

CEC450

Real-Time Systems

Lecture 15 – Block Diagram Design Examples



Design Elements for Proof-of-Concept

- Top N Capability (Functional) Oriented Requirements
 - State and Explain what your solution “must” do or “shall” do
 - Hold Q&A and Ask for Reviewer Input on Completeness, Errors and Omissions
- Top N Real-Time Requirements [C_i , T_i , D_i or each S_i]
 - State and Explain Service request frequency drivers and relative deadlines
 - How did you estimate or measure C_i WCET
- Single Page High Level Block Diagram of Software System
 - Show End-to-End Elements and Dataflow
 - Source to Sink (Top Left Corner to Bottom Right)
- CFD/DFD, Flow Charts, State Machines or Other Design Models
- Proof-of-Concept Time-Stamp Tracing Analysis

Top Level Design Examples

STS-85 Payload
(Flown 1997, U. of Colorado)



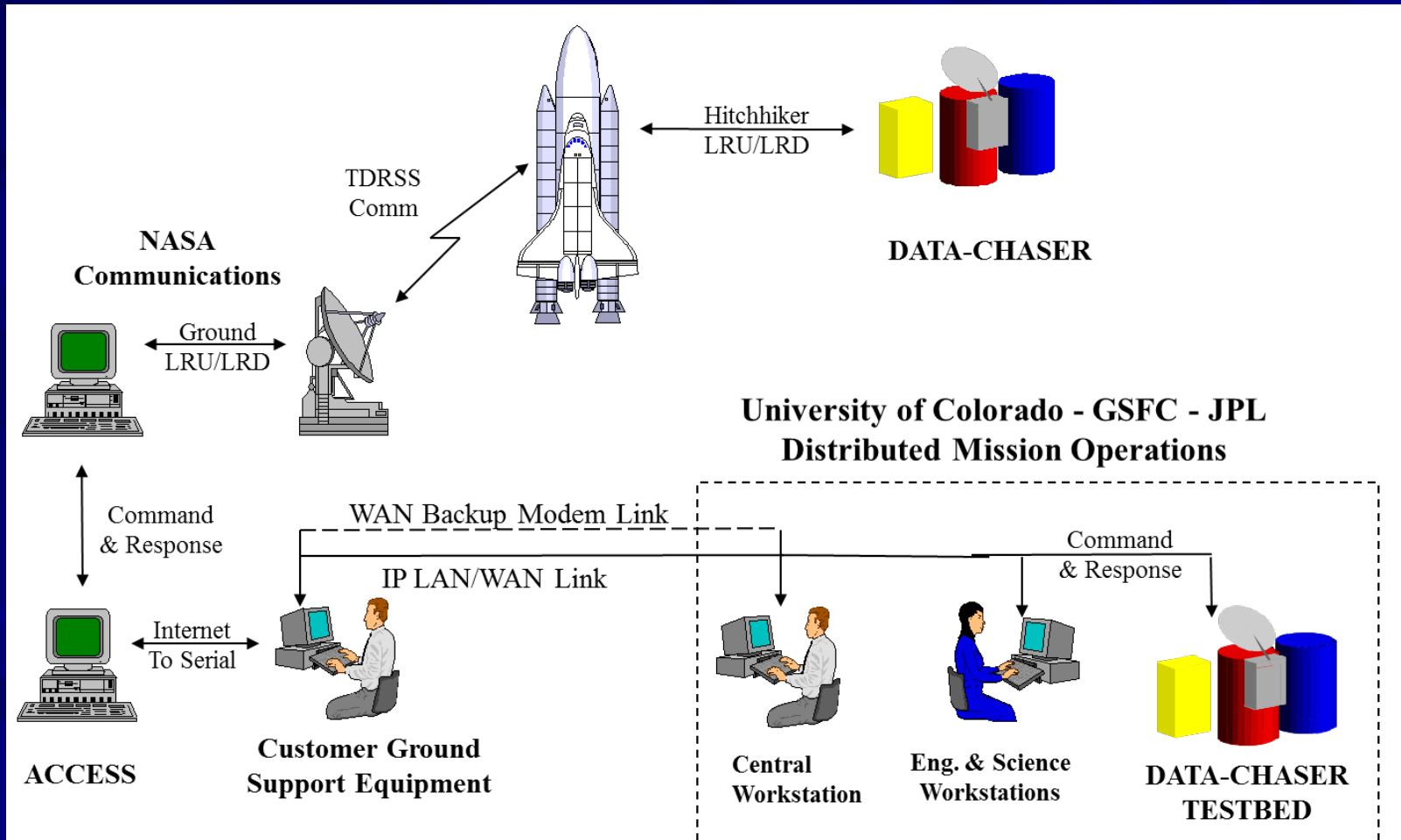
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Payload Operations Requirements

