

Image Processing and Visual Communications

Statistical Image Modeling


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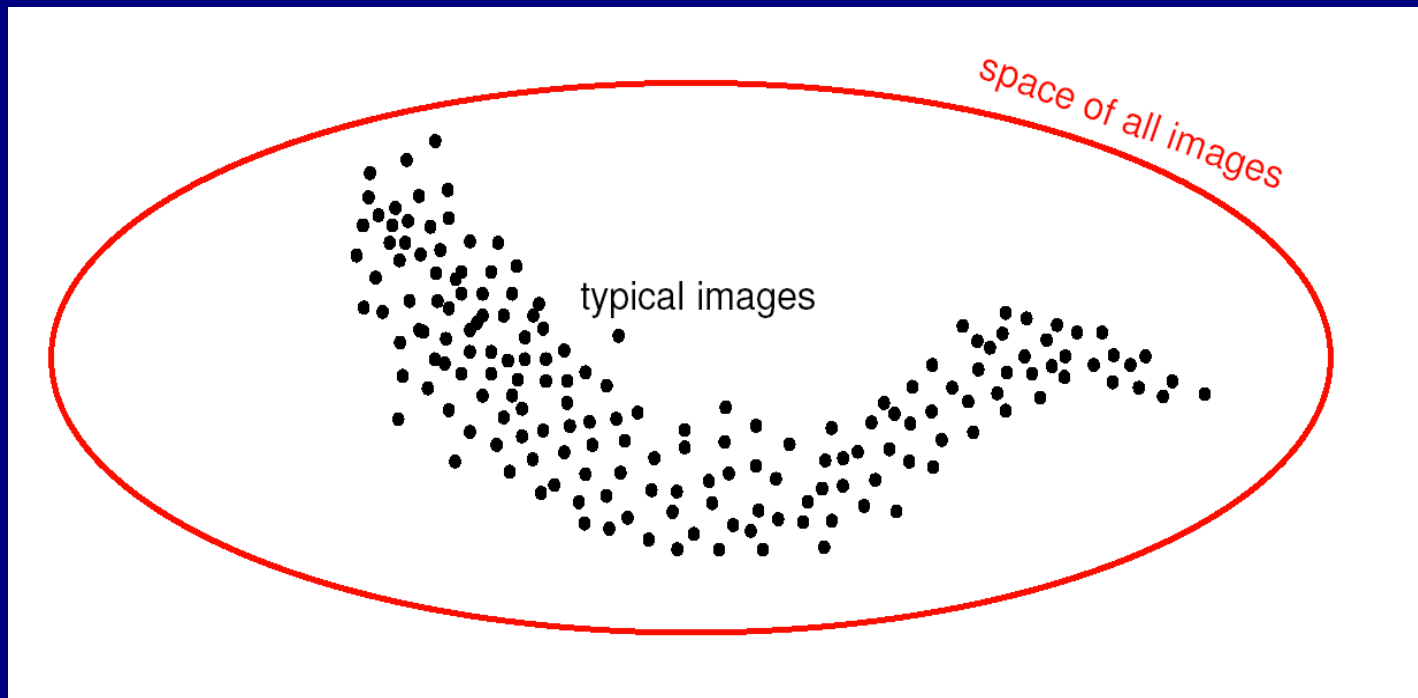
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Outline

- **Statistical Image Modeling**
 - Why statistical image modeling?
 - Pixel intensity models
 - Markov random field models
 - Fourier models
 - Wavelet marginal models
 - Wavelet joint models
 - Advanced statistics: phase and orientation
- **Applications of Statistical Image Modeling**
 - Image denoising
 - Other applications

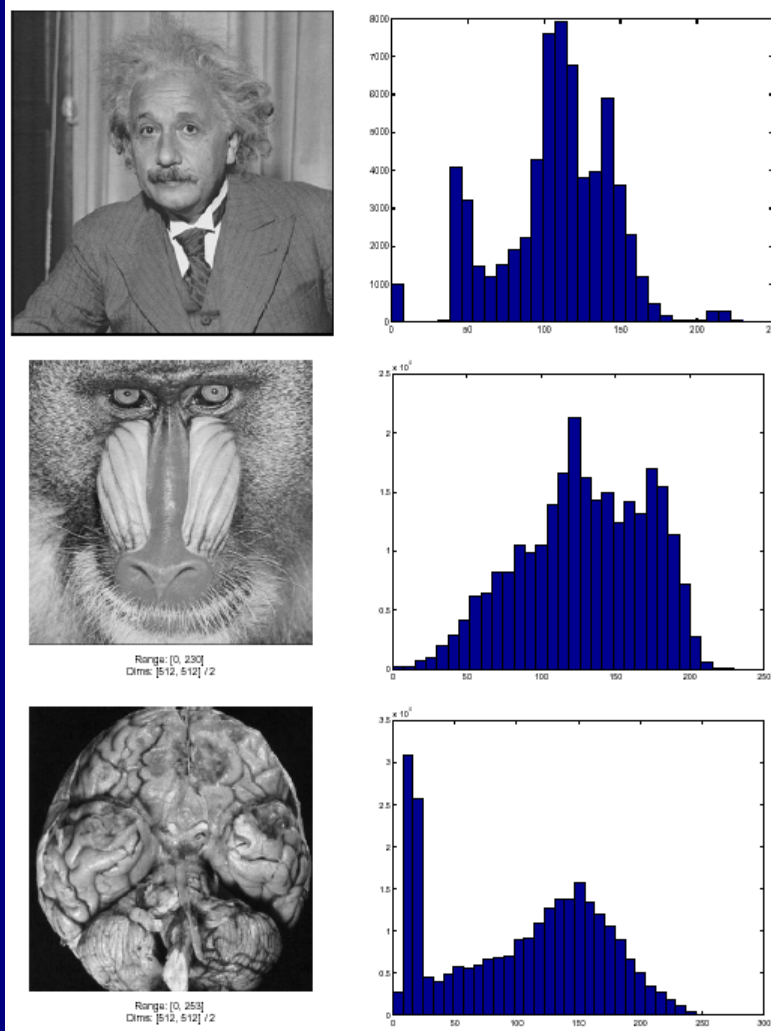
Why Statistical Image Modeling?

- **Prior** Image Probability Distribution 
 - Typical (natural) images occupy an extremely tiny (and unknown-shape) space in the space of all images



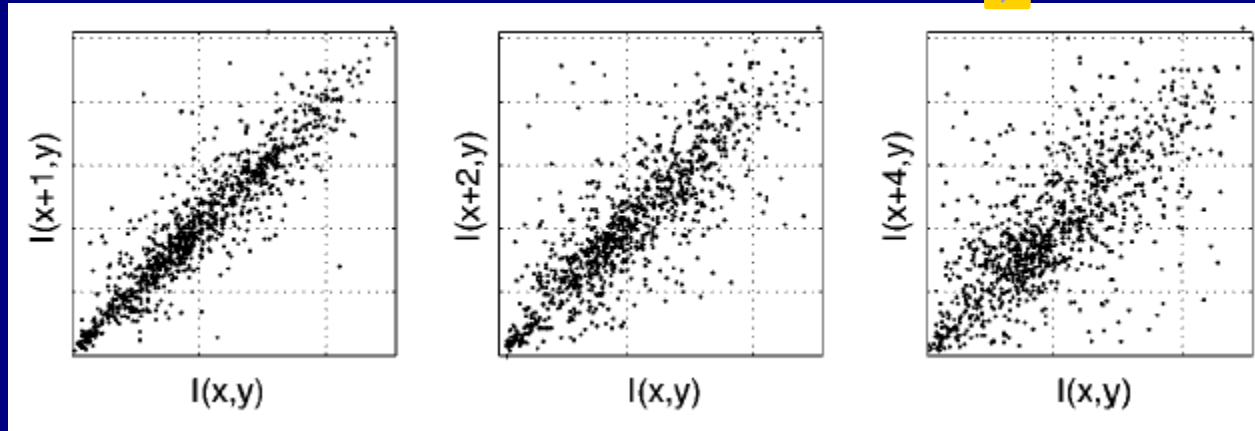
- What's the **Benefit** of Knowing Image Prior?

