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1 BackPropagation

There will be some functions that start with the word "grader" ex: grader_sigmoid(), grader_forwardprop(), grader_backprop() etc, you should not change those function definition. Every Grader function has to return True.

1.1 Loading data

```
[1]: import pickle
  import numpy as np
  from tqdm import tqdm
  import matplotlib.pyplot as plt

with open('data.pkl', 'rb') as f:
     data = pickle.load(f)
  print(data.shape)
  X = data[:, :5]
  y = data[:, -1]
  print(X.shape, y.shape)
(506, 6)
(506, 5) (506,)
```

2 Computational graph

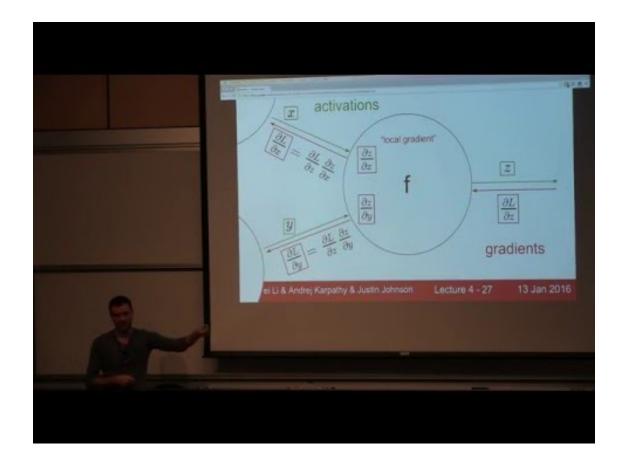
- If you observe the graph, we are having input features [f1, f2, f3, f4, f5] and 9 weights [w1, w2, w3, w4, w5, w6, w7, w8, w9].
- The final output of this graph is a value L which is computed as (Y-Y')^2

3 Task 1: Implementing backpropagation and Gradient checking

Check this video for better understanding of the computational graphs and back propagation

```
[2]: from IPython.display import YouTubeVideo
YouTubeVideo('i940vYb6noo', width="1000", height="500")
```

[2]:



- Write two functions
 - Forward propagation(Write your code in def forward_propagation()) For easy debugging, we will break the computational graph into 3 parts.

Part 1 Part 2 Part 3

- Backward propagation(Write your code in def backward_propagation())

Gradient clipping

Check this blog link for more details on Gradient clipping Algorithm

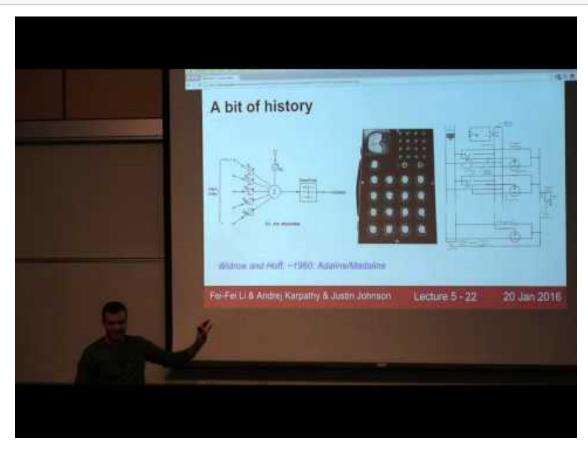
4 Task 2 : Optimizers

- As a part of this task, you will be implementing 3 type of optimizers(methods to update weight)
- Use the same computational graph that was mentioned above to do this task
- Initilze the 9 weights from normal distribution with mean=0 and std=0.01

Check below video and this blog

[3]: from IPython.display import YouTubeVideo
YouTubeVideo('gYpoJMlgyXA',width="1000",height="500")





Algorithm

4.1 Implement below tasks

- ullet Task 2.1: you will be implementing the above algorithm with Vanilla update of weights
- \bullet Task 2.2: you will be implementing the above algorithm with Momentum update of weights
- Task 2.3: you will be implementing the above algorithm with Adam update of weights

Note: If you get any assertion error while running grader functions, please print the variables in grader functions and check which variable is returning False. Recheck your logic for that variable.

