# Non-Linear Least-Squares Minimization and Curve-Fitting for Python

Release 0.9.3

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Warning: Upgrading scripts from version 0.8.3 to 0.9.0? See whatsnew\_090\_label

Lmfit provides a high-level interface to non-linear optimization and curve fitting problems for Python. Lmfit builds on and extends many of the optimization algorithm of scipy.optimize, especially the Levenberg-Marquardt method from optimize.leastsq.

Lmfit provides a number of useful enhancements to optimization and data fitting problems, including:

- Using Parameter objects instead of plain floats as variables. A Parameter has a value that can be varied in the fit, have a fixed value, or have upper and/or lower bounds. A Parameter can even have a value that is constrained by an algebraic expression of other Parameter values.
- Ease of changing fitting algorithms. Once a fitting model is set up, one can change the fitting algorithm used to find the optimal solution without changing the objective function.
- Improved estimation of confidence intervals. While optimize leastsq will automatically calculate uncertainties
  and correlations from the covariance matrix, the accuracy of these estimates are often questionable. To help
  address this, lmfit has functions to explicitly explore parameter space to determine confidence levels even for
  the most difficult cases.
- Improved curve-fitting with the Model class. This extends the capabilities of optimize.curve\_fit, allowing you to turn a function that models for your data into a python class that helps you parametrize and fit data with that model.
- Many pre-built models for common lineshapes are included and ready to use.

The lmfit package is Free software, using an MIT license. The software and this document are works in progress. If you are interested in participating in this effort please use the lmfit github repository.

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## GETTING STARTED WITH NON-LINEAR LEAST-SQUARES FITTING

The lmfit package is designed to provide simple tools to help you build complex fitting models for non-linear least-squares problems and apply these models to real data. This section gives an overview of the concepts and describes how to set up and perform simple fits. Some basic knowledge of Python, numpy, and modeling data are assumed.

To do a non-linear least-squares fit of a model to data or for a variety of other optimization problems, the main task is to write an *objective function* that takes the values of the fitting variables and calculates either a scalar value to be minimized or an array of values that is to be minimized in the least-squares sense. For many data fitting processes, the least-squares approach is used, and the objective function should return an array of (data-model), perhaps scaled by some weighting factor such as the inverse of the uncertainty in the data. For such a problem, the chi-square ( $\chi^2$ ) statistic is often defined as:

$$\chi^2 = \sum_{i}^{N} \frac{[y_i^{\text{meas}} - y_i^{\text{model}}(\mathbf{v})]^2}{\epsilon_i^2}$$

where  $y_i^{\text{meas}}$  is the set of measured data,  $y_i^{\text{model}}(\mathbf{v})$  is the model calculation,  $\mathbf{v}$  is the set of variables in the model to be optimized in the fit, and  $\epsilon_i$  is the estimated uncertainty in the data.

In a traditional non-linear fit, one writes an objective function that takes the variable values and calculates the residual  $y_i^{\text{meas}} - y_i^{\text{model}}(\mathbf{v})$ , or the residual scaled by the data uncertainties,  $[y_i^{\text{meas}} - y_i^{\text{model}}(\mathbf{v})]/\epsilon_i$ , or some other weighting factor. As a simple example, one might write an objective function like this:

```
def residual(vars, x, data, eps_data):
    amp = vars[0]
    phaseshift = vars[1]
    freq = vars[2]
    decay = vars[3]

model = amp * sin(x * freq + phaseshift) * exp(-x*x*decay)

return (data-model)/eps_data
```

To perform the minimization with scipy.optimize, one would do:

```
from scipy.optimize import leastsq
vars = [10.0, 0.2, 3.0, 0.007]
out = leastsq(residual, vars, args=(x, data, eps_data))
```

Though it is wonderful to be able to use python for such optimization problems, and the scipy library is robust and easy to use, the approach here is not terribly different from how one would do the same fit in C or Fortran. There are several practical challenges to using this approach, including:

1. The user has to keep track of the order of the variables, and their meaning – vars[0] is the amplitude, vars[2] is the frequency, and so on, although there is no intrinsic meaning to this order.

- 2. If the user wants to fix a particular variable (*not* vary it in the fit), the residual function has to be altered to have fewer variables, and have the corresponding constant value passed in some other way. While reasonable for simple cases, this quickly becomes a significant work for more complex models, and greatly complicates modeling for people not intimately familiar with the details of the fitting code.
- 3. There is no simple, robust way to put bounds on values for the variables, or enforce mathematical relationships between the variables. In fact, those optimization methods that do provide bounds, require bounds to be set for all variables with separate arrays that are in the same arbitrary order as variable values. Again, this is acceptable for small or one-off cases, but becomes painful if the fitting model needs to change.

These shortcomings are really do solely to the use of traditional arrays of variables, as matches closely the implementation of the Fortran code. The lmfit module overcomes these shortcomings by using objects – a core reason for working with Python. The key concept for lmfit is to use <code>Parameter</code> objects instead of plain floating point numbers as the variables for the fit. By using <code>Parameter</code> objects (or the closely related <code>Parameters</code> – a dictionary of <code>Parameter</code> objects), one can

- 1. forget about the order of variables and refer to Parameters by meaningful names.
- 2. place bounds on Parameters as attributes, without worrying about order.
- 3. fix Parameters, without having to rewrite the objective function.
- 4. place algebraic constraints on Parameters.

To illustrate the value of this approach, we can rewrite the above example as:

```
from lmfit import minimize, Parameters

def residual(params, x, data, eps_data):
    amp = params['amp'].value
    pshift = params['phase'].value
    freq = params['frequency'].value
    decay = params['decay'].value

    model = amp * sin(x * freq + pshift) * exp(-x*x*decay)

    return (data-model)/eps_data

params = Parameters()
params.add('amp', value=10)
params.add('decay', value=0.007)
params.add('phase', value=0.2)
params.add('frequency', value=3.0)

out = minimize(residual, params, args=(x, data, eps_data))
```

At first look, we simply replaced a list of values with a dictionary, accessed by name — not a huge improvement. But each of the named <code>Parameter</code> in the <code>Parameters</code> object holds additional attributes to modify the value during the fit. For example, Parameters can be fixed or bounded. This can be done during definition:

```
params = Parameters()
params.add('amp', value=10, vary=False)
params.add('decay', value=0.007, min=0.0)
params.add('phase', value=0.2)
params.add('frequency', value=3.0, max=10)
```

where vary=False will prevent the value from changing in the fit, and min=0.0 will set a lower bound on that parameters value). It can also be done later by setting the corresponding attributes after they have been created:

```
params['amp'].vary = False
params['decay'].min = 0.10
```

Importantly, our objective function remains unchanged.

The *params* object can be copied and modified to make many user-level changes to the model and fitting process. Of course, most of the information about how your data is modeled goes into the objective function, but the approach here allows some external control; that is, control by the **user** performing the fit, instead of by the author of the objective function.

Finally, in addition to the Parameters approach to fitting data, lmfit allows switching optimization methods without changing the objective function, provides tools for writing fitting reports, and provides better determination of Parameters confidence levels.



**CHAPTER** 

**TWO** 

## DOWNLOADING AND INSTALLATION

## 2.1 Prerequisites

The lmfit package requires Python, Numpy, and Scipy. Scipy version 0.13 or higher is recommended, but extensive testing on compatibility with various versions of scipy has not been done. Lmfit works with Python 2.7, 3.3 and 3.4. No testing has been done with Python 3.5, but as the package is pure Python, relying only on scipy and numpy, no significant troubles are expected. The nose framework is required for running the test suite, and IPython and matplotib are recommended. If Pandas is available, it will be used in portions of lmfit.

## 2.2 Downloads

The latest stable version of lmfit is available from PyPi.

#### 2.3 Installation

If you have pip installed, you can install lmfit with:

```
pip install lmfit
```

or, if you have Python Setup Tools installed, you install lmfit with:

```
easy_install -U lmfit
```

or, you can download the source kit, unpack it and install with:

```
python setup.py install
```

## 2.4 Development Version

To get the latest development version, use:

```
git clone http://github.com/lmfit/lmfit-py.git
```

and install using:

```
python setup.py install
```

## 2.5 Testing

A battery of tests scripts that can be run with the nose testing framework is distributed with lmfit in the tests folder. These are routinely run on the development version. Running nosetests should run all of these tests to completion without errors or failures.

Many of the examples in this documentation are distributed with lmfit in the examples folder, and should also run for you. Many of these require

## 2.6 Acknowledgements

```
Many people have contributed to lmfit.
Matthew Newville wrote the original version and maintains the project.
Till Stensitzki wrote the improved estimates of confidence intervals, and
    contributed many tests, bug fixes, and documentation.
Daniel B. Allan wrote much of the high level Model code, and many
    improvements to the testing and documentation.
Antonino Ingargiola wrote much of the high level Model code and provided
   many bug fixes.
J. J. Helmus wrote the MINUT bounds for leastsq, originally in
   leastsqbounds.py, and ported to lmfit.
E. O. Le Bigot wrote the uncertainties package, a version of which is used
   by lmfit.
Michal Rawlik added plotting capabilities for Models.
A. R. J. Nelson added differential_evolution, emcee, and greatly improved the
    code in the docstrings.
Additional patches, bug fixes, and suggestions have come from Christoph
    Deil, Francois Boulogne, Thomas Caswell, Colin Brosseau, nmearl,
   Gustavo Pasquevich, Clemens Prescher, LiCode, and Ben Gamari.
The lmfit code obviously depends on, and owes a very large debt to the code
in scipy.optimize. Several discussions on the scipy-user and lmfit mailing
lists have also led to improvements in this code.
```

#### 2.7 License

The LMFIT-py code is distribution under the following license:

```
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Daniel B. Allen, Johns Hopkins University

Michal Rawlik, Eidgenossische Technische Hochschule, Zurich

Antonino Ingargiola, University of California, Los Angeles

A. R. J. Nelson, Australian Nuclear Science and Technology Organisation

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**CHAPTER** 

THREE

## **GETTING HELP**

If you have questions, comments, or suggestions for LMFIT, please use the mailing list. This provides an on-line conversation that is and archived well and can be searched well with standard web searches. If you find a bug with the code or documentation, use the github issues Issue tracker to submit a report. If you have an idea for how to solve the problem and are familiar with python and github, submitting a github Pull Request would be greatly appreciated.

If you are unsure whether to use the mailing list or the Issue tracker, please start a conversation on the mailing list. That is, the problem you're having may or may not be due to a bug. If it is due to a bug, creating an Issue from the conversation is easy. If it is not a bug, the problem will be discussed and then the Issue will be closed. While one *can* search through closed Issues on github, these are not so easily searched, and the conversation is not easily useful to others later. Starting the conversation on the mailing list with "How do I do this?" or "Why didn't this work?" instead of "This should work and doesn't" is generally preferred, and will better help others with similar questions. Of course, there is not always an obvious way to decide if something is a Question or an Issue, and we will try our best to engage in all discussions.

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**CHAPTER** 

**FOUR** 

## FREQUENTLY ASKED QUESTIONS

A list of common questions.

## 4.1 What's the best way to ask for help or submit a bug report?

See Getting Help.

## 4.2 Why did my script break when upgrading from Imfit 0.8.3 to 0.9.0?

See whatsnew\_090\_label

## 4.3 I get import errors from IPython

If you see something like:

```
from IPython.html.widgets import Dropdown
ImportError: No module named 'widgets'
```

then you need to install the ipywidgets package. Try 'pip install ipywidgets'.

## 4.4 How can I fit multi-dimensional data?

The fitting routines accept data arrays that are 1 dimensional and double precision. So you need to convert the data and model (or the value returned by the objective function) to be one dimensional. A simple way to do this is to use numpy's ndarray.flatten, for example:

```
def residual(params, x, data=None):
    ....
    resid = calculate_multidim_residual()
    return resid.flatten()
```

## 4.5 How can I fit multiple data sets?

As above, the fitting routines accept data arrays that are 1 dimensional and double precision. So you need to convert the sets of data and models (or the value returned by the objective function) to be one dimensional. A simple way to do this is to use numpy's concatenate. As an example, here is a residual function to simultaneously fit two lines to two different arrays. As a bonus, the two lines share the 'offset' parameter:

```
def fit_function(params, x=None, dat1=None, dat2=None):
    model1 = params['offset'].value + x * params['slope1'].value
    model2 = params['offset'].value + x * params['slope2'].value

    resid1 = dat1 - model1
    resid2 = dat2 - model2
    return numpy.concatenate((resid1, resid2))
```

## 4.6 How can I fit complex data?

As with working with multidimensional data, you need to convert your data and model (or the value returned by the objective function) to be double precision floating point numbers. The simplest approach is to use numpy's ndarray.view method, perhaps like:

```
import numpy as np
def residual(params, x, data=None):
    ....
    resid = calculate_complex_residual()
    return resid.view(np.float)
```

## 4.7 Can I constrain values to have integer values?

Basically, no. None of the minimizers in lmfit support integer programming. They all (I think) assume that they can make a very small change to a floating point value for a parameters value and see a change in the value to be minimized.

## 4.8 How should I cite LMFIT?

See http://dx.doi.org/10.5281/zenodo.11813

#### PARAMETER AND PARAMETERS

This chapter describes Parameter objects which is the key concept of lmfit.

A Parameter is the quantity to be optimized in all minimization problems, replacing the plain floating point number used in the optimization routines from scipy.optimize. A Parameter has a value that can be varied in the fit or have a fixed value, have upper and/or lower bounds. It can even have a value that is constrained by an algebraic expression of other Parameter values. Since Parameters live outside the core optimization routines, they can be used in all optimization routines from scipy.optimize. By using Parameter objects instead of plain variables, the objective function does not have to be modified to reflect every change of what is varied in the fit. This simplifies the writing of models, allowing general models that describe the phenomenon to be written, and gives the user more flexibility in using and testing variations of that model.

Whereas a <code>Parameter</code> expands on an individual floating point variable, the optimization methods need an ordered group of floating point variables. In the <code>scipy.optimize</code> routines this is required to be a 1-dimensional numpy ndarray. For lmfit, where each <code>Parameter</code> has a name, this is replaced by a <code>Parameters</code> class, which works as an ordered dictionary of <code>Parameter</code> objects, with a few additional features and methods. That is, while the concept of a <code>Parameter</code> is central to lmfit, one normally creates and interacts with a <code>Parameters</code> instance that contains many <code>Parameter</code> objects. The objective functions you write for lmfit will take an instance of <code>Parameters</code> as its first argument.

#### 5.1 The Parameter class

#### **Parameters**

- name (None or string will be overwritten during fit if None.) parameter name
- **value** the numerical value for the parameter
- vary (boolean (True/False) [default True]) whether to vary the parameter or not.
- min lower bound for value (None = no lower bound).
- max upper bound for value (None = no upper bound).
- expr (None or string) mathematical expression to use to evaluate value during fit.

Each of these inputs is turned into an attribute of the same name.

After a fit, a Parameter for a fitted variable (that is with vary = True) may have its value attribute to hold the best-fit value. Depending on the success of the fit and fitting algorithm used, it may also have attributes stderr and correl.

#### stderr

the estimated standard error for the best-fit value.

#### correl

a dictionary of the correlation with the other fitted variables in the fit, of the form:

```
{'decay': 0.404, 'phase': -0.020, 'frequency': 0.102}
```

See Bounds Implementation for details on the math used to implement the bounds with min and max.

The expr attribute can contain a mathematical expression that will be used to compute the value for the Parameter at each step in the fit. See *Using Mathematical Constraints* for more details and examples of this feature.

```
set (value=None[, vary=None[, min=None[, max=None[, expr=None]]]]) set or update a Parameters value or other attributes.
```

#### **Parameters**

- name parameter name
- value the numerical value for the parameter
- **vary** whether to vary the parameter or not.
- min lower bound for value
- max upper bound for value
- **expr** mathematical expression to use to evaluate value during fit.

Each argument of set () has a default value of None, and will be set only if the provided value is not None. You can use this to update some Parameter attribute without affecting others, for example:

```
p1 = Parameter('a', value=2.0)
p2 = Parameter('b', value=0.0)
p1.set(min=0)
p2.set(vary=False)
```

to set a lower bound, or to set a Parameter as have a fixed value.

Note that to use this approach to lift a lower or upper bound, doing:

```
p1.set(min=0)
....
# now lift the lower bound
p1.set(min=None) # won't work! lower bound NOT changed
```

won't work – this will not change the current lower bound. Instead you'll have to use np.inf to remove a lower or upper bound:

```
# now lift the lower bound
pl.set(min=-np.inf) # will work!
```

Similarly, to clear an expression of a parameter, you need to pass an empty string, not None. You also need to give a value and explicitly tell it to vary:

```
p3 = Parameter('c', expr='(a+b)/2')
p3.set(expr=None) # won't work! expression NOT changed

# remove constraint expression
p3.set(value=1.0, vary=True, expr='') # will work! parameter now unconstrained
```

#### 5.2 The Parameters class

#### class Parameters

create a Parameters object. This is little more than a fancy ordered dictionary, with the restrictions that:

- 1.keys must be valid Python symbol names, so that they can be used in expressions of mathematical constraints. This means the names must match  $[a-z_{-}][a-z0-9_{-}] *$  and cannot be a Python reserved word.
- 2. values must be valid Parameter objects.

Two methods are provided for convenient initialization of a *Parameters*, and one for extracting *Parameter* values into a plain dictionary.

add (name[, value=None[, vary=True[, min=None[, max=None[, expr=None]]]]]]) add a named parameter. This creates a Parameter object associated with the key name, with optional arguments passed to Parameter:

```
p = Parameters()
p.add('myvar', value=1, vary=True)
```

#### add\_many (self, paramlist)

add a list of named parameters. Each entry must be a tuple with the following entries:

```
name, value, vary, min, max, expr
```

This method is somewhat rigid and verbose (no default values), but can be useful when initially defining a parameter list so that it looks table-like:

```
p = Parameters()
           (Name, Value, Vary, Min, Max,
p.add_many(('amp1',
                   10, True, None, None,
                                            None).
          ('cen1',
                    1.2, True, 0.5, 2.0,
                                            None),
          ('wid1',
                    0.8, True, 0.1, None,
                                            None).
          ('amp2',
                   7.5, True, None, None,
                                            None).
          ('cen2',
                   1.9, True, 1.0, 3.0,
                                            None),
          ('wid2', None, False, None, None, '2*wid1/3'))
```

#### **Parameters**

- **oneline** (boolean) If True prints a one-line parameters representation. Default False.
- colwidth (int) column width for all except the first (i.e. name) column.
- **columns** (*list of strings*) list of columns names to print. All values must be valid *Parameter* attributes.
- **precision** (*int*) number of digits to be printed after floating point.
- **format** (*string*) single-char numeric formatter. Valid values: 'f' floating point, 'g' floating point and exponential, 'e' exponential.

#### valuesdict()

return an ordered dictionary of name:value pairs with the Paramater name as the key and Parameter value as value.

This is distinct from the <code>Parameters</code> itself, as the dictionary values are not <code>Parameter</code> objects, just the <code>value</code>. Using <code>valuesdict()</code> can be a very convenient way to get updated values in a objective function.