Pixel Intensity Statistics: Marginal

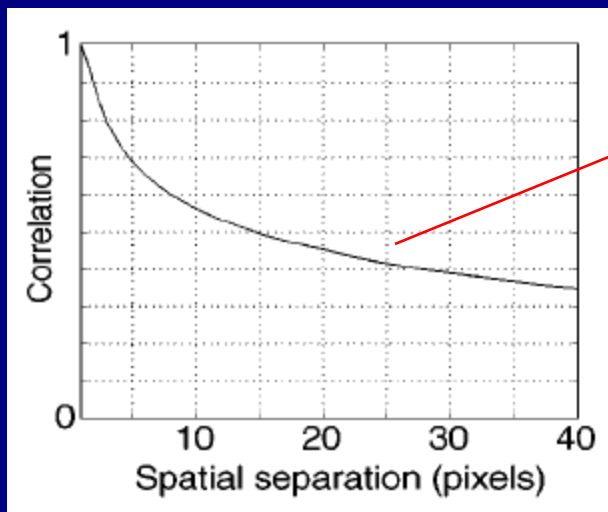


- Does not tell much about what is special of natural images
- What if I scramble the order of image pixels?
- What's the problem?
images are highly “structured”,
or image pixel intensities are
highly dependent (correlated),
which marginal statistics
completely ignore

Pixel Intensity Statistics: Joint



joint distributions of image pixel intensities separated by 1, 2, and 4 pixels



autocorrelation function

autocorrelation function

Fourier transform

power spectrum

Q: What's the underlying assumption here?

A: Stationary (good or bad?)

Pixel Intensity Model: Markov Random Field

- **Random Field \mathbf{x}**

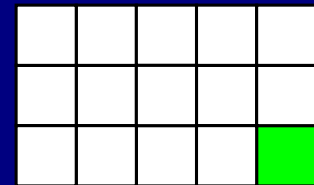
- A collection of RVs on a lattice
- Difficult to define $p(\mathbf{x})$ for images
- “Implicit” but “easier” models

- **Markovianity:**

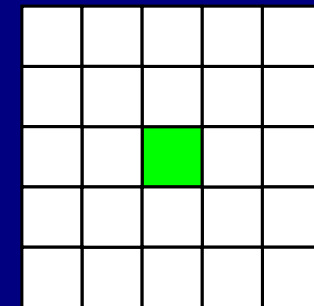
- 1-D: decouple “past” and “future”
- From 1-D to 2-D
- Causal and non-causal neighbors

- **Variations**

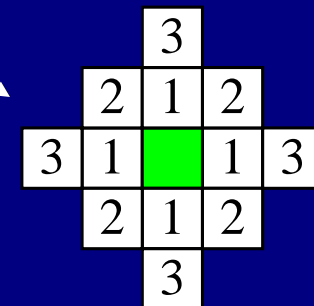
- Gaussian MRF: $p(\mathbf{x})$ Gaussian
- Gibbs MRF: $p(\mathbf{x}) \propto \exp[-\beta E(\mathbf{x})]$
- Extensions:
Gaussian mixture; multi-scale ...



causal neighbors

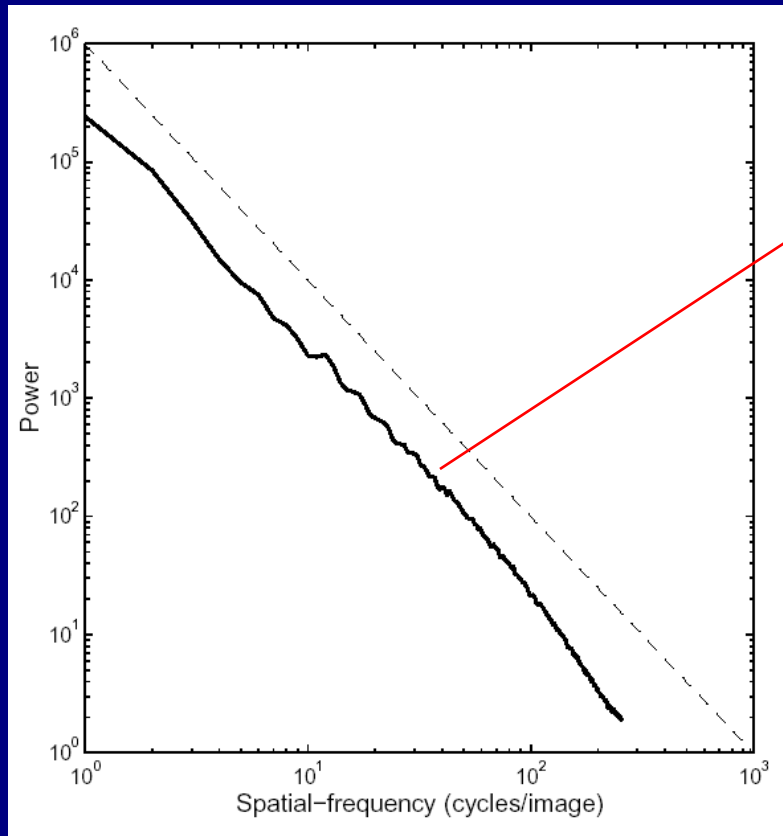


non-causal neighbors



1st, 2nd, 3rd order neighbors

Fourier Magnitude Statistics



straight line!!

$$P(f) = 1 / f^{\beta}$$

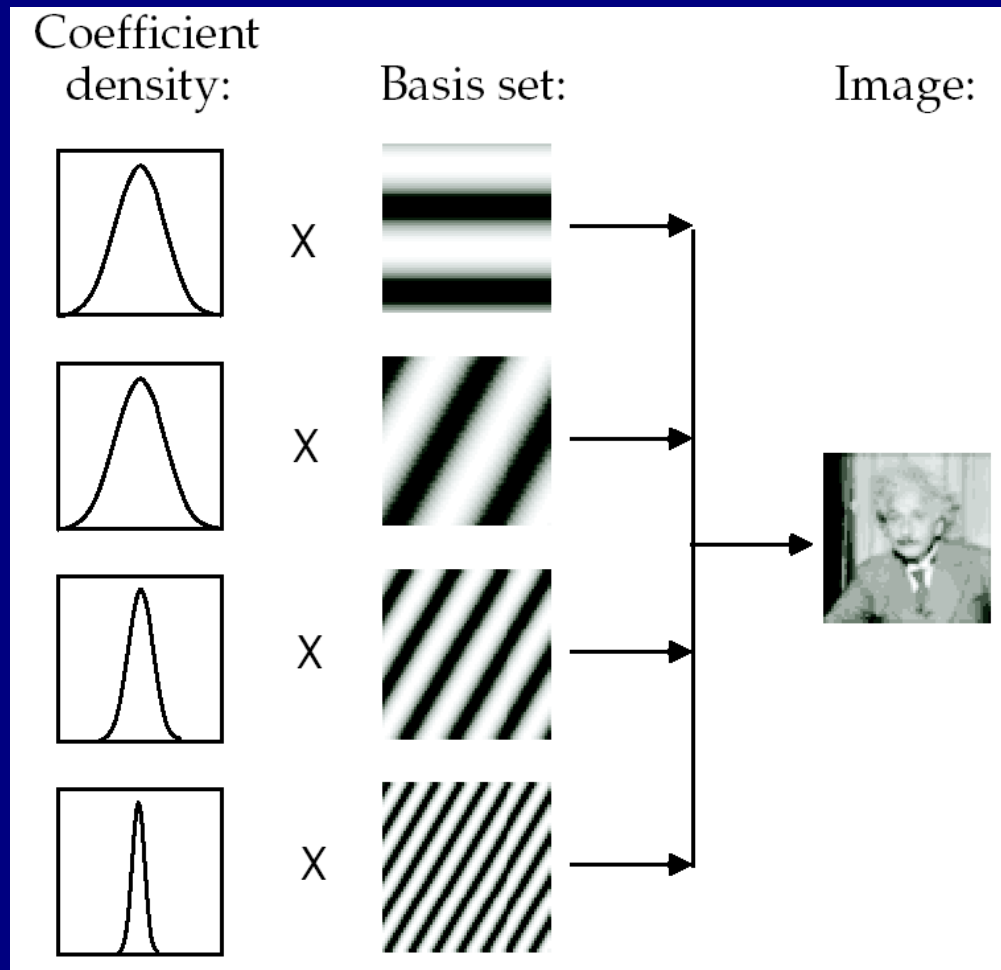
β : typically around 2

Explanations:

