

## Expt 5: - Best First Search & A\* Alg. for Real World Problems

\*

Problem

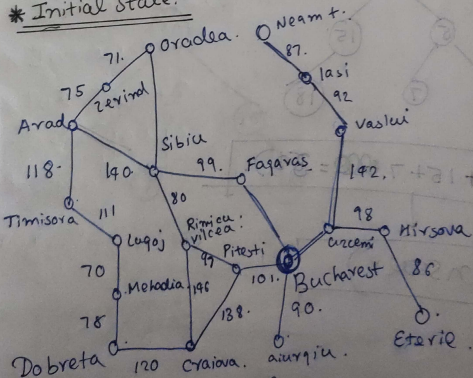
A Romanian map is given we have to find the shortest path with

least path cost using A\* and Best First Search Problem.

\* Path cost: - The sum of the cost from the initial to the final node.

\* Operators: - The node ~~node~~ and the paths (costs) are the operators in this problem

\* Initial State: -



Romanian Map  
Nodes.

# Straight Line Distance to Bucharest

Arad	366
Bucharest [Goal]	0
Craiova	160.
Dobreta	242
Eforie	<del>160</del> 161
Fagaras	<del>160</del> 178
Giurgiu	77
Hirsova	151.
Iasi	226
Iugoj	244.
Mehadia	241
Neamt	234.
Oradea	380
Pitesti	98.
Rimica Vileea	193.
Sibiu	253.
Timisoara	329
Urziceni	80
Vaslui	199
Zerind	379.

## \* Algorithm: -

### (1) Best First Search: -

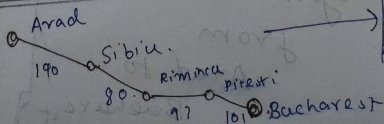
- \* Create a priority queue: `pqueue`.
- \* Insert 'start' in `pqueue`: `pqueue.insert(Search)`
- \* Delete all elements of `pqueue` one by one
- \* If the element is goal. Exit.
- \* Else, traverse neighbours and mark the node examined.

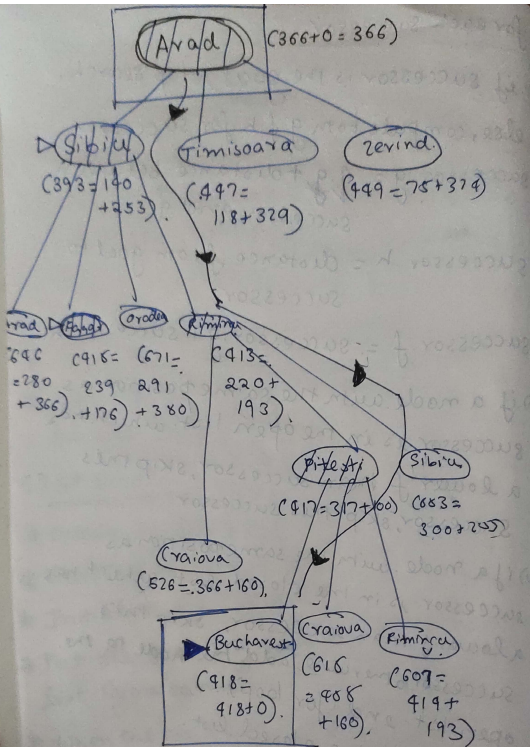
### (2) A\* Star: -

- \* Create two lists - Open and Closed.
- \* Initialize the open list
- \* Initialize the closed list.
- \* Put the starting node on the open list. (You can leave its  $f$  at zero).
- \* When the open list is not empty:
  - (1) Find the node with the least  $f$  on the open list; call it 'q'.
  - (2) Pop q off the open list.
  - (3) Generate q's successors and set their parents to q.

- c) for each successor:
- (i). if successor is the goal, stop search.
  - (ii) else, compute both  $g$  &  $h$  for successor.  
 $\text{successor.g} = g + \text{distance between successor and } q$   
 $\text{successor.h} = \text{distance from goal to successor}$   
 $\text{successor.f} = \text{successor.g} + \text{successor.h}$
  - (iii). if a node with the same position as successor is in the open list which has a lower  $f$  than successor, skip this successor, skip this successor
  - (iv) if a node with the same position as successor is in the closed list which has a lower  $f$  than successor, skip this successor, otherwise, add the node to the open list. end (for loop).
  - (v). push  $q$  on the closed list.  
end (while loop).

Goal state: -





(Calculation  
of Distance  
from  
Arad to  
Bucharest)