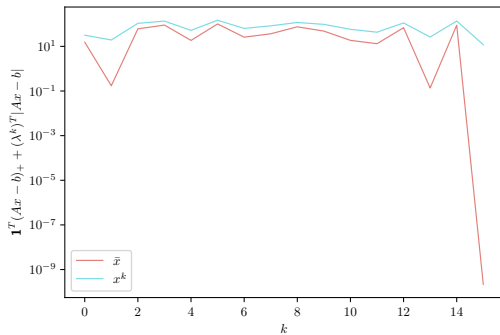
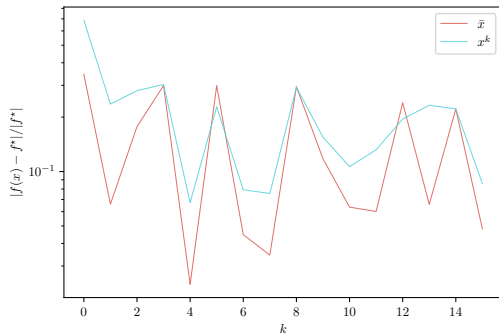
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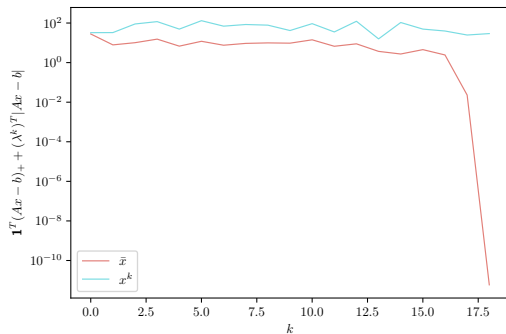
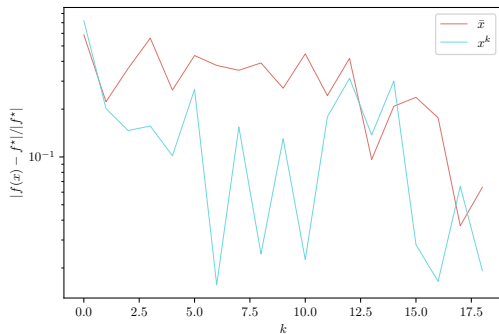
Assignment problem

- ▶ $M = 208$ agents, $m = 8$, $n = 1608$
- ▶ $\epsilon_v = 10\%$ -value suboptimality



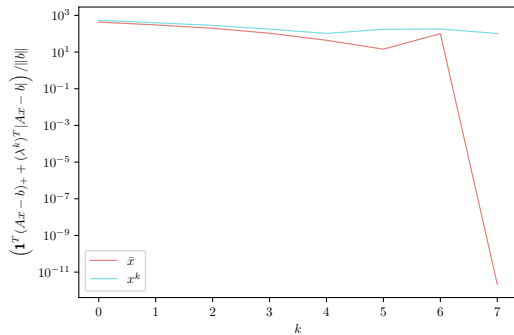
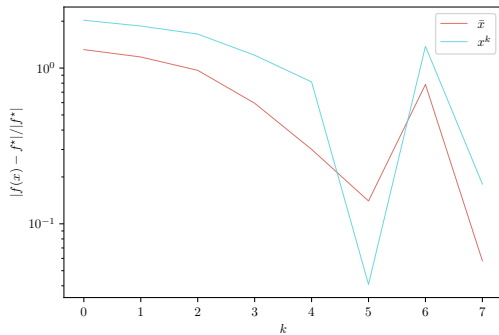
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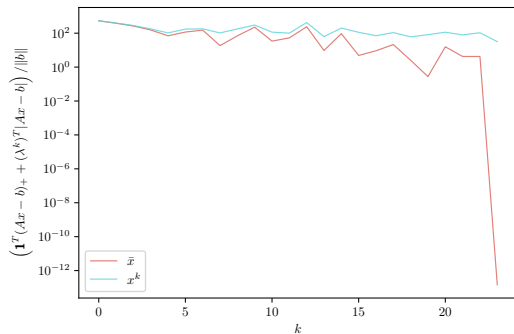
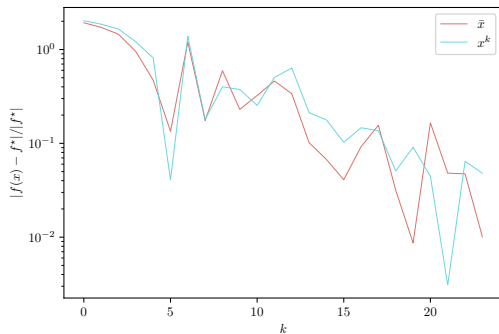
Linear programming

- ▶ $M = 100$ agents, $m = 8$, $n = 800$
- ▶ $\epsilon_v = 10\%$ -value suboptimality



Linear programming

- ▶ $M = 100$ agents, $m = 8$, $n = 800$
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Primal recovery method

- ▶ lower bound

$$\mathcal{L}(x^k, \lambda^k) = \underset{x}{\operatorname{argmin}}(f(x) + \lambda^{kT}(Ax - b)) = -f^*(-A^T \lambda^k) - \lambda^{kT} b \leq p^*$$

- ▶ ϵ_v -value suboptimality

$$\mathcal{L}(\bar{x}^v, \lambda^k) = f(\bar{x}^v) + \lambda^{kT}(A\bar{x}^v - b) \leq p^* + \epsilon_v \sum_{i=1}^M |f_i^*(-A_i^T \lambda^k)|$$

- ▶ ϵ_p -price perturbation

$$\mathcal{L}(\bar{x}^p, \lambda^k) = f(\bar{x}^p) + \lambda^{kT}(A\bar{x}^p - b) \leq p^* + \epsilon_p L \sum_{i=1}^M \|A_i^T \lambda^k\|$$