5 Task 1

5.1 Forward propagation

```
[4]: def sigmoid(z):
         '''In this function, we will compute the sigmoid(z)'''
         # we can use this function in forward and backward propagation
         return 1 / (1 + np.exp(-z))
     def forward_propagation(x, y, w):
         '''In this function, we will compute the forward propagation '''
         # X: input data point, note that in this assignment you are having 5-d data_
      \rightarrow points
         # y: output varible
         # W: weight array, its of length 9, W[0] corresponds to w1 in graph, W[1]_{\sqcup}
      \rightarrow corresponds to w2 in graph,..., W[8] corresponds to w9 in graph.
         # you have to return the following variables
         # exp = part1 (compute the forward propagation until exp and then store the
      \rightarrow values in exp)
         # tanh =part2(compute the forward propagation until tanh and then store the
      \rightarrow values in tanh)
         \# sig = part3(compute the forward propagation until sigmoid and then store_
      \rightarrow the values in sig)
         # now compute remaining values from computional graph and get y'
         # write code to compute the value of L=(y-y')^2
         \# compute derivative of L w.r. to Y' and store it in dl
         # Create a dictionary to store all the intermediate values
         # store L, exp, tanh, siq variables
               = np.dot(w[0], x[0]) + np.dot(w[1], x[1])
               = np.exp(np.dot(t,t) + w[5])
         exp
         tanh = np.tanh(exp + w[6])
               = sigmoid(w[7] + (np.dot(np.sin(np.dot(w[2], x[2]))), np.dot(w[3], u)
      \rightarrow x[3]) + np.dot(w[4], x[4])))
         y_hat = np.dot(sig, w[8]) + tanh
               = (y-y_hat) ** 2
               = -2 * (y - y_hat)
         dl
         return {'dl':dl,'loss':l, 'exp':exp, 'tanh':tanh, 'sigmoid':sig, 'x':x}
```

Grader function - 1

```
[5]: def grader_sigmoid(z):
    val=sigmoid(z)
    assert(val==0.8807970779778823)
    return True
    grader_sigmoid(2)
```

[5]: True

```
Grader function - 2
```

```
[8]: def grader_forwardprop(data):
    dl = (np.round(data['dl'],4)==-1.9285)
    loss=(np.round(data['loss'],4)==0.9298)
    part1=(np.round(data['exp'],4)==1.1273)
    part2=(np.round(data['tanh'],4)==0.8418)
    part3=(np.round(data['sigmoid'],4)==0.5279)
    assert(dl and loss and part1 and part2 and part3)
    return True
    w=np.ones(9)*0.1
    d1=forward_propagation(X[0],y[0],w)
    grader_forwardprop(d1)
```