1. Scale-invariance
2. Edges

power spectrum of images
(in log-log scale)

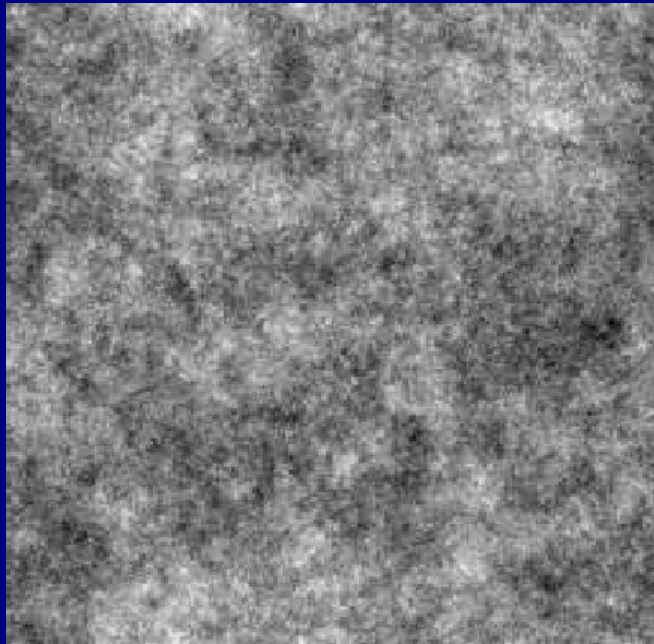
Fourier Magnitude + Gaussian



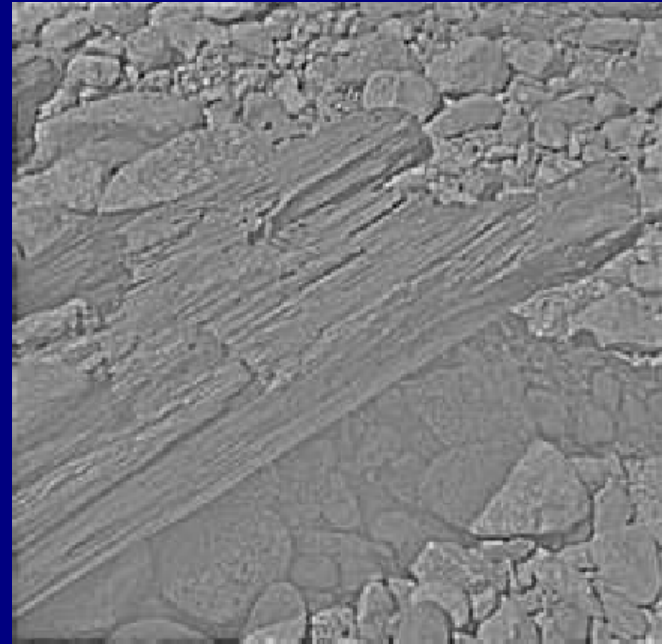
Note: projected Gaussian is still Gaussian

Fourier Magnitude + Gaussian

- Failures of [Fourier Magnitude + Gaussian] Model



A sample drawn from a
 $1/f$ Fourier + Gaussian model
Doesn't look natural! ☹



A natural image after whitening
in Fourier domain
Doesn't look uncorrelated! ☹

Fourier Magnitude + Gaussian

- **Explanations of the Failure**
 - Probability distribution of natural images is not Gaussian
 - Image signals are not stationary
 - Fourier phase is more important than Fourier magnitude

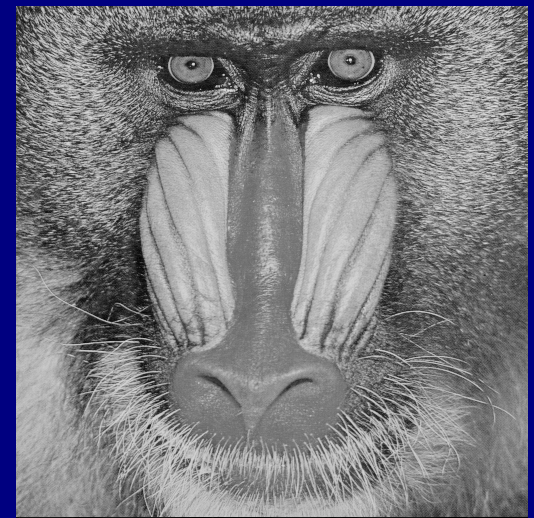


Fourier
phase



combine

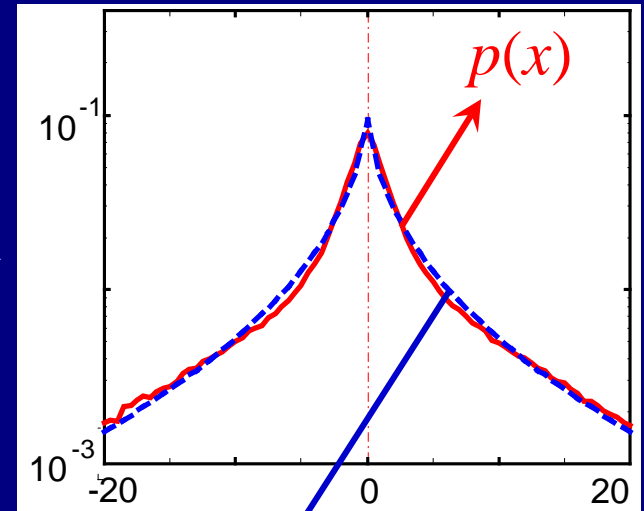
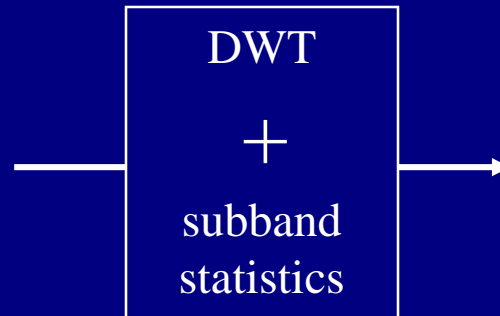
Fourier
magnitude



Modeling on the wrong aspect
of the Fourier transform?!

