

# Admin: Changes in grading • Please send me an email before 10/23/15, if you want to keep 20% weightage to midterm-1.

# Today

- · Information theory, entropy
- Readings
  - Chapter 2 from: [DM] David MacKay. Information Theory, Inference, and Learning Algorithms. (http://www.inference.phy.cam.ac.uk/itprnn/book.html)

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### Entropy, MI, ...

- Entropy  $H[X] = -\sum_{x} P(X = x) \log_2 P(X = x)$
- Conditional Entropy:  $H[C \mid X = x] = -\sum_{c} P(C = c \mid X = x) \log_2 P(C = c \mid X = x)$
- Mutual Information (Expected Information):

$$I[C;X] = H[C] - H[C \mid X] = H[C] - \sum_{x} P(X = x) \log_2 H[C \mid X = x]$$

$$I[C;X] = \sum_{y \in Y} \sum_{x \in X} p(x,y) \log \left(\frac{p(x,y)}{p(x)p(y)}\right); I[C;X] = \int_{Y} \int_{X} p(x,y) \log \left(\frac{p(x,y)}{p(x)p(y)}\right) dxdy$$

- Joint Entropy:  $H[X,Y] = -\sum_{x,y} P(X=x,Y=y) \log_2 P(X=x,Y=y)$
- $I[C;X_1,X_2,...X_k] = H[C] + H[X_1,X_2,...X_k] H[C,X_1,X_2,...X_k] = H[C] H[C|X_1,X_2,...X_k]$

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## Algorithm to find most informational attribute

 Calculate the entropy of the training set, T, using the percentages,  $p_+$  and  $p_-$ , of the positive and negative examples:

$$H(T) = -p_{+} \log_{2} p_{+} - p_{-} \log_{2} p_{-}$$

- For each attribute, a, that divides T into subsets, T<sub>i</sub>, with relative sizes P<sub>i</sub>, do the following:
  - (i) calculate the entropy of each subset, T<sub>i</sub>
  - (ii) calculate the average entropy:  $H(T, a) = \Sigma_i P_i H(T_i)$
  - (iii) calculate information gain: I(T, a) = H(T) H(T, a)
- · Choose the attribute with the highest value of information gain.

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# Example

Example	crust	shape	filling	Class
	size		size	
<i>e</i> 1	big	circle	small	pos
<i>e</i> 2	small	circle	small	pos
<i>e</i> 3	big	square	small	neg
e4	big	triangle	small	neg
<i>e</i> 5	big	square	big	pos
e6	small	square	small	neg
e7	small	square	big	pos
e8	big	circle	big	pos

- $H(T) = -p_{+} \log_{2} p_{+} p_{-} \log_{2} p_{-} = -(5/8) \log(5/8) (3/8) \log(3/8) = 0.945$
- Now calculate entropies of subsets defined by attribute (a=shape) (and repeat for all attributes).
  - H(shape = square) = -(2/4) log (2/4) (2/4) log (2/4) = 1
  - H(shape = circle) = -(3/3) log (3/3) (0/3) log (0/3) = 0
  - H(shape = triangle) =  $-(0/1) \log(0/1) (1/1) \log(1/1) = 0$
- From these, we obtain the average entropy of the system where the class labels and the value of attribute shape is known as
  - $H(T, shape) = (4/8) \times 1 + (3/8) \times 0 + (1/8) \times 0 = 0.5$

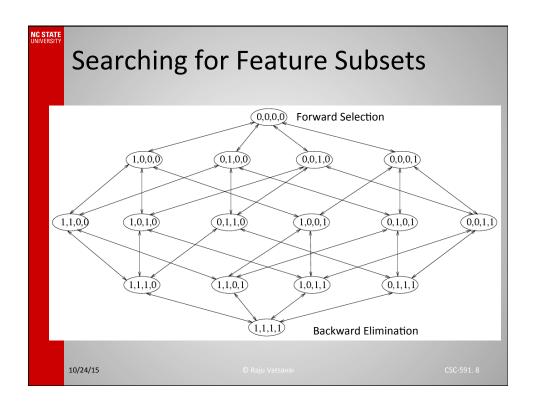
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# Example

- Repeating the process for each attribute, we get
  - H(T, curst-size) = 0.951; H(T, filling-size) = 0.607
- Now compute information gains:
  - -I(T, shape) = H(T) H(T, shape) = 0.954-0.5 = 0.454
    - -I(T, curst-size) = 0.954 0.951 = 0.003
    - -I(T, filling-size) = 0.954 0.607 = 0.347
- Therefore, maximum information is contributed by the shape attribute

