

Lecture 10. Recurrent Neural

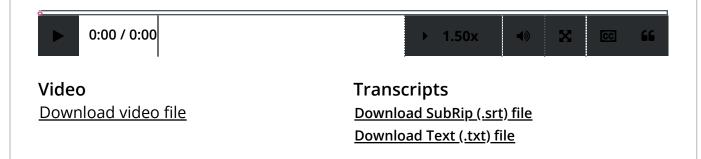
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5. Gating and LSTM Gating and LSTM





Gating

1/1 point (graded)

Recall that the most simple, single-layered RNN can be written in equation as:

$$s_t = \tanh(W^{s,s}s_{t-1} + W^{s,x}x_t).$$

Recognize that, in the above formulation, s_t is always overwritten with the calculated result $\tanh{(W^{s,s}s_{t-1}+W^{s,x}x_t)}$.

Now, we introduce a gate vector g_t of the same dimension as s_t , which determines "how much information to overwrite in the next state." In equation, a single-layered gated RNN can be written as:

$$egin{aligned} g_t &= \operatorname{sigmoid}\left(W^{g,s}s_{t-1} + W^{g,x}x_t
ight) \ s_t &= (1-g_t) \bigodot s_{t-1} + g_t \bigodot anh\left(W^{s,s}s_{t-1} + W^{s,x}x_t
ight). \end{aligned}$$

where the sign \odot denotes element-wise multiplication. Now, which of the following is true about the gate g_t ? (Choose all those apply.)

- If the ith element of g_t is 1, the ith element of s_t and that of s_{t-1} are equal
- lacksquare If the ith element of g_t is 0, the ith element of s_t and that of s_{t-1} are equal
- lacksquare If g_t is a vector whose elements are all 1, s_t and s_{t-1} are equal
- lacksquare If g_t is a vector whose elements are all 0, s_t and s_{t-1} are equal



Solution:

Let the ith element of s_t , g_t , s_{t-1} be s_t^i , g_t^i , s_{t-1}^i .

If the ith element of g_t is 0, $(1-g_t^i)=1$, so

$$s_t^i = s_{t-1}^i.$$

Thus, if the ith element of g_t is 0, the ith element of s_t and that of s_{t-1} are equal. Also, if g_t is a vector whose elements are all 0, s_t and s_{t-1} are equal.

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1 Answers are displayed within the problem

LSTM

1/1 point (graded)

Which of the following components of an LSTM represent the context or state?

(Choose all that apply.) $oxed{oxed{c}_t}$		
$\boxed{ \checkmark h_t}$		
$\bigcirc o_t$		
lacksquare		
✓		

Solution:

 c_t represents the memory cell, and h_t represents the visible state. Together they make up the context or state. The other two choices are the output and input gate, respectively. They simply accommodate new inputs and output predictions, and are not part of the context/state

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LSTM Calculations

1/1 point (graded)

Let all the neural network's weight matrices, the hidden state, and the memory cell be a scalar 1. Let the new x-value be 5. Calculate the value of the new hidden state. Round sigmoid to 1 or 0, and round \tanh to -1 or 1.

$$f_t = \operatorname{sigmoid}(W^{f,h}h_{t-1} + W^{f,x}x_t)$$
 forget gate $i_t = \operatorname{sigmoid}(W^{i,h}h_{t-1} + W^{i,x}x_t)$ input gate $o_t = \operatorname{sigmoid}(W^{o,h}h_{t-1} + W^{o,x}x_t)$ output gate $c_t = f_t \odot c_{t-1} + i_t \odot \tanh(W^{c,h}h_{t-1} + W^{c,x}x_t)$ memory cell



- 1
- 0
- _5



Solution:

The forget gate is equal to sigmoid(6), or 1. The same applies for the input and output gate. The memory cell is equal to $1+ \tanh(1+6)$, which is 2. The new hidden state is therefore $\tanh(2)$, or 1.

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 $h_t = o_t \odot \tanh(c_t)$ visible state

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is hidden state and visible state same thing?
is h_t is called both hidden and visible state?

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