

Course > Unit 3 Neural networks (2.5 weeks) > Homework 4 > 3. Backpropagation

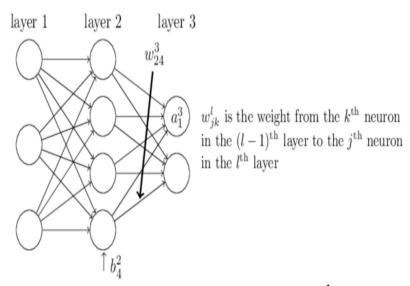
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# 3. Backpropagation

One of the key steps for training multi-layer neural networks is stochastic gradient descent. We will use the back-propagation algorithm to compute the gradient of the loss function with respect to the model parameters.

Consider the L-layer neural network below:



In the following problems, we will the following notation:  $b^l_j$  is the bias of the  $j^{th}$  neuron in the  $l^{th}$  layer,  $a^l_j$  is the activation of  $j^{th}$  neuron in the  $l^{th}$  layer, and  $w^l_{jk}$  is the weight for the connection from the  $k^{th}$  neuron in the  $(l-1)^{th}$  layer to the  $j^{th}$  neuron in the  $l^{th}$  layer.

If the activation function is f and the loss function we are minimizing is C, then the equations describing the network are:

$$egin{aligned} a_j^l &= f\left(\sum_k w_{jk}^l a_k^{l-1} + b_j^l
ight) \end{aligned}$$

Loss 
$$= C(a^L)$$

Note that notations without subscript denote the corresponding vector or matrix, so that  $a^l$  is activation vector of the  $l^{th}$  layer, and  $w^l$  is the weights matrix in  $l^{th}$  layer.

For 
$$l=1,\ldots,L$$
.

# Computing the Error

2/2 points (graded)

Let the weighted inputs to the d neurons in layer l be defined as  $z^l\equiv w^la^{l-1}+b^l$ , where  $z^l\in\mathbb{R}^d$ . As a result, we can also write the activation of layer l as  $a^l\equiv f(z^l)$ , and the "error" of neuron j in layer l as  $\delta^l_j\equiv \frac{\partial C}{\partial z^l_j}$ . Let  $\delta^l\in\mathbb{R}^d$  denote the full vector of errors associated with layer l.

Back-propagation will give us a way of computing  $\delta^l$  for every layer.

Assume there are d outputs from the last layer (i.e.  $a^L \in \mathbb{R}^d$  ). What is  $\delta^L_j$  for the last layer?

$$igotimes rac{\partial C}{\partial a_j^L} f'\left(z_j^L
ight)$$

$$igcup_{k=1}^d rac{\partial C}{\partial a_k^L} f'\left(z_j^L
ight)$$

$$\bigcirc \frac{\partial C}{\partial a_j^L}$$

$$igcup f'\left(z_{j}^{L}
ight)$$



What is  $\delta^l_j$  for all l 
eq L?

$$igotimes \sum_{k} w_{kj}^{l+1} \delta_{k}^{l+1} f'\left(z_{j}^{l}
ight)$$

$$igcup \delta_k^{l+1} f'\left(z_j^l
ight)$$

$$\bigcap \sum_{k}w_{jk}^{l-1}\delta_{j}^{l-1}f^{\prime}\left(z_{j}^{l}\right)$$

$$igcup_k w_{kj}^{l+1} \delta_k^{l+1} f(z_j^l)$$



### **Solution:**

We make use of the chain rule.

1. By definition, 
$$\delta_j^L=rac{\partial C}{\partial a_i^L}rac{\partial a_j^L}{\partial z_i^L}=rac{\partial C}{\partial a_j^L}f'\left(z_j^L
ight).$$

2. We have:

$$egin{aligned} \delta_j^l &= rac{\partial C}{\partial z_j^l} \ &= \sum_k rac{\partial C}{\partial z_k^{l+1}} rac{\partial z_k^{l+1}}{\partial z_j^l} \ &= \sum_k rac{\partial z_k^{l+1}}{\partial z_j^l} \delta_k^{l+1} \end{aligned}$$

Then we have  $z_k^{l+1} = \sum_j w_{kj}^{l+1} a_j^l + b_k^{l+1} = \sum_j w_{kj}^{l+1} f(z_j^l) + b_k^{l+1}.$  Taking the derivative of this with respect to  $z_j^l$  gives  $w_{kj}^{l+1} f'(z_j^l).$ 

Combining the two gives the final answer:  $\delta_j^l = \sum_k w_{kj}^{l+1} \delta_k^{l+1} f'\left(z_j^l
ight)$ .

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You have used 2 of 2 attempts

• Answers are displayed within the problem

## Parameter Derivatives

2/2 points (graded)

During SGD we are interested in relating the errors computed by back-propagation to the quantities of real interest: the partial derivatives of the loss with respect to our parameters. Here that is  $\frac{\partial C}{\partial w_{it}^l}$  and  $\frac{\partial C}{\partial b_i^l}$ .

What is  $rac{\partial C}{\partial w^l_{jk}}$ ? Write in terms of the variables  $a^{l-1}_k$  ,  $w^l_j$  ,  $b^l_j$  , and  $\delta^l_j$  if necessary.

