# Tejaswin Parthasarathy GRADUATE STUDENT, MECHANICAL SCIENCES

EDUCATION	University of Illinois at Urbana-Champaign (UIUC), USA Master of Science, Mechanical Sciences and Engineering	<b>GPA: 4.00/4.00</b> 2016 - 2018 (Tentative)
	Indian Institute of Technology Madras (IITM), India Bachelor of Technology (Honours), Mechanical Engineering	<b>Cumulative GPA: 9.67/10.00</b> 2012 - 2016
RESEARCH INTERESTS	Fluid physics, Numerical Fluid Dynamics, Numerical Algorithms allel Computing, Flow and Instability Control, Aeroacoustics	, High Performance and Par-
Publications	<b>Tejaswin Parthasarathy</b> and Mattia Gazzola. "Scaling arguments lating cylinders", 70 <sup>th</sup> Annual Meeting of the APS Division of Fl Talk	
	Mattia Gazzola and <b>Tejaswin Parthasarathy</b> . "Viscous streamin port", 70 <sup>th</sup> Annual Meeting of the APS Division of Fluid Dynamics	
	Das, Shyama Prasad, and <b>Tejaswin Parthasarathy</b> . "Effect of pausing synthetic jet." International Journal of Fluid Mechanics Rese	
	Parthasarathy, Tejaswin and S. P. Das. "Some aspects of flow confusing synthetic jets." Journal of Physics: Conference Series. Vol. 2017. (15 <sup>th</sup> Asian Congress of Fluid Mechanics)	
	Parthasarathy, Tejaswin, Vignesh Srinivasaragavan, and Soundar "ADAMS-MATLAB Co-Simulation of A Serial Manipulator." MAT 95. EDP Sciences, 2017. ICMME 2016	
AWARDS & ACHIEVEMENTS	Awarded the H.C.Ting Distinguished Fellowship at UIUC for sch Secured the Z-Wing Award for comprehensive performance across Pursued the Honours degree at IITM, completing 3 additional gr to select meritorious students Secured the Dr. Vivekanand Kochikar Award and Dr. Dinesh Ba lence in academics in B.Tech. Mechanical Engineering Awarded the Nissan Global Foundation Scholarship for compre IITM Awarded the KVPY Fellowship & DST-Inspire Fellowship for sc National high-school Olympiad (Astronomy, Physics) finalist	s Narmada <sup>1</sup> [2016] aduate level courses, offered [2016] alagangadhar Prize for excel- [2015] Ref. ehensive performance across [2014] Ref.
SKILLS	Computing: C, C++, Matlab, Python, Bash, LATEX Software: Git, Makefiles, SolidWorks, Fluent, MS Excel, Tecplot, P. Other: HPC systems, Parallelism APIs (OpenMP, TBB, MPI) & High	
RESEARCH PROJECTS	Viscous Streaming - Physics & Applications Advisor : Prof. Mattia Gazzola, MechSE, UIUC	Dec '16 - Present

<sup>&</sup>lt;sup>1</sup>Residence hall at IITM

- Numerically investigating the fundamental physics of the viscous streaming (after extensive validation) using fluids, model-order reduction and dynamical systems theory, while simultaneously deriving design principles for broad deployment in micro scale & biological systems
- Leading the group's fluid dynamics research as the primary software & scientific developer of a 2D uniform resolution DNS code, used to investigate a variety of Fluid-Structure Interaction (FSI) problems
- Enhanced the scalability and performance of the shared memory code by refining data structures, optimizing memory access and localizing operators, improving the time to solution by 40%
- Co-wrote key parts of a NSF career proposal with Prof. Gazzola, exploring ideas for research direction and providing technical content

### Flow Control over aerofoils using Synthetic Jets

Advisor: Prof. S.P Das, HTML, IITM

Jul '15 - Apr '16

- Extensively simulated and validated the cases of uncontrolled flow over an aerofoil, synthetic jets in quiescent media and controlled flow over an aerofoil
- Numerically investigated the effect of parameters on the control of boundary layer using single synthetic jets over 2-D aerofoils, with an emphasis on understanding the flow physics
- Optimized the operational parameters of the aforementioned synthetic jets to achieve performance enhancement and explored the use of quick return mechanisms to control the time of blowing/suction
- Contributed to the fundamental understanding of the effect of synthetic jets as a means of extracting energy from the flow to control/enhance the lift and shedding performance

