Queue¹

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(Queue)

 $^{^{1}\}mathrm{C}$ code is developed on the board (and the same is not available in slides)

Introduction

• Motivation for First-In-Fist-Out (FIFO) data structure job scheduling message buffers

• Essential operations to be supported include:

enqueue an element to queue dequeue an element from queue

(Queue)

Fixed-size queue

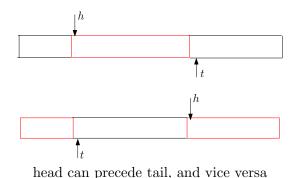
```
#define QUEUESIZE 1000
typedef struct {
   void *p[QUEUESIZE];
   int head; //p[head] is the element to be dequeued
   int tail; //enqueued element is placed at p[tail]
} Queue;
int initialize(Queue *q);
int enqueue(Queue *q, void *data);
void *dequeue(Queue *q);
```

Fixed-size queue

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```

• drawback in viewing p[] as a linear array: overflow may occur while many entries in p[] are not utilized

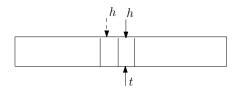
Fixed-size circular queue²



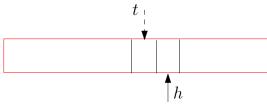
- array p in the queue data structure (mentioned above) is viewed as a circular
- move head and tail over p[] using modular arithmetic

 $^{^{2}}$ considered to be the default queue: the word circular may not always be mentioned 4 D > 4 B > 4 E > 4 E > E 990 (Queue)

Fixed-size circular queue (cont)



indicates queue is empty (reset tail to -1 and head to 0)



indicates queue is full

5 / 10

Worst-case time complexity

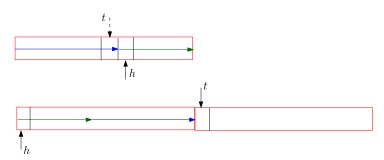
- enqueue: O(1) time and O(1) space
- dequeue: O(1) time and O(1) space

6 / 10

Dynamic-sized circular queue

```
typedef struct {
   int capacity;
   int head; //p[head] is the element to be dequeued
   int tail; //enqueued element is placed at p[tail]
   void **p; //p is a pointer to an array of void *s
} Queue;
int initialize(Queue *q,
                int initialCapacity);
int destroy(Queue *q);
int enqueue(Queue *q, void *data);
void *dequeue(Queue *q);
```

Dynamic-sized circular queue



resize when the queue is full

- ullet when the overflow occurs, double the size of buffer pointed by p
- when the queue is one-quarter full, halve the size of buffer pointed by $p \leftarrow \text{homework}$
- in both of these cases, avoid using realloc (which implicitly frees old buffer) instead use malloc and explicitly free the old buffer

Deque

data structure having provision for adding/removing at either of its ends is known as a doubly-ended queue (a.k.a. $deque^3$)

homework: implement the dynamic-sized deque

Stack using Queue, and vice versa

Homework:

- Implement Stack using Queue and analyze the asymptotic time and space complexities of the resultant push and pop
- Implement Queue using Stack and analyze the asymptotic time and space complexities of the resultant enqueue and dequeue

(Queue)