After [Oppenheim & Lim '81]

Wavelet Marginal Model



coefficient histogram in log-scale

Generalized Gaussian Density [Mallat '89]:

$$p_m(x) = \frac{\beta}{2\alpha\Gamma(1/\beta)} e^{-(|x|/\alpha)^\beta}$$

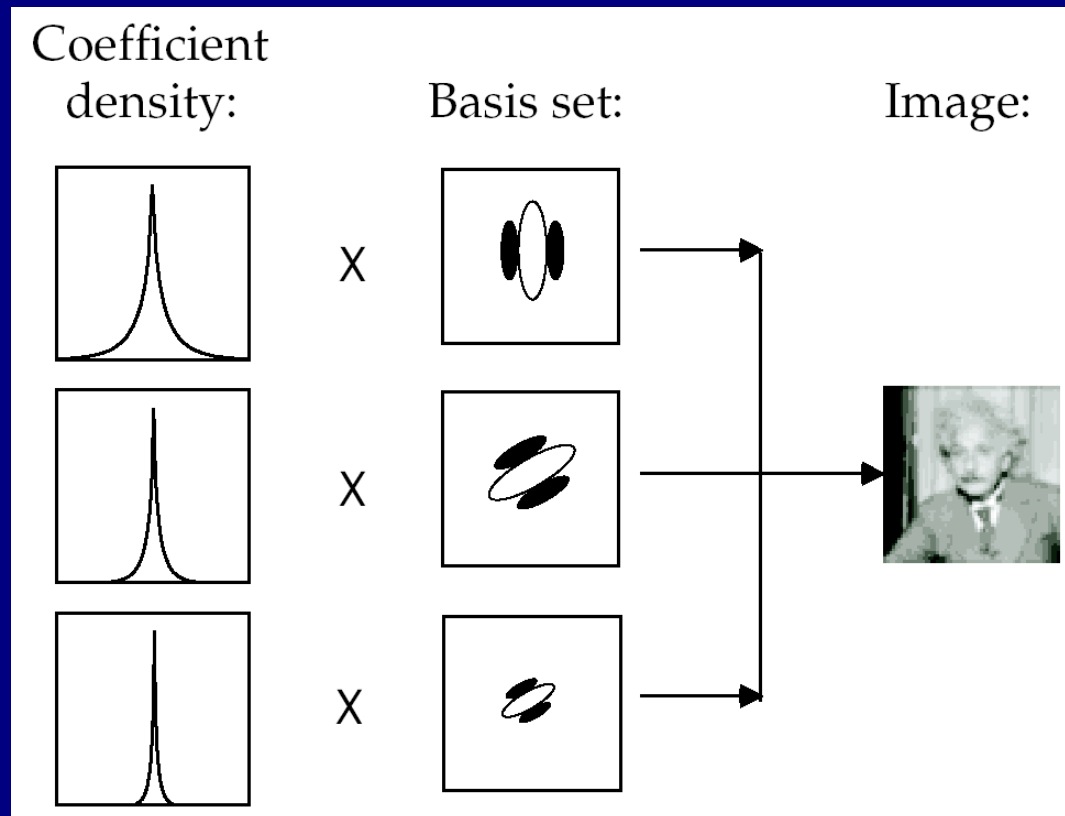
α : scale (variance) parameter

β : peakedness parameter, typically between 0.3 ~ 1.2

Gaussian: $\beta = 2 \rightarrow$ higher entropy, lower kurtosis

Laplacian: $\beta = 1$

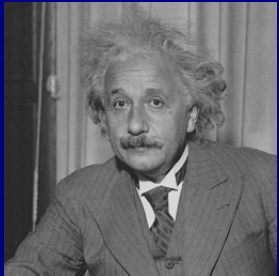
Wavelet + Non-Gaussian Marginal



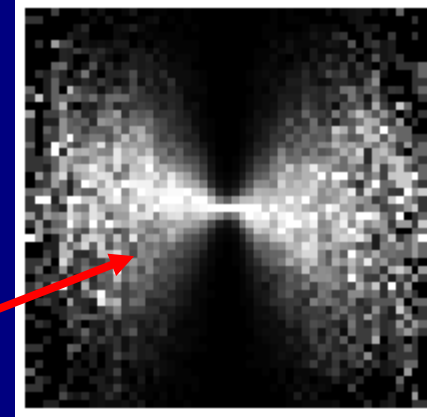
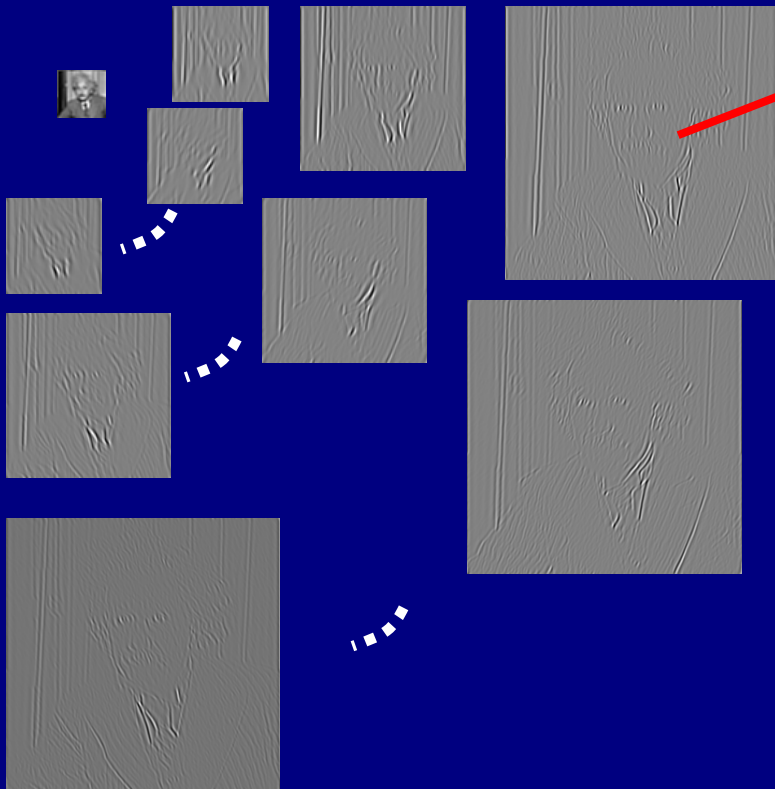
- **Limitation**

- Still cannot capture the dependency between neighboring coefficients (both intra- and inter-channel dependencies)

Wavelet Joint Statistics



↓ steerable pyramid decomposition
[Simoncelli *et al.* '92]

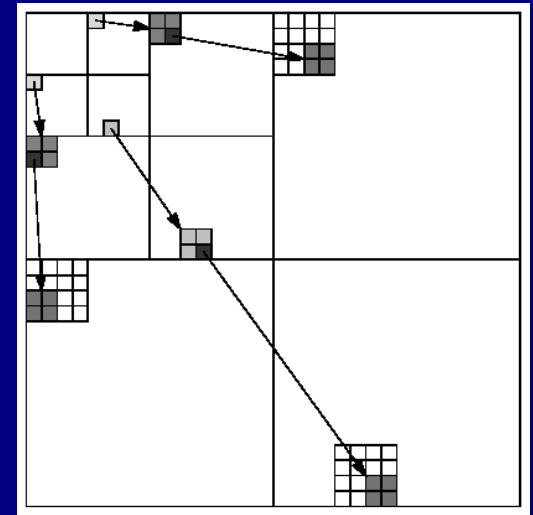


conditional histogram of neighboring coefficients
A "bow-tie" structure [Simoncelli '97]

- Significant (large magnitude) coefficients tend to appear in clusters (neighbors in intra-channel spatial location, and across scales and orientations)

Wavelet Joint Models

- **Hidden Markov Tree** [Crouse, Nowak & Baraniuk '98]



- Hidden states: $S \rightarrow$ small coefficient; $L \rightarrow$ large coefficient
- Hidden state transition matrix

$$A = \begin{bmatrix} p^{S \rightarrow S} & p^{S \rightarrow L} \\ p^{L \rightarrow S} & p^{L \rightarrow L} \end{bmatrix}$$

where

$$p^{S \rightarrow S} > \frac{1}{2}, \quad p^{L \rightarrow L} > \frac{1}{2}$$

Why?