```
clumps (**kws)
    return a JSON string representation of the Parameter object. This can be saved or used to
    re-create or re-set parameters, using the loads() method.
    Optional keywords are sent json.dumps().

dump (file, **kws)
    write a JSON representation of the Parameter object to a file or file-like object in file - really
    any object with a write() method. Optional keywords are sent json.dumps().

loads (sval, **kws)
    use a JSON string representation of the Parameter object in sval to set all parameter settings.
    Optional keywords are sent json.loads().

load (file, **kws)
    read and use a JSON string representation of the Parameter object from a file or file-like object in file - really any object with a read() method. Optional keywords are sent
    json.loads().
```

## 5.3 Simple Example

Using Parameters ' and minimize () function (discussed in the next chapter) might look like this:

```
#!/usr/bin/env python
#<examples/doc_basic.py>
from lmfit import minimize, Parameters, Parameter, report_fit
import numpy as np
# create data to be fitted
x = np.linspace(0, 15, 301)
data = (5. * np.sin(2 * x - 0.1) * np.exp(-x*x*0.025) +
       np.random.normal(size=len(x), scale=0.2) )
# define objective function: returns the array to be minimized
def fcn2min(params, x, data):
    """ model decaying sine wave, subtract data"""
   amp = params['amp'].value
   shift = params['shift'].value
   omega = params['omega'].value
   decay = params['decay'].value
   model = amp * np.sin(x * omega + shift) * np.exp(-x*x*decay)
   return model - data
# create a set of Parameters
params = Parameters()
params.add('amp', value= 10, min=0)
params.add('decay', value= 0.1)
params.add('shift', value= 0.0, min=-np.pi/2., max=np.pi/2)
params.add('omega', value= 3.0)
# do fit, here with leastsq model
result = minimize(fcn2min, params, args=(x, data))
# calculate final result
final = data + result.residual
```

```
# write error report
report_fit(result.params)

# try to plot results

try:
    import pylab
    pylab.plot(x, data, 'k+')
    pylab.plot(x, final, 'r')
    pylab.show()

except:
    pass

#<end of examples/doc_basic.py>
```

Here, the objective function explicitly unpacks each Parameter value. This can be simplified using the <code>Parameters</code> valuesdict() method, which would make the objective function <code>fcn2min</code> above look like:

```
def fcn2min(params, x, data):
    """ model decaying sine wave, subtract data"""
    v = params.valuesdict()

model = v['amp'] * np.sin(x * v['omega'] + v['shift']) * np.exp(-x*x*v['decay'])
    return model - data
```

The results are identical, and the difference is a stylistic choice.

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## PERFORMING FITS, ANALYZING OUTPUTS

As shown in the previous chapter, a simple fit can be performed with the minimize() function. For more sophisticated modeling, the Minimizer class can be used to gain a bit more control, especially when using complicated constraints or comparing results from related fits.

**Warning:** Upgrading scripts from version 0.8.3 to 0.9.0? See whatsnew\_090\_label

## 6.1 The minimize () function

The minimize() function is a wrapper around Minimizer for running an optimization problem. It takes an objective function (the function that calculates the array to be minimized), a Parameters object, and several optional arguments. See Writing a Fitting Function for details on writing the objective.

minimize (function, params[, args=None[, kws=None[, method='leastsq'[, scale\_covar=True[, iter\_cb=None[, \*\*fit\_kws]]]]]]) find values for the params so that the sum-of-squares of the array returned from function is minimized.

#### Parameters

- **function** (callable.) function to return fit residual. See Writing a Fitting Function for details.
- params (Parameters.) a Parameters dictionary. Keywords must be strings that match [a-z\_] [a-z0-9\_] \* and cannot be a python reserved word. Each value must be Parameter.
- args(tuple) arguments tuple to pass to the residual function as positional arguments.
- **kws** (dict) dictionary to pass to the residual function as keyword arguments.
- method (string (default leastsq)) name of fitting method to use. See Choosing Different Fitting Methods for details
- **scale\_covar** (bool (default True)) whether to automatically scale covariance matrix (leastsq only)
- iter\_cb (callable or None) function to be called at each fit iteration. See *Using a Iteration Callback Function* for details.
- fit\_kws (dict) dictionary to pass to optimize.leastsq or optimize.minimize.

**Returns** *MinimizerResult* instance, which will contain the optimized parameter, and several goodness-of-fit statistics.

Changed in version 0.9.0: return value changed to MinimizerResult

On output, the params will be unchanged. The best-fit values, and where appropriate, estimated uncertainties and correlations, will all be contained in the returned <code>MinimizerResult</code>. See <code>MinimizerResult</code> – the optimization result for further details.

For clarity, it should be emphasized that this function is simply a wrapper around *Minimizer* that runs a single fit, implemented as:

## 6.2 Writing a Fitting Function

An important component of a fit is writing a function to be minimized – the *objective function*. Since this function will be called by other routines, there are fairly stringent requirements for its call signature and return value. In principle, your function can be any python callable, but it must look like this:

```
func(params, *args, **kws):
```

calculate objective residual to be minimized from parameters.

#### **Parameters**

- params (Parameters.) parameters.
- args positional arguments. Must match args argument to minimize ()
- **kws** keyword arguments. Must match kws argument to minimize ()

**Returns** residual array (generally data-model) to be minimized in the least-squares sense.

**Return type** numpy array. The length of this array cannot change between calls.

A common use for the positional and keyword arguments would be to pass in other data needed to calculate the residual, including such things as the data array, dependent variable, uncertainties in the data, and other data structures for the model calculation.

The objective function should return the value to be minimized. For the Levenberg-Marquardt algorithm from <code>leastsq()</code>, this returned value **must** be an array, with a length greater than or equal to the number of fitting variables in the model. For the other methods, the return value can either be a scalar or an array. If an array is returned, the sum of squares of the array will be sent to the underlying fitting method, effectively doing a least-squares optimization of the return values.

Since the function will be passed in a dictionary of Parameters, it is advisable to unpack these to get numerical values at the top of the function. A simple way to do this is with Parameters.valuesdict(), as with:

```
def residual(pars, x, data=None, eps=None):
    # unpack parameters:
    # extract .value attribute for each parameter
    parvals = pars.valuesdict()
    period = parvals['period']
    shift = parvals['shift']
    decay = parvals['decay']

if abs(shift) > pi/2:
    shift = shift - sign(shift)*pi

if abs(period) < 1.e-10:
    period = sign(period)*1.e-10</pre>
```

```
model = parvals['amp'] * sin(shift + x/period) * exp(-x*x*decay*decay)

if data is None:
    return model

if eps is None:
    return (model - data)
return (model - data)/eps
```

In this example, x is a positional (required) argument, while the data array is actually optional (so that the function returns the model calculation if the data is neglected). Also note that the model calculation will divide x by the value of the 'period' Parameter. It might be wise to ensure this parameter cannot be 0. It would be possible to use the bounds on the Parameter to do this:

```
params['period'] = Parameter(value=2, min=1.e-10)
```

but putting this directly in the function with:

```
if abs(period) < 1.e-10:
    period = sign(period) *1.e-10</pre>
```

is also a reasonable approach. Similarly, one could place bounds on the decay parameter to take values only between -pi/2 and pi/2.

## **6.3 Choosing Different Fitting Methods**

By default, the Levenberg-Marquardt algorithm is used for fitting. While often criticized, including the fact it finds a *local* minima, this approach has some distinct advantages. These include being fast, and well-behaved for most curve-fitting needs, and making it easy to estimate uncertainties for and correlations between pairs of fit variables, as discussed in *MinimizerResult – the optimization result*.

Alternative algorithms can also be used by providing the method keyword to the minimize() function or Minimizer.minimize() class as listed in the Table of Supported Fitting Methods.

Table of Supported Fitting Methods:

Fitting Method	method arg to minimize() or	
	Minimizer.minimize()	
Levenberg-Marquardt	leastsq	
Nelder-Mead	nelder	
L-BFGS-B	lbfgsb	
Powell	powell	
Conjugate Gradient	cg	
Newton-CG	newton	
COBYLA	cobyla	
Truncated Newton	tnc	
Dogleg	dogleg	
Sequential Linear Squares	slsqp	
Programming		
Differential Evolution	differential_evolution	

**Note:** The objective function for the Levenberg-Marquardt method **must** return an array, with more elements than variables. All other methods can return either a scalar value or an array.

**Warning:** Much of this documentation assumes that the Levenberg-Marquardt method is the method used. Many of the fit statistics and estimates for uncertainties in parameters discussed in *MinimizerResult – the optimization result* are done only for this method.

## 6.4 MinimizerResult - the optimization result

#### class MinimizerResult (\*\*kws)

New in version 0.9.0.

An optimization with <code>minimize()</code> or <code>Minimizer.minimize()</code> will return a <code>MinimizerResult</code> object. This is an otherwise plain container object (that is, with no methods of its own) that simply holds the results of the minimization. These results will include several pieces of informational data such as status and error messages, fit statistics, and the updated parameters themselves.

Importantly, the parameters passed in to <code>Minimizer.minimize()</code> will be not be changed. To to find the best-fit values, uncertainties and so on for each parameter, one must use the <code>MinimizerResult.params</code> attribute.

#### params

the Parameters actually used in the fit, with updated values, stderr and correl.

#### var names

ordered list of variable parameter names used in optimization, and useful for understanding the the values in init\_vals and covar.

#### covar

covariance matrix from minimization (leastsq only), with rows/columns using var\_names.

#### init\_vals

list of initial values for variable parameters using var\_names.

#### nfev

number of function evaluations

#### success

boolean (True/False) for whether fit succeeded.

#### errorbars

boolean (True/False) for whether uncertainties were estimated.

#### message

message about fit success.

#### ier

integer error value from optimize.leastsq (leastsq only).

#### lmdif\_message

message from optimize.leastsq (leastsq only).

#### nvarys

number of variables in fit  $N_{\text{varys}}$ 

#### ndata

number of data points: N

#### nfree '

degrees of freedom in fit:  $N - N_{\text{varvs}}$ 

#### residual

residual array, return value of func (): Resid

chisqr

chi-square:  $\chi^2 = \sum_i^N [\text{Resid}_i]^2$ 

redchi

reduced chi-square:  $\chi^2_{\nu} = \chi^2/(N - N_{\text{varys}})$ 

aic

Akaike Information Criterion statistic (see below)

bic

Bayesian Information Criterion statistic (see below).

#### 6.4.1 Goodness-of-Fit Statistics

Table of Fit Results: These values, including the standard Goodness-of-Fit statistics, are all attributes of the MinimizerResult object returned by minimize() or Minimizer.minimize().

Attribute Name	Description / Formula
nfev	number of function evaluations
nvarys	number of variables in fit $N_{\rm varys}$
ndata	number of data points: $N$
nfree '	degrees of freedom in fit: $N - N_{\text{varys}}$
residual	residual array, return value of func (): Resid
chisqr	chi-square: $\chi^2 = \sum_i^N [\text{Resid}_i]^2$
redchi	reduced chi-square: $\chi^2_{\nu} = \chi^2/(N - N_{\text{varys}})$
aic	Akaike Information Criterion statistic (see below)
bic	Bayesian Information Criterion statistic (see below)
var_names	ordered list of variable parameter names used for init_vals and covar
covar	covariance matrix (with rows/columns using var_names
init_vals	list of initial values for variable parameters

Note that the calculation of chi-square and reduced chi-square assume that the returned residual function is scaled properly to the uncertainties in the data. For these statistics to be meaningful, the person writing the function to be minimized must scale them properly.

After a fit using using the leastsq() method has completed successfully, standard errors for the fitted variables and correlations between pairs of fitted variables are automatically calculated from the covariance matrix. The standard error (estimated  $1\sigma$  error-bar) go into the stderr attribute of the Parameter. The correlations with all other variables will be put into the correlations of the Parameter – a dictionary with keys for all other Parameters and values of the corresponding correlation.

In some cases, it may not be possible to estimate the errors and correlations. For example, if a variable actually has no practical effect on the fit, it will likely cause the covariance matrix to be singular, making standard errors impossible to estimate. Placing bounds on varied Parameters makes it more likely that errors cannot be estimated, as being near the maximum or minimum value makes the covariance matrix singular. In these cases, the <code>errorbars</code> attribute of the fit result (<code>Minimizer</code> object) will be False.

#### 6.4.2 Akaike and Bayesian Information Criteria

The MinimizerResult includes the traditional chi-square and reduced chi-square statistics:

$$\chi^2 = \sum_{i}^{N} r_i^2$$

$$\chi^2_{\nu} = \chi^2/(N - N_{\text{varys}})$$

where r is the residual array returned by the objective function (likely to be (data-model) /uncertainty for data modeling usages), N is the number of data points (ndata), and  $N_{\text{varys}}$  is number of variable parameters.

Also included are the Akaike Information Criterion, and Bayesian Information Criterion statistics, held in the aic and bic attributes, respectively. These give slightly different measures of the relative quality for a fit, trying to balance quality of fit with the number of variable parameters used in the fit. These are calculated as

aic = 
$$N \ln(\chi^2/N) + 2N_{\text{varys}}$$
  
bic =  $N \ln(\chi^2/N) + \ln(N) * N_{\text{varys}}$ 

When comparing fits with different numbers of varying parameters, one typically selects the model with lowest reduced chi-square, Akaike information criterion, and/or Bayesian information criterion. Generally, the Bayesian information criterion is considered the most conservative of these statistics.

## 6.5 Using a Iteration Callback Function

An iteration callback function is a function to be called at each iteration, just after the objective function is called. The iteration callback allows user-supplied code to be run at each iteration, and can be used to abort a fit.

```
iter_cb (params, iter, resid, *args, **kws):
    user-supplied function to be run at each iteration
```

#### **Parameters**

- params (Parameters.) parameters.
- iter (integer) iteration number
- resid (ndarray) residual array.
- args positional arguments. Must match args argument to minimize ()
- **kws** keyword arguments. Must match kws argument to minimize ()

**Returns** residual array (generally data-model) to be minimized in the least-squares sense.

Return type None for normal behavior, any value like True to abort fit.

Normally, the iteration callback would have no return value or return None. To abort a fit, have this function return a value that is True (including any non-zero integer). The fit will also abort if any exception is raised in the iteration callback. When a fit is aborted this way, the parameters will have the values from the last iteration. The fit statistics are not likely to be meaningful, and uncertainties will not be computed.

## 6.6 Using the Minimizer class

For full control of the fitting process, you'll want to create a Minimizer object.

#### **Parameters**

• **function** (*callable*.) – objective function to return fit residual. See *Writing a Fitting Function* for details.

- params (dict) a dictionary of Parameters. Keywords must be strings that match [a-z\_][a-z0-9\_]\* and is not a python reserved word. Each value must be Parameter.
- fcn\_args (tuple) arguments tuple to pass to the residual function as positional arguments.
- fcn kws (dict) dictionary to pass to the residual function as keyword arguments.
- iter\_cb (callable or None) function to be called at each fit iteration. See *Using a Iteration Callback Function* for details.
- **scale\_covar** (bool (default True).) flag for automatically scaling covariance matrix and uncertainties to reduced chi-square (leastsq only)
- **kws** (*dict*) dictionary to pass as keywords to the underlying scipy.optimize method.

The Minimizer object has a few public methods:

```
minimize (method='leastsq', params=None, **kws)
perform fit using either leastsq() or scalar_minimize().
```

#### **Parameters**

- **method** (str.) name of fitting method. Must be one of the names in *Table of Supported Fitting Methods*
- params (Parameters or None) a Parameters dictionary for starting values

**Returns** *MinimizerResult* object, containing updated parameters, fitting statistics, and information.

Changed in version 0.9.0: return value changed to MinimizerResult

Additional keywords are passed on to the correspond <code>leastsq()</code> or <code>scalar\_minimize()</code> method.

leastsq(params=None, scale\_covar=True, \*\*kws)

perform fit with Levenberg-Marquardt algorithm. Keywords will be passed directly to optimize.leastsq. By default, numerical derivatives are used, and the following arguments are set:

leastsq() arg	Default Value	Description	
xtol	1.e-7	Relative error in the approximate solution	
ftol	1.e-7	Relative error in the desired sum of squares	
maxfev	2000*(nvar+1)	maximum number of function calls (nvar= # of	
		variables)	
Dfun	None	function to call for Jacobian calculation	

Changed in version 0.9.0: return value changed to MinimizerResult

**scalar\_minimize** (*method='Nelder-Mead'*, *params=None*, *hess=None*, *tol=None*, \*\*kws) perform fit with any of the scalar minimization algorithms supported by optimize.minimize.

scalar_minimize() arg	Default Value	Description
method	Nelder-Mead	fitting method
tol	1.e-7	fitting and parameter tolerance
hess	None	Hessian of objective function

Changed in version 0.9.0: return value changed to MinimizerResult

#### prepare\_fit (\*\*kws)

prepares and initializes model and Parameters for subsequent fitting. This routine prepares the conversion of Parameters into fit variables, organizes parameter bounds, and parses, "compiles" and checks constrain

expressions. The method also creates and returns a new instance of a MinimizerResult object that contains the copy of the Parameters that will actually be varied in the fit.

This method is called directly by the fitting methods, and it is generally not necessary to call this function explicitly.

Changed in version 0.9.0: return value changed to MinimizerResult

emcee (params=None, steps=1000, nwalkers=100, burn=0, thin=1, ntemps=1, pos=None, reuse\_sampler=False, workers=1, float\_behavior='posterior', is\_weighted=True, seed=None)

Bayesian sampling of the posterior distribution for the parameters using the emcee Markov Chain Monte Carlo package. The method assumes that the prior is Uniform. You need to have emcee installed to use this method.

#### **Parameters**

- params (Parameters or None) a Parameters dictionary for starting values
- **steps** (*int*) How many samples you would like to draw from the posterior distribution for each of the walkers?
- nwalkers (int) Should be set so nwalkers >> nvarys, where nvarys are the number of parameters being varied during the fit. "Walkers are the members of the ensemble. They are almost like separate Metropolis-Hastings chains but, of course, the proposal distribution for a given walker depends on the positions of all the other walkers in the ensemble." from
- **burn** (*int*) Discard this many samples from the start of the sampling regime.
- **thin** (*int*) Only accept 1 in every *thin* samples.
- **ntemps** (*int*) If *ntemps* > 1 perform a Parallel Tempering.
- **pos** (np.ndarray) Specify the initial positions for the sampler. If ntemps == 1 then pos.shape should be (nwalkers, nvarys). Otherwise, (ntemps, nwalkers, nvarys). You can also initialise using a previous chain that had the same ntemps, nwalkers and nvarys.
- reuse\_sampler (bool) If you have already run emcee() on a given Minimizer object then it possesses an internal sampler attribute. You can continue to draw from the same sampler (retaining the chain history) if you set this option to True. Otherwise a new sampler is created. The nwalkers, ntemps and params keywords are ignored with this option. Important: the Parameters used to create the sampler must not change in-between calls to emcee(). Alteration of Parameters would include changed min, max, vary and expr attributes. This may happen, for example, if you use an altered Parameters object and call the minimize() method in-between calls to emcee().
- **workers** (*int* or *Pool-like*) For parallelization of sampling. It can be any Poollike object with a map method that follows the same calling sequence as the built-in map function. If int is given as the argument, then a multiprocessing-based pool is spawned internally with the corresponding number of parallel processes. 'mpi4py'-based parallelization and 'joblib'-based parallelization pools can also be used here. **Note**: because of multiprocessing overhead it may only be worth parallelising if the objective function is expensive to calculate, or if there are a large number of objective evaluations per step (*ntemps* \* *nwalkers* \* *nvarys*).
- float\_behavior (str) Specifies the meaning of the objective function if it returns a float. One of:

'posterior' - the objective function returns a log-posterior probability

'chi2' - the objective function is returning  $\chi^2$ .

<sup>1</sup> http://dan.iel.fm/emcee/current/user/line/

See Notes for further details.

- is\_weighted (bool) Has your objective function been weighted by measurement uncertainties? If is\_weighted is True then your objective function is assumed to return residuals that have been divided by the true measurement uncertainty (data model) / sigma. If is\_weighted is False then the objective function is assumed to return unweighted residuals, data model. In this case emcee will employ a positive measurement uncertainty during the sampling. This measurement uncertainty will be present in the output params and output chain with the name \_\_lnsigma. A side effect of this is that you cannot use this parameter name yourself. Important this parameter only has any effect if your objective function returns an array. If your objective function returns a float, then this parameter is ignored. See Notes for more details.
- **seed** (int or np.random.RandomState) If seed is an int, a new np.random.RandomState instance is used, seeded with seed. If seed is already a np.random.RandomState instance, then that np.random.RandomState instance is used. Specify seed for repeatable sampling.

Returns MinimizerResult object containing updated params, statistics, etc. The MinimizerResult also contains the chain, flatchain and Inprob attributes. The chain and flatchain attributes contain the samples and have the shape (nwalkers, (steps - burn) // thin, nvarys) or (ntemps, nwalkers, (steps - burn) // thin, nvarys), depending on whether Parallel tempering was used or not. nvarys is the number of parameters that are allowed to vary. The flatchain attribute is a pandas.DataFrame of the flattened chain, chain.reshape(-1, nvarys). To access flattened chain values for a particular parameter use result.flatchain[parname]. The Inprob attribute contains the log probability for each sample in chain. The sample with the highest probability corresponds to the maximum likelihood estimate.

This method samples the posterior distribution of the parameters using Markov Chain Monte Carlo. To do so it needs to calculate the log-posterior probability of the model parameters, F, given the data, D,  $\ln p(F_{true}|D)$ . This 'posterior probability' is calculated as:

$$\ln p(F_{true}|D) \propto \ln p(D|F_{true}) + \ln p(F_{true})$$

where  $\ln p(D|F_{true})$  is the 'log-likelihood' and  $\ln p(F_{true})$  is the 'log-prior'. The default log-prior encodes prior information already known about the model. This method assumes that the log-prior probability is -np.inf (impossible) if the one of the parameters is outside its limits. The log-prior probability term is zero if all the parameters are inside their bounds (known as a uniform prior). The log-likelihood function is given by  $^1$ :

$$\ln p(D|F_{true}) = -\frac{1}{2} \sum_{n} \left[ \frac{(g_n(F_{true}) - D_n)^2}{s_n^2} + \ln(2\pi s_n^2) \right]$$

The first summand in the square brackets represents the residual for a given datapoint (g being the generative model). This term represents  $\chi^2$  when summed over all datapoints. Ideally the objective function used to create lmfit.Minimizer should return the log-posterior probability,  $\ln p(F_{true}|D)$ . However, since the in-built log-prior term is zero, the objective function can also just return the log-likelihood, unless you wish to create a non-uniform prior.

If a float value is returned by the objective function then this value is assumed by default to be the log-posterior probability, i.e. *float\_behavior is 'posterior'*. If your objective function returns  $\chi^2$ , then you should use a value of 'chi2' for float\_behavior. emcee will then multiply your  $\chi^2$  value by -0.5 to obtain the posterior probability.

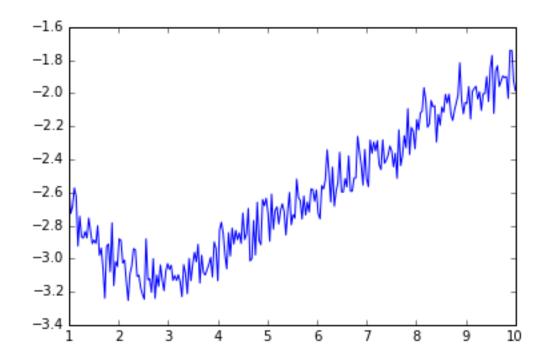
However, the default behaviour of many objective functions is to return a vector of (possibly weighted) residuals. Therefore, if your objective function returns a vector, res, then the vector is assumed to contain the residuals. If  $is\_weighted$  is True then your residuals are assumed to be correctly weighted by the standard deviation of the data points (res = (data - model) / sigma) and the log-likelihood (and log-posterior probability) is calculated as: -0.5 \* np.sum(res \*\*2). This ignores the second summand in the square brackets. Consequently, in order to calculate a

fully correct log-posterior probability value your objective function should return a single value. If  $is\_weighted$  is False then the data uncertainty,  $s_n$ , will be treated as a nuisance parameter and will be marginalised out. This is achieved by employing a strictly positive uncertainty (homoscedasticity) for each data point,  $s_n = exp(\_lnsigma)$ .  $\_lnsigma$  will be present in MinimizerResult.params, as well as Minimizer.chain, nvarys will also be increased by one.

## 6.7 emcee () - calculating the posterior probability distribution of parameters

emcee () can be used to obtain the posterior probability distribution of parameters, given a set of experimental data. An example problem is a double exponential decay. A small amount of Gaussian noise is also added in:

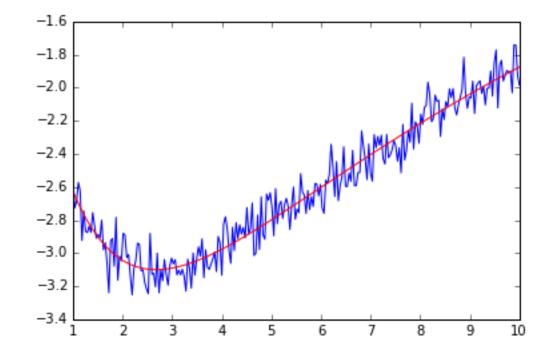
```
>>> import numpy as np
>>> import lmfit
>>> import matplotlib.pyplot as plt
>>> x = np.linspace(1, 10, 250)
>>> np.random.seed(0)
>>> y = 3.0 * np.exp(-x / 2) - 5.0 * np.exp(-(x - 0.1) / 10.) + 0.1 * np.random.randn(len(x))
>>> plt.plot(x, y)
>>> plt.show()
```



Create a Parameter set for the initial guesses:

Solving with *minimize* () gives the Maximum Likelihood solution.:

```
>>> mi = lmfit.minimize(residual, p, method='Nelder')
>>> lmfit.printfuncs.report_fit(mi.params, min_correl=0.5)
[[Variables]]
    a1:     2.98623688 (init= 4)
    a2:     -4.33525596 (init= 4)
    t1:     1.30993185 (init= 3)
    t2:     11.8240752 (init= 3)
[[Correlations]] (unreported correlations are < 0.500)
>>> plt.plot(x, y)
>>> plt.plot(x, residual(mi.params) + y, 'r')
>>> plt.show()
```



However, this doesn't give a probability distribution for the parameters. Furthermore, we wish to deal with the data uncertainty. This is called marginalisation of a nuisance parameter. emcee requires a function that returns the log-posterior probability. The log-posterior probability is a sum of the log-prior probability and log-likelihood functions. The log-prior probability is assumed to be zero if all the parameters are within their bounds and *-np.inf* if any of the parameters are outside their bounds.:

```
>>> # add a noise parameter
>>> mi.params.add('f', value=1, min=0.001, max=2)

>>> # This is the log-likelihood probability for the sampling. We're going to estimate the
>>> # size of the uncertainties on the data as well.
>>> def lnprob(p):
... resid = residual(p)
... s = p['f']
... resid *= 1 / s
... resid *= resid
... resid *= resid
... resid += np.log(2 * np.pi * s**2)
... return -0.5 * np.sum(resid)
```

Now we have to set up the minimizer and do the sampling.:

```
>>> mini = lmfit.Minimizer(lnprob, mi.params)
>>> res = mini.emcee(burn=300, steps=600, thin=10, params=mi.params)
```

Lets have a look at those posterior distributions for the parameters. This requires installation of the corner package.:

```
import corner
corner.corner(res.flatchain, labels=res.var_names, truths=list(res.params.valuesdict().values())
12.75
 215
 25
 300
 $3,8
30
 $?2
 ₽.
 077
 0,20
 000
```

The values reported in the *MinimizerResult* are the medians of the probability distributions and a 1 sigma quantile, estimated as half the difference between the 15.8 and 84.2 percentiles. The median value is not necessarily the same as the Maximum Likelihood Estimate. We'll get that as well. You can see that we recovered the right uncertainty level on the data.:

```
>>> print("median of posterior probability distribution")
>>> print('-----')
>>> lmfit.report_fit(res.params)
median of posterior probability distribution
[[Variables]]
   al: 3.00975345 +/- 0.151034 (5.02%) (init= 2.986237)
   a2: -4.35419204 +/- 0.127505 (2.93%) (init=-4.335256)
   t1: 1.32726415 +/- 0.142995 (10.77%) (init= 1.309932)
   t2: 11.7911935 +/- 0.495583 (4.20%) (init= 11.82408)
        0.09805494 + - 0.004256 (4.34\%) (init= 1)
[[Correlations]] (unreported correlations are < 0.100)
   C(a2, t2)
                               = 0.981
   C(a2, t1)
                               = -0.927
   C(t1, t2)
                               = -0.880
   C(a1, t1)
                               = -0.519
                               = 0.195
   C(a1, a2)
                               = 0.146
   C(a1, t2)
>>> # find the maximum likelihood solution
>>> highest_prob = np.argmax(res.lnprob)
>>> hp_loc = np.unravel_index(highest_prob, res.lnprob.shape)
>>> mle_soln = res.chain[hp_loc]
>>> for i, par in enumerate(p):
      p[par].value = mle_soln[i]
>>> print("\nMaximum likelihood Estimation")
>>> print('-----')
>>> print(p)
Maximum likelihood Estimation
Parameters([('a1', <Parameter 'a1', 2.9943337359308981, bounds=[-inf:inf]>),
('a2', <Parameter 'a2', -4.3364489105166593, bounds=[-inf:inf]>),
('t1', <Parameter 't1', 1.3124544105342462, bounds=[-inf:inf]>),
('t2', <Parameter 't2', 11.80612160586597, bounds=[-inf:inf]>)])
>>> # Finally lets work out a 1 and 2-sigma error estimate for 't1'
>>> quantiles = np.percentile(res.flatchain['t1'], [2.28, 15.9, 50, 84.2, 97.7])
>>> print("2 sigma spread", 0.5 * (quantiles[-1] - quantiles[0]))
2 sigma spread 0.298878202908
```

# 6.8 Getting and Printing Fit Reports

**fit\_report** (*result*, *modelpars=None*, *show\_correl=True*, *min\_correl=0.1*) generate and return text of report of best-fit values, uncertainties, and correlations from fit.

#### **Parameters**

- result MinimizerResult object as returned by minimize ().
- modelpars Parameters with "Known Values" (optional, default None)
- **show\_correl** whether to show list of sorted correlations [True]
- min correl smallest correlation absolute value to show [0.1]

If the first argument is a Parameters object, goodness-of-fit statistics will not be included.

```
report_fit (result, modelpars=None, show_correl=True, min_correl=0.1)
print text of report from fit_report().
```

An example fit with report would be

```
#!/usr/bin/env python
#<examples/doc_withreport.py>
from __future__ import print_function
from lmfit import Parameters, minimize, fit_report
from numpy import random, linspace, pi, exp, sin, sign
p_true = Parameters()
p_true.add('amp', value=14.0)
p_true.add('period', value=5.46)
p_true.add('shift', value=0.123)
p_true.add('decay', value=0.032)
def residual(pars, x, data=None):
   vals = pars.valuesdict()
   amp = vals['amp']
   per = vals['period']
   shift = vals['shift']
   decay = vals['decay']
   if abs(shift) > pi/2:
       shift = shift - sign(shift)*pi
   model = amp * sin(shift + x/per) * exp(-x*x*decay*decay)
   if data is None:
       return model
   return (model - data)
n = 1001
xmin = 0.
xmax = 250.0
random.seed(0)
noise = random.normal(scale=0.7215, size=n)
x = linspace(xmin, xmax, n)
data = residual(p_true, x) + noise
fit_params = Parameters()
fit_params.add('amp', value=13.0)
fit_params.add('period', value=2)
fit_params.add('shift', value=0.0)
fit_params.add('decay', value=0.02)
out = minimize(residual, fit_params, args=(x,), kws={'data':data})
print(fit_report(out))
#<end of examples/doc_withreport.py>
```

which would write out:

```
[[Fit Statistics]]
  # function evals = 85
  # data points = 1001
  reduced chi-square = 0.500
   Akaike info crit = -685.215
   Bayesian info crit = -665.579
[[Variables]]
  amp: 13.9121944 +/- 0.141202 (1.01%) (init= 13)
   period: 5.48507044 +/- 0.026664 (0.49%) (init= 2)
   shift: 0.16203676 + - 0.014056 (8.67\%) (init= 0)
  decay: 0.03264538 + - 0.000380 (1.16\%) (init= 0.02)
[[Correlations]] (unreported correlations are < 0.100)
   C(period, shift) = 0.797
   C(amp, decay)
                           = 0.582
   C(amp, shift)
                            = -0.297
                           = -0.243
   C(amp, period)
  C(shift, decay)
                            = -0.182
   C(period, decay)
                           = -0.150
```

Non-Linear	Least-Squares	Minimization a	nd Curve-Fittin	ig for Python, R	elease 0.9.3	

# MODELING DATA AND CURVE FITTING

A common use of least-squares minimization is *curve fitting*, where one has a parametrized model function meant to explain some phenomena and wants to adjust the numerical values for the model to most closely match some data. With scipy, such problems are commonly solved with scipy.optimize.curve\_fit, which is a wrapper around scipy.optimize.leastsq. Since Lmfit's *minimize()* is also a high-level wrapper around scipy.optimize.leastsq it can be used for curve-fitting problems, but requires more effort than using scipy.optimize.curve\_fit.

Here we discuss lmfit's *Model* class. This takes a model function – a function that calculates a model for some data – and provides methods to create parameters for that model and to fit data using that model function. This is closer in spirit to scipy.optimize.curve\_fit, but with the advantages of using Parameters and lmfit.

In addition to allowing you turn any model function into a curve-fitting method, Lmfit also provides canonical definitions for many known line shapes such as Gaussian or Lorentzian peaks and Exponential decays that are widely used in many scientific domains. These are available in the <code>models</code> module that will be discussed in more detail in the next chapter (*Built-in Fitting Models in the models module*). We mention it here as you may want to consult that list before writing your own model. For now, we focus on turning python function into high-level fitting models with the <code>Model</code> class, and using these to fit data.

# 7.1 Example: Fit data to Gaussian profile

Let's start with a simple and common example of fitting data to a Gaussian peak. As we will see, there is a buit-in GaussianModel class that provides a model function for a Gaussian profile, but here we'll build our own. We start with a simple definition of the model function:

```
>>> from numpy import sqrt, pi, exp, linspace
>>>
>>> def gaussian(x, amp, cen, wid):
... return amp * exp(-(x-cen)**2 /wid)
...
```

We want to fit this objective function to data y(x) represented by the arrays y and x. This can be done easily with optimize.curve\_fit:

```
>>> from scipy.optimize import curve_fit
>>>
>>> x = linspace(-10,10)
>>> y = y = gaussian(x, 2.33, 0.21, 1.51) + np.random.normal(0, 0.2, len(x))
>>>
>>> init_vals = [1, 0, 1]  # for [amp, cen, wid]
>>> best_vals, covar = curve_fit(gaussian, x, y, p0=init_vals)
>>> print best_vals
```

We sample random data point, make an initial guess of the model values, and run optimize.curve\_fit with the model function, data arrays, and initial guesses. The results returned are the optimal values for the parameters and the covariance matrix. It's simple and very useful. But it misses the benefits of lmfit.

To solve this with lmfit we would have to write an objective function. But such a function would be fairly simple (essentially, data - model, possibly with some weighting), and we would need to define and use appropriately named parameters. Though convenient, it is somewhat of a burden to keep the named parameter straight (on the other hand, with optimize.curve\_fit you are required to remember the parameter order). After doing this a few times it appears as a recurring pattern, and we can imagine automating this process. That's where the <code>Model</code> class comes in.

Model allows us to easily wrap a model function such as the gaussian function. This automatically generate the appropriate residual function, and determines the corresponding parameter names from the function signature itself:

```
>>> from lmfit import Model
>>> gmod = Model(gaussian)
>>> gmod.param_names
set(['amp', 'wid', 'cen'])
>>> gmod.independent_vars)
['x']
```

The Model gmod knows the names of the parameters and the independent variables. By default, the first argument of the function is taken as the independent variable, held in <code>independent\_vars</code>, and the rest of the functions positional arguments (and, in certain cases, keyword arguments – see below) are used for Parameter names. Thus, for the <code>gaussian</code> function above, the parameters are named <code>amp</code>, <code>cen</code>, and <code>wid</code>, and <code>x</code> is the independent variable – all taken directly from the signature of the model function. As we will see below, you can specify what the independent variable is, and you can add or alter parameters, too.

The parameters are *not* created when the model is created. The model knows what the parameters should be named, but not anything about the scale and range of your data. You will normally have to make these parameters and assign initial values and other attributes. To help you do this, each model has a make\_params () method that will generate parameters with the expected names:

```
>>> params = gmod.make_params()
```

This creates the Parameters but doesn't necessarily give them initial values – again, the model has no idea what the scale should be. You can set initial values for parameters with keyword arguments to make\_params():

```
>>> params = gmod.make_params(cen=5, amp=200, wid=1)
```

or assign them (and other parameter properties) after the Parameters has been created.

A <code>Model</code> has several methods associated with it. For example, one can use the <code>eval()</code> method to evaluate the model or the <code>fit()</code> method to fit data to this model with a <code>Parameter</code> object. Both of these methods can take explicit keyword arguments for the parameter values. For example, one could use <code>eval()</code> to calculate the predicted function:

```
>>> x = linspace(0, 10, 201)
>>> y = gmod.eval(x=x, amp=10, cen=6.2, wid=0.75)
```

Admittedly, this a slightly long-winded way to calculate a Gaussian function. But now that the model is set up, we can also use its fit () method to fit this model to data, as with:

```
>>> result = gmod.fit(y, x=x, amp=5, cen=5, wid=1)
```

Putting everything together, the script to do such a fit (included in the examples folder with the source code) is:

```
#!/usr/bin/env python
#<examples/doc_model1.py>
from numpy import sqrt, pi, exp, linspace, loadtxt
from lmfit import Model
```

```
import matplotlib.pyplot as plt

data = loadtxt('modelld_gauss.dat')
x = data[:, 0]
y = data[:, 1]

def gaussian(x, amp, cen, wid):
    "1-d gaussian: gaussian(x, amp, cen, wid)"
    return (amp/(sqrt(2*pi)*wid)) * exp(-(x-cen)**2 /(2*wid**2))

gmod = Model(gaussian)
result = gmod.fit(y, x=x, amp=5, cen=5, wid=1)

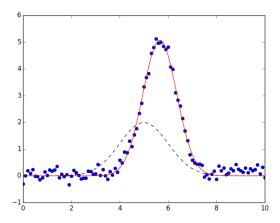
print(result.fit_report())

plt.plot(x, y, 'bo')
plt.plot(x, result.init_fit, 'k--')
plt.plot(x, result.best_fit, 'r--')
plt.show()
#<end examples/doc_model1.py>
```

which is pretty compact and to the point. The returned result will be a *ModelResult* object. As we will see below, this has many components, including a fit\_report () method, which will show:

```
[[Model]]
   gaussian
[[Fit Statistics]]
   # function evals = 33
   # data points = 101
   # variables
                    = 3
                 = 3.409
   chi-square
   reduced chi-square = 0.035
   Akaike info crit = -333.218
   Bayesian info crit = -325.373
[[Variables]]
   amp: 8.88021829 +/- 0.113594 (1.28%) (init= 5)
         5.65866102 +/- 0.010304 (0.18%) (init= 5)
        0.69765468 + - 0.010304 (1.48\%) (init= 1)
[[Correlations]] (unreported correlations are < 0.100)
                               = 0.577
   C(amp, wid)
```

The result will also have <u>init\_fit</u> for the fit with the initial parameter values and a <u>best\_fit</u> for the fit with the best fit parameter values. These can be used to generate the following plot:



which shows the data in blue dots, the best fit as a solid

red line, and the initial fit as a dashed black line.

Note that the model fitting was really performed with 2 lines of code:

```
gmod = Model(gaussian)
result = gmod.fit(y, x=x, amp=5, cen=5, wid=1)
```

These lines clearly express that we want to turn the gaussian function into a fitting model, and then fit the y(x) data to this model, starting with values of 5 for amp, 5 for cen and 1 for wid. This is much more expressive than optimize.curve\_fit:

```
best_vals, covar = curve_fit(gaussian, x, y, p0=[5, 5, 1])
```

In addition, all the other features of lmfit are included: Parameters can have bounds and constraints and the result is a rich object that can be reused to explore the model fit in detail.

# 7.2 The Model class

The Model class provides a general way to wrap a pre-defined function as a fitting model.

Create a model based on the user-supplied function. This uses introspection to automatically converting argument names of the function to Parameter names.

#### **Parameters**

- func (callable) model function to be wrapped
- independent\_vars (None (default) or list of strings.) list of argument names to func that are independent variables.
- param\_names (None (default) or list of strings) list of argument names to func that should be made into Parameters.
- missing (one of None (default), 'none', 'drop', or 'raise'.) how to handle missing values
- **prefix** (*string*) prefix to add to all parameter names to distinguish components in a *CompositeModel*.
- name (None or string.) name for the model. When None (default) the name is the same as the model function (func).

• **kws** – additional keyword arguments to pass to model function.

Of course, the model function will have to return an array that will be the same size as the data being modeled. Generally this is handled by also specifying one or more independent variables.

## 7.2.1 Model class Methods

```
Model.eval (params=None[, **kws]) evaluate the model function for a set of parameters and inputs.
```

#### **Parameters**

- params (None (default) or Parameters) parameters to use for fit.
- **kws** additional keyword arguments to pass to model function.

**Returns** ndarray for model given the parameters and other arguments.

If params is None, the values for all parameters are expected to be provided as keyword arguments. If params is given, and a keyword argument for a parameter value is also given, the keyword argument will be used.

Note that all non-parameter arguments for the model function – **including all the independent variables!** – will need to be passed in using keyword arguments.

```
Model.fit (data[, params=None[, weights=None[, method='leastsq'[, scale_covar=True[, iter_cb=None[, **kws]]]]]])

perform a fit of the model to the data array with a set of parameters.
```

#### **Parameters**

- data (ndarray-like) array of data to be fitted.
- params (None (default) or Parameters) parameters to use for fit.
- weights (None (default) or ndarray-like.) weights to use for residual calculation in fit.
- method (string (default leastsq)) name of fitting method to use. See Choosing Different Fitting Methods for details
- **scale\_covar** (bool (default True)) whether to automatically scale covariance matrix (leastsq only)
- iter\_cb (callable or None) function to be called at each fit iteration. See *Using a Iteration Callback Function* for details.
- verbose (bool (default True)) print a message when a new parameter is created due to a hint
- **kws** additional keyword arguments to pass to model function.

Returns ModelResult object.

If params is None, the internal params will be used. If it is supplied, these will replace the internal ones. If supplied, weights will be used to weight the calculated residual so that the quantity minimized in the least-squares sense is weights\*(data - fit). weights must be an ndarray-like object of same size and shape as data.

Note that other arguments for the model function (including all the independent variables!) will need to be passed in using keyword arguments.

```
Model.guess(data, **kws)
```

Guess starting values for model parameters.

param data data array used to guess parameter values

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type func ndarray

param kws additional options to pass to model function.

return Parameters with guessed initial values for each parameter.

by default this is left to raise a NotImplementedError, but may be overwritten by subclasses. Generally, this method should take some values for data and use it to construct reasonable starting values for the parameters.

#### Model.make\_params(\*\*kws)

Create a set of parameters for model.

param kws optional keyword/value pairs to set initial values for parameters.

return Parameters.

The parameters may or may not have decent initial values for each parameter.

Model.set\_param\_hint(name, value=None[, min=None[, max=None[, vary=True[, expr=None]]]]

set *hints* to use when creating parameters with Model.make\_param() for the named parameter. This is especially convenient for setting initial values. The name can include the models prefix or not.

#### **Parameters**

- name (string) parameter name.
- value (float) value for parameter
- min (None or float) lower bound for parameter value
- max (None or float) upper bound for parameter value
- vary (boolean) whether to vary parameter in fit.
- **expr** (*string*) mathematical expression for constraint

See Using parameter hints.

# Model.print\_param\_hints(colwidth=8)

Prints a nicely aligned text-table of parameters hints.

The argument *colwidth* is the width of each column, except for first and last columns.

## 7.2.2 Model class Attributes

#### func

The model function used to calculate the model.

# independent\_vars

list of strings for names of the independent variables.

#### missina

describes what to do for missing values. The choices are

- •None: Do not check for null or missing values (default)
- 'none': Do not check for null or missing values.
- •'drop': Drop null or missing observations in data. If pandas is installed, pandas.isnull is used, otherwise numpy.isnan is used.
- 'raise': Raise a (more helpful) exception when data contains null or missing values.

#### name

name of the model, used only in the string representation of the model. By default this will be taken from the model function.

#### opts

extra keyword arguments to pass to model function. Normally this will be determined internally and should not be changed.

#### param hints

Dictionary of parameter hints. See *Using parameter hints*.

#### param\_names

list of strings of parameter names.

## prefix

prefix used for name-mangling of parameter names. The default is ". If a particular *Model* has arguments amplitude, center, and sigma, these would become the parameter names. Using a prefix of gl\_ would convert these parameter names to gl\_amplitude, gl\_center, and gl\_sigma. This can be essential to avoid name collision in composite models.

# 7.2.3 Determining parameter names and independent variables for a function

The Model created from the supplied function func will create a Parameters object, and names are inferred from the function arguments, and a residual function is automatically constructed.

By default, the independent variable is take as the first argument to the function. You can explicitly set this, of course, and will need to if the independent variable is not first in the list, or if there are actually more than one independent variables.

If not specified, Parameters are constructed from all positional arguments and all keyword arguments that have a default value that is numerical, except the independent variable, of course. Importantly, the Parameters can be modified after creation. In fact, you'll have to do this because none of the parameters have valid initial values. You can place bounds and constraints on Parameters, or fix their values.

# 7.2.4 Explicitly specifying independent\_vars

As we saw for the Gaussian example above, creating a Model from a function is fairly easy. Let's try another:

```
>>> def decay(t, tau, N):
...    return N*np.exp(-t/tau)
...
>>> decay_model = Model(decay)
>>> print decay_model.independent_vars
['t']
>>> for pname, par in decay_model.params.items():
...    print pname, par
...
tau <Parameter 'tau', None, bounds=[None:None]>
N <Parameter 'N', None, bounds=[None:None]>
```

Here, t is assumed to be the independent variable because it is the first argument to the function. The other function arguments are used to create parameters for the model.

If you want tau to be the independent variable in the above example, you can say so:

```
>>> decay_model = Model(decay, independent_vars=['tau'])
>>> print decay_model.independent_vars
['tau']
```

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```
>>> for pname, par in decay_model.params.items():
...    print pname, par
...
t <Parameter 't', None, bounds=[None:None]>
N <Parameter 'N', None, bounds=[None:None]>
```

You can also supply multiple values for multi-dimensional functions with multiple independent variables. In fact, the meaning of *independent variable* here is simple, and based on how it treats arguments of the function you are modeling:

independent variable a function argument that is not a parameter or otherwise part of the model, and that will be required to be explicitly provided as a keyword argument for each fit with Model.fit() or evaluation with Model.eval().

Note that independent variables are not required to be arrays, or even floating point numbers.

# 7.2.5 Functions with keyword arguments

If the model function had keyword parameters, these would be turned into Parameters if the supplied default value was a valid number (but not None, True, or False).

```
>>> def decay2(t, tau, N=10, check_positive=False):
...    if check_small:
...         arg = abs(t)/max(1.e-9, abs(tau))
...         else:
...         arg = t/tau
...         return N*np.exp(arg)
...
>>> mod = Model(decay2)
>>> for pname, par in mod.params.items():
...         print pname, par
...
t <Parameter 't', None, bounds=[None:None]>
N <Parameter 'N', 10, bounds=[None:None]>
```

Here, even though N is a keyword argument to the function, it is turned into a parameter, with the default numerical value as its initial value. By default, it is permitted to be varied in the fit – the 10 is taken as an initial value, not a fixed value. On the other hand, the <code>check\_positive</code> keyword argument, was not converted to a parameter because it has a boolean default value. In some sense, <code>check\_positive</code> becomes like an independent variable to the model. However, because it has a default value it is not required to be given for each model evaluation or fit, as independent variables are.

# 7.2.6 Defining a prefix for the Parameters

As we will see in the next chapter when combining models, it is sometimes necessary to decorate the parameter names in the model, but still have them be correctly used in the underlying model function. This would be necessary, for example, if two parameters in a composite model (see *Composite Models*: adding (or multiplying) Models or examples in the next chapter) would have the same name. To avoid this, we can add a prefix to the Model which will automatically do this mapping for us.

```
>>> def myfunc(x, amplitude=1, center=0, sigma=1):
...
```

```
>>> mod = Model(myfunc, prefix='f1_')
>>> for pname, par in mod.params.items():
... print pname, par
```

```
fl_amplitude <Parameter 'fl_amplitude', None, bounds=[None:None]>
fl_center <Parameter 'fl_center', None, bounds=[None:None]>
fl_sigma <Parameter 'fl_sigma', None, bounds=[None:None]>
```

You would refer to these parameters as f1\_amplitude and so forth, and the model will know to map these to the amplitude argument of myfunc.

# 7.2.7 Initializing model parameters

As mentioned above, the parameters created by <code>Model.make\_params()</code> are generally created with invalid initial values of <code>None</code>. These values **must** be initialized in order for the model to be evaluated or used in a fit. There are four different ways to do this initialization that can be used in any combination:

- 1. You can supply initial values in the definition of the model function.
- 2. You can initialize the parameters when creating parameters with Model.make\_params().
- 3. You can give parameter hints with <code>Model.set\_param\_hint()</code>.
- 4. You can supply initial values for the parameters when you use the <code>Model.eval()</code> or <code>Model.fit()</code> methods.

Of course these methods can be mixed, allowing you to overwrite initial values at any point in the process of defining and using the model.

## Initializing values in the function definition

To supply initial values for parameters in the definition of the model function, you can simply supply a default value:

```
>>> def myfunc(x, a=1, b=0):
>>> ...
```

instead of using:

```
>>> def myfunc(x, a, b):
>>> ...
```

This has the advantage of working at the function level – all parameters with keywords can be treated as options. It also means that some default initial value will always be available for the parameter.

#### Initializing values with Model.make params()

When creating parameters with <code>Model.make\_params()</code> you can specify initial values. To do this, use keyword arguments for the parameter names and initial values:

```
>>> mod = Model(myfunc)
>>> pars = mod.make_params(a=3, b=0.5)
```

#### Initializing values by setting parameter hints

After a model has been created, but prior to creating parameters with <code>Model.make\_params()</code>, you can set parameter hints. These allows you to set not only a default initial value but also to set other parameter attributes controlling bounds, whether it is varied in the fit, or a constraint expression. To set a parameter hint, you can use <code>Model.set\_param\_hint()</code>, as with:

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```
>>> mod = Model(myfunc)
>>> mod.set_param_hint('a', value = 1.0)
>>> mod.set_param_hint('b', value = 0.3, min=0, max=1.0)
>>> pars = mod.make_params()
```

Parameter hints are discussed in more detail in section *Using parameter hints*.

# Initializing values when using a model

Finally, you can explicitly supply initial values when using a model. That is, as with <code>Model.make\_params()</code>, you can include values as keyword arguments to either the <code>Model.eval()</code> or <code>Model.fit()</code> methods:

```
>>> y1 = mod.eval(x=x, a=7.0, b=-2.0)
>>> out = mod.fit(x=x, pars, a=3.0, b=-0.0)
```

These approaches to initialization provide many opportunities for setting initial values for parameters. The methods can be combined, so that you can set parameter hints but then change the initial value explicitly with <code>Model.fit()</code>.

# 7.2.8 Using parameter hints

After a model has been created, you can give it hints for how to create parameters with <code>Model.make\_params()</code>. This allows you to set not only a default initial value but also to set other parameter attributes controlling bounds, whether it is varied in the fit, or a constraint expression. To set a parameter hint, you can use <code>Model.set\_param\_hint()</code>, as with:

```
>>> mod = Model(myfunc)
>>> mod.set_param_hint('a', value = 1.0)
>>> mod.set_param_hint('b', value = 0.3, min=0, max=1.0)
```

Parameter hints are stored in a model's param\_hints attribute, which is simply a nested dictionary:

```
>>> print mod.param_hints
{'a': {'value': 1}, 'b': {'max': 1.0, 'value': 0.3, 'min': 0}}
```

You can change this dictionary directly, or with the <code>Model.set\_param\_hint()</code> method. Either way, these parameter hints are used by <code>Model.make\_params()</code> when making parameters.

An important feature of parameter hints is that you can force the creation of new parameters with parameter hints. This can be useful to make derived parameters with constraint expressions. For example to get the full-width at half maximum of a Gaussian model, one could use a parameter hint of:

```
>>> mod = Model(gaussian)
>>> mod.set_param_hint('fwhm', expr='2.3548*sigma')
```

# 7.3 The ModelResult class

A *ModelResult* (which had been called *ModelFit* prior to version 0.9) is the object returned by *Model.fit*(). It is a subclass of *Minimizer*, and so contains many of the fit results. Of course, it knows the *Model* and the set of Parameters used in the fit, and it has methods to evaluate the model, to fit the data (or re-fit the data with changes to the parameters, or fit with different or modified data) and to print out a report for that fit.

While a <code>Model</code> encapsulates your model function, it is fairly abstract and does not contain the parameters or data used in a particular fit. A <code>ModelResult</code> does contain parameters and data as well as methods to alter and re-do fits. Thus

the *Model* is the idealized model while the *ModelResult* is the messier, more complex (but perhaps more useful) object that represents a fit with a set of parameters to data with a model.

A *ModelResult* has several attributes holding values for fit results, and several methods for working with fits. These include statistics inherited from *Minimizer* useful for comparing different models, including *chisqr*, *redchi*, *aic*, and *bic*.

#### class ModelResult

Model fit is intended to be created and returned by Model.fit().

#### 7.3.1 ModelResult methods

These methods are all inherited from Minimize or from Model.

```
ModelResult.eval(**kwargs)
```

evaluate the model using the best-fit parameters and supplied independent variables. The \*\*kwargs arguments can be used to update parameter values and/or independent variables.

```
ModelResult.eval_components(**kwargs)
```

evaluate each component of a *CompositeModel*, returning an ordered dictionary of with the values for each component model. The returned dictionary will have keys of the model prefix or (if no prefix is given), the model name. The \*\*kwargs arguments can be used to update parameter values and/or independent variables.

```
ModelResult.fit (data=None[, params=None[, weights=None[, method=None[, **kwargs]]]]) fit (or re-fit), optionally changing data, params, weights, or method, or changing the independent variable(s) with the **kwargs argument. See Model.fit() for argument descriptions, and note that any value of None defaults to the last used value.
```

```
ModelResult.fit_report (modelpars=None[, show_correl=True[, '< min_correl=0.1]])
return a printable fit report for the fit with fit statistics, best-fit values with uncertainties and correlations. As with fit_report().
```

#### **Parameters**

- modelpars Parameters with "Known Values" (optional, default None)
- **show\_correl** whether to show list of sorted correlations [True]
- min correl smallest correlation absolute value to show [0.1]

#### ModelResult.conf interval(\*\*kwargs)

calculate the confidence intervals for the variable parameters using <code>confidence.conf\_interval()</code>. All keyword arguments are passed to that function. The result is stored in <code>ci\_out</code>, and so can be accessed without recalculating them.

```
ModelResult.ci_report (with_offset=True)
```

return a nicely formatted text report of the confidence intervals, as from ci report ().