[8]: True

5.2 Backward propagation

```
[9]: def backward_propagation(L,W,dicts):
         '''In this function, we will compute the backward propagation '''
         # L: the loss we calculated for the current point
         # dictionary: the outputs of the forward_propagation() function
         # write code to compute the gradients of each weight [w1,w2,w3,...,w9]
         # Hint: you can use dict type to store the required variables
         \# dw1 = \# in dw1 compute derivative of L w.r.to w1
         # dw2 = # in dw2 compute derivative of L w.r.to w2
         \# dw3 = \# in dw3 compute derivative of L w.r.to w3
         # dw4 = # in dw4 compute derivative of L w.r.to w4
         # dw5 = # in dw5 compute derivative of L w.r.to w5
         # dw6 = # in dw6 compute derivative of L w.r.to w6
         # dw7 = \# in dw7 compute derivative of L w.r.to w7
         \# dw8 = \# in dw8 compute derivative of L w.r.to w8
         \# dw9 = \# in dw9 compute derivative of L w.r.to w9
         dw = \{\}
         dw['dw1'] = dicts['dl'] * 2 * dicts['x'][0] * dicts['exp'] * (np.dot(W[0],
      \rightarrowdicts['x'][0]) + np.dot(W[1], dicts['x'][1])) * (1 - (dicts['tanh']**2))
         dw['dw2'] = dicts['dl'] * 2 * dicts['x'][1] * dicts['exp'] * (np.dot(W[0],
      \rightarrowdicts['x'][0]) + np.dot(W[1], dicts['x'][1])) * (1 - (dicts['tanh']**2))
         dw['dw3'] = dicts['dl'] * dicts['x'][2] * W[8] * np.cos(np.dot(W[2])_{ij})
      \rightarrowdicts['x'][2])) * (np.dot(W[4], dicts['x'][4]) + np.dot(W[3],

dicts['x'][3])) * dicts['sigmoid'] * (1 - dicts['sigmoid'])

         dw['dw4'] = dicts['dl'] * dicts['x'][3] * W[8] * np.sin(np.dot(W[2])_u

→dicts['x'][2])) * dicts['sigmoid'] * (1 - dicts['sigmoid'])
         dw['dw5'] = dicts['dl'] * dicts['x'][4] * W[8] * np.sin(np.dot(W[2],__

dicts['x'][2])) * dicts['sigmoid'] * (1 - dicts['sigmoid'])

         dw['dw6'] = dicts['dl'] * dicts['exp'] * (1 - (dicts['tanh']**2))
```

```
dw['dw7'] = dicts['dl'] * (1 - (dicts['tanh']**2))
dw['dw8'] = dicts['dl'] * W[8] * dicts['sigmoid'] * (1 - dicts['sigmoid'])
dw['dw9'] = dicts['dl'] * dicts['sigmoid']

return dw
# return dW, dW is a dictionary with gradients of all the weights
```

Grader function - 3

```
[10]: def grader_backprop(data):
          dw1=(np.round(data['dw1'],8)==-0.22973323)
          dw2=(np.round(data['dw2'],8)==-0.02140761)
          dw3=(np.round(data['dw3'],8)==-0.00562541)
          dw4=(np.round(data['dw4'],8)==-0.00465794)
          dw5=(np.round(data['dw5'],8)==-0.00100772)
          dw6=(np.round(data['dw6'],8)==-0.63347519)
          dw7=(np.round(data['dw7'],8)==-0.56194184)
          dw8=(np.round(data['dw8'],8)==-0.04806288)
          dw9=(np.round(data['dw9'],8)==-1.01810444)
          assert(dw1 and dw2 and dw3 and dw4 and dw5 and dw6 and dw7 and dw8 and dw9)
          return True
      w=np.ones(9)*0.1
      d1=forward_propagation(X[0],y[0],w)
      d1=backward_propagation(X[0],w,d1)
      grader_backprop(d1)
```

[10]: True

5.3 Implement gradient checking

```
[18]: W = np.ones(9)*0.1
def gradient_checking(data_point, W):
    x_train = data_point[:5]
    y_train = data_point[-1]

forward_result = forward_propagation(x_train, y_train, W)
    backward_result = backward_propagation(x_train, W, forward_result)
    delta = 10 ** -7

approx_gradient = {}
    gradient_checking = {}
    for ind in range(W.shape[0]):
        temp_w_i = temp_w_ii = W
        temp = W[ind]
        temp_w_i[ind] = temp + delta
        forward_result_i = forward_propagation(x_train, y_train, temp_w_i)
```

```
backward_result_i = backward_propagation(x_train, temp_w_i,_
 →forward_result_i)
        temp w ii[ind] = temp - delta
        forward_result_ii = forward_propagation(x_train, y_train, temp_w_ii)
        backward result ii = backward propagation(x train, temp w i, |
 →forward_result_ii)
        approx_gradient['dw{}'.format(ind+1)] = (forward_result_i['loss'] -__

→forward_result_ii['loss'])/( 2 * delta)

    for key in backward result.keys():
        gradient_checking[key] = (backward_result[key] - approx_gradient[key]) /
 → (backward_result[key] + approx_gradient[key])
    return gradient_checking
grad = gradient_checking(data[0], W)
print(grad)
{'dw1': -4.918867403857781e-10, 'dw2': 4.313072065448279e-07, 'dw3':
-5.96991379072821e-08, 'dw4': 5.328311462684123e-07, 'dw5':
```