Wavelet Joint Models

- Gaussian Scale Mixture

\mathbf{x} : A vector of neighboring coefficients

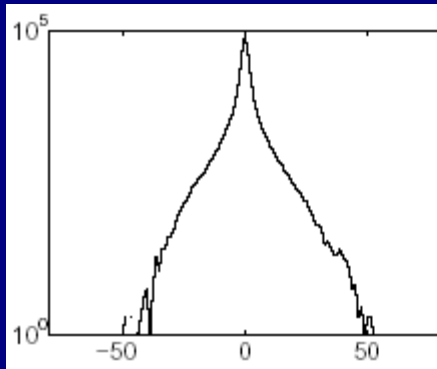
z : multiplier

$$\mathbf{x} \stackrel{d}{=} \sqrt{z} \mathbf{u}$$

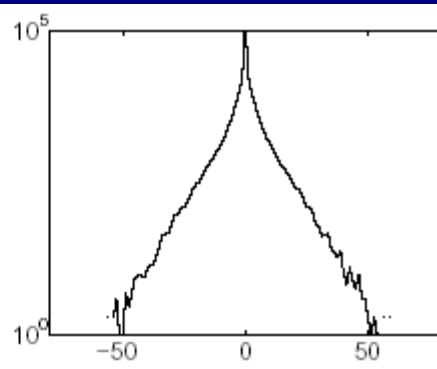
\mathbf{u} : zero-mean Gaussian vector with covariance \mathbf{C}_u

PDF:

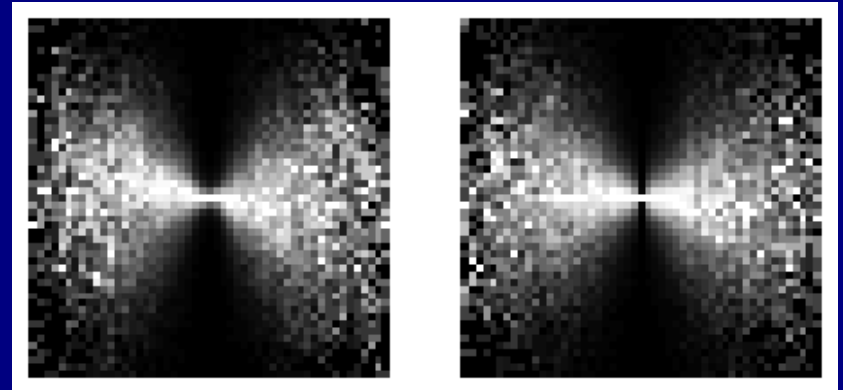
$$\begin{aligned} p_{\mathbf{x}}(\mathbf{x}) &= \int p(\mathbf{x}|z) p_z(z) dz \\ &= \int \frac{\exp(-\mathbf{x}^T (z \mathbf{C}_u)^{-1} \mathbf{x} / 2)}{(2\pi)^{N/2} |z \mathbf{C}_u|^{1/2}} p_z(z) dz \end{aligned}$$



real



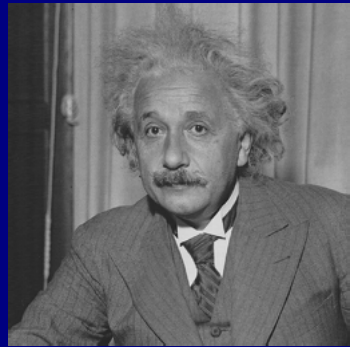
simulated



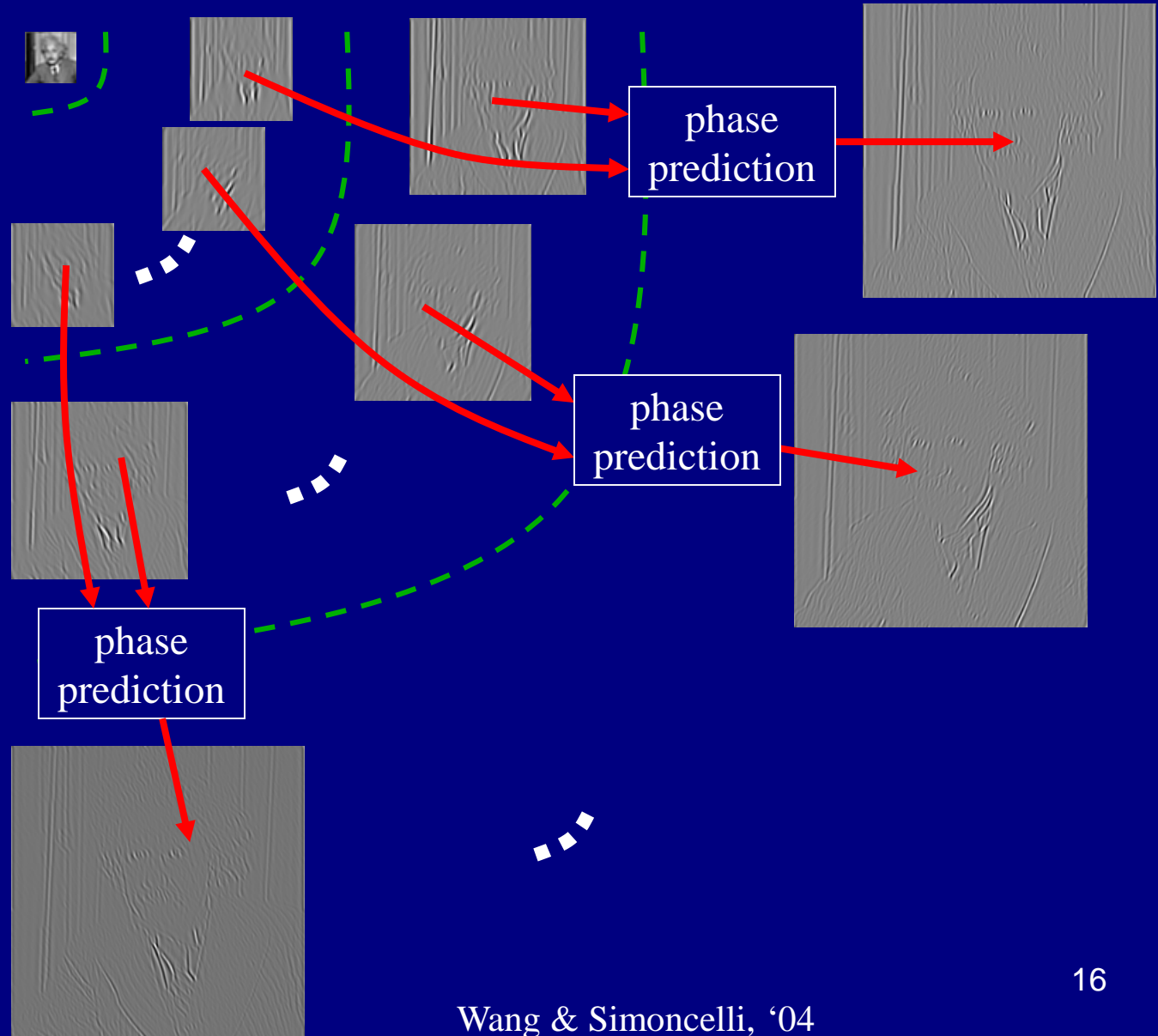
real

simulated

Wavelet Phase Statistics

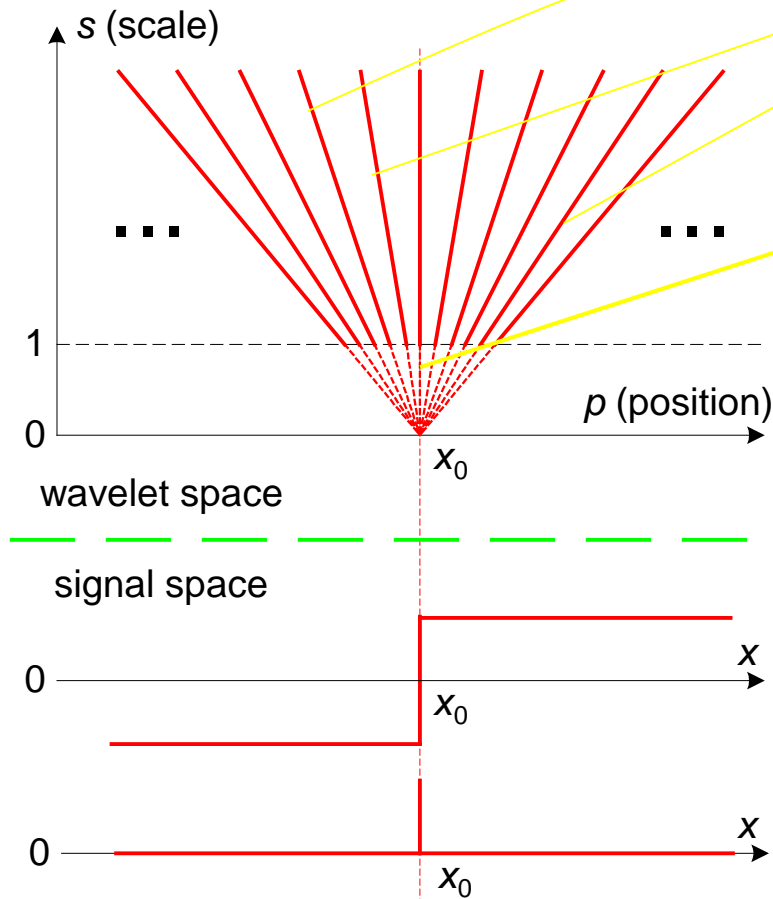


steerable pyramid
decomposition
[Simoncelli *et al.* '92]