```
ModelResult.plot(datafmt='o', fitfmt='-', initfmt='-', yerr=None, numpoints=None, fig=None, data_kws=None, fit_kws=None, init_kws=None, ax_fit_kws=None, fig_kws=None) init_kws=None, ax_fit_kws=None, fig_kws=None)
```

Plot the fit results and residuals using matplotlib, if available. The plot will include two panels, one showing the fit residual, and the other with the data points, the initial fit curve, and the best-fit curve. If the fit model included weights or if yerr is specified, errorbars will also be plotted.

#### **Parameters**

- datafmt (None or string.) matplotlib format string for data curve.
- **fitfmt** (None or string.) matplotlib format string for best-fit curve.
- initfmt matplotlib format string for initial curve.

- yerr (None or ndarray.) array of uncertainties for data array.
- numpoints (None or integer) number of points to display
- **fig** (None or matplotlib.figure.Figure) matplotlib Figure to plot on.
- data\_kws (None or dictionary) keyword arguments passed to plot for data curve.
- fit kws (None or dictionary) keyword arguments passed to plot for best-fit curve.
- init\_kws (None or dictionary) keyword arguments passed to plot for initial curve.
- ax\_res\_kws (None or dictionary) keyword arguments passed to creation of matplotlib axes for the residual plot.
- ax\_fit\_kws (None or dictionary) keyword arguments passed to creation of matplotlib
  axes for the fit plot.
- fig\_kws (None or dictionary) keyword arguments passed to creation of matplotlib fig-

#### Returns matplotlib.figure.Figure

This combines ModelResult.plot\_fit() and ModelResult.plot\_residual().

If yerr is specified or if the fit model included weights, then matplotlib.axes. Axes. errorbar is used to plot the data. If yerr is not specified and the fit includes weights, yerr set to 1/self.weights

If fig is None then matplotlib.pyplot.figure(\*\*fig\_kws) is called.

ModelResult.plot\_fit (ax=None, datafmt='o', fitfmt='-', initfmt='-', yerr=None, numpoints=None, data\_kws=None, fit\_kws=None, init\_kws=None, ax\_kws=None)

Plot the fit results using matplotlib, if available. The plot will include the data points, the initial fit curve, and the best-fit curve. If the fit model included weights or if yerr is specified, errorbars will also be plotted.

# **Parameters**

- **ax** (None or matplotlib.axes.Axes.) matplotlib axes to plot on.
- datafmt (None or string.) matplotlib format string for data curve.
- fitfmt (None or string.) matplotlib format string for best-fit curve.
- initfmt matplotlib format string for initial curve.
- yerr (None or ndarray.) array of uncertainties for data array.
- numpoints (None or integer) number of points to display
- data\_kws (None or dictionary) keyword arguments passed to plot for data curve.
- fit\_kws (None or dictionary) keyword arguments passed to plot for best-fit curve.
- init\_kws (None or dictionary) keyword arguments passed to plot for initial curve.
- ax\_kws (None or dictionary) keyword arguments passed to creation of matplotlib axes.

## **Returns** matplotlib.axes.Axes

For details about plot format strings and keyword arguments see documentation of matplotlib.axes.Axes.plot().

If yerr is specified or if the fit model included weights, then matplotlib.axes. Axes. errorbar is used to plot the data. If yerr is not specified and the fit includes weights, yerr set to 1/self.weights

If ax is None then matplotlib.pyplot.gca(\*\*ax\_kws) is called.

ModelResult.plot\_residuals (ax=None, datafmt='o', yerr=None, data\_kws=None, fit\_kws=None, ax kws=None)

Plot the fit residuals (data - fit) using matplotlib. If yerr is supplied or if the model included weights, errorbars will also be plotted.

param ax matplotlib axes to plot on.

type ax None or matplotlib.axes. Axes.

param datafmt matplotlib format string for data curve.

type datafmt None or string.

param yerr array of uncertainties for data array.

type yerr None or ndarray.

param numpoints number of points to display

type numpoints None or integer

param data\_kws keyword arguments passed to plot for data curve.

type data\_kws None or dictionary

param fit\_kws keyword arguments passed to plot for best-fit curve.

type fit\_kws None or dictionary

param ax\_kws keyword arguments passed to creation of matplotlib axes.

type ax\_kws None or dictionary

returns matplotlib.axes.Axes

For details about plot format strings and keyword arguments see documentation of matplotlib.axes.Axes.plot().

If yerr is specified or if the fit model included weights, then matplotlib.axes. Axes. errorbar is used to plot the data. If yerr is not specified and the fit includes weights, yerr set to 1/self.weights

If ax is None then matplotlib.pyplot.gca(\*\*ax\_kws) is called.

# 7.3.2 ModelResult attributes

#### aic

floating point best-fit Akaike Information Criterion statistic (see *MinimizerResult – the optimization result*).

#### best fit

ndarray result of model function, evaluated at provided independent variables and with best-fit parameters.

#### best values

dictionary with parameter names as keys, and best-fit values as values.

#### bic

floating point best-fit Bayesian Information Criterion statistic (see MinimizerResult – the optimization result).

## chisqr

floating point best-fit chi-square statistic (see *MinimizerResult – the optimization result*).

#### ci\_out

confidence interval data (see *Calculation of confidence intervals*) or *None* if the confidence intervals have not been calculated.

#### covar

ndarray (square) covariance matrix returned from fit.

#### data

ndarray of data to compare to model.

#### errorbars

boolean for whether error bars were estimated by fit.

#### ier

integer returned code from optimize.leastsq.

#### init\_fit

ndarray result of model function, evaluated at provided independent variables and with initial parameters.

#### init\_params

initial parameters.

#### init\_values

dictionary with parameter names as keys, and initial values as values.

#### iter cb

optional callable function, to be called at each fit iteration. This must take take arguments of params, iter, resid, \*args, \*\*kws, where params will have the current parameter values, iter the iteration, resid the current residual array, and \*args and \*\*kws as passed to the objective function. See *Using a Iteration Callback Function*.

#### jacfcn

optional callable function, to be called to calculate jacobian array.

#### lmdif\_message

string message returned from optimize.leastsq.

#### message

string message returned from minimize().

#### method

string naming fitting method for minimize ().

#### model

instance of Model used for model.

#### ndata

integer number of data points.

#### nfev

integer number of function evaluations used for fit.

#### nfree

integer number of free parameters in fit.

# nvarys

integer number of independent, freely varying variables in fit.

#### params

Parameters used in fit. Will have best-fit values.

# redchi

floating point reduced chi-square statistic (see *MinimizerResult – the optimization result*).

## residual

ndarray for residual.

#### scale covar

boolean flag for whether to automatically scale covariance matrix.

#### success

boolean value of whether fit succeeded.

#### weights

ndarray (or None) of weighting values to be used in fit. If not None, it will be used as a multiplicative factor of the residual array, so that weights\* (data - fit) is minimized in the least-squares sense.

# 7.4 Composite Models: adding (or multiplying) Models

One of the more interesting features of the *Model* class is that Models can be added together or combined with basic algebraic operations (add, subtract, multiply, and divide) to give a composite model. The composite model will have parameters from each of the component models, with all parameters being available to influence the whole model. This ability to combine models will become even more useful in the next chapter, when pre-built subclasses of *Model* are discussed. For now, we'll consider a simple example, and build a model of a Gaussian plus a line, as to model a peak with a background. For such a simple problem, we could just build a model that included both components:

```
def gaussian_plus_line(x, amp, cen, wid, slope, intercept):
    "line + 1-d gaussian"

    gauss = (amp/(sqrt(2*pi)*wid)) * exp(-(x-cen)**2 /(2*wid**2))
    line = slope * x + intercept
    return gauss + line
```

and use that with:

```
mod = Model(gaussian_plus_line)
```

But we already had a function for a gaussian function, and maybe we'll discover that a linear background isn't sufficient which would mean the model function would have to be changed. As an alternative we could define a linear function:

```
def line(x, slope, intercept):
    "a line"
    return slope * x + intercept
```

and build a composite model with just:

```
mod = Model(gaussian) + Model(line)
```

This model has parameters for both component models, and can be used as:

```
#!/usr/bin/env python
#<examples/model_doc2.py>
from numpy import sqrt, pi, exp, loadtxt
from lmfit import Model

import matplotlib.pyplot as plt

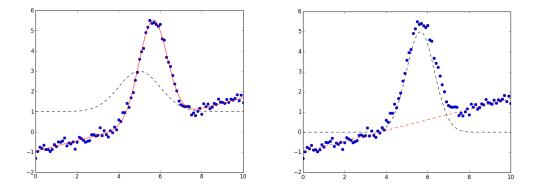
data = loadtxt('model1d_gauss.dat')
x = data[:, 0]
y = data[:, 1] + 0.25*x - 1.0

def gaussian(x, amp, cen, wid):
    "1-d gaussian: gaussian(x, amp, cen, wid)"
    return (amp/(sqrt(2*pi)*wid)) * exp(-(x-cen)**2 /(2*wid**2))
```

#### which prints out the results:

```
[[Model]]
   (Model(gaussian) + Model(line))
[[Fit Statistics]]
   # function evals = 44
                    = 101
   # data points
   # variables
                     = 5
                 = 2.579
   chi-square
   reduced chi-square = 0.027
   Akaike info crit = -355.329
   Bayesian info crit = -342.253
[[Variables]]
                8.45931061 +/- 0.124145 (1.47%) (init= 5)
   amp:
              5.65547872 +/- 0.009176 (0.16%) (init= 5)
   intercept: -0.96860201 +/- 0.033522 (3.46\%) (init= 1)
   slope: 0.26484403 +/- 0.005748 (2.17%) (init= 0)
               0.67545523 + - 0.009916 (1.47\%) (init= 1)
   wid:
[[Correlations]] (unreported correlations are < 0.100)
   C(amp, wid)
                               = 0.666
   C(cen, intercept)
                               = 0.129
```

and shows the plot on the left.



On the left, data is shown in blue dots, the total fit is shown in solid red line, and the initial fit is shown as a black dashed line. In the figure on the right, the data is again shown in blue dots, and the Gaussian component shown as a black dashed line, and the linear component shown as a red dashed line. These components were generated after the

fit using the Models ModelResult.eval\_components() method of the result:

```
comps = result.eval_components()
```

which returns a dictionary of the components, using keys of the model name (or *prefix* if that is set). This will use the parameter values in result.params and the independent variables (x) used during the fit. Note that while the *ModelResult* held in *result* does store the best parameters and the best estimate of the model in result.best fit, the original model and parameters in pars are left unaltered.

You can apply this composite model to other data sets, or evaluate the model at other values of x. You may want to do this to give a finer or coarser spacing of data point, or to extrapolate the model outside the fitting range. This can be done with:

```
xwide = np.linspace(-5, 25, 3001)
predicted = mod.eval(x=xwide)
```

In this example, the argument names for the model functions do not overlap. If they had, the prefix argument to *Model* would have allowed us to identify which parameter went with which component model. As we will see in the next chapter, using composite models with the built-in models provides a simple way to build up complex models.

```
class CompositeModel (left, right, op[, **kws])
```

Create a composite model from two models (*left* and *right* and an binary operator (op). Additional keywords are passed to Model.

#### **Parameters**

- left (Model) left-hand side Model
- right (Model) right-hand side Model
- op (callable, and taking 2 arguments (*left* and *right*).) binary operator

Normally, one does not have to explicitly create a CompositeModel, as doing:

```
mod = Model(fcn1) + Model(fcn2) * Model(fcn3)
```

will automatically create a <code>CompositeModel</code>. In this example, <code>mod.left</code> will be <code>Model(fcn1)</code>, <code>mod.op</code> will be operator.add(), and <code>mod.right</code> will be another CompositeModel that has a <code>left</code> attribute of <code>Model(fcn2)</code>, an <code>op</code> of operator.mul(), and a <code>right</code> of <code>Model(fcn3)</code>.

If you want to use a binary operator other than add, subtract, multiply, or divide that are supported through normal Python syntax, you'll need to explicitly create a <code>CompositeModel</code> with the appropriate binary operator. For example, to convolve two models, you could define a simple convolution function, perhaps as:

```
import numpy as np
def convolve(dat, kernel):
    # simple convolution
    npts = min(len(dat), len(kernel))
    pad = np.ones(npts)
    tmp = np.concatenate((pad*dat[0], dat, pad*dat[-1]))
    out = np.convolve(tmp, kernel, mode='valid')
    noff = int((len(out) - npts)/2)
    return (out[noff:])[:npts]
```

which extends the data in both directions so that the convolving kernel function gives a valid result over the data range. Because this function takes two array arguments and returns an array, it can be used as the binary operator. A full script using this technique is here:

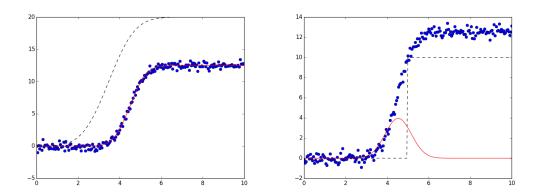
```
#!/usr/bin/env python
#<examples/model_doc3.py>
import numpy as np
```

```
from lmfit import Model, CompositeModel
from lmfit.lineshapes import step, gaussian
import matplotlib.pyplot as plt
# create data from broadened step
npts = 201
x = np.linspace(0, 10, npts)
y = step(x, amplitude=12.5, center=4.5, sigma=0.88, form='erf')
y = y + np.random.normal(size=npts, scale=0.35)
def jump(x, mid):
    "heaviside step function"
   o = np.zeros(len(x))
   imid = max(np.where(x \le mid)[0])
   o[imid:] = 1.0
   return o
def convolve(arr, kernel):
    # simple convolution of two arrays
   npts = min(len(arr), len(kernel))
   pad = np.ones(npts)
   tmp = np.concatenate((pad*arr[0], arr, pad*arr[-1]))
   out = np.convolve(tmp, kernel, mode='valid')
   noff = int((len(out) - npts)/2)
   return out[noff:noff+npts]
# create Composite Model using the custom convolution operator
mod = CompositeModel(Model(jump), Model(gaussian), convolve)
pars = mod.make_params(amplitude=1, center=3.5, sigma=1.5, mid=5.0)
# 'mid' and 'center' should be completely correlated, and 'mid' is
# used as an integer index, so a very poor fit variable:
pars['mid'].vary = False
# fit this model to data array y
result = mod.fit(y, params=pars, x=x)
print (result.fit_report())
plot_components = False
# plot results
plt.plot(x, y,
if plot_components:
    # generate components
   comps = result.eval_components(x=x)
   plt.plot(x, 10*comps['jump'], 'k--')
   plt.plot(x, 10*comps['gaussian'], 'r-')
   plt.plot(x, result.init_fit, 'k--')
   plt.plot(x, result.best_fit, 'r-')
plt.show()
# #<end examples/model_doc3.py>
```

which prints out the results:

```
[[Model]]
   (Model(jump) <function convolve at 0x109ee4488> Model(gaussian))
[[Fit Statistics]]
   # function evals
                      = 23
                      = 201
   # data points
   # variables
                      = 3
   chi-square
                      = 25.789
   reduced chi-square = 0.130
   Akaike info crit = -403.702
   Bayesian info crit = -393.793
[[Variables]]
   mid:
                5 (fixed)
   amplitude: 0.62249894 +/- 0.001946 (0.31\%) (init= 1)
   sigma:
                0.61438887 +/- 0.014057 (2.29%) (init= 1.5)
   center:
                4.51710256 +/- 0.010152 (0.22%) (init= 3.5)
[[Correlations]] (unreported correlations are < 0.100)
   C(amplitude, center)
                               = 0.335
   C(amplitude, sigma)
                                = 0.273
```

# and shows the plots:



Using composite models with built-in or custom operators allows you to build complex models from testable sub-components.

Non-Linear Least-Squares Minimization and Curve-Fitting for Python, Release 0.9.3							

**CHAPTER** 

**EIGHT** 

# BUILT-IN FITTING MODELS IN THE MODELS MODULE

Lmfit provides several builtin fitting models in the *models* module. These pre-defined models each subclass from the *model.Model* class of the previous chapter and wrap relatively well-known functional forms, such as Gaussians, Lorentzian, and Exponentials that are used in a wide range of scientific domains. In fact, all the models are all based on simple, plain python functions defined in the lineshapes module. In addition to wrapping a function into a *model.Model*, these models also provide a guess () method that is intended to give a reasonable set of starting values from a data array that closely approximates the data to be fit.

As shown in the previous chapter, a key feature of the mode. Model class is that models can easily be combined to give a composite model. Model. Thus while some of the models listed here may seem pretty trivial (notably, ConstantModel and LinearModel), the main point of having these is to be able to used in composite models. For example, a Lorentzian plus a linear background might be represented as:

```
>>> from lmfit.models import LinearModel, LorentzianModel
>>> peak = LorentzianModel()
>>> background = LinearModel()
>>> model = peak + background
```

All the models listed below are one dimensional, with an independent variable named x. Many of these models represent a function with a distinct peak, and so share common features. To maintain uniformity, common parameter names are used whenever possible. Thus, most models have a parameter called amplitude that represents the overall height (or area of) a peak or function, a center parameter that represents a peak centroid position, and a sigma parameter that gives a characteristic width. Many peak shapes also have a parameter fwhm (constrained by sigma) giving the full width at half maximum and a parameter height (constrained by sigma and amplitude) to give the maximum peak height.

After a list of builtin models, a few examples of their use is given.

# 8.1 Peak-like models

There are many peak-like models available. These include <code>GaussianModel,LorentzianModel,VoigtModel</code> and some less commonly used variations. The <code>guess()</code> methods for all of these make a fairly crude guess for the value of <code>amplitude</code>, but also set a lower bound of 0 on the value of <code>sigma</code>.

#### 8.1.1 GaussianModel