6 Task 2: Optimizers

-1.1321577367826861e-08}

6.0.1 Algorithm with Vanilla update of weights

5.785228848348613e-07, 'dw6': -2.4944672635960616e-08, 'dw7': -1.5675493248917714e-07, 'dw8': -3.6260816099250785e-08, 'dw9':

```
[67]: # Setting Up Constants
    # Setting Fixed Seeding for better and replicable results
    np.random.seed(42)

# Mean of Normal Distribution of weights
    mu = 0

# Variance of Normal Distribution of weights
    sigma = 0.1

# Learning Rate
    eta = 0.1

# Creating a Normal Distribution of Weights
W = sigma * np.random.randn(9) + mu

# Creating list to capture loss
loss = []
```

```
# For Each Epoch
for epoch in range(0,100):
    # Copying Weights to calculate convergence
   temp = np.copy(W)
    # Creating list to capture at each datapoint loss
   temp_loss = []
   print('Executing Epoch {}'.format(epoch))
    # Looping over each datapoint
   for x_train, y_train in zip(data[:, :5], data[:, -1]):
        # Calculate Forward Propagation
       forward_result = forward_propagation(x_train, y_train, W)
        # Calculate Backward Propagation
       backward result = backward propagation(x_train, W, forward_result)
        # Capturing Loss
       temp_loss.append(forward_result['loss'])
        # Updating Each Set of Weights
       for ind, key in enumerate(backward_result.keys()):
            W[ind] = W[ind] - eta * backward_result[key]
    # Checking for convergence
   if np.where(W - temp > 10 ** -3)[0].shape[0] == 0:
       print('\n')
       print("-"*100)
       print('Weigths Have Converged')
       print("-"*100)
       break
    # Calculating mean loss for each epoch
    loss.append(np.mean(temp_loss))
```

```
Executing Epoch 0
Executing Epoch 1
Executing Epoch 2
Executing Epoch 3
Executing Epoch 4
Executing Epoch 5
Executing Epoch 6
Executing Epoch 7
Executing Epoch 8
Executing Epoch 9
Executing Epoch 10
Executing Epoch 11
```

- Executing Epoch 12
- Executing Epoch 13
- Executing Epoch 14
- Executing Epoch 15
- Executing Epoch 16
- Executing Epoch 17
- Executing Epoch 18
- Executing Epoch 19
- Executing Epoch 20
- Executing Epoch 21
- Executing Epoch 22
- Executing Epoch 23
- Executing Epoch 24
- Executing Epoch 25
- Executing Epoch 26
- Executing Epoch 27
- Executing Epoch 28
- Executing Epoch 29
- Executing Epoch 30
- Executing Epoch 31
- Encouoring Epoch of
- Executing Epoch 32
- Executing Epoch 33
- Executing Epoch 34
- Executing Epoch 35
- Executing Epoch 36
- Executing Epoch 37 Executing Epoch 38
- Executing Epoch 39
- Encouring Epoon of
- Executing Epoch 40
- Executing Epoch 41
- Executing Epoch 42
- Executing Epoch 43
- Executing Epoch 44
- Executing Epoch 45
- Executing Epoch 46
- Executing Epoch 47
- Executing Epoch 48
- Executing Epoch 49
- Executing Epoch 50
- Executing Epoch 51
- Executing Epoch 52
- Executing Epoch 53
- Executing Epoch 54
- Executing Epoch 55
- Executing Epoch 56
- Executing Epoch 57
- Executing Epoch 58
- Executing Epoch 59

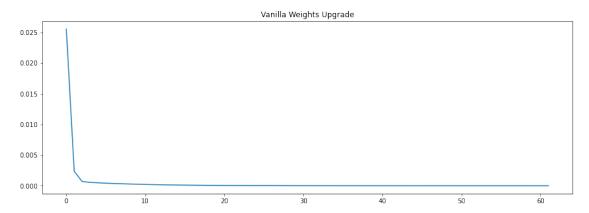
```
Executing Epoch 60
Executing Epoch 61
Executing Epoch 62
```

Weigths Have Converged

Plot between epochs and loss

```
[68]: _, ax = plt.subplots(1, 1, figsize=(15,5))
ax.plot(loss)
ax.set_title('Vanilla Weights Upgrade')
plt.show()

vanilla_loss = loss
```



