

Unit 5 Reinforcement Learning (2

Course > weeks)

> Homework 6 > 3. Q-Learning

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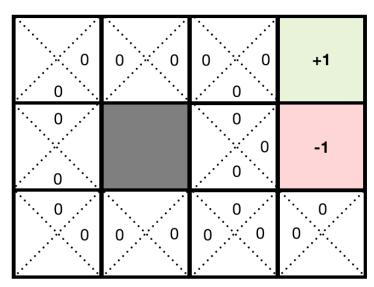
3. Q-Learning

Recall the Q-learning update rule:

$$Q_{i+1}\left(s,a
ight) = Q_{i}\left(s,a
ight) + lpha\left[R\left(s,a,s'
ight) + \gamma max_{a'}Q_{i}\left(s',a'
ight) - Q_{i}\left(s,a
ight)
ight]$$

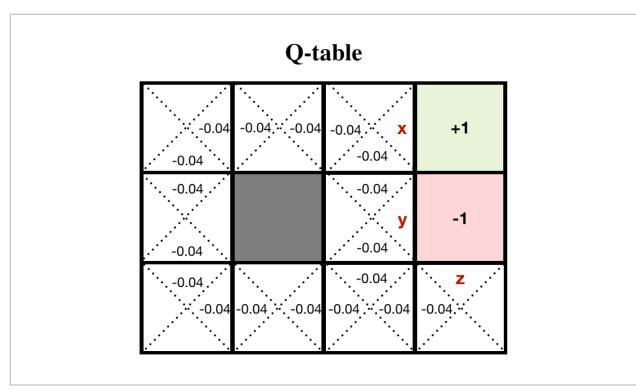
let $\alpha=1$ and $\gamma=1$ in this problem. In the figure below, at each box, we can go up, down, left and right unless the path is blocked and we initialize the Q value for all the actions in all states as 0. The Q value for the 4 directions are labeled in each box below. Moving into the upper right 2 boxes will result in a reward of +1 and -1, and each move will also cost 0.04, or in another word, a reward of -0.04.

Q-table



1st Iteration

3 points possible (graded)



After 1st iteration, enter the Q value at the position represented by x, y and z below:

$$x =$$
 Answer: 0.96

$$y =$$
 Answer: -1.04

$$z =$$
 Answer: -1.04

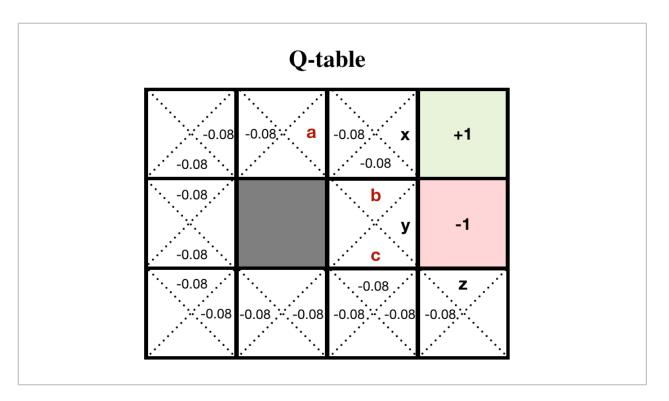
Solution:

Submit You have used 0 of 3 attempts

1 Answers are displayed within the problem

2nd Iteration

3 points possible (graded)



After 2nd iteration, enter the Q value at the position represented by a, b and c below:

$$a=$$
 Answer: 0.92

$$b=$$
 Answer: 0.92

$$c =$$
 Answer: -0.08

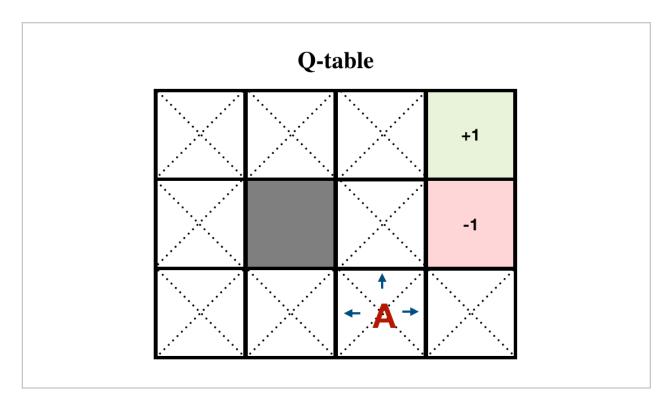
Solution:

Submit You have used 0 of 3 attempts

• Answers are displayed within the problem

2nd Iteration

1 point possible (graded)



After convergence, at state A, which action is the optimal?

UP ✓			
LEFT			
RIGHT			

Solution:

Submit You have used 0 of 1 attempt

1 Answers are displayed within the problem

Epsilon-greedy method 1

1 point possible (graded)

In the ε -greedy method, a larger value of ε would generate experiences that are more consistent with the current Q-value estimates.

True	
☐ False ✔	

Solution:

In the ε -greedy method, we choose a random action with probability ε and choose an action based on our current estimates with probability 1 - ε . Therefore, it is with smaller ε that we would generate experiences which are more consistent with our current Q-value estimates.

Submit

You have used 0 of 1 attempt

• Answers are displayed within the problem

Epsilon-greedy method 2

1 point possible (graded)

In the arepsilon-greedy method, a value of arepsilon=0.999 is likely to lead to the desired learning outcome (better utility) in a highly complex environment.

True		
☐ False ✔		
False		

Solution:

We would pick a random action virtually every time, and in a highly complex environment, it's highly unlikely that we would properly explore the parts of the space that have high rewards.

Submit

You have used 0 of 1 attempt

1 Answers are displayed within the problem

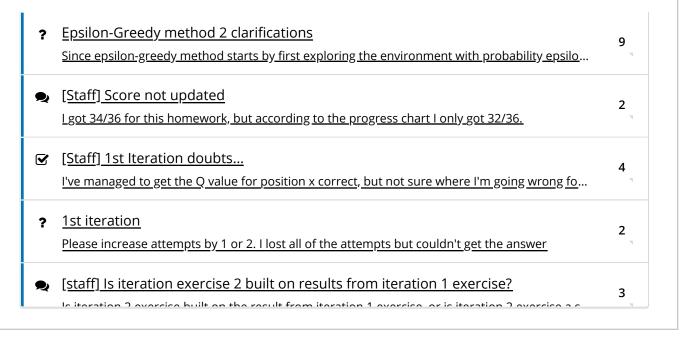
Discussion

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? Does the formula given at the begining of the excersise applies here? Maybe I am wrong, but as this formula is the given for "Q value iteration by sampling" (Lectur	4
What should be the value for Max(Q(s',a')) when it's at the edge state? After reading the answers, I'm still confused as I could not get the results as what's supposed	2
Question about reward value initialization for blocked directions? How should we initialize the reward values for those blocked directions? I found when I initial	3
2nd Iteration Q-values Any hint how to solve 2nd iteration Q value at the position a, b, and c? Also, why reward is no	4
[Staff] Epsilon-greedy method 2 It appears that assumptions needed to solve this problem are "implicit". Could staff make the	6
? <u>I'm completely lost- some hint to start ?</u> see up	7
? <u>Epsilon-greedy method 1</u> <u>Apparently this question is NOT related to the previous question. I thought current Q-value e</u>	1
☑ [STAFF] Progress bar for this homework.	3



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