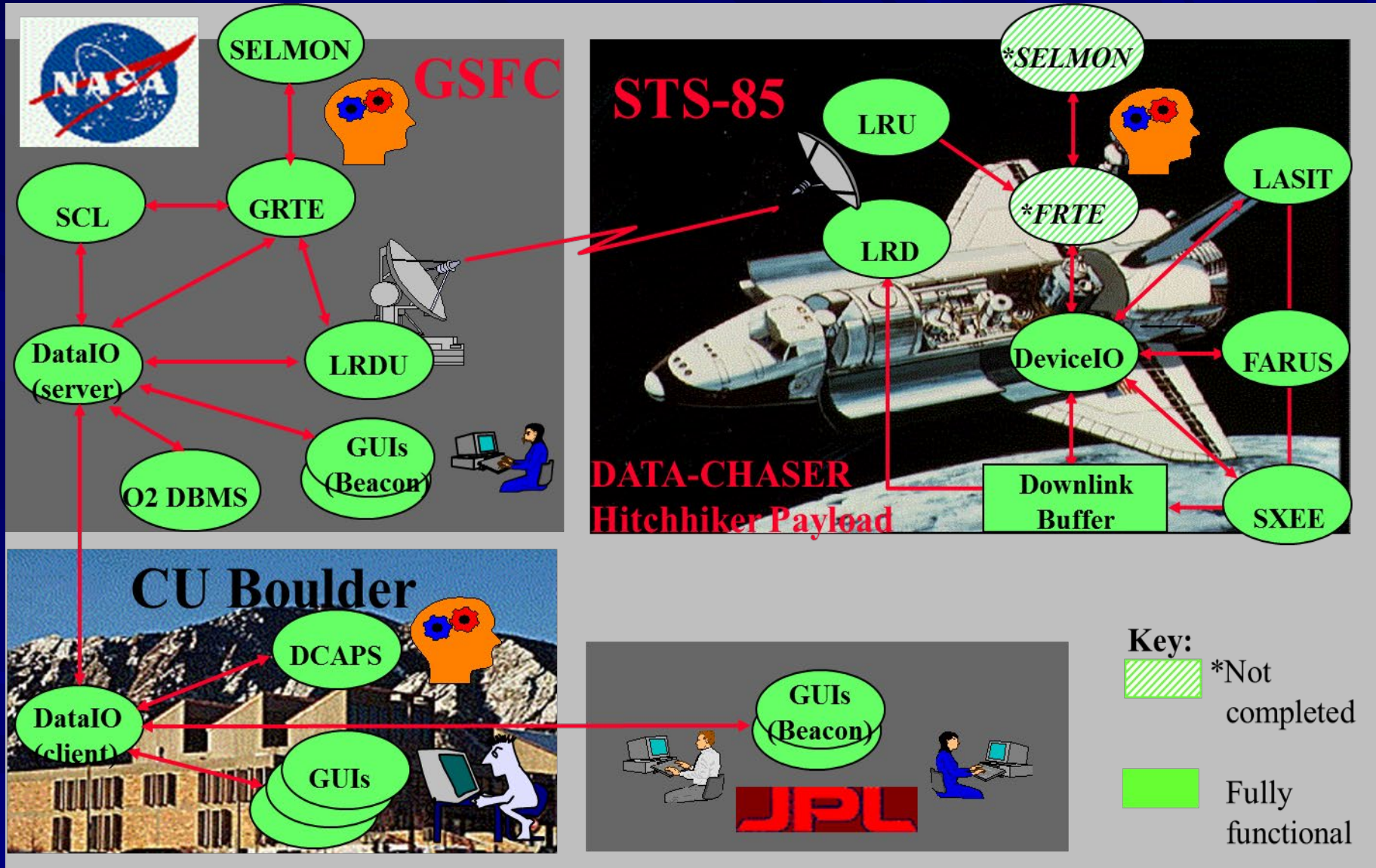
1. The **Embedded System** shall Operate 3 Instruments (LASIT, SXEE, FARUS) According to a Scheduled Observing Plan of the Sun **within STS Imposed Viewing and Operation Constraints**
2. The Health & Status of Each Instrument shall be Reported to the Ground **Continuously at no less than 1 Hz**
3. Science Data Collected by Each Instrument shall be **Streamed** to the Ground **While an Instrument is Observing**
4. Observing Plan Updates must be Uplinked from the Ground Systems **as Command(s) with Response**
5. Commands to Operate Instruments Interactively must be Uplinked from the Ground and Status Indication Response Will be Provided
6. The Embedded System must Interface to **Low-Rate Uplink and Downlink interfaces on STS** for Command/Response, and H&S Telemetry Streaming
7. The Ground Software **at GSFC** must Interface to the **ACCESS LRDU**
8. Telemetry must be Stored in a Time-stamped Database
9. A HMI GUI must Display **H&S Telemetry at GSFC** and Provide a Command/Response Interface
10. **GSFC Ground Systems** must Host a Planning and Operations Rules and Constraints Database and Engine
11. **GSFC Ground Systems** must Host H&S Telemetry Monitoring to Detect Anomalous Behavior to Generate Alerts for the HMI/GUI
12. A Data Bridge **Between GSFC Ground Systems and CU Boulder** must Provide a Command/Response and H&S Telemetry Network Interface
13. **CU Boulder Ground Systems** must Interface an Automated Planning and Scheduling Software Application and Allow it to Generate Uplink Commands to Modify or Replace the Current Embedded System Observing Plan
14. The **CU Boulder Ground Systems** must Provide an HMI/GUI for H&S Telemetry, Command/Response and Automated Planning and Scheduling
15. A **CU Boulder to NASA JPL Data Bridge** must Provide **H&S Telemetry for Beacon Monitoring to NASA JPL** for Display on a High Level Status HMI/GUI