6.0.2 Algorithm with Momrentum update of weights

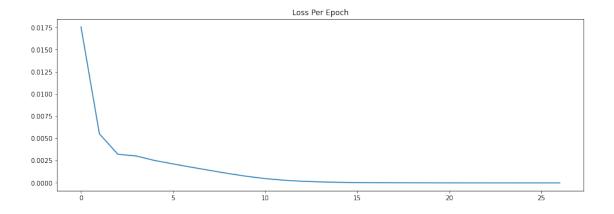
```
[69]: # Setting Up Constants
    # Setting Fixed Seeding for better and replicable results
    np.random.seed(42)
    # Mean
    mu = 0

# Standard Deviation
    sigma = 0.1

# Learning Rate
    eta = 0.1
```

```
# Gamma for momentum
gamma = 0.9
# Calculating weighs from a Normal Distribution
W = sigma * np.random.randn(9) + mu
loss = \Pi
for epoch in range (0,100):
    # Copy Weigts for convergence evaluation
    temp = np.copy(W)
    temp_loss = []
    print('Executing Epoch {}'.format(epoch))
    # Place holder for capturing all the momentum values
    v = \{\}
    for t, points in enumerate(zip(data[:, :5], data[:, -1])):
        x_train = points[0]
        y_train = points[1]
        # Forward Propagation
        forward_result = forward_propagation(x_train, y_train, W)
        # Backward Propagation
        backward_result = backward_propagation(x_train, W, forward_result)
        # Calculating loss for each data point
        temp_loss.append(forward_result['loss'])
        # Weights Updation
        for ind, key in enumerate(backward_result.keys()):
            if t not in v.keys():
                v[t] = \{\}
            if t == 0:
                # Storing values of momentum to be used for the next iteration
                v[t][key] = eta * backward_result[key]
            else:
                # Storing values of momentum to be used for the next iteration
                v[t][key] = gamma * v[t-1][key] + eta * backward_result[key]
            # Updating Weights Using Momentum
            W[ind] = W[ind] - v[t][key]
    # Checking for convergence
    if np.where(W - temp > 10 ** -3)[0].shape[0] == 0:
        print('\n')
        print("-"*100)
        print('Weigths Have Converged')
        print("-"*100)
        break
    loss.append(np.mean(temp_loss))
```

```
Executing Epoch 0
     Executing Epoch 1
     Executing Epoch 2
     Executing Epoch 3
     Executing Epoch 4
     Executing Epoch 5
     Executing Epoch 6
     Executing Epoch 7
     Executing Epoch 8
     Executing Epoch 9
     Executing Epoch 10
     Executing Epoch 11
     Executing Epoch 12
     Executing Epoch 13
     Executing Epoch 14
     Executing Epoch 15
     Executing Epoch 16
     Executing Epoch 17
     Executing Epoch 18
     Executing Epoch 19
     Executing Epoch 20
     Executing Epoch 21
     Executing Epoch 22
     Executing Epoch 23
     Executing Epoch 24
     Executing Epoch 25
     Executing Epoch 26
     Executing Epoch 27
     Weigths Have Converged
     Plot between epochs and loss
[70]: _, ax = plt.subplots(1, 1, figsize=(15,5))
      ax.plot(loss)
      ax.set_title('Loss Per Epoch')
      plt.show()
      momentum_loss = loss
```



6.0.3 Algorithm with Adam update of weights

```
[100]: # Setting Up Constants
       # Setting Fixed Seeding for better and replicable results
       np.random.seed(42)
       # Mean
       mu = 0
       # Standard Deviation
       sigma = 0.1
       # Learning Rate
       eta = 0.1
       # Calculating weights from a Normal Distribution
       W = sigma * np.random.randn(9) + mu
       loss = []
       beta={1:0.9, 2:0.99}
       alpha = 0.001
       epsilon = 10 ** -7
       for epoch in range(0,100):
           # Copy Weigts for convergence evaluation
           temp = np.copy(W)
           temp_loss = []
           print('Executing Epoch {}'.format(epoch))
           print(W)
           # Place holder for capturing all the momentum values
           V = \{\}
           m = \{\}
```