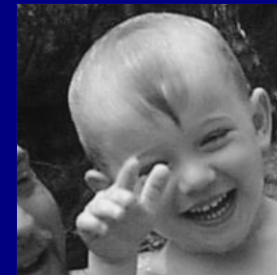
Wavelet Phase Statistics

$$\Phi(F(s, p)) = \Phi\left(F\left(1, x_0 + \frac{p - x_0}{s}\right)\right)$$



$$x_0 + \frac{p - x_0}{s} = \text{Const}$$

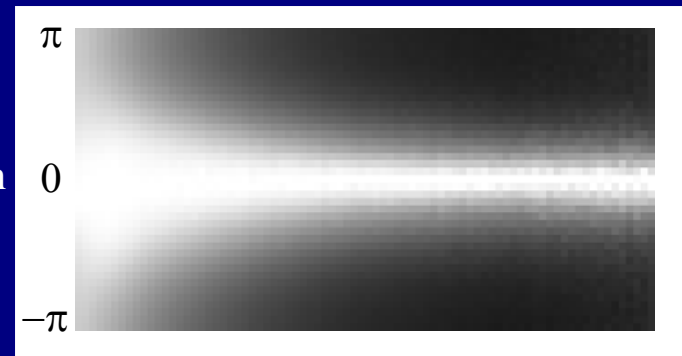
convergent
straight line



1000
natural
images

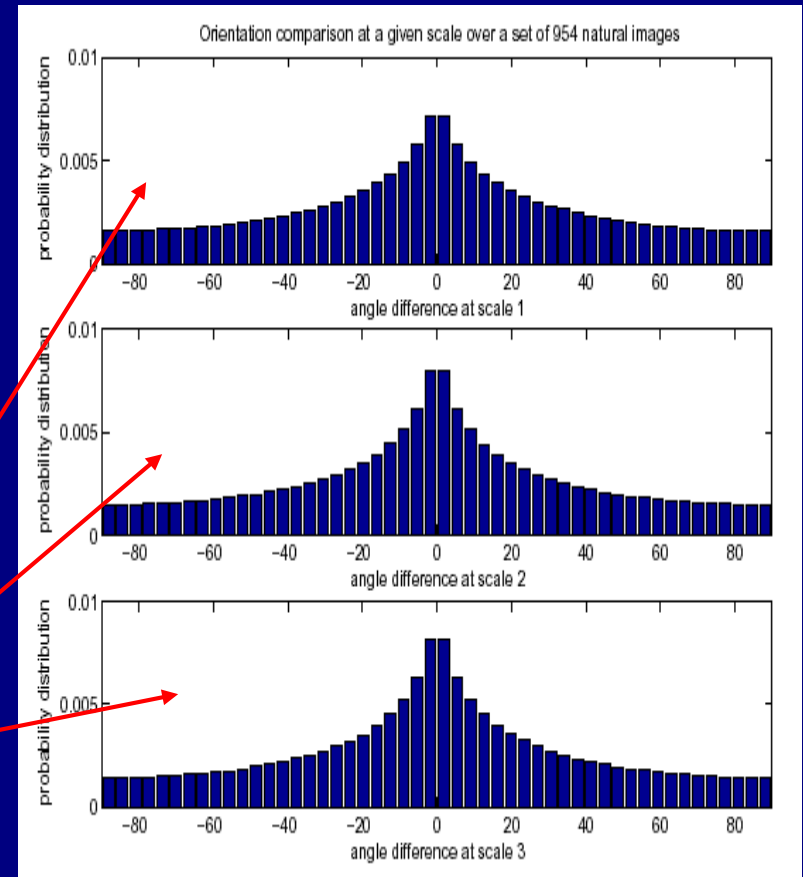
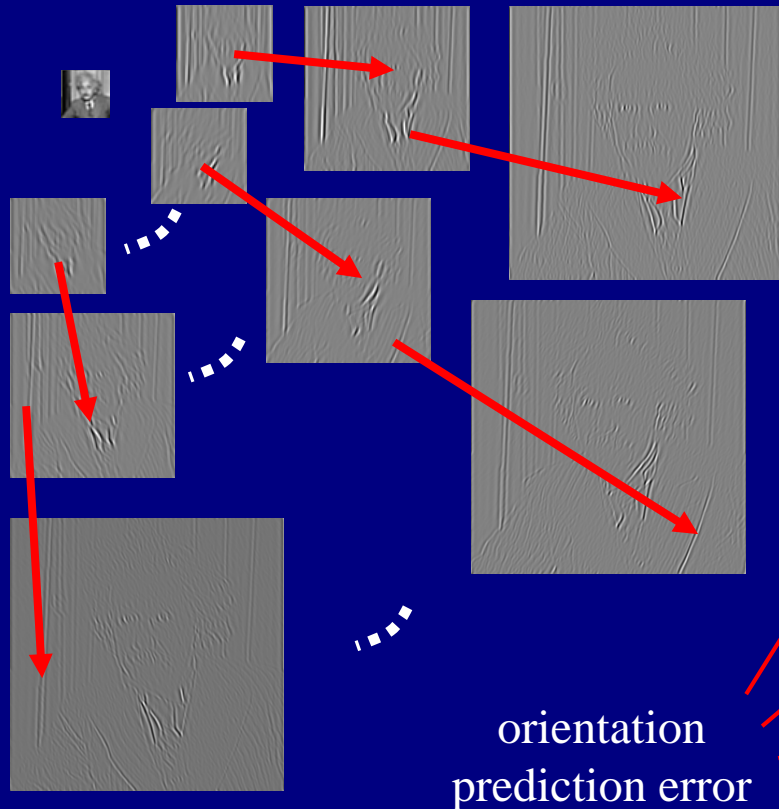