Example of writing superscripts and subscripts:

$$delta\_j ackslash \hat{l}$$
 for  $\delta^l_j$ 

$$w_-(jk)\setminus \hat{\ } l$$
 for  $w^l_{jk}$ 

What is  $rac{\partial C}{\partial b^l_j}$ ? Write in terms of the variables  $a^{l-1}_k$  ,  $w^l_j$  ,  $b^l_j$  , and  $\delta^l_j$  if necessary.

STANDARD NOTATION

#### **Solution:**

1. 
$$rac{\partial C}{\partial w_{jk}^l}=rac{\partial C}{\partial z_j^l}rac{\partial z_j^l}{\partial w_{jk}^l}=a_k^{l-1}\delta_j^l$$

2. 
$$rac{\partial C}{\partial b^l_j}=rac{\partial C}{\partial z^l_j}rac{\partial z^l_j}{\partial b^l_j}=1*\delta^l_j$$

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You have used 1 of 5 attempts

**1** Answers are displayed within the problem

# **Activation Functions: Sigmoid**

4/4 points (graded)

Recall that there are several different possible choices of activation functions f. Let's get more familiar with them and their gradients.

What is the derivative of the sigmoid function,  $\sigma(z) = \frac{1}{1+e^{-z}}$ ? Please write your answer in terms of e and z:

✓ Answer: e^(-z) / (1 + e^(-z))^2

$$rac{e^{-z}}{(1+e^{-z})^2}$$

Which of the following is true of  $\sigma'(z)$  as ||z|| gets large?

- Its magnitude becomes large.
- Its magnitude becomes small.
- It suffers from high variance.



What is the derivative of the ReLU function,  $\operatorname{ReLU}\left(z
ight) = \max\left(0,z
ight)$  for z>0?

1

✓ Answer: 1

1

For z<0?

0

✓ Answer: 0

0

STANDARD NOTATION

### **Solution:**

 $\sigma'(z) = \sigma(z)(1 - \sigma(z))$ . As z gets large in magnitude, the sigmoid function saturates, and the gradient approaches zero.

ReLU is a simple activation function. Above zero, it has a constant gradient of 1.

Below zero, it is always zero.

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**1** Answers are displayed within the problem

# Simple Network

4/4 points (graded)

Consider a simple 2-layer neural network with a single neuron in each layer. The loss function is the quadratic loss:  $C=\frac{1}{2}(y-t)^2$ , where y is the prediction and t is the target.

Starting with input x we have:

- $\bullet \ z_1 = w_1 x$
- $a_1 = \text{ReLU}(z_1)$
- $\bullet \ z_2 = w_2 a_1 + b$
- $ullet \ y = \sigma \left( z_2 
  ight)$
- ullet  $C=rac{1}{2}(y-t)^2$

Consider a target value t=1 and input value x=3. The weights and bias are  $w_1=0.01, w_2=-5$  , and b=-1.

Please provide numerical answers accurate to at least three decimal places.

What is the loss?

0.2884

**✓ Answer:** 0.28842841648243966

What are the derivatives with respect to the parameters?

$$\frac{\partial C}{\partial w_1} = \boxed{2.0809}$$

**✓ Answer:** 2.0809165621704553

$$\frac{\partial C}{\partial w_2} = \begin{bmatrix} -0.00416 \end{bmatrix}$$

**✓ Answer:** -0.00416183312434091

$$\frac{\partial C}{\partial b} = \boxed{-0.1387}$$

**✓ Answer:** -0.13872777081136367

#### STANDARD NOTATION

### **Solution:**

Using the chain rule, we have:

$$ullet rac{\partial C}{\partial w_1} = rac{\partial C}{\partial y} rac{\partial y}{\partial z_2} rac{\partial z_2}{\partial a_1} rac{\partial a_1}{\partial z_1} rac{\partial z_1}{\partial w_1} = (y-t) \, y \, (1-y) \, w_2 {f 1} \{z_1>0\} x$$

$$ullet rac{\partial C}{\partial w_2} = rac{\partial C}{\partial y} rac{\partial y}{\partial z_2} rac{\partial z_2}{\partial w_2} = \left(y-t
ight) y \left(1-y
ight) a_1$$

• 
$$\frac{\partial C}{\partial b} = (y - t) y (1 - y)$$

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You have used 2 of 5 attempts

**1** Answers are displayed within the problem

## **SGD**

1/1 point (graded)

Referring to the previous problem, what is the update rule for  $w_1$  in the SGD algorithm with step size  $\eta$ ? Write in terms of  $w_1$ ,  $\eta$ , and  $\frac{\partial C}{\partial w_1}$ ; enter the latter as (partial()/(partialw\_1), noting the lack of space in the variable names:

Next 
$$w_1 = \boxed{\hspace{1.5cm} ext{w\_1 - eta * (partialC)/(partia)}} \hspace{1.5cm} \hspace{1$$

Answer: w\_1 - eta \* (partialC)/(partialw\_1)

### **STANDARD NOTATION**

#### **Solution:**

The definition of the simple SGD update rule is new\_parameter = old\_parameter - learning\_rate \* derivative of loss w.r.t old parameter.

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You have used 1 of 5 attempts

**1** Answers are displayed within the problem

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