System Block Diagram

- Simple Interfacing between Major Hardware and Software Elements (Components or Subsystems) with User Interaction Shown
- E.g. CU Boulder Space Grant DATA-CHASER Mission (STS-85)



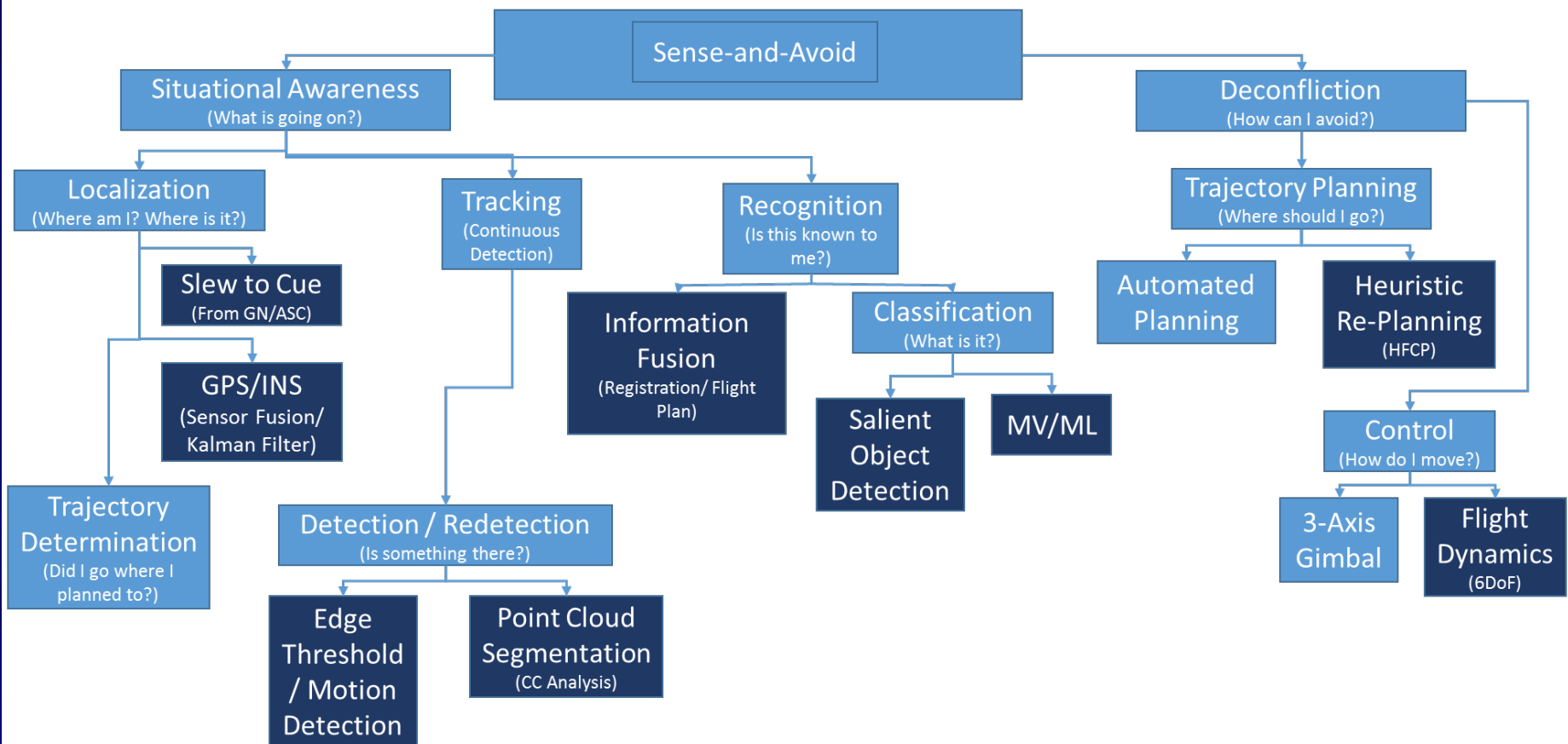
Software End-to-End System



System of Systems Block Diagram

- Complex Systems that are Systems of Systems or Integration of Subsystems that can also stand alone (E.g. Drone Net)
- E.g. [IEEE SOSE](#) (Drone Net IEEE Aerospace - [presentation](#), [paper](#))

Taxonomy of Algorithms and for Urban UTM Navigation and Deconfliction



Application Block Diagram

- Hardware shows standard platform(s), Software, and User Interaction
- Label Interface Dataflow and Protocols
- E.g. Contacts App on AOS