phase
prediction
error



coefficient magnitude

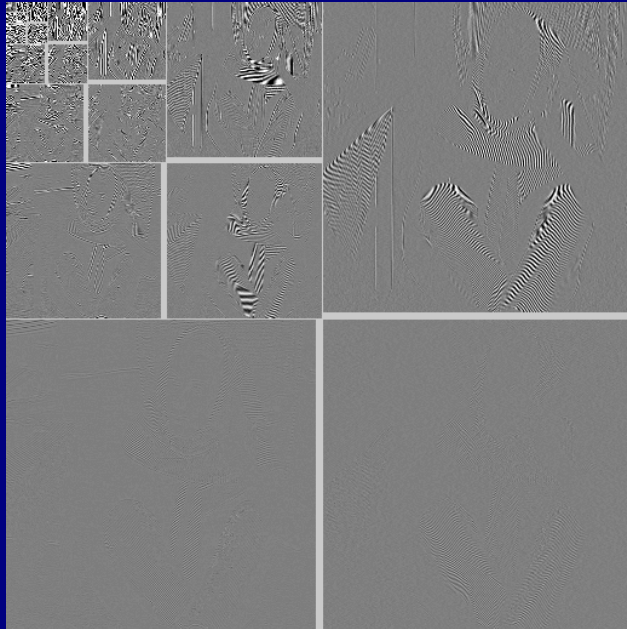
Wavelet Orientation Statistics



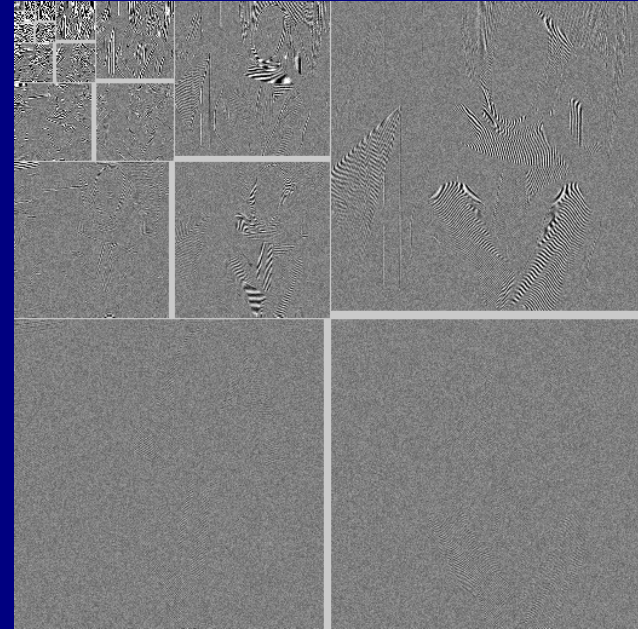
- Orientation at the same spatial location but different scale are correlated.

Application: Image Denoising

- Noisy Image: Observations



DWT of clean “Barbara” image



DWT of noisy “Barbara” image

- More and more noisy from coarser to finer scales (low-pass filtering?)
- More interference with smaller than larger coefficients (thresholding?)
- Signal-to-noise ratio varies over space (locally adaptive filtering?)
- Large coefficients appear in clusters (.....?)
- Large coefficients have correlated orientations and phases (.....?)

Application: Image Denoising

- Denoising Problem

$y = x + w$

x : original
 w : i.i.d. noise, independent of x (zero-mean Gaussian)
 y : observed

– **Goal:** given y , estimate x

- Estimators

- Maximum likelihood: $\hat{x}_{ML} = \arg \max_{\hat{x}} p(y | \hat{x})$
- (Bayes) maximum a posterior: $\hat{x}_{MAP} = \arg \max_{\hat{x}} p(\hat{x} | y)$
- Bayes least square: $\hat{x}_{BLS} = \arg \min_{\hat{x}} E[(x - \hat{x})^2 | y]$

$$\hat{x}_{BLS} = E(x | y) = \int x p(x | y) dx = \int x \frac{p(y | x) p(x)}{p(y)} dx = \frac{\int x p(y | x) p(x) dx}{\int p(y | x) p(x) dx}$$

Why?

Application: Image Denoising

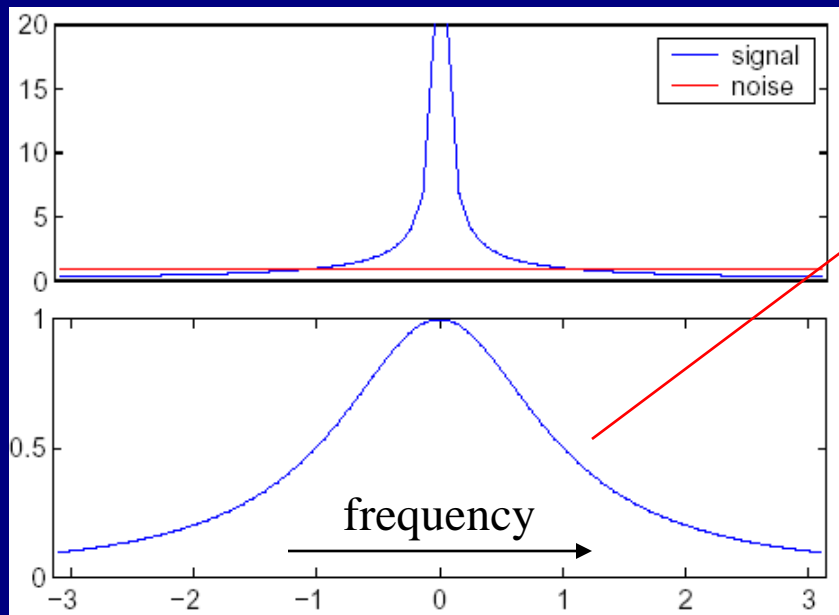
- **Signal Model: Gaussian**

x : zero-mean Gaussian with variance σ_x^2

w : zero-mean Gaussian with variance σ_w^2

- ML estimator: $\hat{x}_{ML} = y$

- MAP and BLS estimator: $\hat{x}_{MAP} = \hat{x}_{BLS} = \frac{\sigma_x^2}{\sigma_x^2 + \sigma_w^2} y$



equivalent to Wiener filtering when applied in the Fourier domain

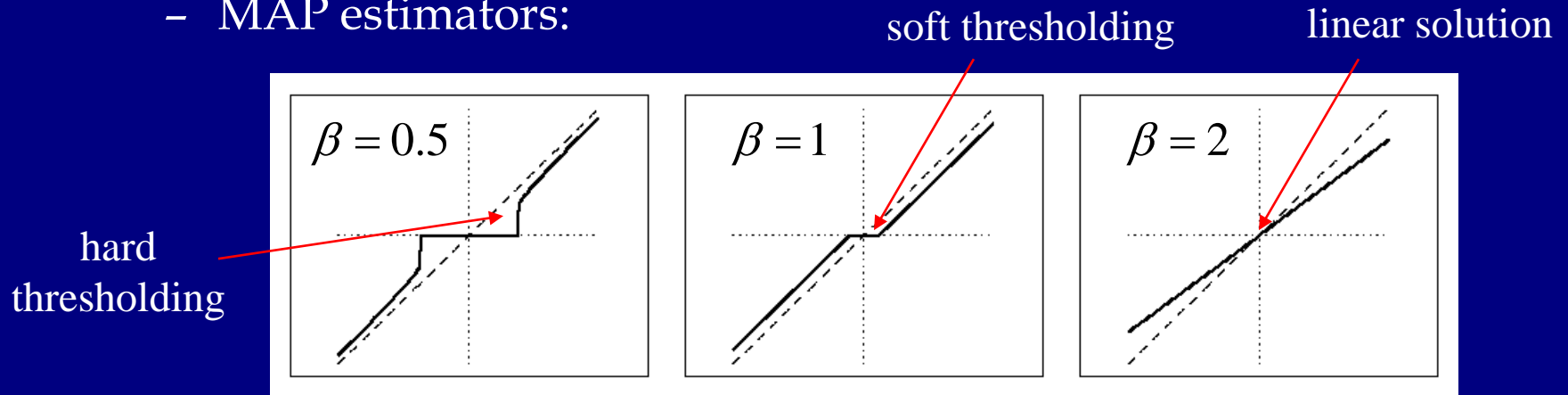
- This explains why Wiener filtered images are always blurred
- Note: the low-pass feature comes from the signal and noise models (not assumed)

Application: Image Denoising

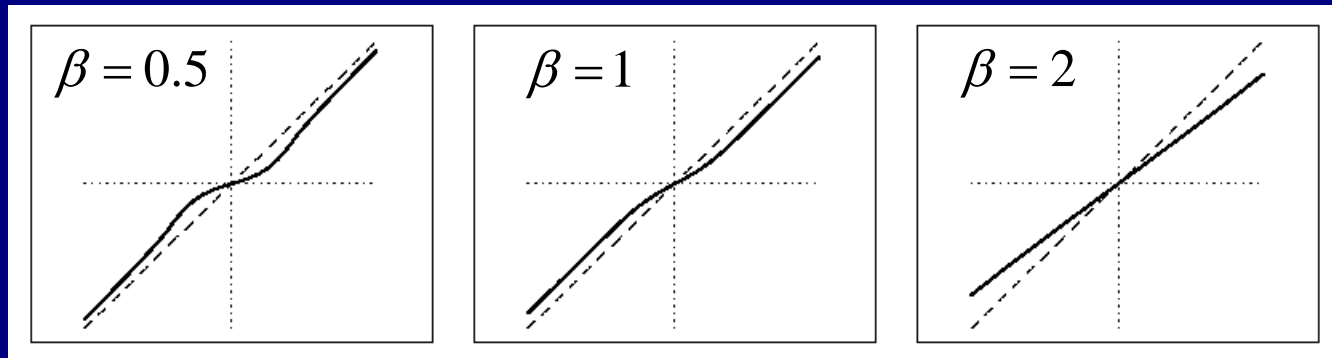
- **Signal Model: Generalized Gaussian**

