

PARTH VINOD PATIL

Contact: +1 7657670983 | Email: parthpatil@purdue.edu | linkedin.com/in/parthvpatil/ | Website: parthvpatil.github.io

Summary

A Robotics Engineer with 3+ years of industry experience and proven expertise in developing software and hardware solutions for autonomous systems; proficient with machine learning, IoT, and embedded systems, and a strong passion for continuous learning.

Education

Purdue University	Master of Science in Electrical & Computer Engineering	[Jan' 24 - Present]
Indian Institute of Technology – Bombay (IIT-B)	B.Tech in Electrical Engineering with honors	[Aug' 17 - Jun' 21]

Publications

ICSE	Recommending Pre-Trained Models for IoT Devices PV Patil, W Jiang, H Peng, et al.	2025
	47th IEEE/ACM International Conference on Software Engineering - SERP4IoT Workshop	
ICSE	Enabling Unit Proofing for Software Implementation Verification PC Amusuo, PV Patil, et al.	2025
	47th IEEE/ACM International Conference on Software Engineering - NIER Track	

Professional Experience

Amazon Robotics	Manufacturing Test Engineer co-op	[Jan' 25 - Aug' 25]
<ul style="list-style-type: none">Contributed to the development of a manufacturing test solution for a state-of-the-art end-of-arm tooling system.Engineered a communication protocol between PLC hardware and a Python application to enable automated testing.		
Drivetrain Ai Technologies	Software Development Engineer 2	[Jan' 23 - Jan' 24]
<ul style="list-style-type: none">Upgraded website-wide search with ElasticSearch, boosting hit rate by 3x and delivering search results within 200ms.Built a ChatGPT integration for search, automating actions, and reducing metric creation time from 10 mins to a few seconds.		
Udaan	Robotics Engineer 2	[Jul' 21 – Jan' 23]
<ul style="list-style-type: none">Led the development of autonomous swarm robots based Goods-To-Person system in a warehouse called 'Vahaan', capable of lifting racks of 500kgs (a high payload weight class) and navigating the layout avoiding human obstaclesDeployed multi-robot path planning algorithm based on D* & node reservation, yielding zero collision paths.Architected the Fleet Management Service, responsible for optimal task allocation, enabling faster picking for items.		
Samsung Electronics	Research Intern	[May' 20 - Jul' 20]
<ul style="list-style-type: none">Collaborated on the development of Samsung SmartThings Hub 3 by migrating device health monitoring from the cloud to a Hub 3 based system with edge computing and using Kafka for syncing events thus saving \$23 million in cloud cost.		

Research & Projects.

Formally verified controller synthesis from Natural Language	Research Guide: James C. Davis	[Aug' 24 – Present]
<ul style="list-style-type: none">Developing a method to synthesize controllers from natural language prompts verified with LTL specifications for correctness.		
Object Manipulation with four Legged Robots	Research Guide: A. Qureshi	[Jan' 24 – Jul' 24]
<ul style="list-style-type: none">Improvise a novel approach for using the leg of the quadruped as a manipulator using Unitree B1 inside Isaac Gym.		
Anomalous Human Activity Detection	Research Guide: R. Velmurugan	[Aug' 20 – Apr' 21]
<ul style="list-style-type: none">Engineered a novel framework for anomaly detection in CCTV videos, leveraging Prototypical CNN to analyze only 5 normal frames and identify anomalies such as robbery, accidents, over-speeding cars, etc in videos		
Autonomous Underwater Vehicle (AUV)	Software Subdivision Lead	[Sep' 17 – Jun' 21]
<ul style="list-style-type: none">Fabricated 'Matsya', an autonomous underwater vehicle, with visual, acoustic, and depth sensors for realistic naval mission.Implemented Extended Kalman filter-based sensor-fusion estimation that reduced pose estimation drifting by 90%.Collaborated with 'Larsen & Toubro Defence' to design an underwater Remotely Operated Vehicle (ROV) deployable in seawater for scanning ship hulls & for surveillance in pots and ocean.		
Django Software Foundation	Google Summer of Code (GSoC)	[May' 19 - Aug' 19]
<ul style="list-style-type: none">Optimized FormSet and similar classes to use declarative syntax, boosting user-friendliness and productivity of forms.Created an 'edit only' mode in ModelFormSet to prevent SQL injection attacks, improving overall security of models.		

Skills and Experience

Languages	Python, C++, C#, Java, Kotlin, Bash, C, Groovy, Rust, Ruby, Go, Assembly, VHDL, ST
Frameworks	• Robotics : ROS, Gazebo, IsaacGym, Codesys • AI/ML : PyTorch, OpenCV, TensorFlow, Pandas
Electrical	Arduino, Raspberry Pi, Tinker-Board, NodeMCU, Crypton FPGA, STM, Beaglebone, Linux