

Unit 0. Course Overview, Homework

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9. Gradients and Optimization

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9. Gradients and Optimization

Multivariable Calculus Review: Simple Gradient

1.0/1 point (graded) Let

$$f: \qquad \mathbb{R}^d \qquad
ightarrow \ egin{pmatrix} eta & & & \mathbb{R} \ & & & & \ eta & & & \ eta & & \ eta & & \ dots & \ eta & & \ dots & \ eta & \ \end{pmatrix} \ \mapsto \ f\left(heta
ight).$$

denote a $\operatorname{differentiable}$ function. The $\operatorname{gradient}$ of f is the vector-valued function

 $abla_{ heta}f: \qquad \mathbb{R}^d \qquad
ightarrow \; \mathbb{R}^d$

$$heta = egin{pmatrix} heta_1 \ heta_2 \ dots \ heta_d \end{pmatrix} \; \mapsto \; egin{pmatrix} rac{\partial f}{\partial heta_1} \ rac{\partial f}{\partial heta_2} \ dots \ rac{\partial f}{\partial heta_d} \end{pmatrix} igg|_{ heta}.$$

Consider

$$f\left(heta
ight) = heta_{1}^{2}+ heta_{2}^{2}$$
 .

Compute the gradient ∇f .

(Enter your answer as a vector, e.g., type **[2,x]** for the vector $\binom{2}{x}$. Note the square brackets, and commas as separators. Enter **theta_i** for θ_i .)

$$abla_{ heta}f\left(heta
ight)= egin{array}{c} 2^{st} ext{[theta_1, theta_2]} \end{array}$$

✓ Answer: [2*theta_1,2*theta_2]

STANDARD NOTATION

Solution:

$$egin{array}{lll} f\left(heta
ight) &=& heta_{1}^{2} + heta_{2}^{2} \ &
abla f\left(heta
ight) &=& \left(rac{\partial f}{\partial heta_{1}}
ight) igg|_{ heta} &=& \left(rac{2 heta_{1}}{2 heta_{2}}
ight). \end{array}$$

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You have used 1 of 3 attempts

1 Answers are displayed within the problem

Geometric Picture of the Function

3/3 points (graded)

As above, consider $f(\theta)=\theta_1^2+\theta_2^2$. Let us visualize $f(\theta)$ as a surface on the (θ_1,θ_2) -plane. We will use the usual horizonal plane as the (θ_1,θ_2) -plane, and the vertical axis as the $f(\theta)$ -axis.

Consider the level curves $heta_1^2+ heta_2^2=K$ where K>0 is some fixed real number.

What is the shapes of such a curve?

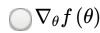
- parabola
- circle
- hyperbola
- line
- ~

Consider how the level curves $\theta_1^2+\theta_2^2=+K$ change as K increases from 0 to ∞ . Does the graph (surface) of $f\left(\theta\right)$ have a global maximum, or global minimum, or neither?

- global maximum
- global minimum
- neither



At each point $heta=(heta_1, heta_2)$ in the $(heta_1, heta_2)$ -plane, f(heta) decreases in the direction of...



$$lacksquare$$
 $-
abla_{ heta}f\left(heta
ight)$



Solution:

The graph of $f(\theta)$ is a paraboloid that opens downwards. Its global maximum is at $\theta=(0,0)$. We see that $\nabla_{\theta}f(\theta)=\left(2\theta_{1},2\theta_{2}\right)^{T}$, and hence $-\nabla_{\theta}f(\theta)$ points towards the origin at all points θ .

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Gradient ascent/descent methods are typical tools for maximizing/minimizing functions. Consider the function $L\left(x,\theta\right)$ where $\theta=\left[\theta_1,\theta_2,\ldots,\theta_n\right]^T$ and $x=\left[x_1,x_2,\ldots,x_n\right]^T$. Our goal is to select θ such to maximize/minimize the value of L while keeping x fixed.

Compute the Gradient

1/1 point (graded)

The gradient $abla_{ heta}L\left(x, heta
ight)$ is a vector with n components:

$$abla_{ heta}L\left(x, heta
ight)=\left(egin{array}{c} rac{\partial}{\partial heta_{1}}L\left(x, heta
ight)\ dots\ rac{\partial}{\partial heta_{n}}L\left(x, heta
ight) \end{array}
ight).$$

(Note that we are treating x as a constant and also differentiating w.r.t. to heta.)

Let

$$L(x,\theta) = \log (1 + \exp (-\theta \cdot x)).$$

(Notice that here the \log function is the natural algorithm.)

Evaluate the gradient $abla_{ heta}L\left(x, heta
ight)$. Which of the following is its $j^{ ext{th}}$ component?

$$\bigcirc \frac{\exp\left(-\theta \cdot x\right)}{1 + \exp\left(-\theta \cdot x\right)}$$

$$\bullet \frac{-x_j \exp(-\theta \cdot x)}{1 + \exp(-\theta \cdot x)}$$

$$\bigcirc rac{-x_j}{1+\exp\left(- heta\cdot x
ight)}$$



Solution:

The derivative of $\log{(x)}=\frac{1}{x}$ and the derivative of $e^{cx}=ce^{cx}$. Applying these rules with the chain rule gives the correct answer.

Submit

You have used 1 of 1 attempt

1 Answers are displayed within the problem

Gradient Ascent or Descent

1/1 point (graded)

The direction of the derivative of a function gives us the direction of the largest change in the function as the independent variables vary.

In gradient ascent/descent methods, we make an educated guess about the next values of θ , with consecutive updates that will hopefully eventually converge to the global minimum of $L\left(x,\theta\right)$ (if it exists).

lf

$$heta' = heta + \epsilon \cdot
abla_{ heta} L\left(x, heta
ight)$$

where ϵ is a small positive real number, Which of the following is true?

$$ullet L\left(x, heta'
ight) > L\left(x, heta
ight)$$

$$igcup L\left(x, heta^{\prime}
ight) < L\left(x, heta
ight)$$



STANDARD NOTATION

Solution:

Consider the one-dimensional case. If the gradient is positive, we obtain θ' by moving from θ in the positive direction. This increases $L\left(x,\theta\right)$. If the gradient is negative, we move in the negative direction, again increasing $L\left(x,\theta\right)$. This analysis extends to higher dimensions. Note that if we used the function above to continue updating θ , we would (in theory) maximize $L\left(x,\theta\right)$. Alternatively if our update rule was $\theta'=\theta-\epsilon\cdot\nabla_{\theta}L\left(x,\theta\right)$, we would minimize the function. There are more complications in higher dimensions, but this is the basic idea behind stochastic gradient descent, which forms the backbone of modern machine learning.

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You have used 1 of 1 attempt

1 Answers are displayed within the problem

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Compute the gradient Don't understand why some are xj an others are just x	3
[STAFF] Some typos in "Geometric Picture of the Function" In "We will use the usual horizonal plane as the $(\theta 1, \theta 2$ -plane, and the vertical axis as the $f(\theta)$	1
In Gradient Ascent or Descent, both answer choices are the same title	4

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