- ML estimator: $\hat{x}_{ML} = y$

- MAP estimators:

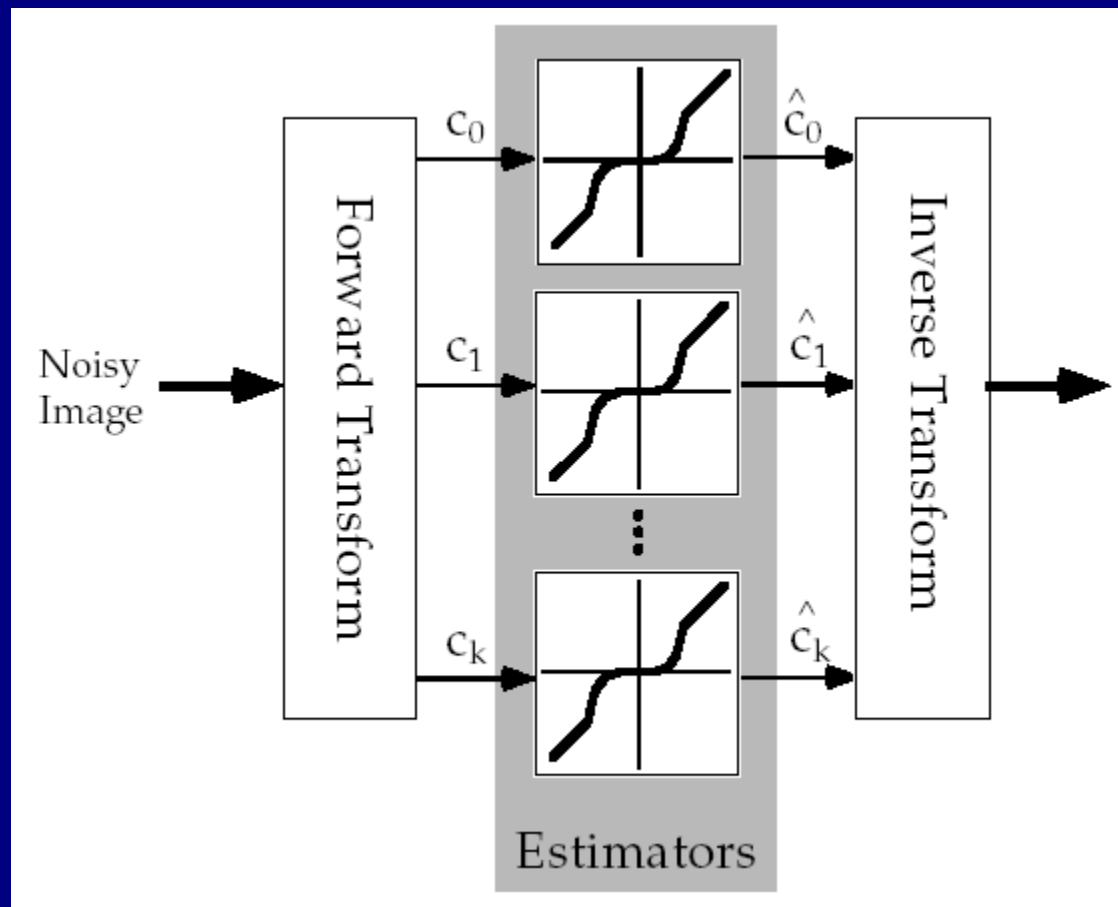


- BLS estimators:



Application: Image Denoising

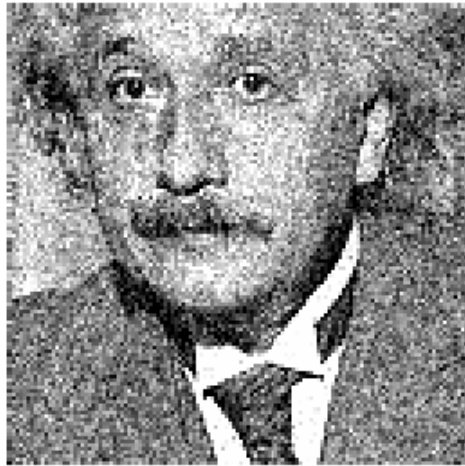
- Application to Images



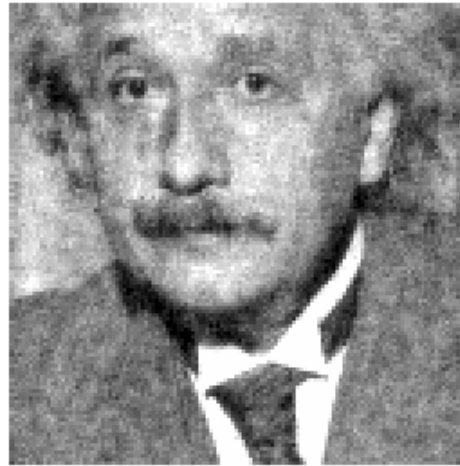
Application: Image Denoising

- Application to Images

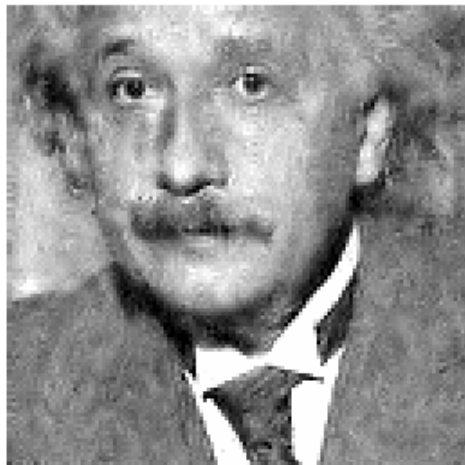
noisy image
SNR = 4.8dB



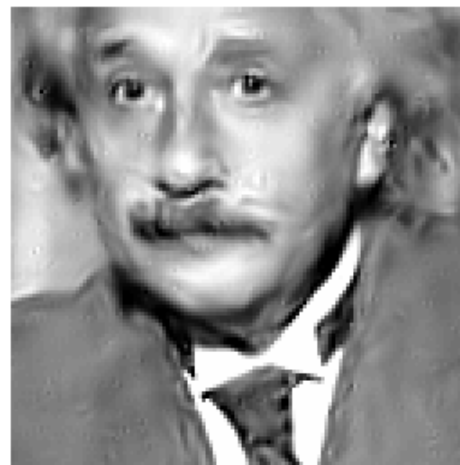
linear filtering
SNR = 10.61dB



nonlinear:
marginal model
+ BLS filtering
SNR = 11.98dB



nonlinear:
joint (GSM) model
+ BLS filtering
SNR = 13.60dB



[Portilla *et al.* '03]

Other Applications of Statistical Image Models

- **Image Compression**
 - Explicit: [Buccigrossi & Simoncelli '99]
 - Implicit: EZW [Shapiro '93], SPIHT [Said & Pearlman '96], JPEG2000 ...
- **Image Restoration**
 - Image model + blur model + noise model
- **Image Enhancement**
 - Moving toward more probable direction in image space
- **Image Quality Assessment**
 - How far an image departs from “natural image clusters”
- **Image (Texture) Segmentation and Classification**
- **Image (Texture) Synthesis**

.....