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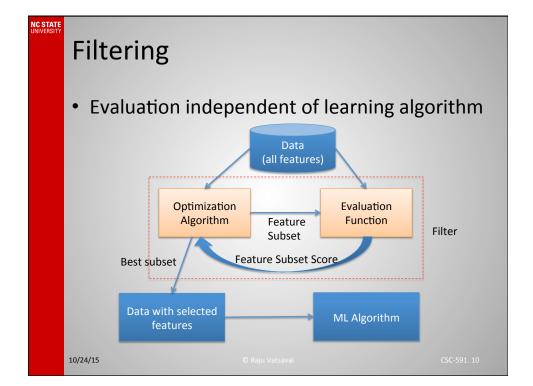


### **Feature Subset Selection**

- Simple Filters
  - Assume features are independent
- Filters
  - Evaluation function is independent of learning algorithm
- Wrappers
  - Evaluation using the machine learning algorithm
- Embedded approaches
  - Feature selection during learning

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# Filtering Approaches

- Distribution based\*
- Idea: Select minimal subset of features whose probability distribution is close to original distribution, i.e., P(C|F subset) ~ P(C|F all)
- Algorithm
  - Start will all features
  - Optimization: Use backward elimination to eliminate predefined number of features
  - Evaluation: the next feature to be eliminated is obtained using cross-entropy measure

\*D. Koller and M. Sahami: Towards optimal feature selection, ICML-1996

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# Filtering Approaches

- Distribution based\*
- Cross Entropy: If p and q are two distributions, then cross entropy of p to q is given by

$$D(p,q) = \sum_{x \in \Omega} p(x) \log \frac{p(x)}{q(x)}$$

- q is approximation of p
- p is also called right distribution (our desired distribution)
- Search space is exponential in number of attributes
- Use the idea of conditional independence
  - Two sets of variables A, B are conditionally independent given a variable X, if P(A=a | X=x, B=b) = P(A=a | X=x).
  - Intuitively removing a feature that is almost independent will not increase the distance between the desired distribution and new distribution with subset.

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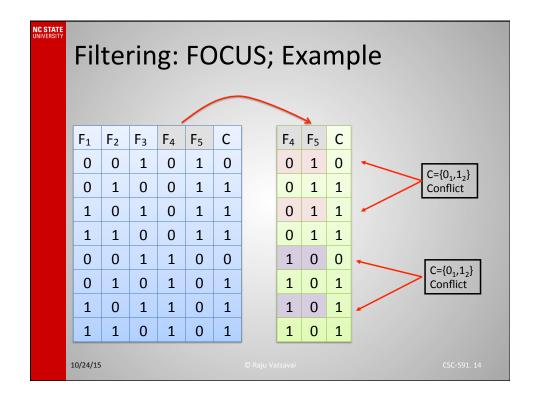
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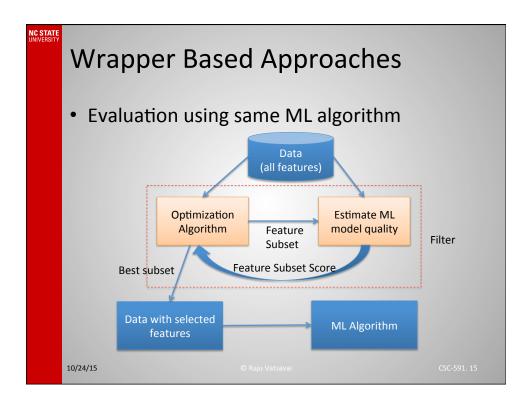
# Filtering: FOCUS Algorithm

- FOCUS: Almallim and Dietterich: Efficient Algorithms for Identifying Relevant Features, AAAI-1992.
- Evaluation
  - In a selected subset
  - Count conflicts in class value (two example with same feature value but different class labels)
- Search
  - All promising subsets of same size are evaluated until a sufficient (no conflict) subset is found
- Improved approaches
  - Using heuristics to avoid evaluating all subsets

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# Wrappers: Instance-based learning • Evaluation (instance-based learning) - Select subset of features - Estimate (ML) model quality using cross validation • Search - Start with rand feature subset - Use beam search with backward elimination [1] or - Use random mutation [2] [1] Aha and Bankert: Feature Selection for case-based classification of cloud-types. AAAI Technical Report WS-94-01. [2] DB Shalak: Prototype and Feature Selection by Sampling and Random Mutation Hill Climbing Algorithms.