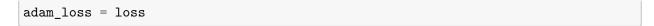
```
for t, points in enumerate(zip(data[:, :5], data[:, -1])):
       x_train = points[0]
       y_train = points[1]
       # Forward Propagation
       forward_result = forward_propagation(x_train, y_train, W)
       # Backward Propagation
       backward_result = backward_propagation(x_train, W, forward_result)
       # Calculating loss for each data point
       temp loss.append(forward result['loss'])
       # Weights Updation
       m cap = \{\}
       v_{cap} = \{\}
       m[t] = \{\}
       v[t] = \{\}
       for ind, key in enumerate(backward_result.keys()):
           if key not in m.keys():
               m[t][key] = {}
               v[t][key] = {}
           # Exponential Decaying Average
           if t == 0:
               m[t][key] = (1-beta[1]) * backward_result[key]
               v[t][key] = (1-beta[2]) * (backward_result[key] ** 2)
           else:
               m[t][key] = (beta[1] * m[t-1][key]) + ((1-beta[1]) *_{\sqcup}
→backward_result[key])
               v[t][key] = (beta[2] * v[t-1][key]) + ((1-beta[2]) *_{\bot}
# Bias Correction
           m_{cap[key]} = m[t][key]/(1-(beta[1] ** 2))
           v_{cap}[key] = v[t][key]/(1-(beta[1] ** 2))
           # Updating Weights Using Momentum
           W[ind] = W[ind] - ((alpha * m_cap[key])/((np.

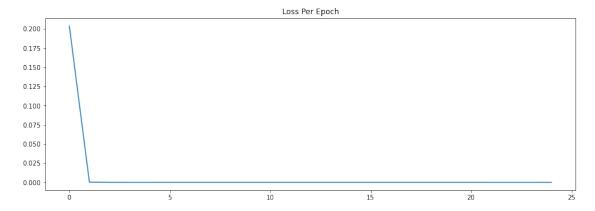
sqrt(v_cap[key]))+epsilon))
   # Checking for convergence
   if np.where(W - temp > 10 ** -2)[0].shape[0] == 0:
       print('\n')
       print("-"*100)
       print('Weigths Have Converged')
       print("-"*100)
       break
```

