PARTH VINOD PATIL

Contact: +1 7657670983 | Email: parthpatil@purdue.edu | linkedin.com/in/parthvpatil/ | Website: parthvpatil.github.io

Summary

A Robotics Engineer with 3+ years of industry experience and proven expertise in developing software and hardware solutions for autonomous systems; proficient with machine learning, IoT, and embedded systems, and a strong passion for continuous learning.

Education

Purdue University Master of Science in Electrical & Computer Engineering

[Jan' 24 - Present]

Courses – Introduction to Robot Learning, Advanced Software Engineering

Indian Institute of Technology – Bombay (IIT-B) B.Tech in Electrical Engineering with honors

[Aug' 17 - Jun' 21]

Courses – Advanced Machine Learning, Digital Image Processing, Control Systems, VLSI Design, Microprocessors

Publications

ICSE Recommending Pre-Trained Models for IoT Devices | NIER Track - SERP4IoT Workshop

2025

47th IEEE International Conference on Software Engineering

ICSE Enabling Unit Proofing for Software Implementation Verification | NIER Track

2024

47th IEEE/ACM International Conference on Software Engineering

Professional Experience

Amazon Robotics | Manufacturing Test Engineering Co-op

[Jan' 25 - Aug' 25]

- Contributed to the development of a manufacturing test solution for a state-of-the-art end-of-arm tooling system.
- Engineered a communication protocol between PLC hardware and a Python application to enable automated testing.

Drivetrain Ai Technologies | Software Development Engineer 2

[Jan' 23 - Jan' 24]

- Upgraded website-wide search with ElasticSearch boosting hit rate by 3x and delivering search results within 200ms.
- Built a ChatGPT integration for search, automating actions and reducing metric creation time from 10 mins to a few seconds.

Udaan | Robotics Engineer 2

[Jul' 21 – Jan' 23]

- Led the development of autonomous **swarm robots** based Goods-To-Person system in a warehouse called 'Vahaan', capable of lifting racks of 500kgs (a high payload weight class) and navigating the layout avoiding human obstacles
- Deployed multi-robot path planning algorithm based on D* & node reservation, yielding zero collision paths.
- Architected the Fleet Management Service, responsible for optimal task allocation, enabling faster picking for items.

Samsung Electronics | Research Intern

[May' 20 - Jul' 20]

• Collaborated on the development of **Samsung SmartThings Hub 3** by migrating device health monitoring from the cloud to a Hub 3 based system with edge computing and using Kafka for syncing events thus saving **\$23 million** in cloud cost.

Research & Projects

Object Manipulation with four Legged Robots | Research | Guide: A. Qureshi

[Jan' 24 – Jul' 24]

• Improvised a novel approach for using the leg of the quadruped as a manipulator using Unitree B1 inside Isaac Gym.

Anomalous Human Activity Detection | Research | Guide: R. Velmurugan

[Aug' 20 – Apr' 21]

• Engineered a novel framework for anomaly detection in CCTV videos, leveraging Prototypical CNN to analyze only 5 normal frames and identify anomalies such as robbery, accidents, over-speeding cars, etc in videos

Autonomous Underwater Vehicle (AUV) | Software Subdivision Lead

[Sep' 17 – Jun' 21]

- Fabricated 'Matsya', an autonomous underwater vehicle, with visual, acoustic, and depth sensors for realistic naval mission.
- Implemented Extended Kalman filter-based sensor-fusion estimation that reduced pose estimation drifting by 90%.
- Collaborated with 'Larsen & Toubro Defence' to design an underwater Remotely Operated Vehicle (ROV) deployable in seawater for scanning ship hulls & for surveillance in pots and ocean.

Django Software Foundation | Google Summer of Code (GSoC)

[May' 19 - Aug' 19]

- Optimized FormSet and similar classes to use declarative syntax, boosting user-friendliness and productivity of forms.
- Created an 'edit only' mode in ModelFormSet to prevent SQL injection attacks, improving overall security of models.

Skills and Experience

Languages Frameworks Electrical Python, C++, C#, Java, Kotlin, Bash, C, Groovy, Rust, Ruby, Go, Assembly, VHDL, ST

•Robotics: ROS, Gazebo, IsaacGym, MuJoCo •AI/ML: PyTorch, OpenCV, TensorFlow, Pandas
Arduina, Passpharry Bi, Tinker Poard, NodeMCLI, Crypton EDGA, STM, Passplanas, Linux

Arduino, Raspberry Pi, Tinker-Board, NodeMCU, Crypton FPGA, STM, Beaglebone, Linux