### Surgical Robot Simulation and Path Planning

Advisor: Prof. S. Soundarapandian, MES, IITM

Dec '14 - Sep '15

- Reverse engineered, modeled and & drafted a path planning algorithm for a defunct robotic arm
- Designed the control software for the aforesaid robotic arm, ensuring precise and accurate path adherence in orthopaedic surgery applications, which was verified by simulating the same in the ADAMS environment, with custom codes for robot activation and feedback control
- Arrived at a final design for retrofitting the arm to meet high degrees of precision and accuracy at affordable costs, with help from ABB, after an iterative design process
- Simultaneously developed a framework for retrofitting obsolete robotic arms for use as an educational aid in robotics labs & courses (for modules such as path planning and trajectory control)

## ACADEMIC PROJECTS

do

Instructor: Prof. Andreas Kloeckner, CS598, UIUC

Aug '17 - Present

-do

do

Instructor: Prof. Laxmikant Kale, CS484, UIUC

Aug '17 - Present

-do

### 3-D Navier-Stokes Solver for simulation of Atmospheric Phenomena

Instructor: Prof. Brian Ford Jewett, ATMS502, UIUC

Feb '17 - May '17

- Developed a 3-D nonlinear quasi-compressible flow solver using Finite Volume Methods (FVM), grid staggering and Operator splitting, with OpenMP for parallelism
- Also developed an equivalent version for 2-D with Adaptive Mesh Refinement (AMR) capabilities

#### Solutions for Potential Flow past Cylinders

Instructor: Prof. Arul K Prakash, AM5530, IITM

Iul '15 - Nov '15

- Analytically derived solutions for potential flow past multiple cylinders using complex number theory, based on Crowdy's seminal work & implemented efficient numerical algorithms in MAT-LAB/Mathematica for solving the system within  $\sim 30$ s

Details and additional projects can be found here.

Relevant Coursework	Fluids Viscous Flows Inviscid Flows Aeroacoustics Turbulent Flows† Flow Instabilities†	Numerics Fast Algorithms Comp. Mechanics Numerical Fluids Intro to CFD†	Math PDE Calculus† Linear Algebra† ODE†	Controls Linear System Control Nonlinear Control†  Computing Parallel Programming	
Professional Experience	Technical Intern, Hindustan Unilever Ltd, India Guide: Sugam Kumar, COO, Khamgaon Division May '15 - Jul				
	<ul> <li>Designed &amp; implemented an indigenous automatic reel-changing mechanism for soap tablet wroping thereby reducing downtime from 41 s per reel change to 4 s &amp; saving \$ 11000 p.a. per line</li> <li>Initiated rollout of this universal, safe&amp; automated design across affiliated soap factories</li> <li>Investigated &amp; partially solved the tablet-infeed jamming issue, reducing incidence by 86 % (controlled environment) &amp; recovering \$6314 p.a. in direct cost</li> </ul>				
	Details of additional experience at TVS Motor Company Ltd. can be found here.				
POSITIONS OF RESPONSIBILITY	Head, Marketing and Shaastra 2016, Annual	l Student Relations Technical Festival of IITN	1	Apr '15 - Jan '16	
	<ul> <li>Managed one of Asia's biggest technical festival, with a budget of \$165000 &amp; a footfall of 30000</li> <li>Spearheaded a team of 40, reaching out to 20000 students across India, improving brand penetration by 10%</li> </ul>				
	Also undertook other leadership roles in student & technical affairs. Please visit here for details.				
EXTRA CURRICULARS	Software Dev.: Member, CSE & THW Illinois chapters and regular HPC workshop participant (XSEDE, Nvidia Deep Learning, BW Scaling to Petascale) Honor Societies: Pi Tau Sigma & Tau Beta Ri Volunteer Work for TBP Hobbies: Hiking, Quizzing, Thespian (Short Film and Dramatics)				

<sup>†</sup> represents courses taken in undergraduate