loss.append(np.mean(temp_loss))

```
Executing Epoch 0
[ 0.04967142 - 0.01382643 \ 0.06476885 \ 0.15230299 - 0.02341534 - 0.0234137 ]
  0.15792128 0.07674347 -0.04694744]
Executing Epoch 1
0.55713967 1.14462593 0.99733857]
Executing Epoch 2
[ \ 0.71668682 \ \ 0.17841498 \ -1.02483006 \ -0.99369323 \ -1.02768891 \ \ 0.56922
  0.67514454 1.05145805 1.00588215]
Executing Epoch 3
[ 0.7550966
              0.02637095 -0.99341282 -1.00774675 -1.02183591 0.70730048
  0.81646929 1.02196702 1.00079792]
Executing Epoch 4
[ \ 0.77917404 \ \ 0.04504284 \ \ -1.00756625 \ \ -1.0060123 \ \ \ -1.00276255 \ \ \ 0.76285014
  0.87641409 1.01920124 1.0039031 ]
Executing Epoch 5
[0.78590844 \ 0.0109296 \ -0.99752301 \ -1.00920052 \ -1.00810754 \ 0.81650671
             1.00893415 1.00518362]
  0.9364778
Executing Epoch 6
[ 0.83864996 -0.02488791 -1.00604472 -1.00327221 -1.01813819  0.86066361
  0.9801075
             0.99788298 1.00469309]
Executing Epoch 7
 \hbox{ [ 0.76945744 } \hbox{ 0.09907162 } \hbox{-1.0015239 } \hbox{ -0.97801338 } \hbox{-0.99057862 } \hbox{ 0.84961851} 
  0.97591525 0.99822687 0.99491219]
Executing Epoch 8
[ \ 0.78804747 \ \ 0.05971815 \ \ -0.9954287 \ \ \ -0.98496291 \ \ -0.99042389 \ \ \ 0.93409867 ]
  1.06430289 1.00797372 0.99303475]
Executing Epoch 9
1.13621376 1.0081935 0.99321198
Executing Epoch 10
[ 0.84444874 -0.08258764 -0.99111715 -1.01333547 -1.00622727 1.07466253
  1.21035964 1.00168986 1.00513244]
Executing Epoch 11
 \hbox{ [ 0.86169512 -0.00676612 -1.00983749 -0.99743721 -1.01252626 \  \  1.07432873] }
  1.21170406 0.9945281 1.00506031]
Executing Epoch 12
[\ 0.77033157 \ \ 0.12153459 \ -0.99978128 \ -0.97937329 \ -0.98369266 \ \ 1.00213066
  1.14647618 0.99626377 0.99457395]
Executing Epoch 13
[0.77084417 \ 0.13924806 \ -0.99634589 \ -0.98611454 \ -0.99775518 \ 1.07109095]
  1.21797124 0.99729933 0.99587703]
Executing Epoch 14
 \hbox{ [ 0.82173543 \  \, 0.05704928 \  \, -0.99703526 \  \, -1.00887589 \  \, -1.00844963 \  \, \, 1.15469229 } 
  1.30100296 0.99852061 1.00523302]
```

```
Executing Epoch 15
      1.2218226
                   0.98918239 1.00024171]
      Executing Epoch 16
      [ \ 0.67383647 \quad 0.23124916 \ -1.00147594 \ -0.97676052 \ -1.00144209 \quad 1.08360021 \\
        1.24359972 0.99854341 0.99046523]
      Executing Epoch 17
       \begin{bmatrix} 0.68000747 & 0.2736527 & -0.99784945 & -0.98954408 & -0.98758955 & 1.01216643 \end{bmatrix} 
        1.17207433 1.00225757 0.99728205]
      Executing Epoch 18
       \begin{smallmatrix} 0.77085062 & 0.27078706 & -0.9891589 & -1.03216815 & -1.00572212 & 0.98663016 \end{smallmatrix} 
        1.14020926 0.99583706 1.01323832]
      Executing Epoch 19
      [ 0.75729412  0.22981133 -0.99967699 -1.00246993 -1.00516742  1.08804358
        1.24445934 1.00092418 1.00279731]
      Executing Epoch 20
      1.22092954 1.00438909 0.98912044]
      Executing Epoch 21
      [\ 0.67197697\ \ 0.32703883\ -0.99760148\ -0.99064119\ -0.98876448\ \ 0.99431126
        1.15634226 1.00444471 0.99665757]
      Executing Epoch 22
      1.19296808 0.99718589 1.00841679]
      Executing Epoch 23
      [ \ 0.70153758 \ \ 0.3237949 \ \ -1.00238696 \ \ -0.99941285 \ \ -1.01068756 \ \ \ 1.05289133
        1.21580877 0.9921103 1.00252318]
      Executing Epoch 24
      [0.75061486 \quad 0.35352831 \quad -0.99195797 \quad -1.01200741 \quad -1.00214524 \quad 1.15048566
        1.30734705 0.99751855 1.00657222]
      Executing Epoch 25
      [ \ 0.74244418 \ \ 0.37994618 \ -1.01306386 \ -1.00514252 \ -1.0159127 \ \ \ 1.10347808
        1.26130887 0.98980567 1.00815956]
      Weigths Have Converged
      Plot between epochs and loss
[101]: _, ax = plt.subplots(1, 1, figsize=(15,5))
      ax.plot(loss)
      ax.set_title('Loss Per Epoch')
      plt.show()
```





Comparision plot between epochs and loss with different optimizers

```
[102]: __, ax = plt.subplots(1, 1, figsize=(20,10))
    ax.plot(vanilla_loss, label='Vanilla',color='Green', alpha=0.7)
    ax.plot(momentum_loss, label='Momentum',color='Blue', alpha=0.9)
    ax.plot(adam_loss, label='Adam',color='Red')
    ax.set_title('Loss Comparison')
    ax.legend()
    plt.show()
```

