

# Assignment 1

Friday, January 13, 2023 2:22 PM

## Exercise 1 (Geometry)

Calculate the rotation of vector  $(4, 7)$  by  $60^\circ$ .

$$\begin{aligned}\vec{v} &= 4\mathbf{i} + 7\mathbf{j} \\ |\vec{v}| &= \sqrt{4^2 + 7^2} = \sqrt{16 + 49} = \sqrt{65} \\ \angle \vec{v} &= \tan^{-1}\left(\frac{7}{4}\right) = 60.25^\circ \approx 60^\circ \\ \vec{v} &= \sqrt{65} e^{i\theta} \\ \text{After rotation, } \vec{v}_n &= \sqrt{65} e^{i\theta_n} \\ \therefore \vec{v} &= -4 + 7\mathbf{j}\end{aligned}$$

## Exercise 2 (Probability)

Your robot is misbehaving, and you're trying to find out why. You narrow it down to three possible software bugs,  $b_1$ ,  $b_2$ , and  $b_3$ . You're not sure which bug it is, but you try the same experiment on a brand new robot to make sure the issue is not hardware-related. You estimate that the anomalous behavior will appear with probability  $\frac{1}{2}$  if it's due to bug  $b_1$ ,  $\frac{1}{3}$  if it's due to bug  $b_2$ , and  $\frac{1}{6}$  if it's due to bug  $b_3$ . Given that the new test shows the anomalous behavior, what probabilities should you assign to the three possible bugs?

Hints:

- Consider the event  $A$  that an anomaly occurs, and the events  $B_1$ ,  $B_2$ , and  $B_3$  that bugs  $b_1$ ,  $b_2$ , and  $b_3$  occur; then,  $P(A|B_1) = \frac{1}{2}$ ,  $P(A|B_2) = \frac{1}{3}$ , and  $P(A|B_3) = \frac{1}{6}$ .
- The problem is asking you the probabilities  $P(B_1|A)$ ,  $P(B_2|A)$ , and  $P(B_3|A)$ . Which formula do we use to calculate this?
- The problem does not give you  $P(A)$ . Which formula do we use to calculate this?
- The problem does not give you  $P(B_1)$ ,  $P(B_2)$ , and  $P(B_3)$ . Think about what they mean: they are the probability that a bug occurs, without information on which specific anomaly occurred. What reason would there be to decide that a bug is more probable than another, if no information is available? You can safely say that all these probabilities can be set to the same constant  $K$ . Since you have no value for  $K$ , maybe there's a hope that in the final formula it will cancel out...

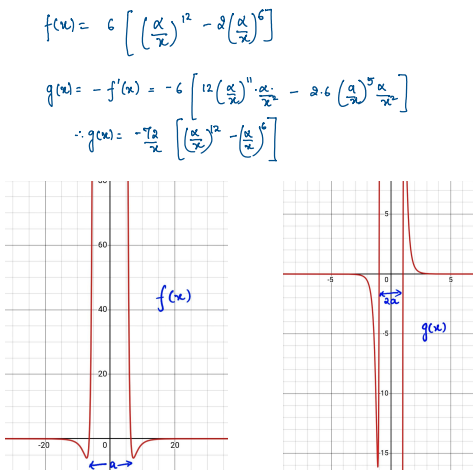
## Exercise 3 (Calculus)

Given

$$f(x) = e^{\left(\left(\frac{\alpha}{x}\right)^{12} - 2\left(\frac{\alpha}{x}\right)^6\right)},$$

- Draw the graph of  $f(x)$ ;
- Calculate and draw the graph of  $g(x) = -\frac{d}{dx}f(x)$ .

To draw the graphs, you can use programs such as Matlab or GNUPlot, or do it by hand.



## Exercise 4 (Differential Equations)

Find all the fixed points for  $\dot{x} = x^2 - 25$  and classify their stability.

$$\begin{aligned}\text{Fixed pts.: } \dot{x} &= x^2 - 25 = (x-5)(x+5) \\ \text{for finding fixed pts.:} \\ x &= 0 \\ \therefore (x-5)(x+5) &= 0 \\ \therefore x^* &= \pm 5\end{aligned}$$

$$\begin{aligned}\text{Stability: } f(x) &= \dot{x} = x^2 - 25 \\ \therefore f'(x) &= 2x\end{aligned}$$

$$\begin{aligned}\forall x = +5 &\rightarrow f'(x^*) = 10 > 0 \rightarrow \text{Unstable} \\ \forall x = -5 &\rightarrow f'(x^*) = -10 < 0 \rightarrow \text{Stable}.\end{aligned}$$

$$\begin{aligned}\therefore x = +5 &\rightarrow \text{Fixed / Unstable} \\ x = -5 &\rightarrow \text{Fixed / Stable}.\end{aligned}$$