```
class GaussianModel (missing=None[, prefix=''[, name=None[, **kws]]])
```

A model based on a Gaussian or normal distribution lineshape. Parameter names: amplitude, center, and sigma. In addition, parameters fwhm and height are included as constraints to report full width at half maxi-

mum and maximum peak height, respectively.

$$f(x; A, \mu, \sigma) = \frac{A}{\sigma \sqrt{2\pi}} e^{\left[-(x-\mu)^2/2\sigma^2\right]}$$

where the parameter amplitude corresponds to A, center to  $\mu$ , and sigma to  $\sigma$ . The full width at half maximum is  $2\sigma\sqrt{2\ln 2}$ , approximately  $2.3548\sigma$ 

#### 8.1.2 LorentzianModel

class LorentzianModel (missing=None[, prefix=', name=None[, \*\*kws]]])

A model based on a Lorentzian or Cauchy-Lorentz distribution function. Parameter names: amplitude, center, and sigma. In addition, parameters fwhm and height are included as constraints to report full width at half maximum and maximum peak height, respectively.

$$f(x; A, \mu, \sigma) = \frac{A}{\pi} \left[ \frac{\sigma}{(x - \mu)^2 + \sigma^2} \right]$$

where the parameter amplitude corresponds to A, center to  $\mu$ , and sigma to  $\sigma$ . The full width at half maximum is  $2\sigma$ .

# 8.1.3 VoigtModel

class VoigtModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

A model based on a Voigt distribution function. Parameter names: amplitude, center, and sigma. A gamma parameter is also available. By default, it is constrained to have value equal to sigma, though this can be varied independently. In addition, parameters fwhm and height are included as constraints to report full width at half maximum and maximum peak height, respectively. The definition for the Voigt function used here is

$$f(x; A, \mu, \sigma, \gamma) = \frac{A \text{Re}[w(z)]}{\sigma \sqrt{2\pi}}$$

where

$$z = \frac{x - \mu + i\gamma}{\sigma\sqrt{2}}$$
$$w(z) = e^{-z^2}\operatorname{erfc}(-iz)$$

and erfc() is the complimentary error function. As above, amplitude corresponds to A, center to  $\mu$ , and sigma to  $\sigma$ . The parameter gamma corresponds to  $\gamma$ . If gamma is kept at the default value (constrained to sigma), the full width at half maximum is approximately  $3.6013\sigma$ .

# 8.1.4 PseudoVoigtModel

 $\textbf{class PseudoVoigtModel} \ (\textit{missing} = None \big[, \textit{prefix} = \text{``} \big[, \textit{name} = None \big[, **kws \big] \big] \big] \big)$ 

a model based on a pseudo-Voigt distribution function, which is a weighted sum of a Gaussian and Lorentzian distribution functions with that share values for amplitude (A), center  $(\mu)$  and full width at half maximum (and so have constrained values of sigma  $(\sigma)$ . A parameter fraction  $(\alpha)$  controls the relative weight of the Gaussian and Lorentzian components, giving the full definition of

$$f(x; A, \mu, \sigma, \alpha) = \frac{(1 - \alpha)A}{\sigma_q \sqrt{2\pi}} e^{\left[-(x - \mu)^2 / 2\sigma_g^2\right]} + \frac{\alpha A}{\pi} \left[\frac{\sigma}{(x - \mu)^2 + \sigma^2}\right]$$

where  $\sigma_g = \sigma/\sqrt{2\ln 2}$  so that the full width at half maximum of each component and of the sum is  $2\sigma$ . The guess () function always sets the starting value for fraction at 0.5.

# 8.1.5 MoffatModel

class MoffatModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

a model based on a Moffat distribution function, the parameters are amplitude (A), center  $(\mu)$ , a width parameter sigma  $(\sigma)$  and an exponent beta  $(\beta)$ . For  $(\beta = 1)$  the Moffat has a Lorentzian shape.

$$f(x; A, \mu, \sigma, \beta) = A \left[ \left( \frac{x - \mu}{\sigma} \right)^2 + 1 \right]^{-\beta}$$

the full width have maximum is  $2\sigma\sqrt{2^{1/\beta}-1}$ . guess () function always sets the starting value for beta to 1.

#### 8.1.6 Pearson7Model

class Pearson7Model (missing=None[, prefix='`[, name=None[, \*\*kws]]])

A model based on a Pearson VII distribution. This is a Lorenztian-like distribution function. It has the usual parameters amplitude (A), center  $(\mu)$  and sigma  $(\sigma)$ , and also an exponent (m) in

$$f(x; A, \mu, \sigma, m) = \frac{A}{\sigma \beta (m - \frac{1}{2}, \frac{1}{2})} \left[ 1 + \frac{(x - \mu)^2}{\sigma^2} \right]^{-m}$$

where  $\beta$  is the beta function (see special.beta in scipy.special). The guess () function always gives a starting value for exponent of 1.5.

#### 8.1.7 StudentsTModel

class StudentsTModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

A model based on a Student's t distribution function, with the usual parameters amplitude (A), center ( $\mu$ ) and sigma ( $\sigma$ ) in

$$f(x; A, \mu, \sigma) = \frac{A\Gamma(\frac{\sigma+1}{2})}{\sqrt{\sigma\pi} \Gamma(\frac{\sigma}{2})} \left[ 1 + \frac{(x-\mu)^2}{\sigma} \right]^{-\frac{\sigma+1}{2}}$$

where  $\Gamma(x)$  is the gamma function.

# 8.1.8 BreitWignerModel

class BreitWignerModel (missing=None[, prefix='`[, name=None[, \*\*kws]]])

A model based on a Breit-Wigner-Fano function. It has the usual parameters amplitude (A), center  $(\mu)$  and sigma  $(\sigma)$ , plus q(q) in

$$f(x; A, \mu, \sigma, q) = \frac{A(q\sigma/2 + x - \mu)^2}{(\sigma/2)^2 + (x - \mu)^2}$$

# 8.1.9 LognormalModel

class LognormalModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

A model based on the Log-normal distribution function. It has the usual parameters amplitude (A), center  $(\mu)$  and sigma  $(\sigma)$  in

$$f(x; A, \mu, \sigma) = \frac{Ae^{-(\ln(x) - \mu)/2\sigma^2}}{x}$$

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# 8.1.10 DampedOcsillatorModel

class DampedOcsillatorModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

A model based on the Damped Harmonic Oscillator Amplitude. It has the usual parameters amplitude (A), center  $(\mu)$  and sigma  $(\sigma)$  in

$$f(x; A, \mu, \sigma) = \frac{A}{\sqrt{[1 - (x/\mu)^2]^2 + (2\sigma x/\mu)^2}}$$

# 8.1.11 ExponentialGaussianModel

class ExponentialGaussianModel (missing=None[, prefix='`[, name=None[, \*\*kws]]])

A model of an Exponentially modified Gaussian distribution. It has the usual parameters amplitude (A), center  $(\mu)$  and sigma  $(\sigma)$ , and also gamma  $(\gamma)$  in

$$f(x; A, \mu, \sigma, \gamma) = \frac{A\gamma}{2} \exp\left[\gamma(\mu - x + \gamma\sigma^2/2)\right] \operatorname{erfc}\left(\frac{\mu + \gamma\sigma^2 - x}{\sqrt{2}\sigma}\right)$$

where  ${\tt erfc}$  () is the complimentary error function.

#### 8.1.12 SkewedGaussianModel

class SkewedGaussianModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

A variation of the above model, this is a Skewed normal distribution. It has the usual parameters amplitude (A), center  $(\mu)$  and sigma  $(\sigma)$ , and also gamma  $(\gamma)$  in

$$f(x; A, \mu, \sigma, \gamma) = \frac{A}{\sigma\sqrt{2\pi}} e^{\left[-(x-\mu)^2/2\sigma^2\right]} \left\{ 1 + \operatorname{erf}\left[\frac{\gamma(x-\mu)}{\sigma\sqrt{2}}\right] \right\}$$

where erf () is the error function.

# 8.1.13 DonaichModel

class DonaichModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

A model of an Doniach Sunjic asymmetric lineshape, used in photo-emission. With the usual parameters amplitude (A), center  $(\mu)$  and sigma  $(\sigma)$ , and also gamma  $(\gamma)$  in

$$f(x; A, \mu, \sigma, \gamma) = A \frac{\cos\left[\pi\gamma/2 + (1 - \gamma)\arctan\left((x - \mu)/\sigma\right)\right]}{\left[1 + (x - \mu)/\sigma\right]^{(1 - \gamma)/2}}$$

# 8.2 Linear and Polynomial Models

These models correspond to polynomials of some degree. Of course, lmfit is a very inefficient way to do linear regression (see polyfit or stats.linregress), but these models may be useful as one of many components of composite model.

# 8.2.1 ConstantModel

class ConstantModel (missing=None[, prefix='`[, name=None[, \*\*kws]]])

a class that consists of a single value, c. This is constant in the sense of having no dependence on the independent variable x, not in the sense of being non-varying. To be clear, c will be a variable Parameter.

## 8.2.2 LinearModel

class LinearModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])
 a class that gives a linear model:

$$f(x; m, b) = mx + b$$

with parameters slope for m and intercept for b.

# 8.2.3 QuadraticModel

class QuadraticModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])
 a class that gives a quadratic model:

$$f(x; a, b, c) = ax^2 + bx + c$$

with parameters a, b, and c.

## 8.2.4 ParabolicModel

class ParabolicModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])
 same as QuadraticModel.

# 8.2.5 PolynomialModel

class PolynomialModel (degree, missing=None[, prefix=''[, name=None[, \*\*kws]]]) a class that gives a polynomial model up to degree (with maximum value of 7).

$$f(x; c_0, c_1, \dots, c_7) = \sum_{i=0,7} c_i x^i$$

with parameters c0, c1, ..., c7. The supplied degree will specify how many of these are actual variable parameters. This uses polyval for its calculation of the polynomial.

# 8.3 Step-like models

Two models represent step-like functions, and share many characteristics.

# 8.3.1 StepModel

A model based on a Step function, with four choices for functional form. The step function starts with a value 0, and ends with a value of A (amplitude), rising to A/2 at  $\mu$  (center), with  $\sigma$  (sigma) setting the characteristic width. The supported functional forms are linear (the default), at an or arctan for an arctangent function, erf for an error function, or logistic for a logistic function. The forms are

$$\begin{split} f(x;A,\mu,\sigma, &\text{form} = '\text{linear'}) &= A \min\left[1, \max\left(0,\alpha\right)\right] \\ f(x;A,\mu,\sigma, &\text{form} = '\text{arctan'}) &= A[1/2 + \arctan\left(\alpha\right)/\pi] \\ f(x;A,\mu,\sigma, &\text{form} = '\text{erf'}) &= A[1 + \text{erf}(\alpha)]/2 \\ f(x;A,\mu,\sigma, &\text{form} = '\text{logistic'}) &= A[1 - \frac{1}{1 + e^{\alpha}}] \end{split}$$

where  $\alpha = (x - \mu)/\sigma$ .

# 8.3.2 RectangleModel

A model based on a Step-up and Step-down function of the same form. The same choices for functional form as for StepModel are supported, with linear as the default. The function starts with a value 0, and ends with a value of A (amplitude), rising to A/2 at  $\mu_1$  (center1), with  $\sigma_1$  (sigma1) setting the characteristic width. It drops to rising to A/2 at  $\mu_2$  (center2), with characteristic width  $\sigma_2$  (sigma2).

$$\begin{split} f(x;A,\mu,\sigma,\text{form} = '\text{linear'}) &= A\{\min\left[1,\max\left(0,\alpha_{1}\right)\right] + \min\left[-1,\max\left(0,\alpha_{2}\right)\right]\} \\ f(x;A,\mu,\sigma,\text{form} = '\text{arctan'}) &= A\left[\arctan\left(\alpha_{1}\right) + \arctan\left(\alpha_{2}\right)\right]/\pi \\ f(x;A,\mu,\sigma,\text{form} = '\text{erf'}) &= A\left[\operatorname{erf}(\alpha_{1}) + \operatorname{erf}(\alpha_{2})\right]/2 \\ f(x;A,\mu,\sigma,\text{form} = '\text{logistic'}) &= A\left[1 - \frac{1}{1 + e^{\alpha_{1}}} - \frac{1}{1 + e^{\alpha_{2}}}\right] \end{split}$$

where  $\alpha_1 = (x - \mu_1)/\sigma_1$  and  $\alpha_2 = -(x - \mu_2)/\sigma_2$ .

# 8.4 Exponential and Power law models

#### 8.4.1 Exponential Model

 $\textbf{class ExponentialModel} \ (\textit{missing} = None \big[, \textit{prefix} = \text{``} \big[, \textit{name} = None \big[, **kws \big] \big] \big] \big] )$ 

A model based on an exponential decay function. With parameters named amplitude (A), and decay  $(\tau)$ , this has the form:

$$f(x; A, \tau) = Ae^{-x/\tau}$$

# 8.4.2 PowerLawModel

class PowerLawModel (missing=None[, prefix=''[, name=None[, \*\*kws]]])

A model based on a Power Law. With parameters named amplitude (A), and exponent (k), this has the form:

$$f(x; A, k) = Ax^k$$

# 8.5 User-defined Models

As shown in the previous chapter (*Modeling Data and Curve Fitting*), it is fairly straightforward to build fitting models from parametrized python functions. The number of model classes listed so far in the present chapter should make it clear that this process is not too difficult. Still, it is sometimes desirable to build models from a user-supplied function. This may be especially true if model-building is built-in to some larger library or application for fitting in which the user may not be able to easily build and use a new model from python code.

The <code>ExpressionModel</code> allows a model to be built from a user-supplied expression. This uses the asteval module also used for mathematical constraints as discussed in <code>Using Mathematical Constraints</code>.

# 8.5.1 ExpressionModel

**class ExpressionMode1** (*expr*, *independent\_vars=None*, *init\_script=None*, \*\*kws)

A model using the user-supplied mathematical expression, which can be nearly any valid Python expression.

#### **Parameters**

- expr (string) expression use to build model
- **independent\_vars** (None (default) or list of strings for independent variables.) list of argument names in expression that are independent variables.
- init\_script (None (default) or string) python script to run before parsing and evaluating expression.

with other parameters passed to model. Model, with the notable exception that ExpressionModel does not support the prefix argument.

Since the point of this model is that an arbitrary expression will be supplied, the determination of what are the parameter names for the model happens when the model is created. To do this, the expression is parsed, and all symbol names are found. Names that are already known (there are over 500 function and value names in the asteval namespace, including most python builtins, more than 200 functions inherited from numpy, and more than 20 common lineshapes defined in the lineshapes module) are not converted to parameters. Unrecognized name are expected to be names either of parameters or independent variables. If *independent\_vars* is the default value of None, and if the expression contains a variable named x, that will be used as the independent variable. Otherwise, *independent\_vars* must be given.

For example, if one creates an ExpressionModel as:

```
>>> mod = ExpressionModel('off + amp * exp(-x/x0) * sin(x*phase)')
```

The name exp will be recognized as the exponent function, so the model will be interpreted to have parameters named off, amp, x0 and phase. In addition, x will be assumed to be the sole independent variable. In general, there is no obvious way to set default parameter values or parameter hints for bounds, so this will have to be handled explicitly.

To evaluate this model, you might do the following:

```
>>> x = numpy.linspace(0, 10, 501)
>>> params = mod.make_params(off=0.25, amp=1.0, x0=2.0, phase=0.04)
>>> y = mod.eval(params, x=x)
```

While many custom models can be built with a single line expression (especially since the names of the lineshapes like *gaussian*, *lorentzian* and so on, as well as many numpy functions, are available), more complex models will inevitably require multiple line functions. You can include such Python code with the *init\_script* argument. The text of this script is evaluated when the model is initialized (and before the actual expression is parsed), so that you can define functions to be used in your expression.

As a probably unphysical example, to make a model that is the derivative of a Gaussian function times the logarithm of a Lorentzian function you may could to define this in a script:

```
>>> script = """
def mycurve(x, amp, cen, sig):
    loren = lorentzian(x, amplitude=amp, center=cen, sigma=sig)
    gauss = gaussian(x, amplitude=amp, center=cen, sigma=sig)
    return log(loren)*gradient(gauss)/gradient(x)
```

and then use this with ExpressionModel as:

As above, this will interpret the parameter names to be *height*, *mid*, and *wid*, and build a model that can be used to fit data.

# 8.6 Example 1: Fit Peaked data to Gaussian, Lorentzian, and Voigt profiles

Here, we will fit data to three similar line shapes, in order to decide which might be the better model. We will start with a Gaussian profile, as in the previous chapter, but use the built-in <code>GaussianModel</code> instead of writing one ourselves. This is a slightly different version rom the one in previous example in that the parameter names are different, and have built-in default values. We'll simply use:

```
from numpy import loadtxt
from lmfit.models import GaussianModel

data = loadtxt('test_peak.dat')
x = data[:, 0]
y = data[:, 1]

mod = GaussianModel()

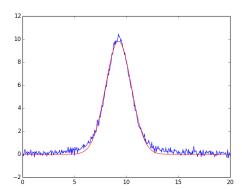
pars = mod.guess(y, x=x)
out = mod.fit(y, pars, x=x)
print(out.fit_report(min_correl=0.25))
```

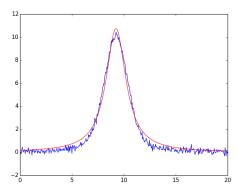
## which prints out the results:

```
[[Model]]
   gaussian
[[Fit Statistics]]
   # function evals = 23
   # data points
                   = 401
   # variables
                    = 3
                    = 29.994
   chi-square
   reduced chi-square = 0.075
                    = -1030.763
   Akaike info crit
   Bayesian info crit = -1018.781
[[Variables]]
   sigma:
               1.23218319 +/- 0.007374 (0.60%) (init= 1.35)
              2.90156963 +/- 0.017366 (0.60%) == '2.3548200*sigma'
   fwhm:
              9.81457973 +/- 0.050872 (0.52%) == '0.3989423*amplitude/sigma'
   height:
               9.24277049 +/- 0.007374 (0.08%) (init= 9.25)
   center:
   amplitude: 30.3135571 +/- 0.157126 (0.52%) (init= 29.08159)
```

```
[[Correlations]] (unreported correlations are < 0.250)
C(sigma, amplitude) = 0.577</pre>
```

We see a few interesting differences from the results of the previous chapter. First, the parameter names are longer. Second, there are fwhm and height parameters, to give the full width at half maximum and maximum peak height. And third, the automated initial guesses are pretty good. A plot of the fit:





Fit

to peak with Gaussian (left) and Lorentzian (right) models.

shows a decent match to the data — the fit worked with no explicit setting of initial parameter values. Looking more closing, the fit is not perfect, especially in the tails of the peak, suggesting that a different peak shape, with longer tails, should be used. Perhaps a Lorentzian would be better? To do this, we simply replace GaussianModel with LorentzianModel to get a LorentzianModel:

```
from lmfit.models import LorentzianModel
mod = LorentzianModel()
```

with the rest of the script as above. Perhaps predictably, the first thing we try gives results that are worse:

```
[[Model]]
   Model(lorentzian)
[[Fit Statistics]]
   # function evals
                    = 27
                      = 401
   # data points
   # variables
                      = 3
                      = 53.754
   chi-square
   reduced chi-square = 0.135
   Akaike info crit = -796.819
   Bayesian info crit = -784.837
[[Variables]]
   sigma:
                1.15484517 +/- 0.013156 (1.14%) (init= 1.35)
   fwhm:
                2.30969034 +/- 0.026312 (1.14%)
                                                  == '2.0000000*sigma'
                10.7420881 +/- 0.086336 (0.80%)
   height:
   '0.3183099*amplitude/sigm
                                a'
   center:
                9.24438944 +/- 0.009275 (0.10%) (init= 9.25)
                38.9728645 +/- 0.313857 (0.81%) (init= 36.35199)
[[Correlations]] (unreported correlations are < 0.250)
   C(sigma, amplitude)
```

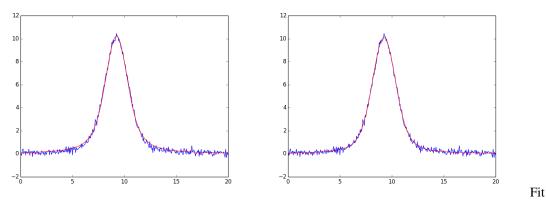
with the plot shown on the right in the figure above. The tails are now too big, and the value for  $\chi^2$  almost doubled. A Voigt model does a better job. Using VoigtModel, this is as simple as using:

```
from lmfit.models import VoigtModel
mod = VoigtModel()
```

with all the rest of the script as above. This gives:

```
[[Model]]
   Model (voigt)
[[Fit Statistics]]
   # function evals
                      = 19
   # data points
                      = 401
   # variables
   chi-square
                      = 14.545
   reduced chi-square = 0.037
   Akaike info crit = -1320.995
   Bayesian info crit = -1309.013
[[Variables]]
   sigma:
                0.73015574 +/- 0.003684 (0.50%) (init= 0.8775)
              0.73015574 + - 0.003684 (0.50\%) == 'sigma'
   gamma:
   fwhm:
               2.62951718 + - 0.013269 (0.50\%) == '3.6013100 \times sigma'
   height:
              19.5360268 + - 0.075691 (0.39\%) = 0.3989423 \times amplitude/sigm
   center: 9.24411142 +/- 0.005054 (0.05%) (init= 9.25)
   amplitude: 35.7554017 +/- 0.138614 (0.39%) (init= 43.62238)
[[Correlations]] (unreported correlations are < 0.250)
   C(sigma, amplitude)
```

which has a much better value for  $\chi^2$  and an obviously better match to the data as seen in the figure below (left).



to peak with Voigt model (left) and Voigt model with gamma varying independently of sigma (right).

Can we do better? The Voigt function has a  $\gamma$  parameter (gamma) that can be distinct from sigma. The default behavior used above constrains gamma to have exactly the same value as sigma. If we allow these to vary separately, does the fit improve? To do this, we have to change the gamma parameter from a constrained expression and give it a starting value using something like:

```
mod = VoigtModel()
pars = mod.guess(y, x=x)
pars['gamma'].set(value=0.7, vary=True, expr='')
```

## which gives:

```
[[Model]]
  Model(voigt)
[[Fit Statistics]]
  # function evals = 23
  # data points = 401
  # variables = 4
  chi-square = 10.930
  reduced chi-square = 0.028
  Akaike info crit = -1432.556
  Bayesian info crit = -1416.580
```

```
[[Variables]]
                0.89518950 +/- 0.014154 (1.58%) (init= 0.8775)
   sigma:
                0.52540156 +/- 0.018579 (3.54\%) (init= 0.7)
   gamma:
                3.22385492 +/- 0.050974 (1.58%)
   fwhm:
                                                 == '3.6013100*sigma'
                15.2374711 +/- 0.299235 (1.96%)
   height:
'0.3989423*amplitude/sigm
                            a'
                9.24374845 +/- 0.004419 (0.05%) (init= 9.25)
   center:
                34.1914716 +/- 0.179468 (0.52%) (init= 43.62238)
   amplitude:
[[Correlations]] (unreported correlations are < 0.250)
                                = -0.928
   C(sigma, gamma)
                                = 0.821
   C(gamma, amplitude)
   C(sigma, amplitude)
                                = -0.651
```

and the fit shown on the right above.

Comparing the two fits with the Voigt function, we see that  $\chi^2$  is definitely improved with a separately varying gamma parameter. In addition, the two values for gamma and sigma differ significantly – well outside the estimated uncertainties. More compelling, reduced  $\chi^2$  is improved even though a fourth variable has been added to the fit. In the simplest statistical sense, this suggests that gamma is a significant variable in the model. In addition, we can use both the Akaike or Bayesian Information Criteria (see *Akaike and Bayesian Information Criteria*) to assess how likely the model with variable gamma is to explain the data than the model with gamma fixed to the value of sigma. According to theory,  $\exp(-(\text{AIC1} - \text{AIC0})/2)$  gives the probably that a model with AIC' is more likely than a model with AIC0. For the two models here, with AIC values of -1432 and -1321 (Note: if we had more carefully set the value for weights based on the noise in the data, these values might be positive, but there difference would be roughly the same), this says that the model with gamma fixed to sigma has a probably less than 1.e-25 of being the better model.

# 8.7 Example 2: Fit data to a Composite Model with pre-defined models

Here, we repeat the point made at the end of the last chapter that instances of <code>model.Model</code> class can be added together to make a *composite model*. By using the large number of built-in models available, it is therefore very simple to build models that contain multiple peaks and various backgrounds. An example of a simple fit to a noisy step function plus a constant:

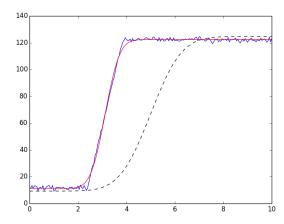
```
#!/usr/bin/env python
#<examples/doc_stepmodel.py>
import numpy as np
from lmfit.models import StepModel, LinearModel
import matplotlib.pyplot as plt
x = np.linspace(0, 10, 201)
y = np.ones_like(x)
y[:48] = 0.0
y[48:77] = np.arange(77-48)/(77.0-48)
y = 110.2 * (y + 9e-3*np.random.randn(len(x))) + 12.0 + 2.22*x
step_mod = StepModel(form='erf', prefix='step_')
line_mod = LinearModel(prefix='line_')
pars = line_mod.make_params(intercept=y.min(), slope=0)
pars += step_mod.guess(y, x=x, center=2.5)
mod = step_mod + line_mod
out = mod.fit(y, pars, x=x)
```

```
print(out.fit_report())

plt.plot(x, y)
plt.plot(x, out.init_fit, 'k--')
plt.plot(x, out.best_fit, 'r-')
plt.show()
#<end examples/doc_stepmodel.py>
```

After constructing step-like data, we first create a <code>StepModel</code> telling it to use the <code>erf</code> form (see details above), and a <code>ConstantModel</code>. We set initial values, in one case using the data and <code>guess()</code> method for the initial step function paramaters, and <code>make\_params()</code> arguments for the linear component. After making a composite model, we run <code>fit()</code> and report the results, which gives:

```
[[Model]]
[[Model]]
    (Model(step, prefix='step_', form='erf') + Model(linear, prefix='line_'))
[[Fit Statistics]]
    # function evals = 51
    # data points
                       = 201
    # variables
   chi-square
                       = 648.584
   reduced chi-square = 3.309
   Akaike info crit = 250.532
   Bayesian info crit = 267.048
[[Variables]]
   line_slope:
                    2.06986083 +/- 0.097005 (4.69%) (init= 0)
   line_intercept: 11.7526825 +/- 0.288725 (2.46%) (init= 10.7017)
   step_center: 3.12329688 + /- 0.005441 (0.17\%) (init= 2.5) step_sigma: 0.67050317 + /- 0.011480 (1.71\%) (init= 1.428571)
    step_amplitude: 111.673928 +/- 0.681024 (0.61%) (init= 134.6809)
[[Correlations]] (unreported correlations are < 0.100)
   C(line\_slope, step\_amplitude) = -0.878
   C(step\_sigma, step\_amplitude) = 0.563
   C(line_slope, step_sigma)
                                = -0.455
   C(line\_intercept, step\_center) = 0.426
   C(line\_slope, line\_intercept) = -0.307
   C(line_slope, step_center)
                                 = -0.234
   C(line\_intercept, step\_sigma) = -0.139
   C(line\_intercept, step\_amplitude) = -0.122
    C(\text{step\_center, step\_amplitude}) = 0.108
```



with a plot of

# 8.8 Example 3: Fitting Multiple Peaks – and using Prefixes

As shown above, many of the models have similar parameter names. For composite models, this could lead to a problem of having parameters for different parts of the model having the same name. To overcome this, each <code>model.Model</code> can have a <code>prefix</code> attribute (normally set to a blank string) that will be put at the beginning of each parameter name. To illustrate, we fit one of the classic datasets from the NIST StRD suite involving a decaying exponential and two gaussians.

```
#!/usr/bin/env python
#<examples/doc_nistgauss.py>
import numpy as np
from lmfit.models import GaussianModel, ExponentialModel
import sys
import matplotlib.pyplot as plt
dat = np.loadtxt('NIST_Gauss2.dat')
x = dat[:, 1]
y = dat[:, 0]
exp_mod = ExponentialModel(prefix='exp_')
pars = exp_mod.guess(y, x=x)
gauss1 = GaussianModel(prefix='g1_')
pars.update( gauss1.make_params())
pars['g1_center'].set(105, min=75, max=125)
pars['g1_sigma'].set(15, min=3)
pars['g1_amplitude'].set(2000, min=10)
gauss2 = GaussianModel(prefix='g2_')
pars.update(gauss2.make_params())
pars['g2_center'].set(155, min=125, max=175)
pars['g2_sigma'].set(15, min=3)
pars['g2_amplitude'].set(2000, min=10)
mod = gauss1 + gauss2 + exp_mod
init = mod.eval(pars, x=x)
plt.plot(x, y)
plt.plot(x, init, 'k--')
out = mod.fit(y, pars, x=x)
print (out.fit_report (min_correl=0.5))
plt.plot(x, out.best_fit, 'r-')
plt.show()
#<end examples/doc_nistgauss.py>
```

where we give a separate prefix to each model (they all have an amplitude parameter). The prefix values are attached transparently to the models.

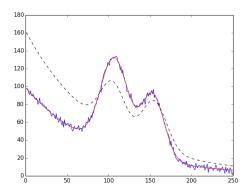
Note that the calls to make\_param() used the bare name, without the prefix. We could have used the prefixes, but because we used the individual model gauss1 and gauss2, there was no need.

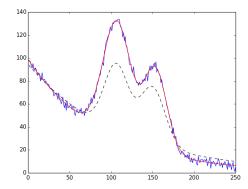
Note also in the example here that we explicitly set bounds on many of the parameter values.

The fit results printed out are:

```
[[Model]]
        ((Model(gaussian, prefix='g1_') + Model(gaussian, prefix='g2_')) + Model(exponential, prefix='exponential, prefix=
[[Fit Statistics]]
        # function evals
                                                    = 250
        # data points
        # variables
                                                    = 8
        chi-square
                                                    = 1247.528
        reduced chi-square = 5.155
        Akaike info crit = 425.995
       Bayesian info crit = 454.167
[[Variables]]
        exp_amplitude: 99.0183282 +/- 0.537487 (0.54%) (init= 162.2102)
                                              90.9508861 +/- 1.103105 (1.21%) (init= 93.24905)
        exp_decay:
        g1_amplitude:
                                              4257.77318 +/- 42.38336 (1.00%) (init= 2000)
        g1_sigma:
                                               16.6725753 +/- 0.160481 (0.96%) (init= 15)
                                               107.030954 +/- 0.150067 (0.14%) (init= 105)
        g1_center:
                                               39.2609137 +/- 0.377905 (0.96%)
                                                                                                                            == '2.3548200*g1_sigma'
        g1_fwhm:
        g1_height:
                                               101.880231 +/- 0.592170 (0.58%)
        '0.3989423*g1_amplitude/g1_
                                                                                sigma'
        g2_amplitude: 2493.41770 +/- 36.16947 (1.45%) (init= 2000)
                                             13.8069484 +/- 0.186794 (1.35%) (init= 15)
        g2_sigma:
       g2_center:
                                            153.270100 +/- 0.194667 (0.13%) (init= 155)
                                               32.5128783 +/- 0.439866 (1.35%)
        q2_fwhm:
                                                                                                                           == '2.3548200*g2_sigma'
        g2_height:
                                               72.0455934 +/- 0.617220 (0.86%)
        '0.3989423*g2_amplitude/g2_
                                                                                sigma'
[[Correlations]] (unreported correlations are < 0.500)
        C(g1_amplitude, g1_sigma)
                                                                      = 0.824
        C(g2_amplitude, g2_sigma)
                                                                           = 0.815
        C(exp\_amplitude, exp\_decay) = -0.695
        C(g1_sigma, g2_center)
                                                                           = 0.684
        C(g1_center, g2_amplitude)
                                                                         = -0.669
        C(g1_center, g2_sigma)
                                                                           = -0.652
        C(g1\_amplitude, g2\_center) = 0.648
        C(g1_center, g2_center)
                                                                           = 0.621
        C(g1_sigma, g1_center)
                                                                           = 0.507
        C(exp_decay, g1_amplitude)
                                                                           = -0.507
```

We get a very good fit to this problem (described at the NIST site as of average difficulty, but the tests there are generally deliberately challenging) by applying reasonable initial guesses and putting modest but explicit bounds on the parameter values. This fit is shown on the left:





One final point on setting initial values. From looking at the data itself, we can see the two Gaussian peaks are reasonably well separated but do overlap. Furthermore, we can tell that the initial guess for the decaying exponential component was poorly estimated because we used the full data range. We can simplify the initial parameter values by using this, and by defining an index\_of() function to limit the data range. That is, with:

```
def index_of(arrval, value):
    "return index of array *at or below* value "
    if value < min(arrval): return 0
    return max(np.where(arrval<=value)[0])

ix1 = index_of(x, 75)
ix2 = index_of(x, 135)
ix3 = index_of(x, 175)

exp_mod.guess(y[:ix1], x=x[:ix1])
gauss1.guess(y[ix1:ix2], x=x[ix1:ix2])
gauss2.guess(y[ix2:ix3], x=x[ix2:ix3])</pre>
```

we can get a better initial estimate. The fit converges to the same answer, giving to identical values (to the precision printed out in the report), but in few steps, and without any bounds on parameters at all:

```
[[Model]]
   ((Model(gaussian, prefix='g1_') + Model(gaussian, prefix='g2_')) + Model(exponential, prefix='e
[[Fit Statistics]]
   # function evals = 48
   # data points = 250
   # variables
                     = 8
   chi-square
                    = 1247.528
   reduced chi-square = 5.155
   Akaike info crit = 425.995
   Bayesian info crit = 454.167
[[Variables]]
   exp_amplitude: 99.0183281 +/- 0.537487 (0.54%) (init= 94.53724)
   exp_decay:

and amplitude:
                   90.9508862 +/- 1.103105 (1.21%) (init= 111.1985)
                   4257.77322 +/- 42.38338 (1.00%) (init= 2126.432)
   g1_sigma: 16.6725754 +/- 0.160481 (0.96\%) (init= 14.5)
                  107.030954 +/- 0.150067 (0.14%) (init= 106.5)
   g1_center:
                  39.2609141 +/- 0.377905 (0.96%)
                                                   == '2.3548200*q1_sigma'
   g1_fwhm:
   g1_height:
                 101.880231 +/- 0.592171 (0.58%)
                                                   ==
   '0.3989423*g1_amplitude/g1_
                                 sigma'
   g2_amplitude: 2493.41766 +/- 36.16947 (1.45%) (init= 1878.892)
   g2_sigma:
                  13.8069481 +/- 0.186794 (1.35%) (init= 15)
                  153.270100 +/- 0.194667 (0.13%) (init= 150)
   g2_center:
   g2_fwhm:
                  32.5128777 +/- 0.439866 (1.35%) == '2.3548200*g2_sigma'
   g2_height:
                 72.0455935 +/- 0.617221 (0.86%) ==
   '0.3989423*g2_amplitude/g2_
                               sigma'
[[Correlations]] (unreported correlations are < 0.500)
   C(g1\_amplitude, g1\_sigma) = 0.824
   C(g2_amplitude, g2_sigma)
                              = 0.815
   C(exp\_amplitude, exp\_decay) = -0.695
   C(g1_sigma, g2_center)
                              = 0.684
   C(g1\_center, g2\_amplitude) = -0.669
   C(g1\_center, g2\_sigma) = -0.652
   C(g1\_amplitude, g2\_center) = 0.648
   C(g1_center, g2_center)
                             = 0.621
   C(g1_sigma, g1_center)
                               = 0.507
   C(exp_decay, g1_amplitude)
                             = -0.507
```

This script is in the file doc nistgauss2.py in the examples folder, and the fit result shown on the right above

shows an improved initial estimate of the data.					

Non-Linear Least-Squares Minimization and Curve-Fitting for Python, Release 0.9.3

**CHAPTER** 

NINE

### CALCULATION OF CONFIDENCE INTERVALS

The lmfit *confidence* module allows you to explicitly calculate confidence intervals for variable parameters. For most models, it is not necessary: the estimation of the standard error from the estimated covariance matrix is normally quite good.

But for some models, e.g. a sum of two exponentials, the approximation begins to fail. For this case, lmfit has the function conf\_interval() to calculate confidence intervals directly. This is substantially slower than using the errors estimated from the covariance matrix, but the results are more robust.

# 9.1 Method used for calculating confidence intervals

The F-test is used to compare our null model, which is the best fit we have found, with an alternate model, where one of the parameters is fixed to a specific value. The value is changed until the difference between  $\chi_0^2$  and  $\chi_f^2$  can't be explained by the loss of a degree of freedom within a certain confidence.

$$F(P_{fix}, N - P) = \left(\frac{\chi_f^2}{\chi_0^2} - 1\right) \frac{N - P}{P_{fix}}$$

N is the number of data-points, P the number of parameter of the null model.  $P_{fix}$  is the number of fixed parameters (or to be more clear, the difference of number of parameters between our null model and the alternate model).

Adding a log-likelihood method is under consideration.

## 9.2 A basic example

First we create an example problem:

before we can generate the confidence intervals, we have to run a fit, so that the automated estimate of the standard errors can be used as a starting point:

Now it is just a simple function call to calculate the confidence intervals:

```
>>> ci = lmfit.conf_interval(mini, result)
>>> lmfit.printfuncs.report_ci(ci)
    99.70%
            95.00%
                      67.40%
                                  0.00%
                                          67.40%
                                                    95.00%
                                                             99.70%
            0.09905
   0.09886
                      0.09925
                              0.09944
                                          0.09963
                                                   0.09982
                                                             0.10003
   1.94751
           1.96049 1.97274 1.97741
                                         1.99680
                                                   2.00905
                                                             2.02203
```

This shows the best-fit values for the parameters in the 0.00% column, and parameter values that are at the varying confidence levels given by steps in  $\sigma$ . As we can see, the estimated error is almost the same, and the uncertainties are well behaved: Going from 1  $\sigma$  (68% confidence) to 3  $\sigma$  (99.7% confidence) uncertainties is fairly linear. It can also be seen that the errors are fairy symmetric around the best fit value. For this problem, it is not necessary to calculate confidence intervals, and the estimates of the uncertainties from the covariance matrix are sufficient.

## 9.3 An advanced example

Now we look at a problem where calculating the error from approximated covariance can lead to misleading result – two decaying exponentials. In fact such a problem is particularly hard for the Levenberg-Marquardt method, so we first estimate the results using the slower but robust Nelder-Mead method, and *then* use Levenberg-Marquardt to estimate the uncertainties and correlations

```
import lmfit
import numpy as np
import matplotlib
# matplotlib.use('WXAgg')
import matplotlib.pyplot as plt
x = np.linspace(1, 10, 250)
np.random.seed(0)
y = 3.0*np.exp(-x/2) -5.0*np.exp(-(x-0.1)/10.) + 0.1*np.random.randn(len(x))
p = lmfit.Parameters()
p.add_many(('a1', 4.), ('a2', 4.), ('t1', 3.), ('t2', 3.))
def residual(p):
  v = p.valuesdict()
  return v['a1']*np.exp(-x/v['t1']) + v['a2']*np.exp(-(x-0.1)/v['t2'])-y
# create Minimizer
mini = lmfit.Minimizer(residual, p)
# first solve with Nelder-Mead
out1 = mini.minimize(method='Nelder')
# then solve with Levenberg-Marquardt using the
# Nelder-Mead solution as a starting point
```

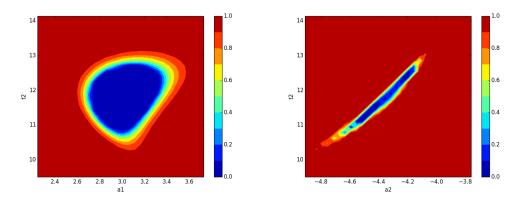
```
out2 = mini.minimize(method='leastsq', params=out1.params)
lmfit.report_fit(out2.params, min_correl=0.5)
ci, trace = lmfit.conf_interval(mini, out2, sigmas=[0.68,0.95],
                                trace=True, verbose=False)
lmfit.printfuncs.report_ci(ci)
plot_type = 2
if plot_type == 0:
   plt.plot(x, y)
   plt.plot(x, residual(out2.params)+y )
elif plot_type == 1:
   cx, cy, grid = lmfit.conf_interval2d(mini, out2, 'a2','t2',30,30)
   plt.contourf(cx, cy, grid, np.linspace(0,1,11))
   plt.xlabel('a2')
   plt.colorbar()
   plt.ylabel('t2')
elif plot_type == 2:
   cx, cy, grid = lmfit.conf_interval2d(mini, out2, 'a1','t2',30,30)
   plt.contourf(cx, cy, grid, np.linspace(0,1,11))
   plt.xlabel('a1')
   plt.colorbar()
   plt.ylabel('t2')
elif plot_type == 3:
   cx1, cy1, prob = trace['a1']['a1'], trace['a1']['t2'],trace['a1']['prob']
   cx2, cy2, prob2 = trace['t2']['t2'], trace['t2']['a1'],trace['t2']['prob']
   plt.scatter(cx1, cy1, c=prob, s=30)
   plt.scatter(cx2, cy2, c=prob2, s=30)
   plt.gca().set_xlim((2.5, 3.5))
   plt.gca().set_ylim((11, 13))
   plt.xlabel('a1')
   plt.ylabel('t2')
if plot_type > 0:
   plt.show()
```

#### which will report:

```
[[Variables]]
   al: 2.98622120 +/- 0.148671 (4.98%) (init= 2.986237)
   a2: -4.33526327 +/- 0.115275 (2.66%) (init=-4.335256)
   t1: 1.30994233 +/- 0.131211 (10.02%) (init= 1.309932)
        11.8240350 +/- 0.463164 (3.92%) (init= 11.82408)
[[Correlations]] (unreported correlations are < 0.500)
   C(a2, t2)
                              = 0.987
   C(a2, t1)
                               = -0.925
   C(t1, t2)
                               = -0.881
   C(a1, t1)
                               = -0.599
             68.00%
                       0.00%
     95.00%
                                68.00%
                                          95.00%
                                         3.34076
   2.71850 2.84525 2.98622 3.14874
a1
a2 -4.63180 -4.46663 -4.33526 -4.22883 -4.14178
t2 10.82699 11.33865 11.82404 12.28195 12.71094
t1 1.08014 1.18566 1.30994 1.45566 1.62579
```

Again we called conf\_interval(), this time with tracing and only for 1- and  $2\sigma$ . Comparing these two different estimates, we see that the estimate for al is reasonably well approximated from the covariance matrix, but the estimates for al and especially for tl, and tl are very asymmetric and that going from  $1\sigma$  (68% confidence) to  $2\sigma$  (95% confidence) is not very predictable.

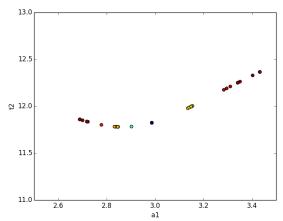
Let plots mad of the confidence region are shown the figure on the left below for a1 and  $\pm 2$ , and for a2 and  $\pm 2$  on the right:



Neither of these plots is very much like an ellipse, which is implicitly assumed by the approach using the covariance matrix.

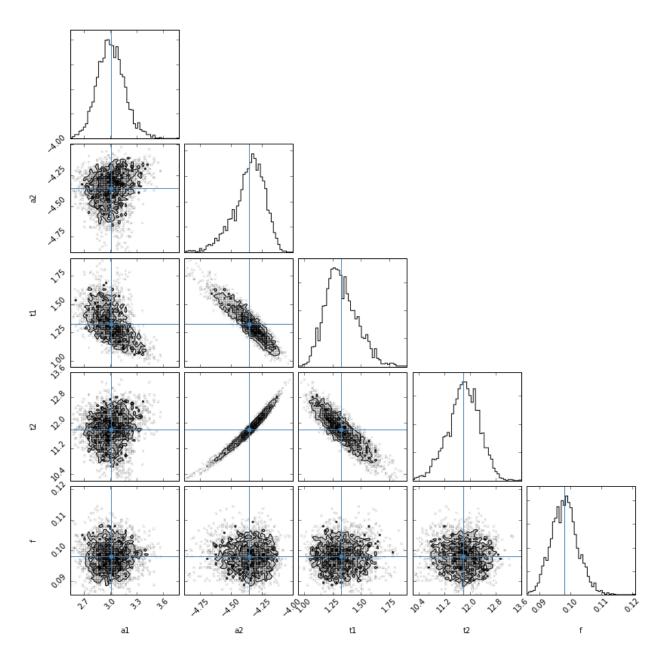
The trace returned as the optional second argument from <code>conf\_interval()</code> contains a dictionary for each variable parameter. The values are dictionaries with arrays of values for each variable, and an array of corresponding probabilities for the corresponding cumulative variables. This can be used to show the dependence between two parameters:

```
>>> x, y, prob = trace['al']['al'], trace['al']['t2'], trace['al']['prob']
>>> x2, y2, prob2 = trace['t2']['t2'], trace['t2']['al'], trace['t2']['prob']
>>> plt.scatter(x, y, c=prob, s=30)
>>> plt.scatter(x2, y2, c=prob2, s=30)
>>> plt.gca().set_xlim((1, 5))
>>> plt.gca().set_ylim((5, 15))
>>> plt.xlabel('al')
>>> plt.ylabel('t2')
>>> plt.show()
```



which shows the trace of values:

Minimizer.emcee() method uses Markov Chain Monte Carlo to sample the posterior probability distribution. These distributions demonstrate the range of solutions that the data supports. The following image was obtained by using Minimizer.emcee() on the same problem.



Credible intervals (the Bayesian equivalent of the frequentist confidence interval) can be obtained with this method. MCMC can be used for model selection, to determine outliers, to marginalise over nuisance parameters, etc. For example, you may have fractionally underestimated the uncertainties on a dataset. MCMC can be used to estimate the true level of uncertainty on each datapoint. A tutorial on the possibilities offered by MCMC can be found at <sup>1</sup>.

## 9.4 Confidence Interval Functions

conf\_interval (minimizer, result, p\_names=None, sigmas=(0.674, 0.95, 0.997), trace=False, maxiter=200, verbose=False, prob\_func=None)

Calculates the confidence interval for parameters from the given a MinimizerResult, output from minimize.

The parameter for which the ci is calculated will be varied, while the remaining parameters are re-optimized for

<sup>&</sup>lt;sup>1</sup> http://jakevdp.github.io/blog/2014/03/11/frequentism-and-bayesianism-a-practical-intro/

minimizing chi-square. The resulting chi-square is used to calculate the probability with a given statistic e.g. F-statistic. This function uses a 1d-rootfinder from scipy to find the values resulting in the searched confidence region.

#### **Parameters**

- minimizer (Minimizer) The minimizer to use, holding objective function.
- result (MinimizerResult) The result of running minimize().
- **p\_names** (list, optional) Names of the parameters for which the ci is calculated. If None, the ci is calculated for every parameter.
- **sigmas** (*list*, *optional*) The probabilities (1-alpha) to find. Default is 1,2 and 3-sigma.
- **trace** (bool, optional) Defaults to False, if true, each result of a probability calculation is saved along with the parameter. This can be used to plot so called "profile traces".
- maxiter (int) Maximum of iteration to find an upper limit. Default is 200.
- **prob\_func** (None or callable) Function to calculate the probability from the optimized chi-square. Default (None) uses built-in f\_compare (F test).
- **verbose** (bool) print extra debuging information. Default is False.

#### Returns

- **output** (dict) A dict, which contains a list of (sigma, vals)-tuples for each name.
- **trace\_dict** (*dict*) Only if trace is set true. Is a dict, the key is the parameter which was fixed. The values are again a dict with the names as keys, but with an additional key 'prob'. Each contains an array of the corresponding values.

#### See also:

```
conf_interval2d()
```

### **Examples**

```
>>> from lmfit.printfuncs import *
>>> mini = minimize(some_func, params)
>>> mini.leastsq()
True
>>> report_errors(params)
... #report
>>> ci = conf_interval(mini)
>>> report_ci(ci)
... #report
```

Now with quantiles for the sigmas and using the trace.

```
>>> ci, trace = conf_interval(mini, sigmas=(0.25, 0.5, 0.75, 0.999), trace=True)
>>> fixed = trace['para1']['para1']
>>> free = trace['para1']['not_para1']
>>> prob = trace['para1']['prob']
```

This makes it possible to plot the dependence between free and fixed.

**conf\_interval2d** (*minimizer*, *result*, *x\_name*, *y\_name*, *nx*=10, *ny*=10, *limits*=None, *prob\_func*=None) Calculates confidence regions for two fixed parameters.

The method is explained in *conf\_interval*: here we are fixing two parameters.

#### **Parameters**

- minimizer (Minimizer) The minimizer to use, holding objective function.
- result (MinimizerResult) The result of running minimize().
- **x\_name** (string) The name of the parameter which will be the x direction.
- **y\_name** (string) The name of the parameter which will be the y direction.
- ny  $(nx_i)$  Number of points.
- limits (tuple: optional) Should have the form ((x\_upper, x\_lower),(y\_upper, y\_lower)). If not given, the default is 5 std-errs in each direction.

#### Returns

- $\mathbf{x} ((nx)-array) \mathbf{x}$ -coordinates
- y ((ny)-array) y-coordinates
- grid ((nx,ny)-array) grid contains the calculated probabilities.

#### **Examples**

```
>>> mini = Minimizer(some_func, params)
>>> result = mini.leastsq()
>>> x, y, gr = conf_interval2d(mini, result, 'para1', 'para2')
>>> plt.contour(x,y,gr)
```

**Other Parameters prob\_func** (None or callable) – Function to calculate the probability from the optimized chi-square. Default (None) uses built-in f compare (F test).

```
ci_report (ci, with_offset=True, ndigits=5)
    return text of a report for confidence intervals
```

#### **Parameters**

- with\_offset (bool (default *True*)) whether to subtract best value from all other values.
- ndigits (int (default 5)) number of significant digits to show

### Returns

**Return type** text of formatted report on confidence intervals.

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## **BOUNDS IMPLEMENTATION**

This section describes the implementation of <code>Parameter</code> bounds. The MINPACK-1 implementation used in optimize.leastsq for the Levenberg-Marquardt algorithm does not explicitly support bounds on parameters, and expects to be able to fully explore the available range of values for any Parameter. Simply placing hard constraints (that is, resetting the value when it exceeds the desired bounds) prevents the algorithm from determining the partial derivatives, and leads to unstable results.

Instead of placing such hard constraints, bounded parameters are mathematically transformed using the formulation devised (and documented) for MINUIT. This is implemented following (and borrowing heavily from) the leastsqbound from J. J. Helmus. Parameter values are mapped from internally used, freely variable values  $P_{\rm internal}$  to bounded parameters  $P_{\rm bounded}$ . When both min and max bounds are specified, the mapping is

$$P_{\text{internal}} = \arcsin\left(\frac{2(P_{\text{bounded}} - \min)}{(\max - \min)} - 1\right)$$
  
 $P_{\text{bounded}} = \min + \left(\sin(P_{\text{internal}}) + 1\right)\frac{(\max - \min)}{2}$ 

With only an upper limit max supplied, but min left unbounded, the mapping is:

$$P_{\text{internal}} = \sqrt{(\max - P_{\text{bounded}} + 1)^2 - 1}$$
  
 $P_{\text{bounded}} = \max + 1 - \sqrt{P_{\text{internal}}^2 + 1}$ 

With only a lower limit min supplied, but max left unbounded, the mapping is:

$$P_{\text{internal}} = \sqrt{(P_{\text{bounded}} - \min + 1)^2 - 1}$$
  
 $P_{\text{bounded}} = \min - 1 + \sqrt{P_{\text{internal}}^2 + 1}$ 

With these mappings, the value for the bounded Parameter cannot exceed the specified bounds, though the internally varied value can be freely varied.

It bears repeating that code from leastsqbound was adopted to implement the transformation described above. The challenging part (Thanks again to Jonathan J. Helmus!) here is to re-transform the covariance matrix so that the uncertainties can be estimated for bounded Parameters. This is included by using the derivate  $dP_{\rm internal}/dP_{\rm bounded}$  from the equations above to re-scale the Jacobin matrix before constructing the covariance matrix from it. Tests show that this re-scaling of the covariance matrix works quite well, and that uncertainties estimated for bounded are quite reasonable. Of course, if the best fit value is very close to a boundary, the derivative estimated uncertainty and correlations for that parameter may not be reliable.

The MINUIT documentation recommends caution in using bounds. Setting bounds can certainly increase the number of function evaluations (and so computation time), and in some cases may cause some instabilities, as the range of acceptable parameter values is not fully explored. On the other hand, preliminary tests suggest that using max and min to set clearly outlandish bounds does not greatly affect performance or results.

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**CHAPTER** 

**ELEVEN** 

### **USING MATHEMATICAL CONSTRAINTS**

Being able to fix variables to a constant value or place upper and lower bounds on their values can greatly simplify modeling real data. These capabilities are key to lmfit's Parameters. In addition, it is sometimes highly desirable to place mathematical constraints on parameter values. For example, one might want to require that two Gaussian peaks have the same width, or have amplitudes that are constrained to add to some value. Of course, one could rewrite the objective or model function to place such requirements, but this is somewhat error prone, and limits the flexibility so that exploring constraints becomes laborious.

To simplify the setting of constraints, Parameters can be assigned a mathematical expression of other Parameters, builtin constants, and builtin mathematical functions that will be used to determine its value. The expressions used for constraints are evaluated using the asteval module, which uses Python syntax, and evaluates the constraint expressions in a safe and isolated namespace.

This approach to mathematical constraints allows one to not have to write a separate model function for two Gaussians where the two sigma values are forced to be equal, or where amplitudes are related. Instead, one can write a more general two Gaussian model (perhaps using GaussianModel) and impose such constraints on the Parameters for a particular fit.

### 11.1 Overview

Just as one can place bounds on a Parameter, or keep it fixed during the fit, so too can one place mathematical constraints on parameters. The way this is done with lmfit is to write a Parameter as a mathematical expression of the other parameters and a set of pre-defined operators and functions. The constraint expressions are simple Python statements, allowing one to place constraints like:

```
pars = Parameters()
pars.add('frac_curve1', value=0.5, min=0, max=1)
pars.add('frac_curve2', expr='1-frac_curve1')
```

as the value of the *frac\_curve1* parameter is updated at each step in the fit, the value of *frac\_curve2* will be updated so that the two values are constrained to add to 1.0. Of course, such a constraint could be placed in the fitting function, but the use of such constraints allows the end-user to modify the model of a more general-purpose fitting function.

Nearly any valid mathematical expression can be used, and a variety of built-in functions are available for flexible modeling.

# 11.2 Supported Operators, Functions, and Constants

The mathematical expressions used to define constrained Parameters need to be valid python expressions. As you'd expect, the operators '+', '-', '\*', '/', '\*\*', are supported. In fact, a much more complete set can be used, including Python's bit- and logical operators:

```
+, -, *, /, **, &, |, ^, <<, >>, %, and, or,
==, >, >=, <, <=, !=, ~, not, is, is not, in, not in
```

The values for e (2.7182818...) and pi (3.1415926...) are available, as are several supported mathematical and trigonometric function:

```
abs, acos, acosh, asin, asinh, atan, atan2, atanh, ceil, copysign, cos, cosh, degrees, exp, fabs, factorial, floor, fmod, frexp, fsum, hypot, isinf, isnan, ldexp, log, log10, log1p, max, min, modf, pow, radians, sin, sinh, sqrt, tan, tanh, trunc
```

In addition, all Parameter names will be available in the mathematical expressions. Thus, with parameters for a few peak-like functions:

```
pars = Parameters()
pars.add('amp_1', value=0.5, min=0, max=1)
pars.add('cen_1', value=2.2)
pars.add('wid_1', value=0.2)
```

The following expression are all valid:

```
pars.add('amp_2', expr='(2.0 - amp_1**2)')
pars.add('cen_2', expr='cen_1 * wid_2 / max(wid_1, 0.001)')
pars.add('wid_2', expr='sqrt(pi)*wid_1')
```

In fact, almost any valid Python expression is allowed. A notable example is that Python's 1-line *if expression* is supported:

```
pars.add('bounded', expr='param_a if test_val/2. > 100 else param_b')
```

which is equivalent to the more familiar:

```
if test_val/2. > 100:
    bounded = param_a
else:
    bounded = param_b
```

# 11.3 Using Inequality Constraints

A rather common question about how to set up constraints that use an inequality, say,  $x+y \le 10$ . This can be done with algebraic constraints by recasting the problem, as  $x+y=\delta$  and  $\delta \le 10$ . That is, first, allow x to be held by the freely varying parameter x. Next, define a parameter delta to be variable with a maximum value of 10, and define parameter y as delta - x:

```
pars = Parameters()
pars.add('x', value = 5, vary=True)
pars.add('delta', value = 5, max=10, vary=True)
pars.add('y', expr='delta-x')
```

The essential point is that an inequality still implies that a variable (here, *delta*) is needed to describe the constraint. The secondary point is that upper and lower bounds can be used as part of the inequality to make the definitions more convenient.

## 11.4 Advanced usage of Expressions in Imfit

The expression used in a constraint is converted to a Python Abstract Syntax Tree, which is an intermediate version of the expression – a syntax-checked, partially compiled expression. Among other things, this means that Python's own parser is used to parse and convert the expression into something that can easily be evaluated within Python. It also means that the symbols in the expressions can point to any Python object.

In fact, the use of Python's AST allows a nearly full version of Python to be supported, without using Python's built-in eval() function. The asteval module actually supports most Python syntax, including for- and while-loops, conditional expressions, and user-defined functions. There are several unsupported Python constructs, most notably the class statement, so that new classes cannot be created, and the import statement, which helps make the asteval module safe from malicious use.

One important feature of the asteval module is that you can add domain-specific functions into the it, for later use in constraint expressions. To do this, you would use the asteval attribute of the *Minimizer* class, which contains a complete AST interpreter. The asteval interpreter uses a flat namespace, implemented as a single dictionary. That means you can preload any Python symbol into the namespace for the constraints:

```
def mylorentzian(x, amp, cen, wid):
    "lorentzian function: wid = half-width at half-max"
    return (amp / (1 + ((x-cen)/wid)**2))

fitter = Minimizer()
fitter.asteval.symtable['lorentzian'] = mylorentzian
```

and this lorentzian() function can now be used in constraint expressions.

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